

RENDICONTI
del
SEMINARIO MATEMATICO
della
UNIVERSITÀ DI PADOVA

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***N*-symmetric submanifolds**

Rendiconti del Seminario Matematico della Università di Padova,
tome 84 (1990), p. 123-134

http://www.numdam.org/item?id=RSMUP_1990__84__123_0

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$\frac{1}{N}$ -Symmetric Submanifolds.

G. ROMANI (*)

SUNTO. - Nel presente lavoro si caratterizzano le sottovarietà di \mathbf{R}^n che sono trasformate in sè dalla simmetria di \mathbf{R}^n rispetto ad un qualunque loro primo spazio normale. Queste sottovarietà sono dette $\frac{1}{N}$ -simmetriche e sono caratterizzate dall'avere la prima applicazione normale totalmente geodetica.

Introduction.

In [F] Ferus demonstrates that the submanifolds M of \mathbf{R}^n having the second fundamental form, s_M , parallel, $\nabla s_M = 0$, are characterized in extrinsic terms as the submanifolds of \mathbf{R}^n transformed locally in itself by the reflection of \mathbf{R}^n with respect to any normal space of the submanifold; such submanifolds are called (locally) *symmetric submanifolds*.

In [R.V.] Ruh and Vilms show how the condition $\nabla s_M = 0$ is equivalent to that the Gauss map, g_M , of the submanifold is totally geodesic: $\nabla(g_M)_* = 0$. One has, therefore, that

THEOREM. M is a (locally) symmetric submanifold of \mathbf{R}^n if and only if $\nabla(g_M)_* = 0$.

Recently in [C.R.] there have been introduced for the sub-

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Work done under support by M.P.I. 60% and 40%:

manifolds M of \mathbb{R}^n some maps, $\overset{k}{v}_M$, that generalise the Gauss map in that, for $k = 0$, $\overset{\circ}{v}_M = g_M$.

In [C.R.] it is shown how $\nabla(\overset{k}{v}_M)_* = 0$ implies $\overset{k}{v}_M = \text{const}$ for $k > 1$ and how, therefore, the only significant conditions are the $\nabla(\overset{\circ}{v}_M)_* = \nabla(g_M)_* = 0$ already studied, and the $\nabla(\overset{1}{v}_M)_* = 0$.

It is precisely the condition $\nabla(\overset{1}{v}_M)_* = 0$ that will be dealt with here.

Called s_M the second fundamental form of the submanifold M of \mathbb{R}^n , the space generated by the vectors $s_M(X_p, X_p)$, $X_p \in T_p(M)$ is called *first normal space to M in p* and indicated with $\overset{1}{N}_p(M)$. If the submanifold M is *nicely curved* in a way that will later be explained, the dimension on $\overset{1}{N}_p(M)$ does not depend from p and will be indicated with $\overset{1}{n}$.

The map $\overset{1}{v}_M$, that has been mentioned, is therefore defined as the map $\overset{1}{v}_M: M \rightarrow G(\overset{1}{n}, n - \overset{1}{n})$ that $p \in M$ associate $\overset{1}{v}_M(p) = \overset{1}{N}_p(M)$.

Therefore it will be demonstrated that

THEOREM. $\nabla(\overset{1}{v}_M)_* = 0$ if and only if for each $p \in M$ the reflection of \mathbb{R}^n with respect to $\overset{1}{N}_p(M)$ transforms locally M in itself.

In analogy to the definition given by Ferus in [F] these other submanifolds which we have considered will be called *$\overset{1}{N}$ -symmetric submanifolds*.

Still in [C.R.] sufficient and necessary conditions are given in order that one has $\nabla(\overset{\circ}{v}_M)_* (= \nabla(g_M)_* = \nabla s_M) = 0$, and $\nabla(\overset{1}{v}_M)_* = 0$. From such conditions one deduces at once that $\nabla(\overset{\circ}{v}_M)_* = 0 \Rightarrow \nabla(\overset{1}{v}_M)_* = 0$, and that, therefore, the (locally) symmetric submanifolds are a particular case of the $\overset{1}{N}$ -symmetric submanifolds.

However, in [K.K] Kowalski and Külich present a notion of generalized k -symmetric submanifold that results in its turn to be a generalization of those $\overset{1}{N}$ -symmetric submanifold: these last ones in fact appear as a particular case of generalized 2-symmetric submanifold, according to Kowalski and Külich [K.K].

