# A Note on the Bifurcation of Solutions for an Elliptic Sublinear Problem. 

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## 1. Introduction.

We consider the following semilinear problem in a bounded domain $\Omega \subset \boldsymbol{R}^{N}$ :

$$
\begin{cases}L u+u^{\theta}=\lambda u & \text { in } \Omega,  \tag{1.1}\\ u \geqslant 0, \quad u \not \equiv 0, & \text { in } \Omega, \\ u=0 & \text { on } \partial \Omega,\end{cases}
$$

where $0<\theta<1$ and $L u$ is a linear differential operator defined as $L u=$ $=-\operatorname{div}(A(x) \nabla u), A(x)$ being a symmetric, bounded and coercive matrix, that is such that

$$
\begin{equation*}
\alpha|\xi|^{2} \leqslant A(x) \xi \cdot \xi \leqslant \beta|\xi|^{2} \tag{1.2}
\end{equation*}
$$

for every $\xi \in \boldsymbol{R}^{\mathrm{N}}$, a.e. $x \in \Omega$, with $\alpha, \beta>0$.
A necessary condition to find nonnegative nontrivial solutions of (1.1) is that $\lambda>\lambda_{1}$, the first eigenvalue of the operator $L$ on $\Omega$ with Dirichlet
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boundary conditions. Notice that (1.1) is the Euler equation of the functional

$$
\begin{array}{r}
J_{\lambda}(u)=\frac{1}{2} \int_{\Omega} A(x) \nabla u \cdot \nabla u d x-\frac{\lambda}{2} \int_{\Omega}\left(u^{+}\right)^{2} d x+\frac{1}{\theta+1} \int_{\Omega}|u|^{\theta+1} d x  \tag{1.3}\\
u \in H_{0}^{1}(\Omega)
\end{array}
$$

which, since $0<\theta<1$, is not bounded from below if $\lambda>\lambda_{1}$.
As it was remarked in [8] (see also [6]), the existence of a solution of (1.1) for every $\lambda>\lambda_{1}$ can be obtained applying the abstract fixed point results by Krasnoselskii ([9]). This approach relies on the definition of the inverse operator of $u \mapsto L u+|u|^{\theta} \frac{u}{|u|}$ and makes use of its compactness properties and the computation of its derivative at zero and at infinity. Similarly, using the results of Rabinowitz in [11], in [6] it is proved the existence of a connected branch of solutions ( $\lambda, u_{\lambda}$ ) bifurcating from infinity at $\lambda=\lambda_{1}$. The same kind of arguments is used in a more general context in [3] to deal also with sublinear eigenvalue problems, following the method developed in [1] (see also [10]).

As a consequence of the previous results, the bifurcation diagram for solutions of (1.1) reads as follows: there is bifurcation from infinity if and only if $\lambda=\lambda_{1}$ while no finite value of $\lambda$ can be a bifurcation point from the zero solution. The aim of this note is to prove that the bifurcation from the trivial solution actually occurs at $\lambda=+\infty$.

More precisely, we prove that there exists a sequence $u_{\lambda}, \lambda>\lambda_{1}$, of Mountain Pass type solutions of (1.1) such that $\left\|u_{\lambda}\right\|_{H_{0}^{1}(\Omega)}$ tends to zero as $\lambda$ goes to infinity. In fact, we do not know whether any sequence of solutions of (1.1) will converge to zero as $\lambda$ tends to infinity, nevertheless the sublinear behavior of the absorption term both near the origin and at infinity yields a classical Mountain Pass type structure to the functional $J_{\lambda}$ which allows to construct such a sequence, obtaining the bifurcation from $u=0$ at $\lambda=+\infty$. This is the result that we prove.

THEOREM 1.1. Let $0<\theta<1$, and let (1.2) be satisfied. Then for every $\lambda>\lambda_{1}$ problem (1.1) admits a solution $u_{\lambda} \in H_{0}^{1}(\Omega)$ which is a critical point of Mountain Pass type of the functional $J_{\lambda}$ defined in (1.3). Moreover this family of solutions $u_{\lambda}$ satisfies

$$
\begin{equation*}
\lim _{\lambda \rightarrow+\infty}\left\|u_{\lambda}\right\|_{H_{0}^{1}(\Omega)}=0 \tag{1.4}
\end{equation*}
$$

