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Some Remarks on an Operational Time Dependent Equation.

G. DA PRATO (*)

Introduction.

Let E be a complex Hilbert space and $\{A(t)\}_{t \in [0, T]}$; $\{B(t)\}_{t \in [0, T]}$ two families of linear operators (generally not bounded) in E .

Consider the Cauchy problem:

$$\begin{cases} U'(t) = A(t)U(t) + U(t)B^*(t) + f(t, U(t)), \\ U(0) = U_0, \end{cases}$$

where f is a mapping $[0, T] \times Q \rightarrow \mathcal{L}(E)$ and $Q \subset \mathcal{L}(E)$.

Problems of this kind arise in several fields as Optimal Control theory ([2], [3], [7], [8], [9]) and the Hartree-Fock time dependent problem in the case of finite Fermi system ([1]).

In this paper we generalize the results contained in [3] and we give some new regularity result for the case where $A(t)$ and $B(t)$ generates « hyperbolic » semi-groups.

1. The semi-group $T \rightarrow e^{tA} T e^{tB}$.

Let E be a complex Hilbert space (norm $|| \cdot ||$, inner product (\cdot, \cdot)). We note by $\mathcal{L}(E)$ (resp. $H(E)$) the complex (resp. real) Banach space of linear bounded (resp. hermitian) operators $E \rightarrow E$ and by $H_+(E)$ the cone of positive operators.

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Let A and B be the infinitesimal generators of two semi-groups e^{tA} and e^{tB} ; we assume that:

$$(1.1) \quad |e^{tA}| < M_A \exp(w_A t), \quad |e^{tB}| < M_B \exp(w_B t).$$

We note finally by $\mathfrak{L}_s(E)$ (resp. $H_s(E)$) the set $\mathfrak{L}(E)$ (resp. $H(E)$) endowed by the strong topology; $\mathfrak{L}_s(E)$ is a locally convex space.

Consider the following semi-group in $\mathfrak{L}_s(E)$:

$$(1.2) \quad G_t(T) = e^{tA} T e^{tB}, \quad \forall T \in \mathfrak{L}(E), t \geq 0,$$

G_t is not strongly continuous in $\mathfrak{L}(E)$, but it is sequentially strongly continuous in $\mathfrak{L}_s(E)$, that is:

$$T_n \rightarrow T \text{ in } \mathfrak{L}_s(E) \Rightarrow G_t(T_n) \rightarrow G_t(T) \text{ in } \mathfrak{L}_s(E)$$

and the mapping:

$$\bar{\mathbf{R}}_+ \rightarrow \mathfrak{L}_s(E), \quad t \rightarrow G_t(T)$$

is continuous $\forall T \in \mathfrak{L}_s(E)$.

If $B = A^*$ (1) it is:

$$(1.3) \quad G_t(T) \in H(E), \quad \forall T \in H(E).$$

Put:

$$(1.4) \quad D(L) = \left\{ T \in \mathfrak{L}(E); \exists \lim_{h \rightarrow 0} \frac{1}{h} (G_h(T)x - Tx), \forall x \in E \right\},$$

$$(1.5) \quad L(T)x = \lim_{h \rightarrow 0^+} \frac{1}{h} (G_h(T)x - Tx), \quad \forall T \in D(L), \forall x \in E.$$

LEMMA 1.1. If $T \in D(L)$ and $x \in D(B)$ then $Tx \in D(A)$ and it is:

$$(1.6) \quad L(T)x = ATx + TBx.$$

PROOF. Let $T \in D(L)$, $x \in D(B)$, $y \in D(A^*)$; it is:

$$(L(T)x, y) = \frac{d}{dh} (Te^{hB}x, e^{hA^*}y)|_{h=0} = (TBx, y) + (Tx, A^*y).$$

(1) A^* is the adjoint of A .

