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# On the Motion of a Non-Homogeneous Ideal Incompressible Fluid in an External Force Field.

Hugo Beirão da Veiga - Alberto Valli (\*)

### 1. Introduction and main results.

In this paper we consider the motion of a non-homogeneous ideal incompressible fluid in a bounded connected open subset  $\Omega$  of  $\mathbb{R}^2$ .

We denote in the sequel by v(t,x) the velocity field, by  $\varrho(t,x)$  the mass density and by  $\pi(t,x)$  the pressure. The Euler equations of the motion are

$$egin{aligned} arrho\left[rac{\partial v}{\partial t} + (v\cdot
abla)\,v - b
ight] &= -
abla\pi & ext{in } Q_T \equiv [0,\,T] imesar{arOmega}\,, \ & ext{div}\,v = 0 & ext{in } Q_T\,, \ & ext{in } Q_T\,, \ & ext{in } Q_T\,, \ & ext{v}\cdot n = 0 & ext{on } [0,\,T] imesarGamma\,, \ & ext{v}\cdot n = 0 & ext{on } [0,\,T] imesarGamma\,, \ & ext{v}\cdot n = 0 & ext{on } [0,\,T] imesarGamma\,, \ & ext{v}\cdot n = 0 & ext{on } [0,\,T] imesarGamma\,, \ & ext{v}\cdot n = 0 & ext{on } [0,\,T] imesarGamma\,, \ & ext{on } [0,$$

where n = n(x) is the unit outward normal vector to the boundary  $\Gamma$  of  $\Omega$ , b = b(t, x) is the external force field and a = a(x),  $\varrho_0 = \varrho_0(x)$ 

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are the initial velocity field and the initial mass density respectively.

When the fluid is homogeneous, i.e. the density  $\varrho_0$  (and consequently  $\varrho$ ), is constant, equations (E) have been studied by several authors. As regards the two-dimensional case, we recall the papers of Wolibner [13], Leray [6], Hölder [3], Schaeffer [10], Yudovich [14], [15], Golovkin [2], Kato [5], Mc Grath [9] and Bardos [1]; for the case of a variable boundary see Valli [12]. For the *n*-dimensional case we recall the papers of Lichtenstein, Ebin and Marsden, Swann, Kato, Bourguignon and Brezis, Temam, Bardos and Frisch.

For non-homogeneous fluids, Marsden [8] has proved the existence of a local solution to problem (E), under the assumption that the external force field b(t,x) is divergence free and tangential to the boundary, i.e. div b=0 in  $Q_T$  and  $b \cdot n=0$  on  $[0,T] \times \Gamma$ . The proof relies on techniques of Riemannian geometry on infinite dimensional manifolds. See also the reference [16].

In this paper we prove the existence of a local solution of problem (E) without any restriction on the external force field b(t, x) but we need condition (A) on the initial mass density  $\varrho_0(x)$  (1).

Our techniques are based on the method of characteristics and on Schauder's fixed point theorem, and in this sense related to the methods of Kato [5] and Mc Grath [9].

We prove the following results (2).

THEOREM A. Let  $\Omega$  be of class  $C^{3+\lambda}$ ,  $0 < \lambda < 1$ , and let  $a \in C^{2+\lambda}(\overline{\Omega})$  with div a = 0 in  $\overline{\Omega}$  and  $a \cdot n = 0$  on  $\Gamma$ ,  $\varrho_0 \in C^{2+\lambda}(\overline{\Omega})$  with  $\varrho_0(x) > 0$  for each  $x \in \overline{\Omega}$ , and  $b \in C^{0,1+\lambda}(Q_T) \cap C^{\lambda,0}(Q_T)$  with rot  $b \in C^{0,1+\lambda}(Q_T) \cap C^{\lambda,0}(Q_T)$ .

Moreover we assume that (1)

$$\left\|\frac{D\varrho_{0}}{\varrho_{0}}\right\|_{\infty} < \left\{ \begin{array}{ll} \frac{1}{K_{1}} & \mbox{if $\Omega$ is simply connected} \;, \\ \\ \frac{1}{K_{1}(1+K_{3}K_{4})} & \mbox{otherwise} \;. \end{array} \right.$$

- (1) Added in proofs. In the authors' papers «On the Euler equations for non-homogeneous fluids» (I), (II) (to appear) condition (A) is dropped and the three dimensional case is proved.
- (2) The definition of  $K_1$  is given in (3.4); those of  $K_3$  and  $K_4$  in (7.21), (7.11) and (7.24).

Then there exist

$$T_1\in \left]0,\ T
ight], \qquad v\in C^{1,2+\lambda}(Q_{T_1})\cap C^{1+\lambda,0}(Q_{T_1})\ ,$$
  $arrho\in C^{2+\lambda,2+\lambda}(Q_{T_1})\ , \qquad \pi\in C^{0,2+\lambda}(Q_{T_1})\cap C^{\lambda,1}(Q_{T_1})\ ,$ 

such that  $(v, \varrho, \pi)$  is a solution of (E) in  $Q_{\pi}$ .

THEOREM B. Assume that  $\varrho_0$  and  $\nabla \varrho_0$  belong to  $L^{\infty}(\Omega)$ ,  $\min \varrho_0 > 0$  and that b belongs to  $L^1(0, T; L^{\infty}(\Omega))$ . Then problem (E) has at most a solution  $(v, \varrho, \pi)$  in the class of vector functions  $v \in L^{\infty}(Q_T)$  such that  $\partial v/\partial t$ ,  $\partial v/\partial x_1$  and  $\partial v/\partial x_2$  are in  $L^1(0, T; L^{\infty}(\Omega))$ . The pressure is unique up to an arbitrary function of t which may be added to it. This result holds in dimension n > 2.

For other uniqueness theorems see also Serrin [11].

The paper consists of two parts. In Part I we prove Theorem A for a simply connected domain  $\Omega$ , and Theorem B. In Part II we prove Theorem A in the general case, i.e. we assume that  $\Gamma$  consists of m+1 simple closed curves  $\Gamma_0$ ,  $\Gamma_1$ , ...,  $\Gamma_m$ , where  $\Gamma_i$  (j=1,...,m) are inside of  $\Gamma_0$  and outside of one another.

### PART I

### 2. Notations.

Let  $\Omega$  be a bounded simply connected open subset of  $\mathbb{R}^2$ .

We denote by  $C^{k+\lambda}(\overline{\mathcal{Q}})$ , k non negative integer,  $0 < \lambda < 1$ , the space of k-times continuously differentiable functions in  $\overline{\mathcal{Q}}$  with  $\lambda$ -Hölder continuous derivatives of order k; by  $C^0(Q_T)$  the space of continuous functions in  $Q_T$ ; by  $C^1(Q_T)$  the space of continuously differentiable functions in  $Q_T$ .

We set

$$D_i arphi \equiv rac{\partial arphi}{\partial x_i} \,, \qquad D^lpha D_i^j arphi \equiv rac{\partial^{|lpha|+j} arphi}{\partial x_1^{lpha_1} \, \partial x_2^{lpha_2} \, \partial t^j} \,,$$

and

$$egin{aligned} C^{k,h}(Q_T) & \equiv ig\{ arphi \in C^0(Q_T) | D^{lpha} D^j_{\ i} arphi \in C^0(Q_T) \ & ext{if} \ 0 \leqslant j \leqslant k, \ & |lpha| \leqslant h \ ext{and} \ j + |lpha| \leqslant \max{(k,\,h)} ig\}, \end{aligned}$$

$$C^{\lambda,0}(Q_T) \equiv ig\{ arphi \in C^0(Q_T) | arphi \ ext{ is $\lambda$-H\"{o}lder continuous in $t$,} \ ext{uniformly with respect to $x$} ig\},$$

$$C^{0,\lambda}(Q_T) = \{ \varphi \in C_0(Q_T) | \varphi \text{ is $\lambda$-H\"{o}lder continuous in } x, \\ \text{uniformly with respect to } t \},$$

$$egin{aligned} C^{\mathtt{k}+\lambda,\hbar}(Q_T) &\equiv ig\{ arphi \in C^{\mathtt{k},\hbar}(Q_T) | D^lpha D^j_t arphi \in C^{\lambda,0}(Q_T) \ & ext{if } j+|lpha| = \max{(k,\,\hbar)} ext{ or if } j=k ig\}, \end{aligned}$$

$$egin{aligned} C^{k,h+\lambda}(Q_T) &\equiv &\Big\{ arphi \in C^{k,h}(Q_T) | D^lpha D^j_t arphi \in C^{0,\lambda}(Q_T) \\ & ext{if } j+|lpha| = \max{(k,h)} \text{ or if } |lpha|=h \Big\}, \end{aligned}$$

$$C^{k+\lambda,h+\lambda}(Q_T) \equiv C^{k+\lambda,h}(Q_T) \cap C^{k,h+\lambda}(Q_T)$$
.

We denote by  $\|\cdot\|_{\infty}$  the supremum norm, both in  $\overline{\Omega}$  or in  $Q_T$ , and by  $[\cdot]_{\lambda}$  the usual  $\lambda$ -Hölder seminorm in  $\overline{\Omega}$ . Furthermore we define

$$\begin{split} [\varphi]_{\lambda,0} & \equiv \sup_{\substack{t,s \in [0,T] \\ t \neq \underline{s} \\ x \in \overline{\Omega}}} \frac{|\varphi(t,x) - \varphi(s,x)|}{|t-s|^{\lambda}} \,, \\ [\varphi]_{0,\lambda} & \equiv \sup_{\substack{x,y \in \overline{\Omega} \\ x \neq y \\ t \in [0,T]}} \frac{|\varphi(t,x) - \varphi(t,y)|}{|x-y|^{\lambda}} \,, \\ [\varphi]_{\text{lip},0} & \equiv \sup_{\substack{t,s \in [0,T] \\ t \neq s \\ x \in \overline{\Omega}}} \frac{|\varphi(t,x) - \varphi(s,x)|}{|t-s|} \,, \\ [\varphi]_{0,\text{lip}} & \equiv \sup_{\substack{x,y \in \overline{\Omega} \\ x \neq y \\ t \in [0,T]}} \frac{|\varphi(t,x) - \varphi(t,y)|}{|x-y|} \,, \end{split}$$

Finally, we set

$$egin{aligned} \|D arphi\|_{\,_{oldsymbol{\infty}}} &\equiv & \sum\limits_{|lpha|=1} \|D^lpha arphi\|_{\,_{oldsymbol{\infty}}}, \ \|D^2 arphi\|_{\,_{oldsymbol{\infty}}} &\equiv & \sum\limits_{|lpha|=2} \|D^lpha arphi\|_{\,_{oldsymbol{\infty}}}, \end{aligned}$$

and analogously for the seminorms  $[\cdot]_{\lambda,0}$  and  $[\cdot]_{0,\lambda}$ .

