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## I. MARGARIA <br> M. Zacchi

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# RIGHT AND LEFT INVERTIBILITY IN $\lambda$ - $\beta$-CALCULUS (*) 

by I. Margaria and M. Zacchi ( ${ }^{1}$ )

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#### Abstract

A characterization of $\lambda$-terms having left and/or right inverses in $\lambda$ - $\beta$-calculus is given and the sets of all and only $\lambda$-terms left/right invertible are constructed. The above results are obtained using the concept of Böhm tree, so this study is further used to characterize the $\lambda$-terms left/right invertible in the graph model $\mathbf{P}_{\omega}$.


Résumé. - Dans ce papier on va caractériser les $\lambda$-termes invertibles à droite et/ou à gauche, en donnant les règles pour construire les deux ensembles constitués respectivement par tous les $\lambda$-termes ayant un inverse droite ou gauche. Puisque ces résultés ont été obtenus par la notion d'arbre de Böhm on peut utiliser cette étude au fin de caractériser les $\lambda$-termes invertibles à droite ou à gauche dans le modèle $\mathbf{P}_{\omega}$.

## 0. INTRODUCTION

Aim of this paper is the characterization of $\lambda$-terms having left and/or right inverses in $\lambda$ - $\beta$-calculus. The semigroup $\Lambda$ of $\lambda-\beta-(\eta)$-terms, having the combinator $\mathbf{I} \equiv \lambda x . x$ as identity element and the operation $\circ$ defined by $X \circ Y=\mathbf{B} X Y$ (where $\mathbf{B} \equiv \lambda x y z . x(y z)$ ) as composition, has been studied with respect to the left/right invertibility problem in [2], [4], [7, p. 167-168], [8], [9].
In particular in the $\lambda$ - $\beta$-calculus the set of normal forms having at least one left or right inverse has been characterized in [4]. The same paper shows that the combinator I is the only normal form having both left and right inverse.
The present paper tries to give the final solution to the invertibility problem in $\lambda$ - $\beta$-calculus showing the necessary and sufficient conditions under which an arbitrary $\lambda$-term possesses a left (right) inverse and characterizing the set of terms for which there exists only one left (right) inverse; for the

[^0]other left (right) invertible terms an infinite number of inverses is proved to exist. The basic definitions which the paper relies on are those of direct approximation [11], of Böhm tree [1] and of partial order relation $\sqsubseteq$ on the set of $\lambda$ - $\Omega$-terms, as stated in [10]. Using these notions it is possible to carry on $\Lambda$ the relation $\check{~ d e f i n i n g ~ a ~} \lambda$-term $X$ less or equal to a $\lambda$-term $Y(X \sqsubseteq Y)$ if and only if its direct approximation $\Phi(X)$ is less or equal to the direct approximation $\Phi(Y)$ of $Y(\Phi(X) \sqsubseteq \Phi(Y))$ and to associate with a $\lambda$-term $X$ the approximation set as the set of $\lambda$ - $\Omega$-terms $\Phi\left(X^{\prime}\right)$ such that $X$ is $\beta$-convertible to $X^{\prime}$. Firstly we notice that every left (right) inverse of a $\lambda$-term $X$ is a left (right) inverse of all $\lambda$-terms $Y$ such that $X \sqsubseteq Y$. Then in order to characterize the set of terms having left inverse, an operation, called terminal extension, is introduced on the set of Böhm trees. Roughly speaking a terminal extension of a Böhm tree $A$ is a Böhm tree $A^{\prime}$ obtained from $A$ modifying a terminal node of $A$ either introducing in its label the abstraction of a new variable or pushing the head variable down of a level and substituting it by a bound variable. So we can prove that a $\lambda$-term $X$ has a left inverse if and only if there exists in the approximation set of $X$ at least one approximation which can be obtained from I applying a sequence of terminal extensions. Moreover it results that every term left invertible, different from I, possesses an infinite number of non-convertible left inverses.

The problem of the right invertibility is approached in a similar way. The operation of adding a son with label $\underline{\Omega}$ to the root of a Böhm tree $A$ to obtain a Böhm tree $A^{\prime}$ is called initial extension. This allows to assert that a $\lambda$-term $X$ has right inverse iff there exists at least one approximation of $X$ which can be obtained from $I$ applying a sequence of initial extensions. Obviously, as a corollary, it results that $\mathbf{I}$ is the only $\lambda$-term both left and right invertible. Furthermore we can prove that the number of right inverses for a right invertible term $X$ is either one or infinite depending on the form of the term itself.