It follows that the mapping:

$$D(A^*) \rightarrow \mathbf{C}, \quad y \rightarrow (Tx, A^*y) = (L(T)x, y) - (TBx, y)$$

is continuous, $Tx \in D(A)$ and:

$$(ATx, y) = (L(T)x, y) - (TBx, y) \neq$$

The following proposition is clear:

PROPOSITION 1.2. *If $T \in D(L)$ then $G_t(T) \in D(L)$ and it is:*

$$(1.7) \quad L(G_t(T)) = e^{tA}L(T)e^{tB},$$

$$(1.8) \quad \frac{d}{dt}(G_t(T)x) = e^{tA}L(T)e^{tB}x.$$

PROPOSITION 1.3. *L is closed in $\mathfrak{L}_s(E)$ and in $\mathfrak{L}(E)$.*

PROOF. Let $T_n \in D(L)$, $T_n \rightarrow T$, $S_n = L(T_n) \rightarrow S$ in $\mathfrak{L}_s(E)$; due to (1.8) it is:

$$e^{tA}T_n e^{tB}x - T_n x = \int_0^t e^{sA}S_n e^{sB}x ds$$

recalling the dominate convergence theorem we obtain:

$$\frac{1}{t}(G_t(T)x - Tx) = \frac{1}{t} \int_0^t G_s(S)x ds$$

it follows $T \in D(L)$ and $L(T) = S$. Therefore L is closed in $\mathfrak{L}_s(E)$ and consequently in $\mathfrak{L}(E)$. \neq

PROPOSITION 1.4. *$D(L)$ is dense in $\mathfrak{L}_s(E)$.*

PROOF. Put:

$$Q_t x = \frac{1}{t} \int_0^t G_s(T)x ds, \quad \forall T \in \mathfrak{L}(E), \quad \forall x \in E,$$

it is:

$$\lim_{t \rightarrow 0^+} Q_t = I \quad \text{in } \mathfrak{L}_s(\mathcal{E}),$$

moreover

$$\frac{1}{h} (G_h(Q_t) - Q_t)x = \frac{1}{th} \left[\int_t^{t+h} - \int_0^h G_s(T)x ds \right]$$

it follows $D_t \in D(L)$ and therefore $D(L)$ is dense in $\mathfrak{L}_s(\mathcal{E})$. \neq

PROPOSITION 1.5. $\varrho(L) \supset]w_A + w_B, \infty[$ and it is ⁽²⁾:

$$(1.9) \quad R(\lambda, L)(T)x = \int_0^\infty e^{-\lambda t} e^{tA} T e^{tB} x dt, \quad \forall x \in \mathcal{E}, \quad \forall \lambda > w_A + w_B,$$

$$(1.10) \quad \|R(\lambda, L)\|_{\mathfrak{L}(\mathcal{E})} \leq M_A M_B (\lambda - w_A - w_B)^{-1}, \quad w_A + w_B < \lambda \text{ } ^{(3)}.$$

PROOF. Put

$$F(T)x = \int_0^\infty e^{-\lambda t} e^{tA} T e^{tB} x dt, \quad \forall T \in \mathfrak{L}(\mathcal{E}).$$

For every $T \in D(L)$ it is:

$$F(L(T))x = \int_0^\infty e^{-\lambda t} G'_t(T)x dt = (\lambda F(T) - T)x$$

moreover if $T \in \mathfrak{L}(\mathcal{E})$ it is:

$$\frac{1}{h} \{G_h(F(T)) - F(T)\}x = \frac{e^{\lambda h} - 1}{h} \int_h^\infty e^{-\lambda t} G_t(T)x dt - \frac{1}{h} \int_0^h e^{-\lambda t} G_t(T)x dt$$

it follows

$$L(F(T))x = (\lambda F(T) - T)x. \quad \neq$$

⁽²⁾ If L is a linear operator, $\varrho(L)$ is the resolvent set and $R(\lambda, L)$ the resolvent of L .

⁽³⁾ $\mathfrak{L}(\mathfrak{L}(\mathcal{E}))$ is the Banach space of the linear bounded operators $\mathfrak{L}(\mathcal{E}) \rightarrow \mathfrak{L}(\mathcal{E})$. We note $\| \cdot \|$ the norm in $\mathfrak{L}(\mathfrak{L}(\mathcal{E}))$.