If  $u = (u_1, u_2)$  is a vector field defined in  $Q_T$ , we write  $u \in C^{\lambda,0}(Q_T)$  if  $u_1, u_2 \in C^{\lambda,0}(Q_T)$ , and we set  $[u]_{\lambda,0} = [u_1]_{\lambda,0} + [u_2]_{\lambda,0}$ ; the same convention is used for the other vector spaces and norms (in  $\overline{\Omega}$  or in  $Q_T$ ).

We put

$$egin{aligned} \operatorname{Rot} \varphi &\equiv \left( rac{\partial arphi}{\partial x_2}, \, -rac{\partial arphi}{\partial x_1} 
ight), \ \operatorname{rot} u &\equiv rac{\partial u_2}{\partial x_1} - rac{\partial u_1}{\partial x_2}, \end{aligned}$$

where  $\varphi$  is a scalar function and  $u = (u_1, u_2)$  is a vector function.

### 3. Preliminaries.

Let  $\varphi \in C^{1,1+\lambda}(Q_T)$  with  $D_t \varphi \in C^{\lambda,0}(Q_T)$ ; we assume that

$$\begin{cases} \|\varphi\|_{0,1+\lambda} \equiv \|\varphi\|_{\infty} + \|D\varphi\|_{\infty} + [D\varphi]_{0,\lambda} \leqslant A \;, \\ \|D_{t}\varphi\|_{\infty} \leqslant B \;, \\ \|D_{t}\varphi\|_{0,\lambda} \equiv \|D_{t}\varphi\|_{\infty} + [D_{t}\varphi]_{0,\lambda} \leqslant C \;, \\ [D_{t}\varphi]_{\lambda,0} \leqslant D \;, \end{cases}$$

where A, B, C, D are positive constants that we will specify in the following (see (4.9)).

Let  $\psi$  be the solution of

$$\left\{ \begin{array}{ll} -\varDelta \psi(t,x) = \varphi(t,x) & \text{ in } \varOmega \,, \\ \psi|_{\varGamma} & = 0 \,, \end{array} \right.$$

for each  $t \in [0, T]$ , i.e.

$$(3.2)' \psi(t, x) = \int_{\Omega} G(x, y) \varphi(t, y) dy$$

where G(x, y) is the Green function for the operator —  $\Delta$  with zero boundary condition.

Put  $\|\chi\|_{k+\lambda} \equiv \sum_{|\alpha| \leq k} \|D^{\alpha}\chi\|_{\infty} + \sum_{|\alpha| = k} [D^{\alpha}\chi]_{\lambda}$ . It is well known that there exist constants  $c = c(\lambda, \Omega)$  such that

(3.3) 
$$\begin{aligned} \|\chi\|_{3+\lambda} &< c \|\Delta\chi\|_{1+\lambda}, \\ \|\chi\|_{2+\lambda} &< c \|\Delta\chi\|_{\lambda}, \\ [D\chi]_{\lambda} &< c \|\Delta\chi\|_{\infty}, \end{aligned}$$

for each  $\chi \in C^{\infty}(\overline{\Omega})$  vanishing on  $\Gamma$ .

Moreover there exists  $K_1 = K_1(\Omega)$  such that

$$\sup_{x\in\overline{\Omega}}\int\limits_{\Omega}\left|\nabla_{x}G(x,y)\right|dy\leqslant\frac{1}{2}K_{1}\;.$$

It is sufficient to choose  $K_1 = 4\pi K \operatorname{diam} \Omega$ , where K is such that

$$(3.4)' |\nabla_x G(x,y)| \leqslant \frac{K}{|x-y|}, \forall x, y \in \overline{\Omega}, x \neq y,$$

(see for instance Lichtenstein [7], pag. 248).

We obtain

LEMMA 3.1. Let  $\varphi \in C^{1,1+\lambda}(Q_T)$  with  $D_t \varphi \in C^{\lambda,0}(Q_T)$  and let  $\psi$  be defined in (3.2). Put

$$(3.5) v \equiv \operatorname{Rot} \psi ;$$

then  $v \in C^{1,2+\lambda}(Q_T)$ ,  $D_t v \in C^{\lambda,0}(Q_T)$  and

$$||v||_{0,2+\lambda} \leq c ||\varphi||_{0,1+\lambda},$$

$$||D_{t}v||_{\infty} \leq \frac{1}{2} K_{1} ||D_{t}\varphi||_{\infty},$$

$$||D_{t}v||_{0,1+\lambda} \leq c ||D_{t}\varphi||_{0,\lambda},$$

$$[D_{t}v]_{\lambda,0} \leq \frac{1}{2} K_{1} [D_{t}\varphi]_{\lambda,0},$$

$$[D_{t}v]_{0,\lambda} \leq c ||D_{t}\varphi||_{\infty}.$$

Moreover div v = 0 and rot  $v = \varphi$  in  $Q_T$ ,  $v \cdot n = 0$  on  $[0, T] \times \Gamma$ .

PROOF. Since  $\varphi \in C^{0,1+\lambda}(Q_T) \subset C^0([0, T]; C^{1+\lambda'}(\overline{\Omega}))$  for each  $\lambda' < \lambda$  (see for instance Kato [5], Lemma 1.2), it follows from Schauder's estimates that  $v \in C^0([0, T]; C^{2+\lambda'}(\overline{\Omega}))$ ; hence  $v, Dv, D^2v \in C^0(Q_T)$ . Moreover estimate (3.6), follows directly from (3.3), i.e.  $v \in C^{0,2+\lambda}(Q_T)$ . Differentiating (3.2)' with respect to t, we have

$$(3.7) D_t \psi(t,x) = \int_{\Omega} G(x,y) D_t \varphi(t,y) dy ;$$

since  $D_t \varphi \in C^{0,\lambda}(Q_T)$ , arguing as above it follows that  $D_t v \in C^{0,1+\lambda}(Q_T)$  and  $(3.6)_3$  holds.

Applying the operator Rot to (3.7) we have

$$D_t v(t, x) = \int_{\Omega} \operatorname{Rot}_x G(x, y) D_t \varphi(t, y) dy$$

and (3.4) yields  $(3.6)_2$  and  $(3.6)_4$ .

Estimate  $(3.6)_5$  follows directly from (3.5) and  $(3.3)_3$ . Finally remark that rot Rot =  $-\Delta$  and that  $v \cdot n$  is a tangential derivative of  $\psi$  at the boundary.  $\square$ 

By using (3.1) one has

$$egin{array}{ll} \|v\|_{0,2+\lambda} & \leqslant cA \;, \ \|D_tv\|_{\infty} & \leqslant rac{1}{2}K_1B \;, \ \|D_tv\|_{0,1+\lambda} \leqslant cC \;, \ [D_tv]_{\lambda,0} & \leqslant rac{1}{2}K_1D \;, \ [D_tv]_{0,\lambda} & \leqslant cB \;. \end{array}$$

Now we construct the stream lines of the vector field v(t, x). We denote by  $c, c_1, c_2, ...,$  constants depending at most on  $\lambda$  and  $\Omega$ .

We put  $U(\sigma, t, x) \equiv y(\sigma)$ ,  $\sigma, t \in [0, T]$ ,  $x \in \overline{\Omega}$ , where  $y(\sigma)$  is the solution of the ordinary differential equation

(3.9) 
$$\begin{cases} \frac{dy}{d\sigma} = v(\sigma, y(\sigma)) & \text{in } [0, T], \\ y(t) = x. \end{cases}$$

Such a solution is global since  $v \cdot n = 0$  on  $[0, T] \times \Gamma$ ; from  $v \in C^{1,2}(Q_T)$  one has  $U \in C^2([0, T] \times Q_T)$ .

We denote by  $\|DU\|_{\infty} = \sup_{\sigma \in [0,T]} \|DU(\sigma, \cdot, \cdot)\|_{\infty}$  and analogously for each norm and seminorm involving U and its derivatives.

We have:

LEMMA 3.2. The vector function  $U(\sigma, t, x)$  satisfies the following estimates:

$$\|DU\|_{\infty} \leqslant 2 \exp[cTA],$$
  $\|D^{2}U\|_{\infty} \leqslant cTA \exp[cTA],$   $[D^{2}U]_{0,\lambda} \leqslant cTA(1+TA) \exp[cTA],$   $[U]_{\mathrm{lip},0} \leqslant cA \exp[cTA],$   $[DU]_{\lambda,0} \leqslant cT^{1-\lambda}A(1+T^{\lambda}A^{\lambda}) \exp[cTA],$   $[D^{2}U]_{\lambda,0} \leqslant cT^{1-\lambda}A(1+T^{\lambda}A^{\lambda})(1+TA) \exp[cTA].$ 

Proof. One obtains these estimates by direct computation of the resolutive formula

$$(3.11) \hspace{1cm} U(\sigma,t,x) = x + \int\limits_t^\sigma \!\! v(\tau,\,U(\tau,t,x))\,d\tau \,.$$

We give only the explicity proof of (3.10)<sub>3</sub>. From (3.11) one gets

 $(3.13) D_{ik}^2 U_j(\sigma, t, x) =$   $= \int_t^{\sigma} \left[ \sum_{\tau,h} (D_{\tau h}^2 v_j)(\tau, U(\tau, t, x)) D_k U_{\tau}(\tau, t, x) D_i U_h(\tau, t, x) + \sum_i (D_h v_j)(\tau, U(\tau, t, x)) D_{ik}^2 U_h(\tau, t, x) \right] d\tau.$ 