The bifurcation from the trivial solution at infinity has already been proved for the semilinear problem

$$
\begin{cases}L u=\lambda u^{p} & \text { in } \Omega  \tag{1.5}\\ u \geqslant 0, \quad u \neq 0, & \text { in } \Omega \\ u=0 & \text { on } \partial \Omega\end{cases}
$$

with $p>1$. For a certain range of values of $p$ this was obtained in [5] via a priori estimates while a general result (for every subcritical $p>1$ ) was proved in [4] using the variational structure of the equation and estimates on the Mountain Pass level of the related functional. Our problem (1.1) is much different with respect to (1.5) since the nonlinearity $\lambda u-u^{\theta}$ is asymptotically linear at infinity and the Mountain Pass character is due to a sublinear positive perturbation. This implies that the approaches of these previous papers do not work, in particular the standard regularity (bootstrap) argument is not such helpful and the method used in [4] would only give here an estimate on the $L^{\theta+1}(\Omega)$ norm of $u$. For this reason we use here a refined construction of the Mountain Pass solutions $u_{\lambda}$, which are obtained through a recurrence argument, allowing, at fixed $\bar{\lambda}$, to estimate $J_{\bar{\lambda}}$ on the paths $\left[0, u_{\lambda}\right]$, where $\lambda<\bar{\lambda}$ and $u_{\lambda}$ is the Mountain Pass solution previously found.

Let us stress that, in dimension $N=1$, a full study of the equation (1.1) is carried out in the recent work [7]. In that paper the case of the $p$ laplace operator is also considered and the set of solutions of the problem is fully characterized, giving multiplicity results as well. While our results can be proved without relevant changes for the $p$-laplace operator as well, we cannot give here a full picture of the behavior of the solutions in dependence of $\lambda$.

## 2. Proof of Theorem 1.1.

We denote by $\lambda_{1}$ the first eigenvalue of the operator $L$ with Dirichlet boundary conditions on $\partial \Omega$, and by $\varphi_{1}$ the positive eigenfunction such that $L \varphi_{1}=\lambda_{1} \varphi_{1},\left\|\varphi_{1}\right\|_{L^{2}(\Omega)}=1$.

Proof of Theorem 1.1. The proof of Theorem 1.1 is a consequence of the following two Propositions.

Proposition 2.1. Let $\lambda>\lambda_{1}$. Then problem (1.1) admits a solution $u_{\lambda}$ which is a critical point of Mountain Pass type of the functional $J_{\lambda}$
defined in (1.3). Moreover $u_{\lambda}$ satisfies:

$$
\begin{equation*}
J_{\lambda}\left(u_{\lambda}\right) \leqslant\left(\frac{1}{\theta+1}-\frac{1}{2}\right) \frac{\left(\int_{\Omega}|w|^{\theta+1} d x\right)^{\frac{2}{1-\theta}}}{\left(\lambda \int_{\Omega} w^{2}-\int_{\Omega} A(x) \nabla w \cdot \nabla w d x\right)^{\frac{1+\theta}{1-\theta}}} \tag{2.1}
\end{equation*}
$$

for every $w: \lambda \int_{\Omega} w^{2} d x-\int_{\Omega} A(x) \nabla w \cdot \nabla w d x>0$.

Proof. We are going to use the classical theorem of Ambrosetti and Rabinowitz ([2]) with a little change in the choice of the paths.

We start by proving that $u=0$ is a local minimum for the functional $J_{\lambda}$. Precisely, we claim that

$$
\begin{equation*}
\exists \varrho>0: \quad J_{\lambda}(u)>0 \quad \forall u \in \bar{B}_{\varrho} \backslash\{0\}=\left\{\|u\|_{H_{0}^{1}(\Omega)} \leqslant \varrho, u \neq 0\right\}, \tag{2.2}
\end{equation*}
$$

which will easily imply that

$$
\begin{equation*}
\exists \sigma: \quad J_{\lambda}(u) \geqslant \sigma \quad \forall u:\|u\|_{H_{0}^{1}(\Omega)}=\varrho . \tag{2.3}
\end{equation*}
$$

In order to prove (2.2) we argue by contradiction. If (2.2) were not true, it would exist a sequence $u_{n}$ in $H_{0}^{1}(\Omega)$ such that:

$$
\left\|u_{n}\right\|_{H_{0}^{1}(\Omega)} \rightarrow 0, \quad u_{n} \neq 0, \quad J_{\lambda}\left(u_{n}\right) \leqslant 0 \quad \forall n \in \boldsymbol{N}
$$

that is

$$
\begin{equation*}
\frac{1}{2} \int_{\Omega} A(x) \nabla u_{n} \cdot \nabla u_{n} d x+\frac{1}{\theta+1} \int_{\Omega}\left|u_{n}\right|^{\theta+1} d x \leqslant \frac{\lambda}{2} \int_{\Omega}\left|u_{n}\right|^{2} d x \tag{2.4}
\end{equation*}
$$