PROPOSITION 1.6. *If $T_n \rightarrow T$ in $C([0, T]; \mathfrak{L}_s(E))$ ⁽⁴⁾ then*

$$G_t(T_n(t)) \rightarrow G_t(T(t)) \quad \text{in } C([0, T]; \mathfrak{L}_s(E)).$$

PROOF. Let $x \in E$; for every $\varepsilon > 0$ there exists $n_\varepsilon \in \mathbb{N}$, $f_1, \dots, f_{n_\varepsilon}$ in $C([0, T])$ and $x_1, \dots, x_{n_\varepsilon} \in E$ such that:

$$\left| e^{tB}x - \sum_{i=1}^{n_\varepsilon} f_i(t)x_i \right| < \varepsilon, \quad \forall t \in [0, T],$$

it follows:

$$\begin{aligned} |G_t(T(t) - T_n(t))x| &\leq M_B \exp(|w_B|T) |(T(t) - T_n(t))e^{tB}x| \leq \\ &\leq M_B \exp(|w_B|T) \varepsilon (|T(t)| + |T_n(t)|) + \\ &\quad + M_B \exp(|w_B|T) \sum_{i=1}^{n_\varepsilon} |f_i(t)| |T(x)x_i - T_n(t)x_i|. \end{aligned}$$

Choose N such that $|T_n(t) \leq N|$, then:

$$\begin{aligned} |G_t(T(t) - T_n(t))x| &\leq 2N M_B \exp(|w_B|T) \varepsilon + \\ &\quad + M_B \exp(|w_B|T) \sum_{i=1}^{n_\varepsilon} |\varphi_i(t)| |T(x)x_i - T_n(x)x_i|. \end{aligned}$$

Choose n'_ε such that:

$$|T(t)x_i - T_n(t)x_i| \leq \varepsilon / (n_\varepsilon \text{Max} \{|\varphi_i|; i = 1, 2, \dots, n_\varepsilon\}), \quad \forall n > n_\varepsilon,$$

then

$$n > n'_\varepsilon \Rightarrow |G_t(T(t) - T_n(t))x| \leq (2N + 1) M_B \exp(|w_B|T) \varepsilon. \quad \neq$$

2. The linear problem.

Let $\mathcal{A} = \{A(t)\}_{t \in [0, T]}$, $\mathcal{B} = \{B(t)\}_{t \in [0, T]}$ be two families of linear operators in E .

Let F be a Hilbert space (norm $\| \cdot \|$, inner product (\cdot, \cdot)) continuously and densely embedded in E .

⁽⁴⁾ $C([0, T]; \mathfrak{L}_s(E))$ is the set of the mappings $[0, T] \rightarrow \mathfrak{L}_s(E)$ continuous; due to the Banach-Steinhaus theorem every $u \in C([0, T]; \mathfrak{L}_s(E))$ is bounded.

Let finally Z be an isometric isomorphism in $\mathfrak{L}(F, E)$.

We assume:

- (2.1) $\left\{ \begin{array}{l} a) \mathcal{A} \text{ (resp. } \mathcal{B}) \text{ is } (M_A, w_A)\text{-stable and } w_A\text{-measurable (resp. } \\ \text{ } (M_B, w_B)\text{-stable and } w_B\text{-measurable) in } E \text{ }^{(5)}. \\ b) \text{ It is } F \subset D(A(t)) \text{ (resp. } D(B(t))), A(t) \text{ (resp. } B(t)) \in \mathfrak{L}(F, E) \\ \text{ and } |A(t)| \text{ (resp. } |B(t)|) \text{ is bounded in } [0, T] \text{ }^{(6)}. \\ c) \text{ The mapping } A(\cdot)x \text{ (resp. } B(\cdot)x) \text{ is continuous } \forall x \in F. \\ d) \text{ There exists a mapping } H \text{ (resp. } K): [0, T] \rightarrow \mathfrak{L}(E) \text{ such} \\ \text{ that:} \\ d_1) H \text{ (resp. } K) \text{ is bounded in } [0, T] \text{ and strongly measur-} \\ \text{ able in } E. \\ d_2) \text{ It is:} \\ ZA(t)Z^{-1}x = A(t)x + H(t)x, \quad \forall x \in D(A(t)), \\ ZB(t)Z^{-1}x = B(t)x + K(t)x, \quad \forall x \in D(B(t)). \end{array} \right.$

If [2.1] is fulfilled it is known ([4], [6]) that there exists an evolution operator $G_A(t, s)$ (resp. $G_B(t, s)$) for the problem:

$$u' = A(t)u, \quad u(0) = x \quad (\text{resp. } u' = B(t)u, \quad u(0) = x).$$

Moreover G_A (resp. G_B): $\Delta = \{(t, s) \in [0, T]^2; t \geq s\} \rightarrow \mathfrak{L}(E)$ is strongly continuous and $G(r, s) \in \mathfrak{L}(F)$.

