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A Principle Involving the Variation of the Metric Tensor in a Stationary Space-Time of General Relativity.

LUCIANO BATTAIA (*)

SUMMARY - Within general relativity we introduce a variational principle, involving the variation of the metric tensor in a stationary spacetime, and concerning the equilibrium of an elastic body capable of couple stresses but not of heat conduction.

1. Introduction.

In this work we consider an elastic body C capable of couple stresses but not of heat conduction and we assume absence of electromagnetic phenomena.

Basing ourselves on a certain variational theorem involving the variation of the space-time metric, firstly formulated by Taub in [4] and extended by Schöpf and Bressan to the non-polar and polar cases respectively — cf. [3] and [2]—, we introduce a variational principle concerning the rest of a body C of the type above.

More in detail we prove that if C_3 is a certain 3-dimensional region of a stationary spacetime S_4 , the equilibrium of the body C, in the stationary frame (x), is physically possible if and only if the functional

$$J = \int_{c_{s}} (R + 16\pi hc^{-4}\varrho) \sqrt{-g} \, dC_{s}$$

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is stationary with respect to certain variations of the metric, where R is the bicontracted Riemann tensor, h Cavedish's constant, c the velocity of light in vacuum and ϱ the proper actual density of matter energy.

This theorem is an analogue of the relativistic variational principle proved in [1].

2. Preliminaries.

We follow the theory of continuous media in general relativity constructed by Bressan, cf. [2] (cf. also [1] and the references therein).

Let C be a continuous body and T a process physically possible for C in a space-time S_4 of general relativity. We shall consider only regular motions for C, e.g. without slidings and splittings; hence C can be regarded as a collection of material points.

By (x) we denote an admissible frame; by $g_{\alpha\beta} = g_{\alpha\beta}(x^{\varrho})$ (1) the metric tensor corresponding to \mathfrak{I} ; by $u^{\varrho}[A^{\varrho}]$ the four velocity [acceleration] of C at the event point \mathfrak{E} .

Then we consider a particular process \mathfrak{I}^* physically possible for the universe containing C, the world-tube $W^*_{\mathbb{C}}$ of C in \mathfrak{I}^* and an admissible frame (y). We call S^*_3 the intersection of $W^*_{\mathbb{C}}$ with the hypersurface $y^0 = 0$. We use the co-ordinate y^L of the intersection of S^*_3 with the world line of the point P^* of C as L-th material co-ordinate (²).

We represent the arbitrary (regular) motion of C in the system of co-ordinates (x) by means of the functions

(1)
$$x^{\alpha} = \hat{x}^{\alpha}(t, y^1, y^2, y^3),$$

where t is an arbitrary time parameter.

If T::: is a double tensor field associated to the event point x^{ϱ} and the material point y^{L} , we shall denote by $T:::_{,\varrho}$ the ordinary partial derivative, by $T:::_{,\varrho}$ the covariant derivative and by $T:::_{,u}$ the lagrangian spatial derivative based on the map (1) and introduced by Bressan.

We are interested in an elastic body C capable of couple stress but not of heat conduction and we shall always assume thet electromagnetic phenomena are absent.

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⁽¹⁾ Greek and Latin indices run over 0, 1, 2, 3 and 1, 2, 3 respectively.

^{(&}lt;sup>2</sup>) Capital and lower case latters represent material and space-time indices respectively.

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We call ϱ the proper actual density of total internal energy, $X^{\alpha\beta}$ the stess tensor, $m^{\alpha\beta\gamma}$ the couple stress tensor and we shall assume as total energy tensor (³)

(2)
$$\mathbb{U}^{\alpha\beta} = \varrho u^{\alpha} u^{\beta} + X^{(\alpha\beta)} + 2m^{(\alpha\lambda\beta)}/_{\lambda} + 2\nu^{(\alpha} u^{\beta)},$$

where

 $v^{\alpha} = 2m^{(\alpha \rho \sigma)} u_{\rho/\sigma}$

This assumption is proved to be physically acceptable in the case considered here (cf. [2]).

3. A theorem concerning the variation of the metric tensor in S_4 .

We always consider a body C of the type specified above and we suppose assigned in S_4 the motion (1) of C and the metric tensor $g_{\alpha\beta} = g_{\alpha\beta}(x)$ (⁴).

We take into account a bounded 4-dimensional domain C_4 of S_4 , where the motion of C is of class $C^{(2)}$ and we call $\mathcal{F}C_4$ its boundary oriented outwards. Furthermore let $\delta g_{\alpha\beta}$ be an arbitrary variation of $g_{\alpha\beta}$, of class $C^{(2)}$ in C_4 and such that

(3)
$$\delta g_{\alpha\beta} = 0 = \delta g_{\alpha\beta,\gamma}$$
 on $\mathcal{F}C_4$.