Finally we notice that the above results about invertibility can be carried on the graph model $\mathbf{P}_{\omega}$ [1, p. 467] and we show that the two functions which map an element of $\mathbf{P}_{\omega}$ into the set of all its right or left inverses, respectively, are not monotonic, i. e. it is possible to find a left (right) inverse of an element $X$ of $\mathbf{P}_{\omega}$ which is not a left (right) inverse of an element $Y$, whereas $X \sqsubseteq Y$ ( $\check{\sim}$ is the usual order relation on $\mathbf{P}_{\omega}$ ).

## 1. NOTATIONS AND DEFINITIONS

In the sequel we will use the following notions and conventions:
i) $\lambda$-calculus means $\lambda$ - $\beta$-calculus, normal form $\lambda$ - $\beta$-normal form, $\geqslant,=, \equiv$
denote $\beta$-reducibility, $\alpha$ - $\beta$-convertibility and modulo $\alpha$ identity, respectively; moreover $\Lambda$ represents the set of $\lambda$-terms;
ii) the word combinator will refer to closed $\lambda$-terms, i. e. terms without free variables; the combinators will be indicated by uppercase, boldface characters, for example $\mathbf{B} \equiv \lambda x y z \cdot x(y z), \mathbf{I} \equiv \lambda x . x$, etc.;
iii) we indicate by means of the ordered sequences of $\lambda$-terms

$$
\left\langle X_{0}, X_{1}, \ldots, X_{k}\right\rangle
$$

the $\lambda$-terms $\lambda z . z X_{0} X_{1} \ldots X_{k}$ where $z$ does not occur free in any $X_{i}, 0 \leqslant i \leqslant k$ (Church $n$-tuple) [6];
iv) C[ ] denotes a context, i. e. a $\lambda$-term where one subterm is missing; $\mathrm{C}[X]$ then denotes the result of filling the missing subterm with $X$ (for a more formal definition see [11]);
v) $X[x:=Y]$ indicates the $\lambda$-term obtained from a $\lambda$-term $X$ by substituting in it the $\lambda$-term $Y$ to every free occurrence (if any) of the variable $x$.

As the concept of approximation of a $\lambda$-term [11] and the related one of Böhm tree [1, p. 211] are very useful for this study, we summarize here the principal definitions and conventions about them.

A $\lambda$-term $X$ has head normal form if it has the form $\lambda x_{1} x_{2} \ldots x_{m} . y X_{1} X_{2} \ldots X_{n}$ where:

- $x_{1}, x_{2}, \ldots, x_{m}$ are variables and $m \geqslant 0$;
- $X_{1}, X_{2}, \ldots, X_{n}$ are $\lambda$-terms and $n \geqslant 0$;
- $y$ is a variable, free or bound (as usual it will be called the head variable of $X$ ).

The direct approximation $\Phi(X)$ of a $\lambda$-term $X$ is defined as follows:
$\Phi(X)=\lambda x_{1} \ldots x_{m} \cdot y \Phi\left(X_{1}\right) \Phi\left(X_{2}\right) \ldots \Phi\left(X_{n}\right)$ if $X=\lambda x_{1} \ldots x_{m} \cdot y X_{1} X_{2} \ldots X_{n} ;$ $\Phi(X)=\underline{\Omega}$, where $\underline{\Omega}$ is an extra constant, if $X$ has not a head normal form.

The set $\Phi(\Lambda)$ will be indicated by $\mathscr{N}$ (set of $\lambda$ - $\Omega$-terms). Inside $\mathscr{N}$ the following partial order relation $\sqsubseteq$ is defined [10]: for any $M, N$ of $\mathscr{N} M \sqsubseteq N$ iff either

$$
M \equiv \underline{\Omega} ; \quad \text { or }
$$

$$
\begin{equation*}
M \equiv \lambda x_{1} x_{2} \ldots x_{n} \cdot x_{j} M_{0} \ldots M_{k} \tag{ii}
\end{equation*}
$$

$$
N \equiv \lambda x_{1} x_{2} \ldots x_{n} \cdot x_{j} N_{0} \ldots N_{k}
$$

and $\quad M_{i} \sqsubseteq N_{i}$ for any $i(0 \leqslant i \leqslant k)$.
Given a $\lambda$-term $X$ we call approximation set of $X: \mathscr{A}(X)$ the subset of $\mathscr{N}$ so defined:

$$
\mathscr{A}(X)=\{M \in \mathscr{N} \mid M \sqsubseteq \Phi(X)\} .
$$

The partial order relation $\subseteq$ can be carried on $\Lambda$ as follows: for any $X, Y$ of $\Lambda, X \subseteq Y$ iff $\Phi(X) \subseteq \Phi(Y)$.