Finally it is:

$$(2.2) \quad \left\{ \begin{array}{l} \lim_{n \rightarrow \infty} G_{A,n} = G_A, \\ \lim_{n \rightarrow \infty} G_{B,n} = G_B, \end{array} \right. \quad \text{in } C(\Delta; \mathfrak{L}_s(E)),$$

⁽⁵⁾ \mathcal{A} is w_A -measurable in E if $\varrho(A(t)) \supset w_A, +\infty[$ and $R(\lambda, A(\cdot))$ is strongly measurable $\forall \lambda > w_A$.

\mathcal{A} is (M_A, w_A) -stable in E if $\varrho(A(t)) \supset w_A, +\infty[$ and it is:

$$\left| \prod_{i=1}^k R(\lambda, A(t_i)) \right| < M_A / (\lambda - w_A)^k$$

$\forall k \in \mathbb{N}, t_1 > t_2 > \dots > t_k, t_i \in [0, T], i = 1, \dots, n.$

⁽⁶⁾ With the topology of $\mathfrak{L}(F, E)$.

where $G_{A,n}$ (resp. $G_{B,n}$) is the evolution operator associated to the problem:

$$u'_n = A_n(t)u_n, \quad u_n(0) = x \quad (\text{resp. } u'_n = B_n(t)u_n, \quad u_n(0) = x)$$

where $A_n(t) = n^2R(n, A(t)) - n$ and $B_n(t) = n^2R(n, B(t)) - n$.

Consider now the problem:

$$(2.3) \quad \begin{cases} T'(t) = A(t)T(t) + T(t)B^*(t) + F(t), & F \in C([0, T]; \mathfrak{L}_s(E)), \\ T(0) = T_0 \in \mathfrak{L}(E). \end{cases}$$

We define $L(t)$ as in (1.4), (1.5) and write (2.3) in the following form:

$$(2.4) \quad \begin{cases} T'(t) = L(t)(T(t)) + F(t), \\ T(0) = T_0. \end{cases}$$

We consider also the approximate problem:

$$(2.5) \quad \begin{cases} T'_n(t) = L_n(t)(T(t)) + F(t), \\ T_n(0) = T_0, \end{cases}$$

where $L_n(t)(T) = A_n(t)T + TB_n^*(t)$.

We say that T is a *strong solution* of (2.4) if there exists:

$$(2.6) \quad \{T_k\} \subset D(L(t)) \cap C^1([0, T]; \mathfrak{L}_s(E)) \quad (*)$$

such that:

$$\begin{cases} T'_k - L(T_k) \rightarrow F & \text{in } C([0, T]; \mathfrak{L}_s(E)), \\ T_k(0) \rightarrow T_0 & \text{in } \mathfrak{L}(E). \end{cases}$$

If $T \in D(L(t)) \cap C^1([0, T]; \mathfrak{L}_s(E))$ and (2.4) is fulfilled we say that T is a *classical solution* of (2.4).

THEOREM 2.1. *Let \mathcal{A} and \mathcal{B} be two family of linear operators in E verifying (2.1). Then for every $T_0 \in \mathfrak{L}(E)$ and $F \in C([0, T]; \mathfrak{L}_s(E))$ the*

(*) $C^1([0, T]; \mathfrak{L}_s(E))$ is the set of the mappings $[0, T] \rightarrow \mathfrak{L}_s(E)$ strongly continuously differentiable.

problem (2.4) has a unique strong solution given by:

$$(2.7) \quad T(t)x = G_A(t, 0)T_0G_B^*(t, 0)x + \int_0^t G_A(t, s)F(s)G_B^*(t, s)x ds.$$

If $T_0 \in \mathfrak{L}(F)$ and $F \in C([0, Y]; \mathfrak{L}_s(F))$ then the solution T is classical.

PROOF. Let first $T_0 \in \mathfrak{L}(F)$ and $F \in C([0, T]; \mathfrak{L}_s(F))$; in this case we can easily verify that T is a classical solution.

In the general case by approximating T_0 and F we can show that $T(t)$, given by (2.7) is a strong solution.