I. Preliminaries.

Let M a m -dimensional submanifold of \mathbb{R}^n . Chosen a point p on M , the tangent space in p to M , $T_p(M)$, is also called the first

osculator space to M in p and indicated with $\overset{1}{O}_p(M): T_p(M) = \overset{1}{O}_p(M)$.

The second osculator space in p to M , $\overset{2}{O}_p(M)$, is defined as the subspace generated by $\overset{1}{X}_p$ and by $\overset{R}{\nabla}_{\overset{1}{X}_p} \overset{2}{X}$ when $\overset{1}{X}_p$ varies in $T_p(M)$, and $\overset{2}{X}$ in $T(M)$ and where with $\overset{R}{\nabla}$ is indicated the covariant derivative in \mathbb{R}^n .

In symbols:

$$\overset{2}{O}_p(M) = \{ \overset{1}{X}_p, \overset{R}{\nabla}_{\overset{1}{X}_p} \overset{2}{X}: \overset{1}{X}_p \in T_p(M), \overset{2}{X} \in T(M) \} .$$

In general the k -th osculator space to M in p is defined putting:

$$(1) \quad \overset{k}{O}_p(M) = \{ \overset{1}{X}_p, \overset{R}{\nabla}_{\overset{1}{X}_p} \overset{2}{X}, \overset{R}{\nabla}_{\overset{1}{X}_p} \overset{R}{\nabla}_{\overset{1}{X}_p} \overset{3}{X}, \dots, \\ \overset{R}{\nabla}_{\overset{1}{X}_p} \overset{R}{\nabla}_{\overset{1}{X}_p} \dots \overset{R}{\nabla}_{\overset{1}{X}_p} \overset{k}{X}: \overset{1}{X}_p \in T_p(M), \overset{2}{X}, \dots, \overset{k}{X} \in T(M) \} .$$

If for each k the dimension of $\overset{k}{O}_p(M)$ does not depend on p it is said that the submanifold M is *niceily curved*.

Naturally $\overset{k}{O}_p(M) \subseteq \overset{k+1}{O}_p(M)$ and evidently if for a certain entire $l > 0$ $\overset{l}{O}_p(M) = \overset{l+1}{O}_p(M)$ then $\overset{l}{O}_p(M) = \overset{l'}{O}_p(M)$ for every $l' > l$. The orthogonal complement of $\overset{k}{O}_p(M)$ in $\overset{k+1}{O}_p(M)$ will be called k -th normal space to M in p and denoted with $\overset{k}{N}_p(M)$, in particular it will result

$$(2) \quad \overset{k+1}{O}_p(M) = \overset{k}{O}_p(M) \oplus \overset{k}{N}_p(M)$$

from which it follows at once that if M is nicely curved then also the dimensions of $\overset{k}{N}_p(M)$ is constant on M .

In the following we will place $\overset{0}{O}_p(M) = \{0\}$ and consequently

$$\overset{0}{N}_p(M) = \overset{1}{O}_p(M) = T_p(M). \text{ From (2) it clearly follows}$$

$$(3) \quad \overset{k+1}{O}_p(M) = \overset{0}{N}_p(M) \oplus \overset{1}{N}_p(M) \oplus \dots \oplus \overset{k}{N}_p(M) .$$

For the notions stated up to here compare [Sp].

If we now suppose M nicely curved we can define for $k = 0, 1, \dots, l-1$ the map $\overset{k}{\nu}_M: M \rightarrow G(\overset{k}{n}, n - \overset{k}{n})$, where with $\overset{k}{n}$ is indicated the constant dimension of $\overset{k}{N}_p(M)$, placing for $p \in M$,

$$\overset{k}{\nu}_M(p) = N_p(M) \quad (\varepsilon G(n, n - \overset{k}{n})).$$

The differential of $\overset{k}{\nu}_M$ in the point p of M , $(\overset{k}{\nu}_M)_{*p}$, gives place to a homomorphism between $T_p(M)$ and $T_{\overset{k}{\nu}_M(p)}(G(\overset{k}{n}, n - \overset{k}{n}))$, but every tangent vector to the grassmannian, $G(n, n - \overset{k}{n})$ of the $\overset{k}{n}$ -spaces of \mathbb{R}^n in its point α , can be thought as a homomorphism between the point α considered as $\overset{k}{n}$ -space and its orthogonal, α^\perp (cfr. [R.V.]).