Setting $w_{n}=\frac{u_{n}}{\left\|u_{n}\right\|_{H_{0}^{1}(\Omega)}}$, we have:

$$
\begin{equation*}
\int_{\Omega}\left|w_{n}\right|^{\theta+1} d x \leqslant \frac{\lambda(\theta+1)}{2}\left\|u_{n}\right\|_{H_{0}^{1}(\Omega)}^{1-\theta} \int_{\Omega}\left|w_{n}\right|^{2} \tag{2.5}
\end{equation*}
$$

Since $\left\|w_{n}\right\|_{H_{0}^{1}(\Omega)}=1$, we have that, up to subsequences, $w_{n}$ converges to a function $w \in H_{0}^{1}(\Omega)$ almost everywhere in $\Omega$, hence we deduce by Fatou's lemma and (2.5) that $w=0$, so that $w_{n}$ strongly converges to zero in $L^{2}(\Omega)$ as well by Rellich theorem. Dividing the equality in (2.4) by $\left\|u_{n}\right\|_{H_{0}^{1}(\Omega)}^{2}$, using the ellipticity of $A(x)$ we conclude that $w_{n}$ tends to zero in $H_{0}^{1}(\Omega)$, contradicting the fact that $\left\|w_{n}\right\|_{H_{0}^{1}(\Omega)}=1$. Thus (2.2) is proved. Now, assume that (2.3) is violated. Then we deduce again the existence of
a sequence $u_{n}$ such that $\left\|u_{n}\right\|_{H_{0}^{1}(\Omega)}=\varrho$ and $\lim _{n \rightarrow \infty} \sup _{\lambda} J_{\lambda}\left(u_{n}\right)=0$. Up to a subsequence we have that there exists a function $u$ in $\bar{B}_{Q}=\left\{\|u\|_{H_{0}^{1}(\Omega)} \leqslant \varrho\right\}$ such that $u_{n}$ weakly converges to $u$ in $H_{0}^{1}(\Omega)$. By lower semicontinuity we get that $J_{\lambda}(u) \leqslant 0$, so that (2.2) implies that $u=0$. As a consequence, $u_{n}$ tends to zero strongly in $L^{2}(\Omega)$, hence from

$$
\frac{\alpha}{2} \int_{\Omega}\left|\nabla u_{n}\right|^{2} d x \leqslant \frac{1}{2} \int_{\Omega} A(x) \nabla u_{n} \cdot \nabla u_{n} d x \leqslant J_{\lambda}\left(u_{n}\right)+\frac{\lambda}{2} \int_{\Omega}\left|u_{n}\right|^{2},
$$

we conclude, since $\limsup _{n \rightarrow \infty} J_{\lambda}\left(u_{n}\right)=0$, that $u_{n}$ strongly converges to zero in $H_{0}^{1}(\Omega)$, which is not possible since $\left\|u_{n}\right\|_{H_{0}^{1}(\Omega)}=\varrho$ for every $n$ in $\boldsymbol{N}$. Thus (2.3) is proved.

The proof that the functional $J_{\lambda}$ satisfies the Palais-Smale condition is standard and the details are left to the reader. Let us just recall that the main tool is, as usual, the proof that a Palais-Smale sequence $u_{n}$ is bounded, in order to apply the compactness properties of the equation. To obtain the boundedness of the sequence $u_{n}$, it is enough to argue by contradiction, assuming that $\left\|u_{n}\right\|_{H_{0}^{1}(\Omega)}$ goes to infinity and reasoning on the normalized sequence $\frac{u_{n}}{\left\|u_{n}\right\|_{H_{0}^{\prime}(\Omega)}}$, which can be proved to strongly converge to zero (actually, it will converge to a nonnegative eigenfunction corresponding to the eigenvector $\lambda$, since $\lambda>\lambda_{1}$ it must converge to zero).

We define now the class of paths to which apply the usual deformation lemma. First, let

$$
C_{\lambda}:=\left\{w \in H_{0}^{1}(\Omega): \lambda \int_{\Omega} w^{2}-\int_{\Omega} A(x) \nabla w \cdot \nabla w d x>0\right\},
$$

which is clearly a nonempty subset of $H_{0}^{1}(\Omega)$ since $\varphi_{1} \in C_{\lambda}$ for every $\lambda>\lambda_{1}$. Note that for any $w \in C_{\lambda}$ we have that there exists only one value $t_{w}>0$ such that $J_{\lambda}\left(t_{w} w\right)=0$.