Assume finally that T is a strong solution of (2.4) and take $\{T_k\}$ as in (2.6). Put $F_k = T_k' - L(T_k)$; it is:

$$\frac{d}{ds}(G_A(t, s)T_k(s)G_B(t, s)x) = G_A(t, s)F_k(s)G_B(t, s)x, \quad \forall x \in E,$$

by integration in $[0, t]$ it follows:

$$T_k(t)x = G_A(t, 0)T_k(0)G_B(t, 0)x + \int_0^t G_A(t, s)F_k(s)G_B(t, s)x ds$$

and, taking the limit for $k \rightarrow \infty$, the conclusion follows.

3. The quasi-linear problem.

Let Q a closed convex set in $\mathfrak{L}(E)$ and f a strongly continuous mapping

$$f: [0, T] \times Q \rightarrow \mathfrak{L}(E), \quad (t, S) \rightarrow f(t, S).$$

Consider the problems:

$$(3.1) \quad \begin{cases} U'(t) - L(t)(U(t)) + f(t, U(t)) = 0, \\ U(0) = U_0, \end{cases}$$

$$(3.2) \quad \begin{cases} U_n'(t) - L_n(t)(U(t)) + f(t, U_n(t)) = 0, \\ U_n(0) = U_0. \end{cases}$$

We say that U is a *strong solution* of (3.1) if there exists $\{U_k\} \subset C(D(L(t)) \cap C^1([0, T]; \mathcal{L}_s(E)))$ such that:

$$\begin{cases} U'_k - L(U_k) + f(t, U_k) \rightarrow 0 & \text{in } C([0, T]; \mathcal{L}_s(E)), \\ U_k(0) \rightarrow U_0 & \mathcal{L}_s(E). \end{cases}$$

If U belongs to $D(L(t)) \cap C^1([0, T]; \mathcal{L}_s(E))$ and fulfils (3.1) we say that U is a *classical solution* of (3.1).

The following proposition is an immediate consequence of the Theorem 2.1.

PROPOSITION 3.1. *U is a strong solution of (3.1) if and only if it is:*

$$(3.3) \quad U(t)x = G_A(t, 0) U_0 B_B^*(t, 0)x - \int_0^t G_A(t, s) f(s, U(s)) G_B^*(t, s)x ds .$$

We remark now that $C([0, T]; \mathcal{L}_s(E))$ is not a metric space, but we can define in it the following norm:

$$(3.4) \quad \|U\| = \text{Sup} \{|U(t)|, t \in [0, T]\}, \quad \forall U \in C([0, T]; \mathcal{L}_s(E)),$$

by virtue of the Banach-Steinhaus theorem.

$C([0, T]; \mathcal{L}_s(E))$ endowed by the norm (3.4) is a Banach space which we note by $B([0, T]; \mathcal{L}_s(E))$.

LEMMA 3.2. *Let K be a closed subset of $B([0, T]; \mathcal{L}_s(E))$ and γ_n, γ mappings $K \rightarrow K$. Assume that:*

$$(3.5) \quad \|\gamma_n(U) - \gamma_n(V)\| \leq \alpha \|U - V\|, \quad \alpha \in]0, 1[, \quad U, V \in K,$$

$$(3.6) \quad \gamma_n(U) \rightarrow \gamma(U) \quad \text{in } C([0, T]; \mathcal{L}_s(E)), \quad \forall U \in K .$$

Then there exists $\{U_n\}$ and U unic in K such that:

$$(3.7) \quad \gamma_n(U_n) = U_n, \quad \gamma(U) = U,$$

$$(3.8) \quad U_n \rightarrow U \text{ in } C([0, T]; \mathcal{L}_s(E)).$$

PROOF. By virtue of the contractions principle there exists U_n and U such that (3.7) is fulfilled.