From this it follows that $(\overset{k}{\nu}_M)_{*p}$ can be thought as a bilinear map between $T_p(M) \times \overset{1}{N}_p(M)$ and $\overset{1}{N}_p(M)^\perp$.

The covariant derivative of $(\overset{k}{\nu}_M)_*$ as bilinear map between $T_p(M) \times \overset{1}{N}_p(M)$ and $\overset{1}{N}_p(M)^\perp$ will be indicated with $\nabla(\overset{k}{\nu}_M)_*$. As already indicated in the introduction for every $k > 1$, $\nabla(\overset{k}{\nu}_M)_* = 0$ it implies $(\overset{k}{\nu}_M)_* = 0$ that is $\overset{k}{\nu}_M = \text{constant}$ (cfr. [C.R.]) for $k = 0$, $\overset{0}{\nu}_M = g_M$ (where g_M is the classical gauss map of M) and the condition $\nabla(g_M)_* (= \nabla(\overset{0}{\nu}_M)_*) = 0$ has been found equivalent to suppose M symmetric submanifold; for that reason we will limit ourselves to the study of the condition $\nabla(\overset{1}{\nu}_M)_* = 0$.

For that purpose, we observe that the first normal space, $\overset{1}{N}_p(M)$, in the point p to M coincides with the space generated by $s_M(X_p, X_p)$, where s_M is the second fundamental form of M , when X_p varies in $T_p(M)$ (cfr. [Sp]).

In the continuation the normal space to a submanifold M of \mathbb{R}^n will be indicated with $N(M)$, furthermore given a subspace H of \mathbb{R}^n , with $P_H: \mathbb{R}^n \rightarrow H$ we will indicate the orthogonal projection of \mathbb{R}^n on H ; given a submanifold S of \mathbb{R}^n with $\overset{S}{\nabla}$ we will indicate the connection on S induced by \mathbb{R}^n ; given a vector sub-bundle $F \rightarrow S$ on S of the product bundle $S \times \mathbb{R}^n$, we will indicate with $\overset{F}{\nabla}$ the connection in F induced by $S \times \mathbb{R}^n$.

II. Let M a nicely curved submanifold of \mathbb{R}^n , of dimension m .

(1) **DEFINITION.** M is a $\overset{1}{N}$ -symmetric submanifold if for any $p \in M$,

the reflection of \mathbb{R}^n with respect to $\overset{1}{N}_p$ transforms locally M in itself.

We prove the

(2) THEOREM. M is $\overset{1}{N}$ -symmetric iff $\nabla(\overset{1}{\nu}_M)_* = 0$.

First we prove the implication

(3)
$$\nabla(\overset{1}{\nu}_M)_* = 0 \Rightarrow M \text{ is } \overset{1}{N}\text{-symmetric}$$

For each $p \in M$ we will define

(4)
$$\begin{aligned} (\overset{\perp}{NT})_p &= (\overset{1}{N}_p(M) \oplus T_p(M))^\perp = \\ &= \overset{1}{N}_p(M)^\perp \cap T_p(M)^\perp = \overset{1}{N}_p(M)^\perp \cap N_p(M) \end{aligned}$$

and with $p + (\overset{\perp}{NT})_p$ the affine subspace of \mathbb{R}^n through the point p parallel to $(\overset{\perp}{NT})_p$.

Let U an open set of \mathbb{R}^n such that $U \cap \left(\bigcup_{p \in M} (p + (\overset{\perp}{NT})_p) \right)$ is a submanifold, \tilde{M} , or \mathbb{R}^n ; for $p \in M \cap U(c \tilde{M})$ we will have