Then we define the set of paths:

$$
X_{\lambda}:=\left\{\gamma \in C\left([0,1], H_{0}^{1}(\Omega)\right): \exists w \in C_{\lambda}: \gamma(0)=0, \gamma(1)=t_{w} w\right\} .
$$

We can then prove that

$$
c:=\inf _{\gamma \in X_{\lambda}} \sup _{[0,1]} J_{\lambda}(\gamma(t))
$$

is a critical value for $J_{\lambda}$. Indeed, let $\varrho$ and $\sigma$ be given from (2.3). Since $J_{\lambda}\left(t_{w} w\right)=0$ it follows from (2.2) that $\left\|t_{w} w\right\|_{H_{0}^{1}(\Omega)}>\varrho$, hence there exists a value $t$ such that $\|\gamma(t)\|_{H_{0}^{1}(\Omega)}=\varrho$ and thus $c \geqslant \sigma$. Now, if the set $K_{c}=$ $=\left\{v \in H_{0}^{1}(\Omega): J_{\lambda}(v)=c, J_{\lambda}^{\prime}(v)=0\right\}$ were empty, it would exist a continuous deformation $\eta:[0,1] \times H_{0}^{1}(\Omega) \rightarrow H_{0}^{1}(\Omega)$ and a value $\varepsilon>0$ such that $\eta(t, v)=v$ for any $v \in H_{0}^{1}(\Omega)$ such that $\left|J_{\lambda}(v)-c\right|>\frac{\sigma}{2}$ and $J_{\lambda}(\eta(1, v)) \leqslant c-\varepsilon$ for every $v$ such that $J_{\lambda}(v) \leqslant c+\varepsilon$. If $\gamma_{\varepsilon}$ is a path such that $\sup _{[0,1]} J_{\lambda}\left(\gamma_{\varepsilon}(t)\right) \leqslant c+\varepsilon$, we have that the path $\eta\left(1, \gamma_{\varepsilon}(t)\right)$ belongs to $X_{\lambda}$ and $\sup _{[0,1]} J_{\lambda}\left(\eta\left(1, \gamma_{\varepsilon}(t)\right)\right) \leqslant c-\varepsilon$, contradicting the definition of $c$. Therefore $c$ is a critical value and there exists a critical point $u_{\lambda}$ in $K_{c}$. Clearly, $u_{\lambda}$ is a weak solution of (1.1). Moreover, note that the path $\gamma(t)=t t_{w} w$ belongs to $X_{\lambda}$ for any $w \in C_{\lambda}$, hence we get:

$$
J_{\lambda}\left(u_{\lambda}\right)=c \leqslant \sup _{[0,1]} J_{\lambda}\left(t t_{w} w\right)
$$

A straightforward calculation implies (2.1).
Proposition 2.2. Let $u_{\lambda}$ be the solution of (1.1) found in Proposition 2.1. Then we have:

$$
\begin{equation*}
\lim _{\lambda \rightarrow+\infty}\left\|u_{\lambda}\right\|_{H_{0}^{1}(\Omega)}=0 \tag{2.6}
\end{equation*}
$$

Proof. We denote, in what follows, by $C$ all possibly different constants which do not depend on $\lambda$. First of all, since $J_{\lambda}^{\prime}\left(u_{\lambda}\right)=0$, we have

$$
\left(\frac{1}{\theta+1}-\frac{1}{2}\right) \int_{\Omega} u_{\lambda}^{\theta+1} d x=J_{\lambda}\left(u_{\lambda}\right)-\frac{1}{2}\left\langle J_{\lambda}^{\prime}\left(u_{\lambda}\right), u_{\lambda}\right\rangle=J_{\lambda}\left(u_{\lambda}\right)
$$

so that using (2.1) we obtain the estimate:

$$
\begin{equation*}
\int_{\Omega} u_{\lambda}^{\theta+1} d x \leqslant \frac{\left(\int_{\Omega}|w|^{\theta+1} d x\right)^{\frac{2}{1-\theta}}}{\left(\lambda \int_{\Omega} w^{2}-\int_{\Omega} A(x) \nabla w \cdot \nabla w d x\right)^{\frac{1+\theta}{1-\theta}}}, \text { fore every } w \in C_{\lambda} \tag{2.7}
\end{equation*}
$$

In particular, choosing $w=\varphi_{1}$ in (2.7) we get

$$
\begin{equation*}
\int_{\Omega} u_{\lambda}^{\theta+1} d x \leqslant \frac{C}{\lambda^{\frac{\theta+1}{1-\theta}}}, \quad \forall \lambda>\lambda_{1} \tag{2.8}
\end{equation*}
$$