Hence one obtains

$$\begin{split} \sum_{i,k,j} |D_{ik}^2 U_j(\sigma,t,x) - D_{ik}^2 U_j(\sigma,t,y)| &\leqslant T |x-y|^{\lambda} \big\{ [D^2 v]_{0,\lambda} [U]_{0,\operatorname{lip}}^{\lambda} \|DU\|_{\infty}^2 + \\ &\quad + 2 \|D^2 v\|_{\infty} \|DU\|_{\infty} [DU]_{0,\lambda} + \|D^2 U\|_{\infty} [Dv]_{0,\lambda} [U]_{0,\operatorname{lip}}^{\lambda} \big\} + \\ &\quad + \|Dv\|_{\infty} \left| \int_{i,k,h}^{\sigma} |D_{ik}^2 U_h(\tau,t,x) - D_{ik}^2 U_h(\tau,t,y)| \, d\tau \right| \end{split}$$

and from Gronwall's lemma

$$\begin{split} \sum_{i,j,k} & |D_{ik}^2 \, U_j(\sigma,t,x) - D_{ik}^2 \, U_j(\sigma,t,y)| \leqslant T |x-y|^{\lambda} \cdot \\ & \cdot \big\{ [D^2 v]_{0,\lambda} [\, U]_{0,\mathrm{lip}}^{\lambda} \|D \, U\|_{\infty}^2 + 2 \, \|D^2 v\|_{\infty} \|D \, U\|_{\infty} [D \, U]_{0,\lambda} + \\ & \quad + \|D^2 \, U\|_{\infty} [D v]_{0,\lambda} [\, U]_{0,\mathrm{lip}}^{\lambda} \big\} \exp \left[ T \|D v\|_{\infty} \right]. \end{split}$$

From  $(3.10)_1$ ,  $(3.10)_2$  and  $(3.8)_1$  one obtains  $(3.10)_3$ . On proving  $(3.10)_4$  and  $(3.10_5)$ , recall that

$$\frac{\partial U(\sigma,t,x)}{\partial t} = -\sum_{h} \frac{\partial U(\sigma,t,x)}{\partial x_{h}} v_{h}(t,x) . \qquad \Box$$

We now study the equation

$$\begin{cases} \frac{\partial \varrho}{\partial t} + v \cdot \nabla \varrho = 0 & \text{in } Q_T, \\ \varrho|_{t=0} & = \varrho_0 & \text{in } \overline{\varOmega}. \end{cases}$$

LEMMA 3.3. Let  $\varrho_0 \in C^{2+\lambda}(\overline{\Omega})$  and  $\varrho_0(x) > 0$  for each  $x \in \overline{\Omega}$ . Then the solution of (3.15) is given by

$$\varrho(t,x) = \varrho_0(U(0,t,x)).$$

Moreover  $\varrho \in C^{2+\lambda,2+\lambda}(Q_T)$  and

$$\left\| \frac{D\varrho}{\varrho} \right\|_{\infty} \leqslant 2 \left\| \frac{D\varrho_{0}}{\varrho_{0}} \right\|_{\infty} \exp\left[cTA\right],$$

$$\left\| \frac{D^{2}\varrho}{\varrho} \right\|_{\infty} \leqslant c \left( TA \left\| \frac{D\varrho_{0}}{\varrho_{0}} \right\|_{\infty} + \left\| \frac{D^{2}\varrho_{0}}{\varrho_{0}} \right\|_{\infty} \right) \exp\left[cTA\right],$$

$$\left[ \frac{D\varrho}{\varrho} \right]_{0,\lambda} \leqslant c \left( TA \left\| \frac{D\varrho_{0}}{\varrho_{0}} \right\|_{\infty} + \left[ \frac{D\varrho_{0}}{\varrho_{0}} \right]_{\lambda} \right) \exp\left[cTA\right],$$

$$\left[ \frac{D^{2}\varrho}{\varrho} \right]_{0,\lambda} \leqslant c \left\{ TA(1+TA) \left\| \frac{D\varrho_{0}}{\varrho_{0}} \right\|_{\infty} + TA \left[ \frac{D\varrho_{0}}{\varrho_{0}} \right]_{\lambda} +$$

$$+ TA \left\| \frac{D^{2}\varrho_{0}}{\varrho_{0}} \right\|_{\infty} + \left[ \frac{D^{2}\varrho_{0}}{\varrho_{0}} \right]_{\lambda} \right\} \exp\left[cTA\right],$$

$$\left[ \frac{D\varrho}{\varrho} \right]_{\lambda,0} \leqslant c \left\{ T^{1-\lambda}A(1+T^{\lambda}A^{\lambda}) \left\| \frac{D\varrho_{0}}{\varrho_{0}} \right\|_{\infty} + A^{\lambda} \left[ \frac{D\varrho_{0}}{\varrho_{0}} \right]_{\lambda} \right\} \exp\left[cTA\right].$$

PROOF. One easily obtains (3.16) by using the method of characteristics. From (3.16) one has

$$egin{aligned} rac{D_i arrho}{arrho}(t,x) &= \sum_h rac{D_h arrho_0}{arrho_0} \left( U(0,t,x) 
ight) D_i U_h(0,t,x) \,, \ & rac{D_{ik}^2 arrho}{arrho}(t,x) &= \sum_{r,h} rac{D_{rh}^2 arrho_0}{arrho_0} \left( U(0,t,x) 
ight) D_k U_r(0,t,x) D_i U_h(0,t,x) \,+ \ & + \sum_h rac{D_h arrho_0}{arrho_0} \left( U(0,t,x) 
ight) D_{ik}^2 U_h(0,t,x) \,. \end{aligned}$$

By using (3.10), we obtain easily estimates (3.17).

### 4. The vorticity equation.

In this number we study the auxiliary equation

$$\begin{cases} \frac{\partial \zeta}{\partial t} + v \cdot \nabla \zeta = \gamma & \text{in } Q_T, \\ \zeta|_{t=0} = \alpha & \text{in } \bar{\Omega}, \end{cases}$$

where  $\alpha(x) \equiv \operatorname{rot} a(x)$ ,  $\beta(t, x) \equiv \operatorname{rot} b(t, x)$ , and  $\gamma(t, x)$  is defined in  $Q_T$  by

$$\gamma \equiv \beta + \frac{\mathrm{Rot}\,\varrho}{\varrho} \left[ \frac{\partial v}{\partial t} + (v \cdot \nabla) v - b \right],$$

where a and b are as in Theorem A.

One integrates (4.1) by the method of characteristics and one obtains

$$\zeta(t,x) = \alpha\big(U(0,t,x)\big) + \int_0^t \gamma\big(\tau,\,U(\tau,t,x)\big)\,d\tau\;.$$

We denote by  $\bar{c}$ ,  $\bar{c}_1$ ,  $\bar{c}_2$ , ..., constants that depend at most on  $\lambda$ ,  $\Omega$ ,  $\|D\varrho_0/\varrho_0\|_{\lambda}$ ,  $\|D^2\varrho_0/\varrho_0\|_{\lambda}$ ,  $\|b\|_{0,1+\lambda}$ ,  $\|b\|_{\lambda,0}$ ,  $\|\beta\|_{0,1+\lambda}$  and  $\|\beta\|_{\lambda,0}$ .

LEMMA 4.1. Under the above conditions the following estimates hold:

$$\|\gamma\|_{\infty} \ll \overline{c}(A^{2}+1) \exp[cTA] + \left\|\frac{D\varrho_{0}}{\varrho_{0}}\right\|_{\infty} K_{1}B \exp[cTA],$$

$$[\gamma]_{0,\lambda} \ll \overline{c}(1+TA)(A^{2}+B+1) \exp[cTA],$$

$$\|D\gamma\|_{\infty} \ll \overline{c}\left\{(1+TA)(A^{2}+B+1)+C\right\} \exp[cTA],$$

$$[D\gamma]_{0,\lambda} \ll \overline{c}\left\{(1+T^{2}A^{2})(A^{2}+B+1)+(1+TA)C\right\} \exp[cTA],$$

$$[\gamma]_{\lambda,0} \ll \overline{c}\left\{T^{1-\lambda}AC+1+A^{\lambda}(A^{2}+B+1)(1+TA)\right\}.$$

$$\cdot \exp[cTA] + \left\|\frac{D\varrho_{0}}{\varrho_{0}}\right\|_{\infty} K_{1}D \exp[cTA].$$

PROOF. It follows by direct computations, using (4.2), (3.8) and (3.17).

Finally we have

LEMMA 4.2. The solution  $\zeta(t, x)$  of (4.1) satisfies:

$$\begin{split} \|\zeta\|_{0,1+\lambda} \leqslant 2 \, \|\alpha\|_{1+\lambda} \exp\left[cTA\right] + \overline{c}T \left\{A \, \|D\alpha\|_{\infty} + \\ &+ (1 + T^2A^2)(A^2 + B + 1) + (1 + TA)\,C\right\} \exp\left[cTA\right], \\ \|D_t\zeta\|_{\infty} \leqslant c_1A \, \|D\alpha\|_{\infty} \exp\left[cTA\right] + \overline{c}_1(A^2 + 1) \exp\left[cTA\right] + \\ &+ \overline{c}TA[(1 + TA)\,(A^2 + B + 1) + C] \exp\left[cTA\right] + \\ &+ \left\|\frac{D\varrho_0}{\varrho_0}\right\|_{\infty} K_1B \exp\left[cTA\right], \\ (4.5) \qquad [D_t\zeta]_{0,\lambda} \leqslant c_2A \left(\|D\zeta\|_{\infty} + [D\zeta]_{0,\lambda}\right) + \\ &+ \overline{c}_2(1 + TA)(A^2 + B + 1) \exp\left[cTA\right], \\ [D_t\zeta]_{\lambda,0} \leqslant c_4A[D\zeta]_{\lambda,0} + cT^{1-\lambda}B\|D\zeta\|_{\infty} + \\ &+ \overline{c}_3A^{\lambda}(A^2 + B + 1)(1 + TA) \exp\left[cTA\right] + \left\|\frac{D\varrho_0}{\varrho_0}\right\|_{\infty} K_1D \exp\left[cTA\right], \end{split}$$

where  $||D\zeta||_{\infty}$ ,  $[D\zeta]_{0,\lambda}$  and  $[D\zeta]_{\lambda,0}$  are bounded respectively by (4.6), (4.7) and (4.8).