We can visualize every element $M$ of $\mathscr{N}$ by means of a suitable tree: the Böhm tree (B. T.) of M. Given an element $M$ of $\mathcal{N}$, the B. T. of $M: B T(M)$ is the labelled tree so defined:
i) if $M \equiv \Omega \quad$ вт $(M) \equiv \Omega$


We will refer to $\mathscr{B}$ as to the set of the B. T. of the elements of $\mathscr{N}$. The nodes of a B. T. will be indicated by strings of natural numbers (included the empty string $\varepsilon$, labelling the root) in the usual way, so that $\beta$ denotes a successor of $\alpha$ if and only if $\alpha$ is a prefix of $\beta: \beta=\alpha \gamma$ for some $\gamma$. Let $A$ be a B. T. and $\alpha$ be a node with label $\lambda x_{1} \ldots x_{n} \cdot y$, in the sequel we will use the following conventions [see 1, p. 218]:
i) $A_{\alpha}$ indicates the subtree of $A$ having as root the node $\alpha$;
ii) $\bar{\alpha}$ indicates the path from the root to the node $\alpha$;
iii) $b(\alpha)$ indicates the vector of the bound variables occurring in the label of $\alpha$, i. e. $b(\alpha)=x_{1} x_{2} \ldots x_{n}$;
$i v) b(\bar{\alpha})$ indicates the vector of the bound variables occurring in the labels of the nodes of the path $\bar{\alpha}$, inductively defined as follows:

$$
\begin{aligned}
& -b(\bar{\varepsilon})=b(\varepsilon) \\
& -b\left(\alpha^{\prime}\langle k\rangle\right)=b\left(\alpha^{\prime}\right) b(k) .
\end{aligned}
$$

By way of example, for the B. T. $A$ of figure 1 , if we choose as node $\alpha$ the node $\langle 10\rangle$, we have:

$$
\begin{aligned}
& b(\alpha)=x_{4} \\
& b(\bar{\alpha})=x_{0} x_{1} x_{2} x_{3} x_{4} \\
& \mathbf{A}_{\alpha} \equiv \lambda \times_{\mathbf{4}} \cdot x_{\mathbf{4}}
\end{aligned}
$$



Figure 1. - A Böhm tree A.
By streching the Böhm tree definition, in the sequel sometimes we will refer to the B. T. of an element $X$ of $\Lambda: B T(X)$, as to the B. T. of its direct approximation.

Obviously any B. T. $A$ of $\mathscr{B}$ will define one and only one term of $\mathscr{N}: M_{A}$ such that $B T\left(M_{A}\right)=A$ (for example for the B. T. $A$ of figure 1

$$
\left.M_{\mathrm{A}} \equiv \lambda x_{0} x_{1} x_{2} x_{3} \cdot x_{3} \underline{\Omega}\left(x_{0}\left(\lambda x_{4} \cdot x_{4} x_{2}\right) x_{6}\right) \lambda x_{5} \cdot x_{1}\right) ;
$$

hence the order relation $\sqsubseteq$ on $\mathcal{N}$ can be carried on $\mathscr{B}: A \sqsubseteq B$ iff $M_{A} \sqsubseteq M_{B}$.

## 2. Right and left invertibility

Aim of this section is to study the conditions under which an arbitrary $\lambda$-term $X$ has right and/or left inverses. In the sequel we use the following notations:
i) $X_{R}\left(X_{L}\right)$ denotes a right (left) inverse of a $\lambda$-term $X$, i. e.,:

$$
\mathbf{B} X X_{R}=\mathbf{I} \quad\left(\mathbf{B} X_{L} X=\mathbf{I}\right) .
$$

ii) $\mathscr{I}_{R}(X)\left(\mathscr{I}_{L}(X)\right)$ denotes the set of all the right (left) inverses of a $\lambda$-term $X$.