To prove (3.8) fix Z in K ; it is:

$$U_n = \lim_{m \rightarrow \infty} \gamma_n^m(Z), \quad U = \lim_{m \rightarrow \infty} \gamma^m(Z) \quad \text{in } B([0, T]; \mathfrak{L}_s(E))$$

and

$$\|U_n - \gamma_n^m(Z)\| \leq \frac{\alpha^m}{1 - \alpha} (\|\gamma_n(Z)\| + \|Z\|)$$

therefore there exists $M > 0$ such that:

$$(3.9) \quad \|U_n - \gamma_n^m(Z)\| \leq M\alpha^m.$$

It is easy to show that:

$$(3.10) \quad \lim_{n \rightarrow \infty} \gamma_n^m(U) = \gamma^m(U) \quad \text{in } C([0, T]; \mathfrak{L}_s(E)), \quad \forall U \in K, \quad m \in \mathbf{N}$$

if $x \in E$ and $t \in [0, T]$ it follows:

$$\begin{aligned} |U(t)x - U_n(t)x| &\leq |U(t)x - \gamma^m(Z)(t)x| + \\ &\quad + |\gamma^m(Z)(t) - \gamma_n^m(Z)(t)x| + |U_n(t)x - \gamma_n^m(Z)(t)x| \end{aligned}$$

due to (3.9) it follows:

$$|U(t)x - U_n(t)x| \leq 2M\alpha^m |x| + |\gamma^m(Z)(t)x - \gamma_n^m(Z)(t)x|$$

and the conclusion follows from (3.10). \neq

We prove now the existence of the maximal solution for the problem (3.1).

We assume:

$$(3.11) \quad \left\{ \begin{array}{l} a) f \in C([0, T] \times Q_s^{(*)}; \mathfrak{L}_s(E)) \cap C([0, T] \times Q; \mathfrak{L}(E)), \\ b) \exists \mu: \mathbf{R}_+ \rightarrow \mathbf{R}_+ \text{ such that:} \\ \quad |f(t, T) - f(t, S)Z| \leq \mu(r)|T - S| \text{ if } |T| \leq r, |S| \leq r, \\ c) \exists \alpha: \mathbf{R}_+ \rightarrow \mathbf{R}_+ \text{ such that:} \\ \quad r > 0, |T| \leq r, T \in Q, \beta \in]0, \alpha(r)[\Rightarrow T - \beta f(t, T) \in Q. \end{array} \right.$$

We remark that $c)$ is trivial if $Q = \mathfrak{L}_s(E)$ or $H(E)$.

(*) Q_s is endowed by the topology of $\mathfrak{L}_s(E)$.

LEMMA 3.3. Assume that:

- i) \mathcal{A} and \mathcal{B} verify (2.1), $U_0 \in Q$,
- ii) $T \in Q \Rightarrow \exp(sA(t))T \exp(sB(t)) \in Q, \forall t \in [0, T]$,
- iii) f verifies (3.11).

Take α, β such that:

$$\begin{cases} \alpha \geq M_A M_B \exp((|w_A| + |w_B|)T) |U_0|, \\ \beta \leq \alpha(2a). \end{cases}$$

Then there exists $\tau > 0$ such that the problem (3.1) has a unique strong solution in $[0, \tau]$.

PROOF. Put:

$$\varphi(t, T) = T - \beta f(t, T)$$

then φ maps $[0, T] \times (Q \cap P(0, 2a))$ in Q (*) and it is:

$$(3.13) \quad |\varphi(t, T) - \varphi(t, S)| \leq (1 + \beta\mu(2a)) |T - S|, \quad \forall T, S \in Q \cap P(0, 2a).$$

Problem (3.1) is equivalent to:

$$(3.14) \quad \begin{cases} U' - L(t)U + \frac{1}{\beta} \varphi(t, U) = 0, \\ U(0) = U_0, \end{cases}$$

put $U = \exp(-t/\beta)V$, then it is:

$$(3.15) \quad V(t)x = G_A(t, 0)U_0G_B^*(t, 0)x + \frac{1}{\beta} \int_0^t e^{s/\beta} G_A(t, s) \varphi(s, U(s)) G_B^*(t, s) x ds$$

which is equivalent to the equation:

$$(3.16) \quad U(t) = G_A(t, 0)U_0G_B^*(t, 0)e^{-t/\beta} + \frac{1}{\beta} \int_0^t e^{-(t-s)/\beta} G_A(t, s) \varphi(s, U(s)) G_B^*(t, s) ds = \gamma(U)(t).$$

(*) $P(0, r) = \{T \in \mathcal{L}(E); |T| \leq r\}$.