PROOF. From (4.3), (3.10) and Lemma 4.1 it follows easily that

$$\|\zeta\|_{\infty} \leqslant \|\alpha\|_{\infty} + \bar{c}T(A^2 + B + 1) \exp[cTA]$$
,

$$egin{aligned} \|D\zeta\|_{\infty} \leqslant 2 \|Dlpha\|_{\infty} \exp\left[cTA
ight] + \\ &+ ar{c}T[(1+TA)(A^2+B+1)+C] \exp\left[cTA
ight], \end{aligned}$$

$$(4.7) [D\zeta]_{0,\lambda} \leq 2[D\alpha]_{\lambda} \exp[cTA] + \\ + \bar{c}T[A\|D\alpha\|_{\infty} + (1 + T^2A^2)(A^2 + B + 1) + (1 + TA)C] \exp[cTA],$$

hence (4.5), holds.

From (4.1), one has  $D_t\zeta = -v \cdot \nabla \zeta + \gamma$ , and by direct computation one obtains (4.5)<sub>2</sub>, (4.5)<sub>3</sub> and (4.5)<sub>4</sub>.

Finally, from (4.3) it follows that:

$$\begin{split} (4.8) \quad & [D\zeta]_{\lambda,0} \! \leqslant \! c_3 A^{\lambda} \! [D\alpha]_{\lambda} \exp{[cTA]} + \\ & + c T^{1-\lambda} A (1 + T^{\lambda} A^{\lambda}) \| D\alpha\|_{\infty} \exp{[cTA]} + \\ & + \bar{c} T^{1-\lambda} \! [(1 + TA) (A^2 + B + 1) + C] (1 + T^{1+\lambda} A^{1+\lambda}) \exp{[cTA]}. \ \ \Box \end{split}$$

We assume in the sequel that condition (A) of Theorem A holds, and we choose the constants A, B, C, D such that

$$(4.9) \begin{cases} A > 2 \|\alpha\|_{1+\lambda}, \\ B > \left\| \frac{D\varrho_0}{\varrho_0} \right\|_{\infty} K_1 B + c_1 A \|D\alpha\|_{\infty} + \overline{c}_1 (A^2 + 1), \\ C > c_1 A \|D\alpha\|_{\infty} + 2 c_2 A \|D\alpha\|_{\lambda} + (\overline{c}_1 + \overline{c}_2) (A^2 + 1) + \\ + \left[ \left\| \frac{D\varrho_0}{\varrho_0} \right\|_{\infty} K_1 + \overline{c}_2 \right] B, \\ D > \left\| \frac{D\varrho_0}{\varrho_0} \right\|_{\infty} K_1 D + c_3 c_4 A^{1+\lambda} [D\alpha]_{\lambda} + \overline{c}_3 (A^2 + B + 1) A^{\lambda} + \overline{c}_3. \end{cases}$$

From (4.5), (4.6), (4.7) and (4.8) it follows that there exists  $T_1 \in (0, T]$  such that

$$egin{aligned} &\|\zeta\|_{0,1+\lambda} \leqslant A \;, \ &\|D_t\zeta\|_{\infty} \leqslant B \;, \ &\|D_t\zeta\|_{0,\lambda} \leqslant C \;, \ &[D_t\zeta[_{\lambda,0} \leqslant D \;, \ \end{array}$$

where the norms are taken on the cylinder  $Q_{T_1} \equiv [0, T_1] \times \overline{\Omega}$ . The set

$$(4.11) S \equiv \{ \varphi \in C^{1}(Q_{T_{1}}) | \|\varphi\|_{0,1+\lambda} \leqslant A, \|D_{t}\varphi\|_{\infty} \leqslant B, \\ \|D_{t}\varphi\|_{0,\lambda} \leqslant C, [D_{t}\varphi]_{\lambda,0} \leqslant D \}$$

is a convex, bounded and closed subset of  $C^1(Q_{T_1})$ .

Moreover the map  $F: \varphi \mapsto \zeta$  defined by (3.2), (3.5), (3.9), (3.15) and (4.3) satisfies

$$(4.12) F(S) \subset S,$$

and, from (4.8),

$$(4.13) [D\zeta]_{\lambda,0} \leqslant \text{const}, \forall \varphi \in S.$$

By the Ascoli-Arzelà theorem and (4.11), (4.13) it follows that F(S) is relatively compact in  $C^1(Q_T)$ .

Finally, we shall see that F is continuous in the  $C^1(Q_{\tau_1})$  topology, hence, by the Schauder fixed point theorem, one has

LEMMA 4.3.  $F: S \rightarrow S$  has a fixed point.

PROOF. It is sufficient to prove that F is continuous from  $C^1(Q_{T_1})$  in  $C^0(Q_{T_1})$ , since F(S) is relatively compact in  $C^1(Q_{T_1})$ .

Let  $\varphi_n \in S$ ,  $\varphi_n \to \varphi$  in  $C^1(Q_{T_1})$ . From (3.2) and (3.5), one has

$$egin{array}{lll} v^n & 
ightarrow v & & ext{in } C^0(Q_{T_1}) \ , \ & Dv^n 
ightarrow Dv & & ext{in } C^0(Q_{T_1}) \ . \end{array}$$

Moreover, from (3.7) and (3.4')

$$(4.15) \qquad \frac{\partial v^n}{\partial t} \to \frac{\partial v}{\partial t} \qquad \text{in } C^0(Q_{T_1}) .$$

On the other hand

$$\begin{split} |\,U^{n}(\sigma,\,t,\,x) - \,U(\sigma,\,t,\,x)\,| \, \leqslant \, & \Big| \int\limits_{t}^{\sigma} \!\! \left[ \,|v^{n}(\tau,\,U^{n}(\tau,\,t,\,x)) - v(\tau,\,U^{n}(\tau,\,t,\,x))| \,+ \right. \\ \\ & + \,|v(\tau,\,U^{n}(\tau,\,t,\,x)) - v(\tau,\,U(\tau,\,t,\,x))| \,\right] d\tau \,| \, \leqslant \\ \\ & \leqslant \, T_{1} \|v_{n} - v\|_{\,\varpi} + \, [v]_{0,\mathrm{lip}} |\int\limits_{\tau}^{\sigma} \!\! U^{n}(\tau,\,t,\,x) - \,U(\tau,\,{}_{t},\,x)| \,d\tau \,\Big| \,\,, \end{split}$$

and from Gronwall's lemma

$$|U^{\mathbf{n}}(\sigma, t, x) - U(\sigma, t, x)| \leqslant T_1 ||v_n - v||_{\infty} \exp \left[T_1[v]_{0, \text{lip}}\right],$$

hence  $U^n \to U$  uniformly in  $[0, T_1] \times Q_{T_1}$ .

Analogously, one evaluates  $|D_i U_j^n(\sigma, t, x) - D_i U_j(\sigma, t, x)|$  by using (3.12), and this gives

$$\|DU^{n}-DU\|_{\infty} \leqslant T_{1}([Dv^{n}]_{0,\text{lip}}\|DU^{n}\|_{\infty}\|U^{n}-U\|_{\infty}+\|DU\|_{\infty}\|Dv^{n}-Dv\|_{\infty})\cdot \exp\left[T_{1}\|Dv^{n}\|_{\infty}\right].$$

Hence  $DU^n \to DU$  uniformly in  $[0, T_1] \times Q_{T_1}$ . Consequently

$$(4.16) \qquad \frac{\operatorname{Rot} \varrho_n}{\varrho_n} \to \frac{\operatorname{Rot} \varrho}{\varrho} \qquad \text{in } C^0(Q_{T_1})$$

and

$$\gamma_n(\sigma, U^n(\sigma, t, x)) \rightarrow \gamma(\sigma, U(\sigma, t, x))$$
 uniformly in  $[0, T_1] \times Q_{T_1}$ .

From (4.3) the thesis follows.

This fixed point  $\zeta = \varphi = F[\varphi]$ , together with the corresponding v and  $\varrho$ , is a solution of the system

$$\begin{cases} \frac{\partial \zeta}{\partial t} + v \cdot \nabla \zeta = \beta + \frac{\operatorname{Rot} \varrho}{\varrho} \cdot \left[ \frac{\partial v}{\partial t} + (v \cdot \nabla)v - b \right] & \text{in } Q_{T_1}, \\ \zeta &= \operatorname{rot} v & \text{in } Q_{T_1}, \\ \operatorname{div} v &= 0 & \text{in } Q_{T_1}, \\ \frac{\partial \varrho}{\partial t} + v \cdot \nabla \varrho = 0 & \text{in } Q_{T_1}, \\ v \cdot n &= 0 & \text{on } [0, T_1] \times \Gamma, \\ \zeta|_{t=0} &= \alpha & \text{in } \overline{\Omega}, \\ \varrho|_{t=0} &= \varrho_0 & \text{in } \overline{\Omega}. \end{cases}$$

### 5. Existence of a solution of system (E) when $\Omega$ is simply connected.

Since

$$\operatorname{rot}\left[(v\cdot\nabla)v\right]=(\operatorname{div}v)\operatorname{rot}v+v\cdot\nabla(\operatorname{rot}v)$$

one has from  $(4.17)_1$ ,  $(4.17)_2$  and  $(4.17)_4$ 

$$arrho \operatorname{rot}\left[rac{\partial v}{\partial t} + \left(v\cdot 
abla
ight)v - b
ight] = \operatorname{Rot} arrho \cdot \left[rac{\partial v}{\partial t} + \left(v\cdot 
abla
ight)v - b
ight].$$

We recall the general identity

$$rot(\varrho w) = \varrho \operatorname{rot} w - (\operatorname{Rot} \varrho) \cdot w,$$

where  $\varrho$  is an arbitrary scalar and w an arbitrary vector, and applying it we obtain

(5.1) 
$$\operatorname{rot}\left\{\varrho\left[\frac{\partial v}{\partial t}+(v\cdot\nabla)v-b\right]\right\}=0\quad \text{ in } Q_{T_1}.$$

When  $\Omega$  is simply connected, it is well known that there exists a

scalar function  $\pi \in C^{0,1}(Q_{T_1})$  such that (E)<sub>1</sub> holds in  $Q_{T_1}$ . Moreover  $\pi \in C^{\lambda,1}(Q_{T_1}) \cap C^{0,2+\lambda}(Q_{T_1})$ : in fact  $\pi(t,x)$  is determined as the integral of  $\nabla \pi \cdot ds$  from a fixed point  $x_0$  to x, along a path independent of t. Since  $\nabla \pi \in C^{\lambda,0}(Q_{T_1})$ , it follows that  $\pi \in C^{\lambda,0}(Q_{T_1})$ . The other statement follows directly from (E)<sub>1</sub>. Furthermore

$$\left\{egin{aligned} &\operatorname{rot}\left(v|_{t=0}-a
ight)=0 & &\operatorname{in}\; ar{\mathcal{Q}}\,, \ &\operatorname{div}\left(v|_{t=0}-a
ight)=0 & &\operatorname{in}\; ar{\mathcal{Q}}\,, \ &\left(v|_{t=0}-a
ight)\cdot n &=0 & &\operatorname{on}\; arGamma\,, \end{aligned}
ight.$$

and consequently (E), holds.