Moreover, for every $\lambda^{\prime}<\lambda$ we have that

$$
\int_{\Omega} A(x) \nabla u_{\lambda^{\prime}} \cdot \nabla u_{\lambda^{\prime}} d x-\lambda^{\prime} \int_{\Omega} u_{\lambda^{\prime}}^{2} d x=-\int_{\Omega} u_{\lambda^{\prime}}^{\theta+1} d x
$$

hence

$$
\int_{\Omega} A(x) \nabla u_{\lambda^{\prime}} \cdot \nabla u_{\lambda^{\prime}} d x-\lambda \int_{\Omega} u_{\lambda^{\prime}}^{2} d x=\left(\lambda^{\prime}-\lambda\right) \int_{\Omega} u_{\lambda^{\prime}}^{2} d x-\int_{\Omega} u_{\lambda^{\prime}}^{\theta+1} d x<0 .
$$

Thus $u_{\lambda^{\prime}} \in C_{\lambda}$ for every $\lambda^{\prime}<\lambda$, so that (2.7) implies:

$$
\int_{\Omega} u_{\lambda}^{\theta+1} d x \leqslant \frac{\left(\int_{\Omega}\left|u_{\lambda^{\prime}}\right|^{\theta+1} d x\right)^{\frac{2}{1-\theta}}}{\left(\lambda \int_{\Omega} u_{\lambda^{\prime}}^{2}-\int_{\Omega} A(x) \nabla u_{\lambda^{\prime}} \cdot \nabla u_{\lambda^{\prime}} d x\right)^{\frac{1+\theta}{1-\theta}}}
$$

which yields, using the equation solved by $u_{\lambda^{\prime}}$,
(2.9) $\int_{\Omega} u_{\lambda}^{\theta+1} d x \leqslant \frac{\left(\int_{\Omega}\left|u_{\lambda^{\prime}}\right|^{\theta+1} d x\right)^{\frac{2}{1-\theta}}}{\left(\left(\lambda-\lambda^{\prime}\right) \int_{\Omega} u_{\lambda^{\prime}}^{2}+\int_{\Omega}\left|u_{\lambda^{\prime}}\right|^{\theta+1} d x\right)^{\frac{1+\theta}{1-\theta}}} \quad \forall \lambda^{\prime}<\lambda$.

Our main task now is proving that the sequence $\left\{u_{\lambda}\right\}$ is bounded in $H_{0}^{1}(\Omega)$. To this purpose, we argue by contradiction. Assume then that $\left\|u_{\lambda}\right\|_{H_{0}^{1}(\Omega)}$ is not bounded. Then we can construct a subsequence $\lambda_{h}$, such that:

$$
\begin{equation*}
\lambda_{h}-\lambda_{h-1} \geqslant 1, \quad\left\|u_{\lambda_{h}}\right\|_{H_{0}^{1}(\Omega)} \geqslant\left\|u_{\lambda_{h-1}}\right\|_{H_{0}^{1}(\Omega)}, \quad \lim _{h \rightarrow \infty}\left\|u_{\lambda_{h}}\right\|_{H_{0}^{1}(\Omega)}=+\infty \tag{2.10}
\end{equation*}
$$

From (2.9) written for $u_{\lambda_{h}}$ and $u_{\lambda_{h-1}}$ we obtain (note that $\lambda_{h}-\lambda_{h-1} \geqslant 1$ ):

$$
\int_{\Omega} u_{\lambda_{h}}^{\theta+1} d x \leqslant \frac{\left(\int_{\Omega}\left|u_{\lambda_{h-1}}\right|^{\theta+1} d x\right)^{\frac{2}{1-\theta}}}{\left(\int_{\Omega} u_{\lambda_{h-1}}^{2}+\int_{\Omega}\left|u_{\lambda_{h-1}}\right|^{\theta+1} d x\right)^{\frac{1+\theta}{1-\theta}}}
$$

In order to simplify our notations, we denote henceforth $u_{\lambda_{h}}$ by $u_{\lambda}$ and
$u_{\lambda_{h-1}}$ by $u_{\lambda-1}$, so that we rewrite the previous inequality as

$$
\begin{equation*}
\int_{\Omega} u_{\lambda}^{\theta+1} d x \leqslant \frac{\left(\int_{\Omega}\left|u_{\lambda-1}\right|^{\theta+1} d x\right)^{\frac{2}{1-\theta}}}{\left(\int_{\Omega} u_{\lambda-1}^{2}+\int_{\Omega}\left|u_{\lambda-1}\right|^{\theta+1} d x\right)^{\frac{1+\theta}{1-\theta}}} \tag{2.11}
\end{equation*}
$$