Consider the functional

(4)
$$I = \int_{c_4} (R + 16\pi h c^{-4}\varrho) \sqrt{-g} \, dC_4 \, .$$

In [2] it is proved that for every variation $\delta g_{lphaeta}$ of the aforementioned type we have

(5)
$$\delta \int_{c_4} (R + 16\pi h c^{-4} \varrho) \sqrt{-g} dC_4 = -\int_{c_4} (A^{\alpha\beta} + 8\pi h c^{-4} \mathfrak{U}^{\alpha\beta}) \delta g_{\alpha\beta} \sqrt{-g} dC_4.$$

(3) We use the notations $2T_{(\alpha\beta)} = T_{\alpha\beta} + T_{\beta\alpha}$; $2T_{[\alpha\beta]} = T_{\alpha\beta} - T_{\beta\alpha}$.

(4) For the constitutive equations of an elastic body C capable of couple stresses in the absence of heat conduction an electromagnetic phenomena see [1].

4. A variational principle concerning equilibrium in a stationary frame.

Let now S_4 be stationary and (x) a stationary frame. The metric tensor, that we always consider as assigned in S_4 , satisfies

$$(6) g_{\alpha\beta,0} = 0$$

We call C_3 the intersection of the world tube W_C of C with the hypersurface $x_0 = 0$.

We identify the arbitrary parameter in the equations (1) of the motion with x^0 and denote by $x^r = \chi^r(y^L)$ the configuration of C in C_3 . We consider the following motion of C:

(7)
$$\begin{cases} x^0 = t \\ x^r = x^r(t, y^L) = \chi^r(y^L) , \end{cases}$$

hence C is in equilibrium with respect to (x).

Consider an arbitrary variation $\delta g_{\alpha\beta} = \delta g_{\alpha\beta}(x^1, x^2, x^3)$ of $g_{\alpha\beta}$ on C_3 , of class $C^{(2)}$ and such that

(8)
$$\delta_{\mathfrak{z}}g_{\alpha\beta} = 0 = \delta_{\mathfrak{z}}g_{\alpha\beta,\gamma}$$
 on $\mathcal{F}C_{\mathfrak{z}}$ $(a, \beta = 0, 1, 2, 3)$.

Consider the functional

(9)
$$J = \int_{c_s} (R + 16\pi h c^{-4} \varrho) \sqrt{-g} \, dC_s \, .$$

We shall prove that the rest (7) of the body C, with respect to the stationary frame (x), is physically possible if and only if

$$(10) \qquad \qquad \delta J = 0$$

for every variation of $g_{\alpha\beta}$ of the aformentioned type.

Let a be a real positive number. We consider the following subsets of $W_{\mathbb{C}}$

$$\begin{split} C_4 &= \left\{ P \in W_{\mathbb{C}} \big| |x^0| \leqslant a + 1 \right\}, \qquad C_4^a &= \left\{ P \in W_{\mathbb{C}} \big| |x^0| \leqslant a \right\}, \\ C_4^+ &= \left\{ P \in W_{\mathbb{C}} \big| a \leqslant x^0 \leqslant a + 1 \right\}, \qquad C_4^- &= \left\{ P \in W_{\mathbb{C}} \big| - (a + 1) \leqslant x^0 \leqslant -a \right\}, \end{split}$$

where by x^{ϱ} we mean the co-ordinates of the point P of S_4 . Let then $\varphi(\xi)$ be an arbitrary function of the real variable ξ , of class $C^{(2)}$ in [0, 1] and such that

(11)
$$\begin{cases} \varphi(1) = \varphi'(1) = \varphi'(0) = \varphi''(0) = 0\\ \varphi(0) = 1\\ \int_{0}^{1} \varphi(\xi) d\xi = 0. \end{cases}$$

Consider the following variation $\delta g_{\alpha\beta}(x_0, x^1, x^2, x^3)$ in C_4

(12)
$$\delta g_{\alpha\beta} = \begin{cases} \delta g_{\alpha\beta}(x^1, x^2, xf) & \text{in } C_4^a \\ \varphi(x_0 - a) \, \delta g_{\alpha\beta} & \text{in } C_4^+ \\ \varphi(-x_0 - a) \, \delta g_{\alpha\beta} & \text{in } C_4^- . \end{cases}$$

On the basis of (11) this variation is of class $C^{(2)}$ in C_4 and satisfies the conditions

(13)
$$\delta g_{\alpha\beta} = 0 = \delta g_{\alpha\beta,\gamma} \quad \text{on } \mathcal{F}C_4.$$

Hence the variational theorem enounciated in the previous paragraph can be applied:

(14)
$$\delta \int_{c_4} (R+16\pi hc^{-4}\varrho) \sqrt{-g} dC_4 = -\int_{c_4} (A^{\alpha\beta}+8\pi hc^{-4}\mathbb{U}^{\alpha\beta}) \delta g_{\alpha\beta} \sqrt{-g} dC_4.$$

The stationarity of spacetime and the equations (7) of equilibrium imply that $g_{\alpha\beta}$, R, $\mathfrak{U}_{\alpha\beta,\varrho}$ do not depend on x^{0} .