(5)
$$T_p(\tilde{M}) = T_p(M) \oplus (\overset{\perp}{NT})_p$$

and

(6)
$$\begin{aligned} N_p(\tilde{M}) &= (T_p(\tilde{M}))^\perp = (T_p(M) \oplus (\overset{\perp}{NT})_p)^\perp = \\ &= (T_p(M)^\perp \cap (\overset{\perp}{NT})_p^\perp = N_p(M) \cap \overset{1}{N}_p(M) = \overset{1}{N}_p(M) \end{aligned}$$

and

(7)
$$T_p(\tilde{M}) = \overset{1}{N}_p(M)^\perp$$

moreover

(8) PROP. M is a totally geodesic submanifold of \tilde{M}

PROOF. If $X_p \in T_p(M)$, $Y \in T(M)$ then

$$\overset{\mathbf{R}}{\nabla}_{X_p} Y \in \overset{1}{O}_p(M) = T_p(M) \oplus \overset{1}{N}_p(M);$$

therefore, (4),

$$P_{(\overset{\perp}{NT})_p} \left(\overset{\mathbf{R}}{\nabla}_{X_p} Y \right) = P_{T_p(M) \oplus \overset{1}{N}_p(M)} \left(\overset{\mathbf{R}}{\nabla}_{X_p} Y \right) = 0;$$

it follows, (5),

$$\overset{\tilde{M}}{\nabla}_{X_p} Y = P_{T_p(\tilde{M})} \left(\overset{\mathbf{R}}{\nabla}_{X_p} Y \right) = P_{T_p(M) \oplus (\overset{1}{N^1} T)_p} \left(\nabla_{X_p} Y \right) = P_{T_p(M)} \left(\overset{\mathbf{R}}{\nabla}_{X_p} Y \right) = \overset{M}{\nabla}_{X_p} Y.$$

Consider now:

a) the gauss map of order zero $\overset{\circ}{\nu}_{\tilde{M}}: \tilde{M} \rightarrow G(n - \overset{1}{n}, \overset{1}{n})$ of \tilde{M}

$$\overset{\circ}{\nu}_{\tilde{M}}(q) = T_q(\tilde{M}) \quad q \in \tilde{M}$$

b) the isometry

$$\mu: G(n - \overset{1}{n}, \overset{1}{n}) \rightarrow G(\overset{1}{n}, n - \overset{1}{n})$$

between the grassmannian $G(n - \overset{1}{n}, \overset{1}{n})$ of the $(n - \overset{1}{n})$ -subspaces of \mathbf{R}^n and the grassmannian $G(\overset{1}{n}, n - \overset{1}{n})$ of the $\overset{1}{n}$ -subspaces of \mathbf{R}^n , that to a $(n - \overset{1}{n})$ -subspace associates to it the orthogonal

c) the map

$$\overset{\circ}{\mu}_{\tilde{M}}: \tilde{M} \rightarrow G(\overset{1}{n}, n - \overset{1}{n})$$

defined by

$$\overset{\circ}{\mu}_{\tilde{M}} = \mu \circ \overset{\circ}{\nu}_{\tilde{M}}$$

therefore:

(9) PROP. For

$$p \in M \cap U(\subset \tilde{M}), \quad X_p, Y_p \in T_p M (\subset T_p(\tilde{M})), \quad \xi_p \in \overset{1}{N}_p(M) (= N_p(\tilde{M}))$$

$$\text{i) } \overset{\circ}{\mu}_{\tilde{M}}(p) = \overset{1}{\nu}_M(p)$$

$$\text{ii) } (\overset{\circ}{\mu}_{\tilde{M}})_*(X_p) = (\overset{1}{\nu}_M)_*(X_p)$$

$$\text{iii) } \nabla_{X_p}(\overset{\circ}{\mu}_{\tilde{M}})_*(Y_p, \xi_p) = \nabla_{X_p}(\overset{1}{\nu}_M)_*(Y_p, \xi_p)$$

PROOF OF i).

$$\overset{\circ}{\mu}_{\tilde{M}}(p) = \mu(\overset{\circ}{\nu}_{\tilde{M}}(p)) \stackrel{a)}{=} \mu(T_p(\tilde{M})) \stackrel{b)}{=} T_p(\overset{\perp}{\tilde{M}}) \stackrel{c)}{=} \overset{1}{N}_p(M) = \overset{1}{\nu}_M(p)$$

PROOF OF ii). It's a natural consequence of i).