Theorem 1: Let $X, Y$ be two $\lambda$-terms of $\Lambda$ for which $X \sqsubseteq Y$, then:

$$
\begin{aligned}
& \text { i) } \mathscr{I}_{\mathrm{R}}(X) \subseteq \mathscr{I}_{\mathrm{R}}(Y) \\
& \text { ii) } \mathscr{I}_{L}(X) \subseteq \mathscr{I}_{L}(Y) \text {. }
\end{aligned}
$$

Proof: i) The assertion is trivially true for $\mathscr{I}_{R}(X)$ empty.
If it is not true, we prove that any right inverse $X_{R}$ of $X$ is also a right inverse for $Y$. By definition we have:
$X\left(X_{R} y\right) \geqslant y$ for any variable $y$ not free in $X$ and $X_{R}$.
Since Lévy has proved (th. 5.8, p. 105 of [10]) that if $X \sqsubseteq Y$ then $\mathbf{C}[X] \sqsubseteq \mathbf{C}[Y]$ for any context $\mathbf{C}\left[\right.$ ], if we choose as context [ ] $\left(X_{R} y\right)$ it will be:

$$
y \leqslant X\left(X_{R} y\right) \sqsubseteq Y\left(X_{R} y\right) \text { hence } Y\left(X_{R} y\right) \geqslant y .
$$

ii) The proof is analogous to the preceding one if we choose as context $X_{L}([\quad] y)$.

### 2.1. Left Invertibility

Definition 2.1.1: Let $A, A^{\prime}$ be two Böhm trees and $\alpha$ a terminal node of $A$ with label $\lambda x_{i_{1}} x_{i_{2}} \ldots x_{i_{h}} . x_{t}$. We say that $A^{\prime}$ is a terminal extension of $A$ in $\alpha$ if $A^{\prime}$ results from $A$ by one of the following substitutions:

1) the label of the node $\alpha$ in $A$ is replaced in $A^{\prime}$ by the label

$$
\left.\lambda x_{i_{1}} x_{i_{2}} \ldots x_{i_{h}} x_{i_{h+1}}, x_{t} \quad \text { (terminal extension of type } 1\right) ;
$$

2) the subtree $A_{\alpha}$ is replaced in $A^{\prime}$ by a subtree $A_{\alpha}^{\prime}$ such that:
a) the label of $\alpha$ is $\lambda x_{i_{1}} \ldots x_{i_{n}} \cdot x_{j}$, where $x_{j}$ is a bound variable distinct from $x_{t}$;
b) $\alpha$ has $m$ sons with $m \geqslant 1$. Each of these sons are terminal nodes, one and only one of them has label $x_{t}$, whereas the remaining $m-1$ have label $\underline{\Omega}$ (see fig. 2) (terminal extension of type 2).


Figure 2. - A terminal extension of type 2.

With every terminal extension $e$ of type 2, we associate the triple

$$
\tau(e)=\left\langle x_{j}, m, k\right\rangle,
$$

where $x_{j}$ and $m$ are respectively the name of the head variable and the number of sons of the node $\alpha$ in $A^{\prime}$ and $k$ indicates that the only son of $\alpha$ in $A^{\prime}$ with label different from $\Omega$ is the $k$-th.

Definition 2.1.2: Let $A, A^{\prime}$ be two Böhm trees.
We say that $A^{\prime}$ is a terminal extension of $A\left(A \underset{t-\mathrm{ext}}{\longrightarrow} A^{\prime}\right)$ if it is a terminal extension of $A$ in some terminal node.

Definition 2.1.3: We call Left Invertible Term Generator Set the subset $\mathscr{L} \subset \mathscr{N}$ inductively defined as follows:
i) $\mathbf{I} \in \mathscr{L}$
ii) $N \in \mathscr{L}$ and $B T(N) \underset{t-\text { ext }}{\longrightarrow} B T\left(N^{\prime}\right) \Rightarrow N^{\prime} \in \mathscr{L}$.

Definition 2.1.4: Let $N$ be an element of $\mathscr{L}$. We call history of $N: \mathscr{H}(N)$ a sequence of elements of $\mathscr{L}:\left\langle N^{0}, N^{1}, \ldots, N^{h}\right\rangle$ such that $N^{0} \equiv \mathbf{I}, N^{h} \equiv N$ and for any $i, 0 \leqslant i \leqslant h-1, B T\left(N^{i}\right) \xrightarrow[t-\mathrm{ext}]{\longrightarrow} B T\left(N^{i+1}\right)$.

Lemma 2.1.1: Every element $N$ of $\mathscr{L}$ has one and only one history: $\mathscr{H}(N)$.
Proof: Obvious from definition 2.1.1 and definition 2.1.3.