Let us set $v_{\lambda}=\frac{u_{\lambda}}{\left\|u_{\lambda}\right\|_{H_{0}^{1}(\Omega)}}$. Then we have:

$$
\begin{equation*}
\left\|v_{\lambda}\right\|_{H_{0}^{1}(\Omega)}=1, \quad L v_{\lambda}+\frac{v_{\lambda}^{\theta}}{\left\|u_{\lambda}\right\|_{H_{0}^{1}(\Omega)}^{1-\theta}}=\lambda v_{\lambda} . \tag{2.12}
\end{equation*}
$$

Moreover, using (2.11) and since $\left\|u_{\lambda}\right\|_{H_{0}^{1}(\Omega)} \geqslant\left\|u_{\lambda-1}\right\|_{H_{0}^{1}(\Omega)}$ we obtain:

$$
\begin{aligned}
& \int_{\Omega} v_{\lambda}^{\theta+1} d x \leqslant \frac{1}{\left\|u_{\lambda}\right\|_{H_{0}^{1}(\Omega)}^{\theta+1}} \frac{\left(\int_{\Omega}\left|u_{\lambda-1}\right|^{\theta+1} d x\right)^{\frac{2}{1-\theta}}}{\left(\int_{\Omega} u_{\lambda-1}^{2}+\int_{\Omega}\left|u_{\lambda-1}\right|^{\theta+1} d x\right)^{\frac{1+\theta}{1-\theta}}} \\
& \leqslant \frac{1}{\left\|u_{\lambda-1}\right\|_{H_{0}^{1}(\Omega)}^{\theta+1}} \frac{\left(\int_{\Omega}\left|u_{\lambda-1}\right|^{\theta+1} d x\right)^{\frac{2}{1-\theta}}}{\left(\int_{\Omega} u_{\lambda-1}^{2}+\int_{\Omega}\left|u_{\lambda-1}\right|^{\theta+1} d x\right)^{\frac{1+\theta}{1-\theta}}} \\
& \leqslant \frac{\int_{\Omega}\left|v_{\lambda-1}\right|^{\theta+1} d x}{\left(1+\frac{\int_{\Omega} u_{\lambda-1}^{2} d x}{\int_{\Omega}\left|u_{\lambda-1}\right|^{\theta+1} d x}\right)^{\frac{1+\theta}{1-\theta}}}
\end{aligned}
$$

which yields:

$$
\begin{equation*}
\int_{\Omega} v_{\lambda}^{\theta+1} d x \leqslant \frac{\int_{\Omega}\left|v_{\lambda-1}\right|^{\theta+1} d x}{1+\left(\frac{\int_{\Omega} u_{\lambda-1}^{2} d x}{\int_{\Omega}\left|u_{\lambda-1}\right|^{\theta+1} d x}\right)^{\frac{1+\theta}{1-\theta}}} \tag{2.13}
\end{equation*}
$$

We claim now that there exists a constant $\varepsilon>0$ such that:

$$
\begin{equation*}
\liminf _{\lambda \rightarrow \infty} \frac{\int_{\Omega} u_{\lambda}^{2} d x}{\int_{\Omega}\left|u_{\lambda}\right|^{\theta+1} d x} \geqslant \varepsilon>0 \tag{2.14}
\end{equation*}
$$

Indeed, assume that (2.14) is not true: then we get that, for a subsequence (not relabeled)

$$
\lim _{\lambda \rightarrow \infty} \frac{\int_{\Omega} u_{\lambda}^{2} d x}{\int_{\Omega}\left|u_{\lambda}\right|^{\theta+1} d x}=0
$$

so that, using (2.8),

$$
\int_{\Omega} v_{\lambda}^{2} d x=\frac{1}{\left\|u_{\lambda}\right\|_{H_{0}^{1}(\Omega)}^{2}} \int_{\Omega} u_{\lambda}^{2} d x \leqslant \frac{C}{\left\|u_{\lambda}\right\|_{H_{0}^{1}(\Omega)}^{2} \lambda{ }^{\frac{\theta+1}{1-\theta}}} .
$$

But, using (2.10) (recall that here $u_{\lambda}=u_{\lambda_{h}}$ ), this implies that

$$
\lim _{\lambda \rightarrow \infty} \lambda \int_{\Omega} v_{\lambda}^{2} d x=0
$$

which yields, from the equation solved by $v_{\lambda}$ (2.12):

$$
\lim _{\lambda \rightarrow \infty} \int_{\Omega}\left|\nabla v_{\lambda}\right|^{2} d x=0
$$