PROOF OF iii).

$$\begin{aligned} \nabla_{X_p}(\overset{\circ}{\mu}_{\tilde{M}})_*(Y_p, \xi_p) &= \\ &= \overset{\overset{N^\perp}{\perp}}{\nabla}_{X_p}[(\overset{\circ}{\mu}_{\tilde{M}})_*(Y, \xi)] - (\overset{\circ}{\mu}_{\tilde{M}})_*(\overset{\tilde{M}}{\nabla}_{X_p} Y, \xi_p) - (\overset{\circ}{\mu}_{\tilde{M}})_*(Y, \overset{\overset{N}{\perp}}{\nabla}_{X_p} \xi) \stackrel{1), (8)}{=} \\ &= \overset{\overset{N^\perp}{\perp}}{\nabla}_{X_p}(\overset{1}{\nu}_M)_*(Y, \xi) - (\overset{1}{\nu}_M)_*(\overset{M}{\nabla}_{X_p} Y, \xi_p) - (\overset{1}{\nu}_M)_*(Y_p, \overset{\overset{N}{\perp}}{\nabla}_{X_p} \xi) = \\ &= \nabla_{X_p}(\overset{1}{\nu}_M)_*(Y_p, \xi_p) \end{aligned}$$

here with X, Y, ξ we indicate extensions of X_p, Y_p in $T(M)$ and of ξ_p in $\overset{1}{N}(M)$.

If we consider that μ is an isometry we will have

$$(10) \quad \nabla(\overset{\circ}{\mu}_{\tilde{M}})_* \stackrel{b)}{=} \nabla(\mu_* \circ (\overset{\circ}{\nu}_{\tilde{M}})_*) = \mu_* \circ (\nabla(\overset{\circ}{\nu}_{\tilde{M}})_*)$$

therefore for the iii)

$$(11) \text{ PROP. For } X_p, Y_p \in T_p(M), \xi_p \in \overset{1}{N}_p(M)$$

$$\mu_*[(\nabla_{X_p}(\overset{\circ}{\nu}_{\tilde{M}})_*)(Y_p)](\xi_p) = \nabla_{X_p}(\overset{1}{\nu}_M)_*(Y_p, \xi_p) .$$

In fact

$$\mu_*[(\nabla_{X_p}(\overset{\circ}{\nu}_{\tilde{M}})_*)(Y_p)](\xi_p) \stackrel{(10)}{=} \nabla_{X_p}(\overset{\circ}{\mu}_{\tilde{M}})_*(Y_p, \xi_p) \stackrel{iii)}{=} \nabla_{X_p}(\overset{1}{\nu}_M)_*(Y_p, \xi_p) .$$

In particular

$$(12) \text{ PROP. } \nabla(\overset{1}{\nu})_* = 0 \text{ iff any } X_p, Y_p \in T_p(M) (\subset T_p(\tilde{M}))$$

$$\nabla_{X_p}(\overset{\circ}{\nu}_{\tilde{M}})_*(Y_p) = 0$$

The (12) follows from (11) considering the fact that μ_* is an isomorfism.

We can now demonstrate that, indicated by $s_{\tilde{M}}$ the second fundamental form on \tilde{M} and with $\tilde{\nabla}s_{\tilde{M}}$ its derivative considering it with values in the orthogonal, $N(\tilde{M})$, to $T(\tilde{M})$, one has

$$(13) \text{ PROP. If } \nabla^{\perp} v_* = 0 \text{ then for any } p \in M, (\tilde{\nabla}s_{\tilde{M}})_p = 0$$

$$(i.e. \tilde{\nabla}_{\tilde{X}_p} s_{\tilde{M}}(\tilde{Y}_p, \tilde{Z}_p) = 0 \quad \forall \tilde{X}_p, \tilde{Y}_p, \tilde{Z}_p \in T_p(\tilde{M}))$$

PROOF. First of all remember that $(\hat{v}_{\tilde{M}})_* = s_{\tilde{M}}$ and that $\nabla(\hat{v}_{\tilde{M}})_* = \tilde{\nabla}s_{\tilde{M}}$ [R.V.]. Then taken $X_p, Y_p \in T_p(M) (\subset T_p(\tilde{M}))$ and $\tilde{Z}_p \in T_p(\tilde{M}) \cdot (\subset T_p(M))$ one has

$$j) \tilde{\nabla}_{X_p} s_{\tilde{M}}(Y_p, \tilde{Z}_p) = \nabla_{X_p}(\hat{v}_{\tilde{M}})_*(Y_p, \tilde{Z}_p) = (\nabla_{X_p}(\hat{v}_{\tilde{M}})_*(Y_p))(\tilde{Z}_p) \stackrel{(12)}{=} 0$$

and, for the symmetry of $s_{\tilde{M}}$

$$jj) \tilde{\nabla}_{X_p} s_{\tilde{M}}(\tilde{Z}_p, Y_p) = \tilde{\nabla}_{X_p} s_{\tilde{M}}(Y_p, \tilde{Z}_p) = 0$$