It is:

$$\|\gamma(U) - \gamma(V)\| \leq M_A M_B \exp((|w_A| + |w_B|)T)(1 - e^{-t/\beta}) \|U - V\| ,$$

$$\forall U, V \in C([0, \tau]; (Q \cap P(0, 2a))_s)$$

and

$$\|\gamma(U)\| \leq a + M_A M_B \exp((|w_A| + |w_B|)T)(1 + \mu(2a))2a +$$

$$+ \text{Sup} \{|\varphi(t, 0)|, t \in [0, T]\}(1 - e^{-t/\beta}) .$$

Therefore there exists $\tau > 0$ such that γ is a contraction in

$$C([0, \tau]; (Q \cap P(0, 2a))_s) . \quad \neq$$

The following theorem is an immediate consequence of Lemma 3.3, Proposition 1.6, Lemma 3.2 and standard arguments.

THEOREM 3.4. *Assume that $\mathcal{A}, \mathcal{B}, f$ verify the hypotheses of Lemma 3.3. Then there exists the maximal solution U of the problem (3.1). If I is the interval where U is defined it is:*

$$U_n \rightarrow U \quad \text{in} \quad C(I, \mathcal{L}_s(E))$$

U_n being the solution of (3.2). Finally if $\|U\|$ is bounded it is $I = [0, T]$.

PROPOSITION 3.5. *Assume that the hypotheses of Theorem 3.4 are fulfilled. Assume moreover:*

$$(3.18) \quad \left\{ \begin{array}{l} \text{i) } M_A = M_B = 1 , \\ \text{ii) } \exists \omega_1 \in \mathbf{R} \text{ such that} \\ |T| \leq |T + \alpha(f(t, T) - f(t, 0) + \omega_1 T)| , \\ \forall \alpha \geq 0 , t \in [0, T] , T \in Q . \end{array} \right.$$

Then the maximal solution of (3.1) verifies the following inequality:

$$(3.19) \quad |U(t)| \leq \exp((w_A + w_B + \omega_1)t) |U_0| +$$

$$+ \int_0^t \exp((w_A + w_B + \omega_1)(t-s)) |f(s, 0)| ds .$$

PROOF. We remember (Kato [5]) that (3.18)-ii) is equivalent to:

$$(3.20) \quad \langle f(t, T) - f(t, 0), \Gamma \rangle \geq -\omega_1 |T|, \quad \forall \Gamma \in \partial|T|,$$

$\partial|T|$ being the sub-differential of the norm in $\mathfrak{L}(E)$.

Due to (3.18) for every $T \in D(L(s))$ there exists $\Gamma \in \partial|T|$ such that

$$(3.21) \quad \langle L(s)(T), \Gamma \rangle \leq (w_A + w_B) |T|.$$

Suppose first that U is a classical solution of (3.1); then

$$(3.22) \quad \begin{aligned} \frac{d^-}{dt} |U(t)| &= \inf \{ \langle U(t), \Gamma \rangle, \Gamma \in \partial|U(t)| \} \leq \\ &\leq \langle L(t)(U(t)), \Gamma \rangle - \langle f(t, U(t)) - f(t, 0), \Gamma \rangle + \langle f(t, 0), \Gamma \rangle \end{aligned}$$

if we take Γ such that

$$\langle L(t)(U(t)), \Gamma \rangle \leq (w_A + w_B) |U(t)|$$

it is

$$(3.13) \quad \frac{d^-}{dt} |U(t)| \leq (w_A + w_B + \omega_1) |U(t)| + |f(t, 0)|$$

which implies (3.19). If U is a strong solution the conclusion follows by approximation. \neq

4. Regularity.

If for every $V \in \mathfrak{L}(F)$ it is $f(t, V) \in \mathfrak{L}(F)$ we put

$$f_z(t, V) = Zf(t, Z^{-1}VZ)Z^{-1}.$$

THEOREM 4.1. *Assume that the hypotheses of Theorem 3.4 are fulfilled. Moreover assume that f maps $[0, T] \times \mathfrak{L}(F)$ in $\mathfrak{L}(F)$ and that f_z verifies (3.11); then if $U_0 \in \mathfrak{L}(E) \cap \mathfrak{L}(F)$ the maximal solution of (3.1) is classical and $U(t) \in \mathfrak{L}(F), \forall t \in [0, T]$.*