This can not hold because of (2.12), hence we deduce that (2.14) must be true. Now, (2.13) and (2.14) together imply that there exists $\bar{\lambda}>\lambda_{1}$ and a constant $\delta>0$ such that:

$$
\int_{\Omega} v_{\lambda}^{\theta+1} d x \leqslant \frac{1}{1+\delta} \int_{\Omega} v_{\lambda-1}^{\theta+1} d x \quad \forall \lambda>\bar{\lambda}
$$

Therefore, we also have that there exists a constant $C>0$ :

$$
\begin{equation*}
\int_{\Omega} v_{\lambda}^{\theta+1} d x \leqslant C\left(\frac{1}{1+\delta}\right)^{\lambda} \tag{2.15}
\end{equation*}
$$

Now, (2.12) implies, on account of standard regularity results (see [12]), that, for a value $p>\frac{N}{2}$ :

$$
\left\|v_{\lambda}\right\|_{L^{\infty}(\Omega)} \leqslant C\left\|\lambda v_{\lambda}\right\|_{L^{p}(\Omega)},
$$

which yields, thanks to (2.15) (take also $p>\theta+1$ ):

$$
1 \leqslant C \lambda\left\|\frac{v_{\lambda}}{\left\|v_{\lambda}\right\|_{L^{\infty}(\Omega)}}\right\|_{L^{p}(\Omega)} \leqslant C \lambda\left\|\frac{v_{\lambda}}{\left\|v_{\lambda}\right\|_{L^{\infty}(\Omega)}}\right\|_{L^{\theta+1}(\Omega)}^{\frac{\theta+1}{p}} \leqslant C \lambda\left(\frac{1}{1+\delta}\right)^{\frac{\lambda}{p}} \frac{1}{\left\|v_{\lambda}\right\|_{L^{\infty}(\Omega)}^{(\theta+1) / p}} .
$$

Then we have

$$
\left\|v_{\lambda}\right\|_{L^{\infty}(\Omega)} \leqslant C \lambda^{\frac{p}{\theta+1}}\left(\frac{1}{1+\delta}\right)^{\frac{\lambda}{\theta+1}},
$$

so that $\left\|v_{\lambda}\right\|_{L^{\infty}(\Omega)}$ converges to zero as $\lambda$ tends to infinity. Then

$$
\lambda \int_{\Omega} v_{\lambda}^{2} d x \leqslant C \lambda \int_{\Omega} v_{\lambda}^{\theta+1} d x \leqslant C \lambda\left(\frac{1}{1+\delta}\right)^{\lambda}
$$

Since (2.12) implies (recall (1.2))

$$
\alpha \int_{\Omega}\left|\nabla v_{\lambda}\right|^{2} d x \leqslant \int_{\Omega} A(x) \nabla v_{\lambda} \cdot \nabla v_{\lambda} d x \leqslant \lambda \int_{\Omega} v_{\lambda}^{2} d x,
$$

we conclude that $v_{\lambda}$ strongly converges to zero in $H_{0}^{1}(\Omega)$, which contradicts the fact that $\left\|v_{\lambda}\right\|_{H_{0}^{1}(\Omega)}=1$. The contradiction proves that no subsequence $u_{\lambda_{h}}$ satisfying (2.10) can exist, and then that $\left\|u_{\lambda}\right\|_{H_{0}^{1}(\Omega)}$ is bounded.

It is now easy to repeat the same arguments to prove that $u_{\lambda}$ converges to zero in $H_{0}^{1}(\Omega)$. Indeed, if this were not true it would exist a value $\bar{\varepsilon}>0$ and a subsequence $u_{\lambda_{h}}$ such that:

$$
\begin{equation*}
\lambda_{h}-\lambda_{h-1} \geqslant 1, \quad\left\|u_{\lambda_{h}}\right\|_{H_{0}^{1}(\Omega)} \geqslant \bar{\varepsilon} \quad \forall h>0 . \tag{2.16}
\end{equation*}
$$