If now $\eta_p, \zeta_p \in (N^{\perp}T)_p (\subset T_p(\tilde{M}))$ it results

$$jjj) (\tilde{\nabla}_{X_p} s_{\tilde{M}})(\eta_p, \xi_p) = 0$$

to prove jjj) let us begin by observing that $\tilde{\nabla}_{X_p} s_{\tilde{M}}(\eta_p, \xi_p)$ one calculates starting from two arbitrary vector fields, η, ζ tangent to \tilde{M} and verifying the condition $\eta(p) = \eta_p, \xi(p) = \xi_p$. Moreover it will be sufficient to define η and ζ along any curve C for p having as tangent vector X_p , and in the points of $(N^{\perp}T)_{p'}$ with $p' \in C$.

We define η, ζ on C in the following manner: if $p' \in C, \eta(p'), \xi(p')$, are the transported by parallelism of η_p and ζ_p in p' along C so that it results

$$1) \tilde{\nabla}_{X_p} \eta = \tilde{\nabla}_{X_p} \zeta = 0$$

$$2) \eta(p'), \zeta(p') \in (N^{\perp}T)_{p'} = \text{orthogonal in } T(\tilde{M}) \text{ of } T(M)$$

the second condition, 2), follows from the fact that $(N^{\perp}T)_p$ is the orthogonal in $T(\tilde{M})$ of $T(M)$ and from the fact that M is totally geodesic in \tilde{M} ; it assures that for every $p' \in C$ and for every $q \in (N^{\perp}T)_{p'}$, we can define $\eta(q) = \eta(p'), \zeta(q) = \zeta(p')$. So for each $p' \in C$

$$3) s_{\tilde{M}}(\eta(p'), \zeta(p')) = 0 \quad ,$$

We will therefore have

$$(\tilde{\nabla}_{X_p} s_{\tilde{M}})(\eta_p, \zeta_p) = \tilde{\nabla}_{X_p}(s_{\tilde{M}}(\eta, \zeta)) - s_{\tilde{M}}(\tilde{\nabla}_{X_p} \eta, \zeta_p) - s_{\tilde{M}}(\eta_p, \tilde{\nabla}_{X_p} \zeta) = 0.$$

They will be now $\tilde{X}_p, \tilde{Y}_p, \tilde{Z}_p \in T_p(\tilde{M})$ and put $\tilde{X}_p = X_p + \eta_p$, $\tilde{Y}_p = Y_p + \theta_p$, $\tilde{Z}_p = Z_p + \zeta_p$ with $X_p, Y_p, Z_p \in T_p(M)$, $\eta_p, \theta_p, \zeta_p \in (\overset{1}{N}T)_p$: We will have

$$(\tilde{\nabla}_{\tilde{X}_p} s_{\tilde{M}})(\tilde{Y}_p, \tilde{Z}_p) = \tilde{\nabla}_{X_p} s_{\tilde{M}}(\tilde{Y}_p, \tilde{Z}_p) + \tilde{\nabla}_{X_p} s_{\tilde{M}}(\tilde{Y}_p, \tilde{Z}_p)_{j),ji),jii)} \overset{1}{=} \tilde{\nabla}_{\eta_p} s_{\tilde{M}}(\tilde{Y}_p, \tilde{Z}_p)$$

but $\tilde{\nabla} s_{\tilde{M}}$ is symmetric with respect to its arguments, so

$$\begin{aligned} (\tilde{\nabla}_{\tilde{X}_p} s_{\tilde{M}})(\tilde{Y}_p, \tilde{Z}_p) &= \tilde{\nabla}_{\tilde{Y}_p} s_{\tilde{M}}(\eta_p, \tilde{Z}_p) = \tilde{\nabla}_{Y_p} s_{\tilde{M}}(\eta_p, \tilde{Z}_p) + \tilde{\nabla}_{\theta_p} s_{\tilde{M}}(\eta_p, \tilde{Z}_p)_{ji),ji)} \overset{1}{=} \\ &= \tilde{\nabla}_{\theta_p} s_{\tilde{M}}(\eta_p, \tilde{Z}) = \tilde{\nabla}_{\tilde{Z}_p} s_{\tilde{M}}(\eta_p, \theta_p) \overset{1}{=} \tilde{\nabla}_{\zeta_p} s_{\tilde{M}}(\eta_p, \theta_p) = 0 \end{aligned}$$

the last equality being the consequence of the fact that η_p and θ_p can be extended along ζ_p in parallel and constant vector fields.