Hence we have found a solution  $(v, \pi, \varrho)$  to problem (E) in  $Q_{\tau}$ . This solution verifies the regularity conditions stated in Theorem A, as follows from Lemmas 3.1 and 3.3.

### Uniqueness of the solution of system (E).

Let  $(v, \pi, \varrho)$  and  $(\tilde{v}, \tilde{\pi}, \tilde{\varrho})$  be two solutions of (E) in  $[0, T] \times \overline{\Omega}$ , under the conditions of Theorem B. We set  $u \equiv \tilde{v} - v$ ,  $\sigma = \tilde{\pi} - \pi$ ,  $\eta = \tilde{\varrho} - \varrho$ . On subtracting the two equations (E)<sub>1</sub>, we obtain

$$(6.1) \qquad \tilde{\varrho} \left[ \frac{\partial u}{\partial t} + (\tilde{v} \cdot \nabla) u + (u \cdot \nabla) v \right] = -\nabla \sigma - \eta \left[ \frac{\partial v}{\partial t} + (v \cdot \nabla) v - b \right].$$

On the other hand from (E)<sub>3</sub> one gets

$$\left(\tilde{\varrho}\,\frac{\partial u}{\partial t},\,u\right)=\frac{1}{2}\,\frac{d}{dt}\left(\tilde{\varrho}u,\,u\right)+\frac{1}{2}\left(\left(\tilde{v}\cdot\nabla\tilde{\varrho}\right)u,\,u\right)\,,$$

where (,) denotes the scalar product in  $L^2(\Omega)$  or in  $[L^2(\Omega)]^2$ . Taking the scalar product of (6.1) with u it follows

$$(6.2) \qquad \frac{1}{2} \frac{d}{dt} \left( \tilde{\varrho} u, u \right) = - \left( \tilde{\varrho} (u \cdot \nabla) v, u \right) - \left( \eta \left[ \frac{\partial v}{\partial t} + (v \cdot \nabla) v - b \right], u \right),$$

since

$$(\tilde{\varrho}(\tilde{v}\cdot\nabla)u,u)+\frac{1}{2}((\tilde{v}\cdot\nabla\tilde{\varrho})u,u)=0$$
;

recall that div  $\tilde{v} = 0$  and  $\tilde{v} \cdot n = 0$ .

Moreover, on subtracting the two equations (E)3, we obtain

$$(6.3) \qquad \qquad \frac{\partial \eta}{\partial t} + v \cdot \nabla \eta = - \, u \cdot \nabla \tilde{\varrho}$$

and taking the scalar product of (6.3) with  $\eta$  it follows

(6.4) 
$$\frac{1}{2} \frac{d}{dt}(\eta, \eta) = -\left(u \cdot \nabla \tilde{\varrho}, \eta\right),$$

since  $(v \cdot \nabla \eta, \eta) = 0$ .

From (6.2) and (6.4) one obtains

(6.5) 
$$\frac{1}{2} \frac{d}{dt} \int_{\Omega} (\tilde{\varrho} |u|^2 + \eta^2) dx = - \int_{\Omega} \tilde{\varrho} [(u \cdot \nabla) v] \cdot u dx - \int_{\Omega} \eta \left[ \frac{\partial v}{\partial t} + (v \cdot \nabla) v - b + \nabla \tilde{\varrho} \right] \cdot u dx.$$

Set

$$f(t) \equiv \frac{1}{2} \int_{\Omega} (\tilde{\varrho}|u|^2 + \eta^2) dx$$
.

Obviously f(0) = 0; moreover from (3.16) and (3.11)

$$\|\nabla\tilde{\varrho}\|_{\infty} \leqslant 2 \|\nabla\varrho_{0}\|_{\infty} \exp\left[\|D\boldsymbol{v}\|_{L^{1}(0,T;L^{\infty}(\Omega))}\right]$$

and consequently from (6.5)

$$f'(t) \leqslant c(t) f(t)$$

where  $c(t) \in L^1(0, T)$ . By Gronwall's lemma f(t) vanishes identically in [0, T], i.e.  $\tilde{v} = v$  and  $\tilde{\varrho} = \varrho$  in  $Q_T$ .

Finally, from (E)<sub>1</sub> it follows that  $\nabla \pi = \nabla \tilde{\pi}$  in  $Q_T$ , i.e.  $\pi = \tilde{\pi}$  up to an arbitrary function of t,

### PART II

### 7. Existence of a solution of system (E) when $\Omega$ is not simply connected.

Let  $\Omega$  be a bounded connected open subset of  $\mathbb{R}^2$ . We assume that  $\Gamma$  consists of m+1 simple closed curves  $\Gamma_0, \Gamma_1, ..., \Gamma_m$ , where  $\Gamma_i$  (j=1,...,m) are inside of  $\Gamma_0$  and outside of one another.

We denote by v the vector field defined in (3.5) and by  $u^{(k)}$ ,  $k=1,\ldots,m$ , the vector fields introduced at the end of §1 in [4]. We have  $u^{(k)} \in C^{2+\lambda}(\overline{\Omega})$ , rot  $u^{(k)} = 0$ , div  $u^{(k)} = 0$  in  $\overline{\Omega}$  and  $u^{(k)} \cdot n = 0$  on  $\Gamma$ . We put

(7.1) 
$$\overline{v}(t,x) \equiv v(t,x) + \sum_{k=1}^{m} \theta_k(t) u^{(k)}(x) \equiv v(t,x) + v'(t,x)$$
,

and consequently we have div  $\overline{v}=0$  and rot  $\overline{v}=\varphi$  in  $Q_T$ ,  $\overline{v}\cdot n=0$  on  $[0,T]\times \Gamma$ .

We define  $\bar{\rho}(t,x)$  to be the solution of

$$\begin{cases} \frac{\partial \bar{\varrho}}{\partial t} + \bar{v} \cdot \nabla \bar{\varrho} = 0 & \text{in } Q_T, \\ \bar{\varrho}|_{t=0} = \varrho_0 & \text{in } \bar{\varOmega}. \end{cases}$$

Now we prove that there exist  $\theta_k(t) \in C^{1+\lambda}([0, T])$  such that

(7.3) 
$$\left( \overline{\varrho} \left[ \frac{\partial \overline{v}}{\partial t} + (\overline{v} \cdot \nabla) \overline{v} - b \right], u^{(k)} \right) = 0 \qquad \forall t \in [0, T],$$

$$(\overline{v}|_{t=0} - a, u^{(k)}) = 0$$

for each k = 1, ..., m. We are going to use the Schauder fixed point theorem.

We consider the map  $\bar{\theta}_k \mapsto \bar{v}$  from  $C^0([0, T])$  in  $C^{0,2+\lambda}(Q_T)$  defined by (7.1), the map  $\bar{v} \mapsto \bar{\varrho}$  from  $C^{0,2+\lambda}(Q_T)$  in  $C^{\lambda,0}(Q_T)$  defined by (7.2) and finally the map  $(\bar{v}, \bar{\varrho}) \mapsto \theta_k$  defined by (7.3), (7.4), i.e.

(7.3)' 
$$\sum_{s=1}^{m} \mu_{ks}(t) \frac{d\theta_{s}(t)}{dt} + \sum_{s,h=1}^{m} \mu_{ksh}(t)\theta_{s}(t)\theta_{h}(t) + \sum_{s=1}^{m} [\nu_{ks}(t) + \eta_{ks}(t)]\theta_{s}(t) + \mu_{k}(t) + \nu_{k}(t) + \eta_{k}(t) = 0 \quad \text{in } [0, T],$$
(7.4)' 
$$\theta_{k}(0) = (a, u^{(k)}),$$

for each k = 1, ..., m. We have defined

$$\mu_{ks}(t) \equiv (\bar{\varrho}u^{(s)}, u^{(k)}), \qquad \mu_{ksh}(t) \equiv (\bar{\varrho}(u^{(s)} \cdot \nabla) u^{(h)}, u^{(k)}),$$

$$v_{ks}(t) \equiv (\bar{\varrho}(v \cdot \nabla) u^{(s)}, u^{(k)}), \qquad \eta_{ks}(t) \equiv (\bar{\varrho}(u^{(s)} \cdot \nabla) v, u^{(k)}),$$

$$\mu_{k}(t) \equiv \left(\bar{\varrho}\frac{\partial v}{\partial t}, u^{(k)}\right), \qquad v_{k}(t) \equiv (\bar{\varrho}(v \cdot \nabla) v, u^{(k)}),$$

$$\eta_{k}(t) \equiv -(\bar{\varrho}b, u^{(k)}).$$

Since  $u^{(k)} \in C^{2+\lambda}(\overline{Q})$ ,  $v \in C^{1,2+\lambda}(Q_T) \cap C^{1+\lambda,0}(Q_T)$  and  $\overline{\varrho} \in C^{\lambda,0}(Q_T)$ , all these coefficients belong to  $C^{\lambda}([0,T])$ .

The notation  $\tilde{c}$ ,  $\tilde{c}_1$ ,  $\tilde{c}_2$ , ..., will be used for constants depending at most on  $\lambda$ ,  $\Omega$ , a, b,  $\varrho_0$ , m,  $u^{(k)}$ .

Assume that estimates (3.1) hold and moreover

(7.6) 
$$\sup_{t \in [0,T]} \left[ \sum_{k=1}^m \tilde{\theta}_i(t)^2 \right]^{\frac{1}{2}} = \|\tilde{\theta}\|_{\infty} \leqslant E,$$

where  $\tilde{\theta} \equiv (\tilde{\theta}_1, ..., \tilde{\theta}_m)$  and E is a constant that will be fixed in the following.