Figure 3. - Böhm trees of the history of the $\lambda$ - $\Omega$-term $\lambda x_{0} x_{1} x_{2} x_{3} \cdot x_{2}\left(\lambda x_{4} \cdot x_{3} \underline{\Omega} x_{0}\right) \underline{\Omega}$.

Definition 2.1.5: Let $N$ be an element of $\mathscr{L}$. We say that $N$ is a term nonhomogeneous for the variable $x_{t}$ if in its history $\mathscr{H}(N)$ there are at least two
terminal extensions $e, e^{\prime}$ of type 2 with $\tau(e)=\left\langle x_{t}, m, k\right\rangle$ and $\tau\left(e^{\prime}\right)=\left\langle x_{t}, m^{\prime}, k^{\prime}\right\rangle$ such that $m \neq m^{\prime}$ and/or $k \neq k^{\prime}$.

Figure $4(a)$ shows the Böhm tree of a term non-homogeneous for the variable $x_{1}$, whereas it is homogeneous for the variable $x_{2}$; instead the term whose Böhm tree is in figure $4(b)$ is homogeneous for each variable occurring as head variable; in such a case we say that the term is homogeneous.


Figure 4. - Böhm trees of a non-homogeneous (a) and of a homogeneous $\lambda$ - $\Omega$-term (b).

From lemma 3 of [3] it follows lemma 2.1.2 which has been rewritten and proved (in a simpler way) using the notation of the present work.

Lemma 2.1.2: Let $N$ be a $\lambda-\underline{\Omega}$ term of $\mathscr{L}$, non-homogeneous for a set of variables $\left\{x_{l_{1}}, x_{l_{2}}, \ldots, x_{l_{k}}\right\}$. We state that there is a normal combinator
$\mathbf{C}_{[m]} \mathbf{I}$ such that the term $N^{\prime}\left[x_{l_{\mathrm{i}}}:=\mathbf{C}_{[m]} \mathbf{I}\right]$, where $N^{\prime}$ is obtained from $N$ by eliminating the abstraction of $x_{l_{i}}$, is non-homogeneous for the set

$$
\left\{x_{l_{1}}, x_{l_{2}}, \ldots, x_{l_{i-1}}, x_{l_{i+1}}, \ldots, x_{l_{k}}\right\} .
$$

Proof: Let $e_{1}, e_{2}, \ldots, e_{n}$ be the terminal extensions of type 2 , occurring in $\mathscr{H}(N)$ such that the first element of $\tau\left(e_{j}\right)$ is $l_{i}(1 \leqslant j \leqslant n)$, i. e.:

$$
\begin{aligned}
& \tau\left(e_{1}\right)=\left\langle x_{l_{i}}, m_{1}, k_{1}\right\rangle \\
& \tau\left(e_{2}\right)=\left\langle x_{l_{i}}, m_{2}, k_{2}\right\rangle \\
& \cdot \cdot \\
& \tau\left(e_{n}\right)=\left\langle x_{l_{i}}, m_{n}, k_{n}\right\rangle .
\end{aligned}
$$

Let $m=\max \left(m_{1}, m_{2}, \ldots, m_{n}\right)$. It is easy to prove that the normal combinator $\mathbf{C}_{[m]} \mathbf{I} \equiv \lambda t_{0} t_{1} \ldots t_{m} \cdot t_{m} t_{0} t_{1} \ldots t_{m-1}$ satisfies the thesis, because it substitutes the different occurrences of $x_{l_{i}}$ by different variables.

Lemma 2.1.3: Every $\lambda$-term $X$ of $\Lambda$, whose direct approximation is in $\mathscr{L}$, has at least a left inverse.

Proof : Firstly we prove that every $\lambda$-term $X$, whose direct approximation is a homogeneous element of $\mathscr{L}$ has a left inverse. From definition 2.1.3 it follows that there is one and only one terminal node of $B T(X)$ having label different from $\underline{\Omega}$; let such a node be $\alpha$ and let $b(\bar{\alpha})=x_{0} x_{1} \ldots x_{n}, n \geqslant 0$. We assert that there are $n$ suitable $\lambda$-terms $\Psi_{1}, \Psi_{2}, \ldots, \Psi_{n}$ such that the sequence $\left\langle\Psi_{1}, \Psi_{2}, \ldots, \Psi_{n}\right\rangle$ is a left inverse for $X$. We prove this assertion by induction on the number $h$ of elements of $\mathscr{H}(\Phi(X))$.

$$
\begin{array}{ll}
h=1 . & X=\mathbf{I} \\
h+1 .
\end{array} \quad X_{L}=\lambda z . z \equiv \mathbf{I} .
$$