From (13) it follows, in particular, that the second fundamental form of \tilde{M} , $s_{\tilde{M}}$, is parallel along each geodesic γ of M (and therefore of \tilde{M} contained on M). From theorem 1 of Strübing [St] it follows, that all the curvatures of each geodesic γ of M are constant and that the vectors of Frenet of even order of γ are found in $N(\tilde{M}) = \overset{1}{N}(M)$, while the odd in $T(\tilde{M})$. From the lemma 1 of Strübing it follows that the reflection of \mathbb{R}^n , with respect to $N(\tilde{M}) = \overset{1}{N}(M)$, changes each geodesic γ of M in itself for each $p \in M$ and therefore changes locally M in itself.

The part now demonstrated by the theorem has an immediate consequence:

(14) LEMMA. If $\nabla^1_{\nu_*} = 0$ then M is locally symmetric.

PROOF. It is seen that if $\nabla^1_{\nu_*} = 0$, M is locally $\overset{1}{N}$ -symmetric; for each $p \in M$ there is, therefore, the reflection of \mathbb{R}^n with respect to $\overset{1}{N}_p(M)$ that induces locally on M an involutive isometry that fixes a sole point of M , namely the point p . This is sufficient for the proof.

III. And now we can demonstrate

$$(1) \quad M \text{ is } \overset{1}{N}\text{-symmetric} \Rightarrow \nabla^1_{\nu_*} = 0.$$

Let us begin by demonstrating the following proposition:

(2) PROP. If $\tau: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is an isometry that maps M in itself, then for each $k = 1, \dots, l$, $\tau(\overset{k}{O}_p(M)) = \overset{k}{O}_{\tau(p)}(M)$

PROOF. By definition

$$\overset{k}{O}_p(M) = \{\overset{1}{X}_p, \overset{\mathbf{R}}{\nabla}_{\overset{1}{X}_p} \overset{2}{X}, \overset{\mathbf{R}}{\nabla}_{\overset{1}{X}_p} \overset{\mathbf{R}}{\nabla}_{\overset{1}{X}_p} \overset{3}{X} \dots \overset{\mathbf{R}}{\nabla}_{\overset{1}{X}_p} \overset{k}{X} : \overset{i}{X} \in T(M)\}$$

but being τ an isometry of \mathbb{R}^n it results

$$a) \quad \tau_*(\overset{\mathbf{R}}{\nabla}_{\overset{1}{X}_p} \overset{2}{X}) = \overset{\mathbf{R}}{\nabla}_{\tau_*(\overset{1}{X}_p)} \tau_*(\overset{2}{X})$$

$$b) \quad \tau_*(\overset{\mathbf{R}}{\nabla}_{\overset{1}{X}_p} \overset{\mathbf{R}}{\nabla}_{\overset{1}{X}_p} \overset{3}{X}) = \overset{\mathbf{R}}{\nabla}_{\tau_*(\overset{1}{X}_p)} \tau_*(\overset{\mathbf{R}}{\nabla}_{\overset{1}{X}_p} \overset{3}{X}) = \overset{\mathbf{R}}{\nabla}_{\tau_*(\overset{1}{X}_p)} \overset{\mathbf{R}}{\nabla}_{\tau_*(\overset{1}{X}_p)} \tau_*(\overset{3}{X})$$

$$c) \quad \tau_*(\overset{\mathbf{R}}{\nabla}_{\overset{1}{X}_p} \overset{\mathbf{R}}{\nabla}_{\overset{1}{X}_p} \dots \overset{\mathbf{R}}{\nabla}_{\overset{1}{X}_p} \overset{k}{X}) = \overset{\mathbf{R}}{\nabla}_{\tau_*(\overset{1}{X}_p)} \overset{\mathbf{R}}{\nabla}_{\tau_*(\overset{1}{X}_p)} \dots \overset{\mathbf{R}}{\nabla}_{\tau_*(\overset{1}{X}_p)} \tau_*(\overset{k}{X})$$

and as $\tau_*(\overset{i}{X}) \in T(M)$ because τ maps M in itself, the written equalities tell us that

$$d) \quad \tau(\overset{k}{O}_p(M)) \subset \overset{k}{O}_{\tau(p)}(M)$$

but τ is bijective, therefore conclusion.