One has

(7.7) 
$$\|\overline{v}\|_{\infty} \leq \|v\|_{\infty} + \sum_{k} \|\tilde{\theta}_{k}\|_{\infty} \|u^{(k)}\|_{\infty} \leq \tilde{c}(A+E) ,$$

$$\|D\overline{v}\|_{\infty} \leq \|Dv\|_{\infty} + \sum_{k} \|\tilde{\theta}_{k}\|_{\infty} \|Du^{(k)}\|_{\infty} \leq \tilde{c}(A+E) .$$

Define  $\overline{U}(\sigma, t, x)$  to be the solution of

$$\left\{egin{aligned} rac{d\overline{U}}{d\sigma}\left(\sigma,t,x
ight)&=\overline{v}ig(\sigma,\,\overline{U}(\sigma,t,x)ig)\;,\ \overline{U}(t,t,x)&=x\;; \end{aligned}
ight.$$

one has, as in  $(3.10)_1$ :

$$(7.8) \qquad [\overline{U}]_{\text{lip,0}} = \left\| \frac{\partial \overline{U}}{\partial t} \right\|_{\infty} = \|D\overline{U}\|_{\infty} \|\overline{v}\|_{\infty} \leqslant 2 \|\overline{v}\|_{\infty} \exp\left[T\|D\overline{v}\|_{\infty}\right].$$

It follows from (7.7) and (7.8) that

(7.9) 
$$[\overline{U}]_{\text{lip},0} \leqslant \tilde{c}(A+E) \exp \left[\tilde{c}T(A+E)\right].$$

From (7.2) one has  $\bar{\varrho}(t,x) = \varrho_0(\bar{U}(0,t,x))$ , hence

(7.10) 
$$\begin{aligned} \|\bar{\varrho}\|_{\infty} \leqslant \|\varrho_{0}\|_{\infty}, \\ [\bar{\varrho}]_{\lambda,0} \leqslant [\varrho_{0}]_{\text{lip}} [\bar{\overline{U}}]_{\lambda,0} \leqslant T^{1-\lambda} [\varrho_{0}]_{\text{lip}} [\bar{\overline{U}}]_{\text{lip},0}. \end{aligned}$$

Define

(7.11) 
$$K_2 = \sup_{k} \|u^{(k)}\|_{L^2(\Omega)}.$$

We have from (7.5)

$$\|\mu_{ks}\|_{\infty} \leqslant K_{\frac{2}{2}}^{2} \|\varrho_{0}\|_{\infty} , \qquad [\mu_{ks}]_{\lambda} \leqslant \tilde{c}T^{1-\lambda}[\varrho_{0}]_{\mathrm{lip}}[\overline{U}]_{\mathrm{lip,0}} , \\ \|\mu_{ksh}\|_{\infty} \leqslant \tilde{c}\|\varrho_{0}\|_{\infty} , \qquad [\mu_{ksh}]_{\lambda} \leqslant \tilde{c}T^{1-\lambda}[\varrho_{0}]_{\mathrm{lip}}[\overline{U}]_{\mathrm{lip,0}} , \\ \|\nu_{ks}\|_{\infty} + \|\eta_{ks}\|_{\infty} \leqslant \tilde{c}A\|\varrho_{0}\|_{\infty} , \\ [\nu_{ks}]_{\lambda} + [\eta_{ks}]_{\lambda} \leqslant \tilde{c}A(\|\varrho_{0}\|_{\infty} + T^{1-\lambda}[\varrho_{0}]_{\mathrm{lip}}[\overline{U}]_{\mathrm{lip,0}}) , \\ \|\mu_{k}\|_{\infty} \leqslant K_{1}K_{2}B|\Omega|^{\frac{1}{2}} \|\varrho_{0}\|_{\infty} , \\ [\mu_{k}]_{\lambda} \leqslant \tilde{c}(D\|\varrho_{0}\|_{\infty} + T^{1-\lambda}[\varrho_{0}]_{\mathrm{lip}}[\overline{U}]_{\mathrm{lip,0}} B) , \\ \|\nu_{k}\|_{\infty} \leqslant \tilde{c}A^{2} \|\varrho_{0}\|_{\infty} , \qquad [\nu_{k}]_{\lambda} \leqslant \tilde{c}A^{2} (\|\varrho_{0}\|_{\infty} + T^{1-\lambda}[\varrho_{0}]_{\mathrm{lip}}[\overline{U}]_{\mathrm{lip,0}}) , \\ \|\eta_{k}\|_{\infty} \leqslant \tilde{c}\|\varrho_{0}\|_{\infty} , \qquad [\eta_{k}]_{\lambda} \leqslant \tilde{c}(\|\varrho_{0}\|_{\infty} + T^{1-\lambda}[\varrho_{0}]_{\mathrm{lip}}[\overline{U}]_{\mathrm{lip,0}}) ,$$

where  $|\Omega| \equiv \text{meas } \Omega$ .

Let M(t) be the  $(m \times m)$ -symmetric matrix  $\{\mu_{ks}(t)\}$ . One sees easily that  $|\xi|^2 \min_{\overline{O}} \varrho_0 \leqslant M(t) \xi \cdot \xi \leqslant \max_{\overline{O}} \varrho_0 |\xi|^2$  for each  $\xi \in \mathbb{R}^m$ , and

$$(7.13) 0 < \left(\min_{\overline{\Omega}} \varrho_{\mathbf{0}}\right)^{m} \leqslant \det M(t) \leqslant \left(\max_{\overline{\Omega}} \varrho_{\mathbf{0}}\right)^{m} \forall t \in [0, T].$$

The element  $\bar{\mu}_{ks}(t)$  of  $[M(t)]^{-1}$  has the form

(7.14) 
$$\bar{\mu}_{ks}(t) = \frac{(-1)^{k+s} M_{ks}(t)}{\det M(t)},$$

where  $M_{ks}(t)$  is the minor of the matrix M(t) corresponding to the (k, s)-element of M(t).

Hence

and by using (7.12)

$$(7.16) \qquad [\bar{\mu}_{ks}]_{\lambda} \leqslant \tilde{c} T^{1-\lambda} [\varrho_0]_{\text{lip}} [\overline{U}]_{\text{lip,0}} \left[ \frac{\|\varrho_0\|_{\infty}^{m-2}}{(\min_{\overline{Q}} \varrho_0)^m} + \frac{\|\varrho_0\|_{\infty}^{2(m-1)}}{(\min_{\overline{Q}} \varrho_0)^{2m}} \right].$$

Applying  $[M(t)]^{-1}$  to (7.3)', one obtains

(7.17) 
$$\frac{d\theta_{k}(t)}{dt} = \sum_{s,h=1}^{m} \bar{\mu}_{ksh}(t)\theta_{s}(t)\theta_{h}(t) + \sum_{s=1}^{m} [\bar{\nu}_{ks}(t) + \bar{\eta}_{ks}(t)]\theta_{s}(t) + \\ + \bar{\mu}_{k}(t) + \bar{\nu}_{k}(t) + \bar{\eta}_{k}(t) \quad \text{in } [0, T],$$

where

(7.18) 
$$\bar{\mu}_k(t) \equiv -\sum_{i=1}^m \bar{\mu}_{ki}(t) \mu_i(t)$$

and analogously for the other coefficients.

Obviously the system (7.17), (7.4)' has an unique local solution  $\theta_k(t)$ ,  $k=1,\ldots,m$ .

Moreover, taking the scalar product of (7.17) with  $\theta(t)$ , one has

$$(7.19) \quad \begin{cases} \frac{1}{2} \frac{d}{dt} |\theta(t)|^2 < \tilde{c} \frac{\|\varrho_0\|_{\infty}^m}{(\min \varrho_0)^m} \\ \frac{1}{\bar{a}} \cdot \{|\theta(t)|^3 + A |\theta(t)|^2 + (A^2 + B + 1) |\theta(t)|\}, \\ |\theta(0)|^2 < \tilde{c}_5^2 \|a\|_{\infty}^2. \end{cases}$$

Hence, if we choose  $E > \tilde{c}_{\mathfrak{s}} \|a\|_{\infty}$  in (7.6), we see that there exists  $T^* \in ]0, T]$  such that

$$|\theta(t)| \leqslant E$$
 in  $[0, T^*]$ .

If we put

$$S_1 \equiv \left\{ ar{ heta}(t) \in C^0([0, T^*]) | \|ar{ heta}\|_{\infty} \leqslant E \right\}$$

and we denote by  $F_1$  the map  $\bar{\theta} \mapsto \theta$  defined by (7.1), (7.2), (7.17) and (7.4), we have  $F_1(S_1) \subset S_1$ .

Moreover from (7.17) and the Ascoli-Arzelà theorem, it follows that  $F_1(S_1)$  is relatively compact in  $C^0([0, T^*])$ .

Finally, we see easily that  $F_1: S_1 \to S_1$  is continuous, consequently  $F_1$  has a fixed point in  $S_1$ .

Hence equation (7.3), (7.4) has a local solution  $\theta(t) \in C^{1+\lambda}$ . We want to prove that  $\theta(t)$  is a global solution.