In this case (2.9) still implies that

$$
\int_{\Omega} u_{\lambda_{h}}^{\theta+1} d x \leqslant \frac{\left(\int_{\Omega}\left|u_{\lambda_{h-1}}\right|^{\theta+1} d x\right)^{\frac{2}{1-\theta}}}{\left(\int_{\Omega} u_{\lambda_{h-1}}^{2}+\int_{\Omega}\left|u_{\lambda_{h-1}}\right|^{\theta+1} d x\right)^{\frac{1+\theta}{1-\theta}}}
$$

and then

$$
\begin{equation*}
\int_{\Omega} u_{\lambda_{h}}^{\theta+1} d x \leqslant \frac{\int_{\Omega}\left|u_{\lambda_{h-1}}\right|^{\theta+1} d x}{1+\left(\frac{\int_{\Omega} u_{\lambda_{h-1}}^{2} d x}{\int_{\Omega}\left|u_{\lambda_{h-1}}\right|^{\theta+1} d x}\right)^{\frac{1+\theta}{1-\theta}}} . \tag{2.17}
\end{equation*}
$$

This is the same inequality as (2.13) previously obtained on $v_{\lambda}$. Thus, the same arguments can now be applied; indeed, we have the alternative
that either there exists a constant $\varepsilon$ such that

$$
\liminf _{h \rightarrow \infty} \frac{\int_{\Omega} u_{\lambda_{h}}^{2} d x}{\int_{\Omega}\left|u_{\lambda_{h}}\right|^{\theta+1} d x} \geqslant \varepsilon>0 \quad \forall h>0
$$

or there exists a further subsequence (not relabeled) such that

$$
\lim _{h \rightarrow \infty} \frac{\int_{\Omega} u_{\lambda_{h}}^{2}}{\int_{\Omega}\left|u_{\lambda_{h}}\right|^{\theta+1} d x}=0
$$

In both cases, the same arguments used before for $v_{\lambda}$ allow to conclude that a subsequence of $u_{\lambda_{h}}$ strongly converges to zero in $H_{0}^{1}(\Omega)$, which contradicts (2.16). This concludes the proof that $u_{\lambda}$ strongly converges to zero in $H_{0}^{1}(\Omega)$

REmark 2.3. Note that, at least if $\frac{N-2}{N+2}<\theta<1$, we can also argue from the proof of Theorem 1.1 that

$$
\lim _{\lambda \rightarrow \infty}\left\|u_{\lambda}\right\|_{L^{\infty}(\Omega)}=0
$$

In fact, recall that we have the estimate:

$$
\int_{\Omega} u_{\lambda}^{\theta+1} d x \leqslant \frac{C}{\lambda^{\frac{\theta+1}{1-\theta}}} \quad \forall \lambda>\lambda_{1} .
$$

If $\frac{N-2}{N+2}<\theta$, then $\frac{\theta+1}{1-\theta}>\frac{N}{2}$, hence we get from the equation solved by $u_{\lambda}$,

$$
\left\|u_{\lambda}\right\|_{L^{\infty}(\Omega)} \leqslant C \lambda\left\|u_{\lambda}\right\|_{L} \frac{\theta+1}{1-\theta}(\Omega) .
$$

Hence, using that $\frac{\theta+1}{1-\theta}>\theta+1$,

$$
1 \leqslant C \lambda\left\|\frac{u_{\lambda}}{\left\|u_{\lambda}\right\|_{L^{\infty}(\Omega)}}\right\|_{L^{\frac{\theta+1}{1-\theta}(\Omega)}} \leqslant C \lambda\left\|\frac{u_{\lambda}}{\left\|u_{\lambda}\right\|_{L^{\infty}(\Omega)}}\right\|_{L^{\theta+1}(\Omega)}^{1-\theta} \leqslant C \frac{1}{\left\|u_{\lambda}\right\|_{L^{\infty}(\Omega)}^{1-\theta}} .
$$

We first deduce from this inequality that $\left\|u_{\lambda}\right\|_{L^{\infty}(\Omega)}$ is bounded, then we obtain, for a value $p$ such that $\max \left\{\theta+1, \frac{N}{2}\right\}<p<\frac{\theta+1}{1-\theta}$ :

$$
\lim _{\lambda \rightarrow \infty} \lambda^{p} \int_{\Omega} u_{\lambda}^{p} d x \leqslant C \lambda^{p} \int_{\Omega} u_{\lambda}^{\theta+1} d x \leqslant C \frac{1}{\lambda^{\frac{\theta+1}{1-\theta}-p}}
$$

so that $\lambda u_{\lambda}$ strongly converges to zero in $L^{p}(\Omega)$ with $p>\frac{N}{2}$. Classical regularity results (see [12]) then imply that $u_{\lambda}$ converges to zero in $L^{\infty}(\Omega)$. In particular, this proves the convergence of $u_{\lambda}$ in $L^{\infty}(\Omega)$ for any value of $\theta$ at least in dimension $N \leqslant 2$.

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