From (2) follows

(3) PROP. If $\tau: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is an isometry of M in itself, then for each $k = 0, 1, \dots, l-1$

$$\tau(\overset{k}{N}_p(M)) = \overset{k}{N}_{\tau(p)}(M).$$

The (3) follows at once from (2) keeping in mind the fact that τ being an isometry preserves the angles and the fact that $\overset{k-1}{N}_p(M)$ is the orthogonal complement of $\overset{k-1}{O}_p(M)$ in $\overset{k}{O}_p(M)$.

Now, let us suppose that M is $\overset{1}{N}$ -symmetric. That implies that for each $p \in M$ the reflection τ_p of \mathbb{R}^n with respect to $\overset{k}{N}_p(M)$ maps locally M in itself. Because of (3) will map therefore in itself the above manifold \tilde{M} : infact, if $q \in \tilde{M}$, or $q \in M$ is then by hypothesis transformed in a point of $M \subset \tilde{M}$, or $q \in (\overset{1}{NT})_p$, for a certain $p' \in M$. But

$$(\overset{1}{NT})_{p'} = \overset{2}{N}_{p'}(M) \oplus \dots \oplus \overset{l-1}{N}_{p'}(M) \oplus [\overset{\circ}{N}_{p'}(M) \oplus \overset{1}{N}_{p'}(M) \oplus \dots \oplus \overset{l-1}{N}_{p'}(M)]^\perp.$$

As for (3) $\overset{i}{N}_{p'}(M)$ ($i = 2, \dots, l-1$) is transformed in $\overset{i}{N}_{\tau_p(p')}(M) \subset \tilde{M}$ and obviously

$$\tau_p([\overset{\circ}{N}_{p'}(M) \oplus \dots \oplus \overset{l-1}{N}_{p'}(M)]^\perp) = [\overset{\circ}{N}_{\tau_p(p')}(M) \oplus \dots \oplus \overset{l-1}{N}_{\tau_p(p')}(M)]^\perp$$

since τ_p is an isometry, one has again the proof.

But we have already seen that $\overset{1}{N}_p(M) = N_p(\tilde{M}) = T_p(\tilde{M})^\perp$ for $p \in M$ therefore the fact that M is $\overset{1}{N}$ -symmetric assures us, for a theorem of Ferus (Lemma 1 of [F]) that $(\overset{\tilde{N}}{\nabla} s_{\tilde{M}})_p = 0$ for $p \in M$.

That implies that for $X_p, Y_p \in T_p(M)$

$$a) \overset{\tilde{N}}{\nabla}_{X_p} s_{\tilde{M}}(Y_p) = 0$$

but $s_{\tilde{M}} = (\overset{\circ}{\nu}_{\tilde{M}})_*$ for which

$$b) \nabla_{X_p} (\overset{\circ}{\nu}_{\tilde{M}})_*(Y_p) = 0$$

and (12) paragraph II enables us to conclude with the thesis: $\nabla^1 \nu_* = 0$.

If we now remember the condition in order that it results $\overset{N}{\nabla} s_M (= \nabla^{\circ} \nu_*) = 0$ and $\nabla^1 \nu_* = 0$, [C.R.], we see at once that $\overset{N}{\nabla} s_M = 0 \Rightarrow \Rightarrow \nabla^1 \nu_* = 0$. It results therefore that the submanifolds $\overset{1}{N}$ -symmetric constitute a generalization of the symmetric submanifolds. Moreover if $\overset{N}{\nabla} s_M = 0$ the osculating space $\overset{2}{O}_p(M) = T_p(M) \oplus \overset{1}{N}_p(M)$ is independent from $p \in M$ and M is all contained on it.

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Manoscritto pervenuto in redazione il 25 luglio 1989.