From (7.3) we have

$$egin{aligned} 0 = & \left(ar{arrho}\left[rac{\partial ar{v}}{\partial t} + (ar{v}\cdot
abla)ar{v} - b
ight], v'
ight) = & \left(ar{arrho}rac{\partial v'}{\partial t}, v'
ight) + \left(ar{arrho}rac{\partial v}{\partial t}, v'
ight) + \\ & + \left(ar{arrho}(ar{v}\cdot
abla)v', v'
ight) + \left(ar{arrho}(ar{v}\cdot
abla)v, v'
ight) - \left(ar{arrho}b, v'
ight). \end{aligned}$$

Moreover

$$ig(ararrho(ar v\cdot
abla)v',v'ig)=-rac12ig((ar v\cdot
ablaararrho)v',v'ig)$$
 ,

and from (7.2)

$$\frac{1}{2}\,\frac{d}{dt}(\bar\varrho v',v') = \!\left(\bar\varrho\,\frac{\partial v'}{\partial t},v'\right) \!-\! \frac{1}{2}\left((\bar v\!\cdot\!\nabla\bar\varrho)v',v'\right)\,.$$

Hence

$$0=rac{1}{2}\,rac{d}{dt}(ararrho v',\,v')+\left(ararrho\,rac{\partial v}{\partial t},\,v'
ight)+\left(ararrho(v'\cdot
abla)v,\,v'
ight)+\left(ararrho(v\cdot
abla)v,\,v'
ight)-\left(ararrho b,\,v'
ight),$$

i.e.

$$\begin{split} \frac{1}{2}\,\frac{d}{dt} \sum_{k,s} & \mu_{ks}(t)\theta_k(t)\theta_s(t) = \\ & = -\sum_k \mu_k(t)\theta_k(t) - \sum_{k,s} \eta_{ks}(t)\theta_k(t)\theta_s(t) - \sum_k \nu_k(t)\theta_k(t) - \sum_k \eta_k(t)\theta_k(t) \;. \end{split}$$

Consequently

$$\begin{split} &\frac{1}{2} \frac{d}{dt} [\boldsymbol{M}(t)\boldsymbol{\theta}(t) \cdot \boldsymbol{\theta}(t)] \leqslant &\tilde{c}_{6} \|\varrho_{0}\|_{\infty} [\boldsymbol{A} |\boldsymbol{\theta}(t)|^{2} + (\boldsymbol{A}^{2} + \boldsymbol{B} + 1) |\boldsymbol{\theta}(t)|] \leqslant \\ &\leqslant &\tilde{c}_{6} \|\varrho_{0}\|_{\infty} \left[ \frac{\boldsymbol{A}}{\min \varrho_{0}} \boldsymbol{M}(t)\boldsymbol{\theta}(t) \cdot \boldsymbol{\theta}(t) + \frac{(\boldsymbol{A}^{2} + \boldsymbol{B} + 1)}{\sqrt{\min \varrho_{0}}} \sqrt{\boldsymbol{M}(t)\boldsymbol{\theta}(t) \cdot \boldsymbol{\theta}(t)} \right], \end{split}$$

 $M(0)\theta(0)\cdot\theta(0)\leqslant \tilde{c}_7\|\varrho_0\|_{\infty}\|a\|_{\infty}^2$ .

Set

$$lpha_1 \! \equiv \! 2 ilde{c}_6 rac{\|arrho_0\|_{\infty}}{\sqrt{\min\limits_{ar{\Omega}} arrho_0}} (A^{\,2} + B + 1) \,, \qquad lpha_2 \! \equiv \! 2 ilde{c}_6 rac{\|arrho_0\|_{\infty}}{\min\limits_{ar{\Omega}} arrho_0} A \,\,;$$

the solution y(t) of

$$\begin{cases} y'(t) = \alpha_1 \sqrt{y(t)} + \alpha_2 y(t), \\ y(0) = \tilde{c}_7 \|\varrho_0\|_{\infty} \|a\|_{\infty}^2, \end{cases}$$

satisfies

$$\alpha_1 + \alpha_2 \sqrt{y(t)} = \left[\alpha_1 + \alpha_2 \sqrt{y(0)}\right] \exp\left[\left(\alpha_2/2\right)t\right],$$

Hence by comparison theorems

$$|\theta(t)| \leq \frac{A^2 + B + 1}{A} \left( \exp\left[\frac{\alpha_2}{2}t\right] - 1 \right) + \sqrt{\tilde{c}_{7} \frac{\|\varrho_{0}\|_{\infty}}{\min \varrho_{0}}} \|a\|_{\infty} \exp\left[\frac{\alpha_2}{2}t\right]$$

$$\forall t \in [0, T],$$

i.e.  $\theta(t)$  is a global solution in [0, T] and

Define

(7.21) 
$$K_3 = m! \frac{\|\varrho_0\|_{\infty}^m}{(\min_{\overline{\Omega}} \varrho_0)^m} K_2^{2m-1} |\Omega|^{\frac{1}{2}}.$$

From (7.12), (7.15) and (7.18) one has

$$\|\bar{\mu}_k\|_{\infty} \leqslant K_3 K_1 B$$
.

Consequently, from (7.17) and (7.15), (7.16)

(7.22) 
$$\left\| \frac{d\theta}{dt} \right\|_{\infty} < \tilde{c}_{9} (\|\theta\|_{\infty}^{2} + A^{2} + 1) + K_{3}K_{1}B,$$

(7.23) 
$$\left[ \frac{d\theta}{dt} \right]_{\lambda} < \tilde{c}_{10} (A^2 + A \|\theta\|_{\infty} + 1) + K_3 K_1 D + \\ + \tilde{c} T^{1-\lambda} ([\overline{U}]_{\text{lip,0}} + \|\theta\|_{\infty} + A) (\|\theta\|_{\infty}^2 + A^2 + B + 1) .$$

Finally, define

(7.24) 
$$K_4 \equiv \sqrt{2} \left[ \sum_k \|u^{(k)}\|_{\infty}^2 \right]^{\frac{1}{2}};$$

from (7.1) and (3.8) one has,

$$\begin{split} \|\overline{v}\|_{0,2+\lambda} & < \widetilde{c}(A + \|\theta\|_{\infty}), \\ \|D_{t}\overline{v}\|_{\infty} & < K_{1}B + K_{4} \left\| \frac{d\theta}{dt} \right\|_{\infty}, \\ \|D_{t}\overline{v}\|_{0,1+\lambda} < \widetilde{c}\left(C + \left\| \frac{d\theta}{dt} \right\|_{\infty}\right), \\ [D_{t}\overline{v}]_{\lambda,0} & < K_{1}D + K_{4} \left[ \frac{d\theta}{dt} \right]_{\lambda}, \\ [D_{t}\overline{v}]_{0,\lambda} & < \widetilde{c}\left(B + \left\| \frac{d\theta}{dt} \right\|_{\infty}\right), \end{split}$$

which replace estimates (3.8).

Set

$$\bar{\gamma} \equiv \beta + \frac{\operatorname{Rot} \bar{\varrho}}{\bar{\varrho}} \cdot \left[ \frac{\partial \bar{v}}{\partial t} + (\bar{v} \cdot \nabla) \, \bar{v} - b \right] \qquad \text{in } Q_T \, ;$$

by replacing v, U,  $\varrho$ ,  $\gamma$  with  $\overline{v}$ ,  $\overline{U}$ ,  $\overline{\varrho}$ ,  $\overline{\gamma}$  in the proofs of Lemmas 3.2, 3.3, 4.1 and by using (7.25) one obtains:

LEMMA 7.1. Let  $\bar{\zeta}(t,x)$  be the solution of

$$\left\{egin{array}{l} rac{\partial ar{\xi}}{\partial t} + ar{v}\!\cdot\!
ablaar{\xi} = ar{\gamma} & in \ Q_{\scriptscriptstyle T}\,, \ ar{\xi}|_{t=0} & = lpha & in \ ar{arOmega}\,. \end{array}
ight.$$

Then Lemma 4.2 is true if we substitute in (4.5), (4.6), (4.7) and (4.8)  $\zeta$  with  $\overline{\zeta}$ , A with  $A + \|\theta\|_{\infty}$ ,  $K_1B$  with  $K_1B + K_4\|d\theta/dt\|_{\infty}$ , B with  $B + \|d\theta/dt\|_{\infty}$ , C with  $C + \|d\theta/dt\|_{\infty}$ ,  $K_1D$  with  $K_1D + K_4[d\theta/dt]_{\lambda}$ . Constants c and  $\overline{c}$ ,  $c_i$  and  $\overline{c}_i$  must be replaced respectively by  $\widetilde{c}$ ,  $\widetilde{c}_i$ . We will denote these new estimates by (4.5)', (4.6)', (4.7)' and (4.8)'.

Hence the existence of a solution of system (4.17) will be a consequence of the existence of a fixed point for the map  $\overline{F}: \varphi \mapsto \overline{\xi}$ .

First of all, we prove that there exists  $T_1 \in ]0, T]$  such that  $\overline{F}(S) \subset S$ , provided that A, B, C, D are chosen in a suitable way in (4.11).

By using (7.20), (7.22) and (7.23), we obtain from Lemma 7.1

that in  $Q_T$  one has

(7.36) 
$$\begin{split} \|\xi\|_{0,1+\lambda} &\leq f_1(T,A,B,C) ,\\ \|D_t \xi\|_{\infty} &\leq f_2(T,A,B,C) ,\\ \|D_t \xi\|_{0,\lambda} &\leq f_3(T,A,B,C) ,\\ [D_t \xi]_{\lambda,0} &\leq f_4(T,A,B,C,D) , \end{split}$$

where the functions  $f_i$  are continuous, non-negative, and non-decreasing with respect to each variable. Hence, if we fix A, B, C, D such that

there exists  $T_1 \in (0, T)$  for which

$$\begin{aligned} \|\xi\|_{0,1+\lambda} &< f_1(T_1, A, B, C) &< A, \\ \|D_t \xi\|_{\infty} &< f_2(T_1, A, B, C) &< B, \\ \|D_t \xi\|_{0,\lambda} &< f_3(T_1, A, B, C) &< C, \\ [D_t \xi]_{\lambda,0} &< f_4(T_1, A, B, C, D) &< D, \end{aligned}$$

in  $Q_{T_1}$ .

It is easy to verify that (7.27) has a solution, provided that condition (A) is satisfied. For example, one can choose successively

$$A > 2 \|\alpha\|_{1+\lambda},$$

$$B > \left\|\frac{D\varrho_{0}}{\varrho_{0}}\right\|_{\infty} K_{1}(1 + K_{3}K_{4})B + \tilde{c}_{1}(A + \tilde{c}_{8})\|D\alpha\|_{\infty} + \\
+ \tilde{c}_{1}[(A + c_{8})^{2} + 1] + \left\|\frac{D\varrho_{0}}{\varrho_{0}}\right\|_{\infty} K_{4}\tilde{c}_{9}(\tilde{c}_{8}^{2} + A^{2} + 1),$$

$$C > B + 2\tilde{c}_{2}(A + \tilde{c}_{8})\|D\alpha\|_{\lambda} + \\
+ \tilde{c}_{2}\{(A + \tilde{c}_{8})^{2} + B + \tilde{c}_{9}(\tilde{c}_{8}^{2} + A^{2} + 1) + K_{3}K_{1}B + 1\},$$

$$D > \left\|\frac{D\varrho_{0}}{\varrho_{0}}\right\|_{\infty} K_{1}(1 + K_{3}K_{4})D + \tilde{c}_{3}\tilde{c}_{4}(A + \tilde{c}_{8})^{1+\lambda}[D\alpha]_{\lambda} + \\
+ \tilde{c}_{3}[(A + \tilde{c}_{8})^{2} + B + \tilde{c}_{9}(\tilde{c}_{8}^{3} + A^{2} + 1) + K_{3}K_{1}B + 1]\cdot \\
\cdot (A + \tilde{c}_{8})^{\lambda} + \tilde{c}_{3} + \left\|\frac{D\varrho_{0}}{\varrho_{0}}\right\|_{\infty} K_{4}\tilde{c}_{10}(A^{2} + \tilde{c}_{8}A + 1).$$

Lemma 4.3 is proved as before, provided that  $\overline{F}: S \mapsto S$  is continuous from  $C^1(Q_{T_1})$  in  $C^0(Q_{T_1})$ .