We have

$$\begin{split} \delta &\int_{C_4^+} R \sqrt{-g} \, dC_4 = \int_{C_4^+} \frac{\partial R \sqrt{-g}}{\partial g_{\alpha\beta}} \, \delta g_{\alpha\beta} \, dC_4 = \int_{C_4^+} \frac{\partial R \sqrt{-g}}{\partial g_{\alpha\beta}} \, \varphi(x^0 - a) \, \delta_3^* g_{\alpha\beta} \, dC_4 = \\ &= \int_{C_4} \frac{\partial R \sqrt{-g}}{\partial g_{\alpha\beta}} \, \delta_3^* g_{\alpha\beta} \, dC_3 \int_{a}^{a+1} \varphi(x^0 - a) \, dx^0 = 0 \, , \end{split}$$

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and analogously

$$\delta \int_{C_4^+} \varrho \sqrt{-g} \, dC_4 = 0 \; .$$

Furthermore in the same way we prove that

$$\delta \int R \sqrt{-g} dC_4 = 0 = \delta \int \varrho \sqrt{-g} dC_4.$$

Hence

(15)
$$\delta \int_{C_4^+} (R + 16\pi h c^{-4} \varrho) \sqrt{-g} \, dC_4 = 0 = \delta \int_{C_4^-} (R + 16\pi h c^{-4} \varrho) \sqrt{-g} \, dC_4 \, .$$

Furthermore

(16)
$$\int_{C_4^a} (R + 16\pi hc^{-4}\varrho) \sqrt{-g} \, dC_4 =$$
$$= \int_{-a}^a dx^0 \int_{C_4} (R + 16\pi hc^{-4}\varrho) \sqrt{-g} \, dC_3 = 2a \int_{C_4} (R + 16\pi hc^{-4}\varrho) \sqrt{-g} \, dC_3 \,.$$

From (15) and (16) we have

(17)
$$\delta \int_{c_4} (R + 16\pi h c^{-4} \varrho) \sqrt{-g} \, dC_4 = 2a \delta_3 \int_{c_4} (R + 16\pi h c^{-4} \varrho) \sqrt{-g} \, dC_3$$

for the variation $\delta g_{\alpha\beta}$ and $\delta g_{\alpha\beta}$ above. We also have

(18)
$$\int (A^{\alpha\beta} + 8\pi hc^{-4} \mathbb{U}^{\alpha\beta}) \, \delta g_{\alpha\beta} \sqrt{-g} \, dC_4 =$$

$$= \int_{C_4^+} (A^{\alpha\beta} + 8\pi hc^{-4} \mathbb{U}^{\alpha\beta}) \varphi(x^0 - a) \, \delta g_{\alpha\beta} \sqrt{-g} \, dC_4 =$$

$$= \int_{C_4^+} (A^{\alpha\beta} + 8\pi hc^{-4} \mathbb{U}^{\alpha\beta}) \, \delta g_{\alpha\beta} \sqrt{-g} \, dC_3 \int_a^{a+1} \varphi(x^0 - a) \, dx^0 = 0 \, .$$

and analogously

(19)
$$\int_{C_{\overline{4}}} (A^{\alpha\beta} + 8\pi h e^{-4} \mathfrak{U}^{\alpha\beta}) \delta g_{\alpha\beta} \sqrt{-g} \, \mathrm{d}C_4 = 0 \; .$$

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Furthermore

(20)
$$\int_{C_4^a} (A^{\alpha\beta} + 8\pi h c^{-4} \mathbb{U}^{\alpha\beta}) \, \delta g_{\alpha\beta} \sqrt{-g} \, dC_4 =$$
$$= \int_{C_4} (A^{\alpha\beta} + 8\pi h c^{-4} \mathbb{U}^{\alpha\beta}) \, \delta g_{\alpha\beta} \sqrt{-g} \, dC_3 \int_{a}^{a} dx^0 =$$
$$= 2a \int_{C_4} (A^{\alpha\beta} + 8\pi h c^{-4} \mathbb{U}^{\alpha\beta}) \, \delta g_{\alpha\beta} \sqrt{-g} \, dC_3 \, .$$

From (14), (17), (18), (19), (20) we deduce

(21)
$$\int_{3} \int_{c_3} (R + 16\pi hc^{-4}\varrho) \sqrt{-g} \, dC_3 = -\int_{c_3} (A^{\alpha\beta} + 8\pi hc^{-4} \mathbb{U}^{\alpha\beta}) \, \delta_3 g_{\alpha\beta} \sqrt{-g} \, dC_3$$

for the variations $\delta g_{\alpha\beta}$ specified above.

From (21) it follows that the variational condition $\delta J = 0$ is equivalent to the validity, in C_3 , of the gravitational equations for C: $A^{\alpha\beta} + 8\pi h e^{-4} \mathcal{U}^{\alpha\beta} = 0$ ($\alpha, \beta = 0, 1, 2, 3$). If we remember that ρ, R , $A^{\alpha\beta}, \mathcal{U}^{\alpha\beta}$ do not depend on x^0 , we can conclude that the variational condition $\delta J = 0$ is equivalent to the validity of the gravitational equations for C in the whole world tube $W_{\rm C}$. This proves the theorem.

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