PROOF. Consider the problems:

$$(4.1) \quad \begin{cases} V'(t) = (A(t) + H(t))V(t) + V(t)(B(t) + K(t)) + f_x(t, V), \\ B(0) = ZU_0Z^{-1}, \end{cases}$$

$$(4.2) \quad \begin{cases} V'_n(t) = (A_n(t) + H_n(t))V_n(t) + \\ \quad \quad \quad + V_n(t)(B_n(t) + K_n(t)) + Zf_n(t, U_n)Z^{-1}, \\ V_n(0) = ZU_0Z^{-1}, \end{cases}$$

where

$$(4.3) \quad \begin{cases} H_n(t) = n^2 R(n, A(t))H(t)R(n, A(t)) + H(t), \\ K_n(t) = n^2 R(n, B(t))K(t)R(n, B(t)) + K(t). \end{cases}$$

By virtue of Theorem 3.4 the problems (4.1) and (4.2) have maximal solutions in $[0, \tau[$, τ being the maximal time for U ; moreover

$$V_n \rightarrow V \quad \text{in } C([0, \tau[; \mathfrak{L}_s(E)).$$

It is easy to see that $V_n = ZU_nZ^{-1}$, therefore

$$U_n \rightarrow U \quad \text{in } C([0, \tau[; \mathfrak{L}_s(E)), \quad ZU_nZ^{-1} \rightarrow V \quad \text{in } \mathfrak{L}_s(E)$$

it follows $U \in \mathfrak{L}(F)$, $V = ZUZ^{-1}$. \neq

REMARK. If A and B are independent of t we have the following result (cf. [3]).

THEOREM 4.2. *Assume that the hypotheses of Theorem 3.4 are fulfilled. Suppose moreover that $f \in C^1([0, T], \mathfrak{L}_s(E))$ and $U_0 \in D(L)$. Then the maximal solution of (3.1) is classical.*

5. Examples.

1) Let $f \in C^2(\mathbf{R})$, put:

$$(5.1) \quad f(T) = \int_{-\infty}^{+\infty} f(\lambda) dE_\lambda, \quad \forall T \in H(E),$$

E_λ being the spectral projector attached to T .

If we choose $Q = H(E)$, $B = A$ then f fulfils (3.11) (cf. Tartar [8]) and (3.1) has a unique maximal solution.

Assume now

$$(5.2) \quad Q = \{T \in H(E); a \leq T \leq b\}, \quad a, b \in \mathbf{R}.$$

LEMMA 5.1. *If $f(a) \leq 0$ and $f(b) \geq 0$ then $\forall r > 0, \exists \beta_r > 0$ such that:*

$$(5.3) \quad |x| < r, \quad x \geq a, \quad \beta \in]0, \beta_r[\Rightarrow x - \beta f(x) \geq a.$$

PROOF. If $f(a) < 0$ the thesis is evident. Assume $f(a) = 0$; then it is $f(x) = (x - a)\psi(x)$ and if $x \geq a$ it is

$$x - a - \beta f(x) = (x - a)(1 - \beta\psi(x)) \geq 0$$

for suitable $\beta. \neq$

The following proposition is now evident

PROPOSITION 5.2. *Assume that (2.1) is fulfilled with $B = A$. Assume moreover that $f \in C^2(\mathbf{R})$, $f(a) \leq 0, f(b) \geq 0$. Then if $a \leq U_0 \leq b$ there exists a unique global solution U such that $a \leq U(t) \leq b$.*

2) *Riccati equation.*

Assume $Q = H_+(E)$, $B = A$, $|e^{tA}| \leq 1$ and (2.1) fulfilled; assume $f(T) = TPT - F(t)$ where $P \geq 0, F(t) \geq 0$; then it is easy to see that f verifies (3.11); therefore (3.1) has a maximal solution in Q . Moreover it is

$$|T| \leq |T + \alpha TPT|, \quad \forall \alpha > 0, \forall T \geq 0,$$

because

$$((T + \alpha TPT)x, x) \geq (Tx, x)$$

therefore if $U_0 \geq 0$ (3.1) has a global solution.

Finally assume $P \in \mathfrak{L}(F)$, put $\bar{P} = ZPZ^{-1}$ then $f_z(V) = V\bar{P}V$ and the hypotheses of the Theorem 4.1 are fulfilled and the solution is classical.

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