Hence, we must prove that if  $\varphi_n \to \varphi$  in  $C^1(Q_{T_n})$ ,  $\varphi_n \in S$ , then  $\overline{v}_n$  and  $\overline{v}$  satisfy (4.14) and (4.15). Since  $v^n$  and v satisfy these last conditions, it is sufficient to prove that

$$egin{aligned} heta^n &
ightarrow heta & ext{uniformly in } [0,\,T_1]\,, \ & rac{d heta^n}{dt} 
ightarrow rac{d heta}{dt} & ext{uniformly in } [0,\,T_1]\,; \end{aligned}$$

we begin by recalling that  $\bar{v}^n$  and  $\varrho_n$  satisfy

$$\begin{cases}
\frac{\partial \overline{\varrho}_{n}}{\partial t} + \overline{v}^{n} \cdot \nabla \overline{\varrho}_{n} = 0 & \text{in } Q_{T_{1}}, \\
\overline{\varrho}_{n}|_{t=0} = \varrho_{0} & \text{in } \overline{\Omega},
\end{cases}$$

$$(7.31) \qquad \left(\overline{\varrho}_{n} \left[ \frac{\partial \overline{v}^{n}}{\partial t} + (\overline{v}^{n} \cdot \nabla) \overline{v}^{n} - b \right], u^{(k)} \right) = 0 \qquad \forall t \in [0, T_{1}], \\
(7.32) \qquad \left(\overline{v}^{n}|_{t=0} - a, u^{(k)}\right) = 0,$$

for each  $k=1,\ldots,m$ .

Set now  $\eta \equiv \overline{\varrho}_n - \overline{\varrho}, \quad u' \equiv v'^n - v', \quad u \equiv v^n - v, \quad \overline{u} \equiv \overline{v}^n - \overline{v} = u + u';$ one obtains from (7.3)

$$(7.33) \qquad \left(\bar{\varrho}_n \left[ \frac{\partial \bar{v}}{\partial t} + (\bar{v} \cdot \nabla) \bar{v} - b \right], \, u^{\scriptscriptstyle (k)} \right) - \left( \eta \left[ \frac{\partial \bar{v}}{\partial t} + (\bar{v} \cdot \nabla) \bar{v} - b \right], \, u^{\scriptscriptstyle (k)} \right) = 0 \; .$$

On substrating (7.33) from (7.31) one has

$$\left(ar{arrho}_nigg[rac{\partial\overline{u}}{\partial t}+(ar{v}^n\cdot
abla)ar{u}+(ar{v}\cdot
abla)ar{v}
ight],\,u^{(k)}
ight)\!=\!-igg(\etaigg[rac{\partial\overline{v}}{\partial t}+(ar{v}\cdot
abla)ar{v}-bigg],\,u^{(k)}
ight),$$

and multipling by  $\theta_k^n - \theta_k$ 

$$(7.34) \qquad \left(\bar{\varrho}_n \left[ \frac{\partial u'}{\partial t} + (\bar{v}^n \cdot \nabla) u' + (u' \cdot \nabla) \bar{v} \right], u' \right) = \\ = -\left(\bar{\varrho}_n \left[ \frac{\partial u}{\partial t} + (\bar{v}^n \cdot \nabla) u + (u \cdot \nabla) \bar{v} \right], u' \right) - \left( \eta \left[ \frac{\partial \bar{v}}{\partial t} + (\bar{v} \cdot \nabla) \bar{v} - b \right], u' \right).$$

From  $(7.30)_1$ 

$$\left(ar{arrho}_{n}rac{\partial u'}{\partial t},u'
ight) = rac{1}{2}rac{d}{dt}(ar{arrho}_{n}u',u') + rac{1}{2}\left((ar{v}^{n}\!\cdot\!
ablaar{arrho}_{n})u',u'
ight)$$

and moreover

$$\left(\bar{\varrho}_{n}(\bar{v}^{n}\cdot\nabla)u',u'\right)=\frac{1}{2}\sum_{i,j}\int_{\Sigma}\bar{\varrho}_{n}\bar{v}_{i}^{n}\frac{\partial u'_{j}^{2}}{\partial x_{i}}dx=-\frac{1}{2}\left((\bar{v}^{n}\cdot\nabla\bar{\varrho}_{n})u',u'\right).$$

Hence (7.34) becomes

$$(7.35) \qquad \frac{1}{2} \frac{d}{dt} (\bar{\varrho}_n u', u') + (\bar{\varrho}_n (u' \cdot \nabla) \bar{v}, u') =$$

$$= -\left(\bar{\varrho}_n \left[ \frac{\partial u}{\partial t} + (\bar{v}^n \cdot \nabla) u + (u \cdot \nabla) \bar{v} \right], u' \right) - \left( \eta \left[ \frac{\partial \bar{v}}{\partial t} + (\bar{v} \cdot \nabla) \bar{v} - b \right], u' \right).$$

On other hand, from (7.30) and (7.2) one obtains

$$rac{\partial \eta}{\partial t} + ar{v} \cdot 
abla \eta = - u' \cdot 
abla ar{arrho}_n - u \cdot 
abla ar{arrho}_n \, ,$$

and taking the scalar product with  $\eta$ 

(7.36) 
$$\frac{1}{2}\frac{d}{dt}(\eta,\eta) = -(\eta u',\nabla \bar{\varrho}_n) - (\eta u,\nabla \bar{\varrho}_n).$$

Set  $f(t) \equiv \frac{1}{2}(\bar{\varrho}_n u', u') + \frac{1}{2}(\eta, \eta)$ : from (7.35) and (7.36) one has

$$\begin{split} \frac{d}{dt}f(t) &\leqslant c(\bar{\varrho}_n u', u') + \left\| \frac{\partial v^n}{\partial t} - \frac{\partial v}{\partial t} \right\|_{\infty} \int_{\Omega} \bar{\varrho}_n |u'| \, dx + \\ &+ c \|Dv^n - Dv\|_{\infty} \int_{\Omega} \bar{\varrho}_n |u'| \, dx + c \|v^n - v\|_{\infty} \int_{\Omega} \bar{\varrho}_n |u'| \, dx + \\ &+ c \int_{\Omega} |\eta| \, |u'| \, dx + c \|v^n - v\|_{\infty} \int_{\Omega} |\eta| \, dx \, , \end{split}$$

since  $\|\overline{v}^n\|_{\infty}$  and  $\|\nabla \overline{\varrho}_n\|_{\infty}$  are bounded, and  $0 < \min_{\overline{\Omega}} \varrho_0 \leqslant \overline{\varrho}_n(t, x) \leqslant \|\varrho_0\|_{\infty}$ . Hence

$$\begin{cases} f'(t) \leqslant cf(t) + c_n \sqrt{f(t)}, \\ f(0) = 0 \end{cases}$$

where  $c_n \to 0$ , and consequently by comparison theorems

(7.37) 
$$f(t) \leqslant \left(\frac{c_n}{c}\right)^2 \left(\exp\left[\frac{ct}{2}\right] - 1\right)^2 \quad \text{in } [0, T_1].$$

Estimate (7.37) gives

(7.38) 
$$\sup_{\substack{t \in [0,T_1]}} \|v'^n - v'\|_{L^{2}(\Omega)} \xrightarrow{n} 0 , \\ \sup_{t \in [0,T_1]} \|\bar{\varrho}_n - \bar{\varrho}\|_{L^{2}(\Omega)} \xrightarrow{n} 0 ,$$

i.e.

(7.39) 
$$\sup_{t \in [0,T_1]} |\theta^n(t) - \theta(t)| = \sup_{t \in [0,T_1]} ||v'^n - v'||_{L^2(\Omega)} \xrightarrow{n} 0.$$

Moreover from (7.5) one has

$$\|\mu_{ks}^n - \mu_{ks}\|_{\infty} \leq c \sup_{t \in [0,T,1]} \|\tilde{\varrho}_n - \tilde{\varrho}\|_{L^2(\Omega)} \xrightarrow{n} 0$$

and analogously for the other coefficients.

Consequently from (7.14) it follows that

$$\|\bar{\mu}_{ks}^n - \bar{\mu}_{ks}\|_{\infty} \xrightarrow{n} 0$$
 ,

and the same is true for each coefficient in (7.17); hence we conclude that

$$\left\|\frac{d\theta^n}{dt} - \frac{d\theta}{dt}\right\|_{\infty} \to 0.$$

As in § 4, we have proved that

$$\mathrm{rot}\left\{ \overline{\varrho} \left[ \frac{\partial \overline{v}}{\partial t} + (\overline{v} \cdot \nabla) \overline{v} - b \right] \right\} = 0 \qquad \text{ in } Q_{T_1} \,,$$

and moreover

$$egin{aligned} \left( \overline{arrho} \left[ rac{\partial \overline{v}}{\partial t} + (\overline{v} \cdot 
abla) \overline{v} - b 
ight], u^{(k)} 
ight) = 0 & \forall t \in [0, T_1], \\ \left( \overline{v}|_{t=0} - a, u^{(k)} 
ight) = 0, \end{aligned}$$

for each k=1,...,m.

As in Kato [5], Lemma 1.6 (see also Hopf [4]), it follows that there exists a scalar function  $\bar{\pi} \in C^{0,1}(Q_{T_1})$  such that (E)<sub>1</sub> holds in  $Q_{T_1}$ . The further regularity properties of  $\bar{\pi}$  are proved as in § 4, since  $\bar{v}$  has the same regularity of v.

Finally, by using (7.4) one obtains that  $\overline{v}|_{t=0} = a$  in  $\overline{\Omega}$ , i.e. we have found a solution  $(\overline{v}, \overline{\pi}, \overline{\varrho})$  of system (E) in  $Q_{T,}$ .

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