Given $\mathscr{H}(\Phi(X))=\left\langle N^{0}, N^{1}, \ldots, N^{h}, N^{h+1}\right\rangle$, let $X^{i}, 0 \leqslant i \leqslant h$, be a $\lambda$-term such that $\Phi\left(X^{i}\right)=N^{i}$, let $X^{h+1}=X$ and $A^{i}=B T\left(N^{i}\right)$. We distinguish two cases either $A^{h+1}$ extends $A^{h}$ by a terminal extension of type 1 or $A^{h+1}$ extends $A^{h}$ by a terminal extension of type 2 . In the first case we say that a left inverse for $X$ can be obtained by adding to the left inverse of $X^{h}$ (existing by induction hypothesis) a generic $\lambda$-term $\Psi_{n}$, i. e.
if

$$
\begin{aligned}
& X_{L}^{h}=\left\langle\Psi_{1}^{h}, \Psi_{2}^{h}, \ldots, \Psi_{n-1}^{h}\right\rangle \\
& X_{L}^{h+1} \quad \text { will be }\left\langle\Psi_{1}^{h}, \Psi_{2}^{h}, \ldots, \Psi_{n-1}^{h}, \Psi_{n}\right\rangle
\end{aligned}
$$

In fact it follows from the definitions of $\mathscr{L}$ and of terminal extension of type 1 that:

$$
\left(X^{h+1} y\right)=\left(X^{h} y\right)\left[y:=\lambda x_{n} \cdot y\right]
$$

vol. $17, \mathrm{n}^{\circ} 1,1983$
and by induction hypothesis:
i. e.:

$$
\begin{aligned}
& \left(X^{h+1} y\right) \Psi_{1}^{h} \Psi_{2}^{h} \ldots \Psi_{n-1}^{h} \geqslant \lambda x_{n} \cdot y \\
& \left(\lambda x_{n} \cdot y\right) \Psi_{n} \geqslant y
\end{aligned}
$$

In the second case, let $\left\langle x_{j}, m, k\right\rangle$ be the triple associated with the $(h+1)-$ th terminal extension. If $x_{j}$ occurs as head variable in some terminal extension preceding the $(h+1)$-th one, from homogeneity hypotesis it follows that the left inverse $X_{L}^{h}$ (existing by induction hypothesis) is also a left inverse for $X^{h+1}$; otherwise we prove that a left inverse of $X^{h+1}$ can be obtained by substituting in the left inverse $X_{L}^{h}$ for the $\lambda$-term $\Psi_{j}^{h}$ the normal combinator (selector)

$$
\begin{aligned}
\mathbf{U}_{k}^{m} & =\lambda t_{1} t_{2} \ldots t_{m} \cdot t_{k}, \quad \text { i. e.: } \\
X_{L}^{h+1} & =\left\langle\Psi_{1}^{h}, \Psi_{2}^{h}, \ldots, \Psi_{j-1}^{h}, \mathbf{U}_{k}^{m}, \Psi_{j+1}^{h}, \ldots\right\rangle
\end{aligned}
$$

It follows from definitions of $\mathscr{L}$ and of terminal extension of type 2, that:

$$
\left(X^{h+1} y\right)=\left(X^{h} y\right)\left[y:=x_{j} X_{1}^{\prime} X_{2}^{\prime} \ldots X_{k-1}^{\prime} y X_{k+1}^{\prime} \ldots X_{m}^{\prime}\right]
$$

where $X_{i}^{\prime}$ are unsolvable terms; then:
$\left(X^{h+1} y\right) \Psi_{1}^{h} \Psi_{2}^{h} \ldots \Psi_{j-1}^{h} \mathbf{U}_{k}^{m} \Psi_{j+1}^{h} \ldots \geqslant \mathbf{U}_{k}^{m} X_{1}^{\prime} X_{2}^{\prime} \ldots X_{k-1}^{\prime} y X_{k+1}^{\prime} \ldots X_{m}^{\prime} \geqslant y$.
Now, let us suppose that $X$ has a direct approximation non-homogeneous only for one variable $x_{i}$. From lemma 2.1.2 it follows that there exists an integer $m$ such that the term $N^{\prime}\left[x_{i}:=\mathbf{C}_{[m]} \mathbf{I}\right]$, where $N^{\prime}$ is obtained from $\Phi(X)$ by eliminating the abstraction of $x_{i}$, is homogeneous. Let $X^{\prime}$ be a $\lambda$-term of $\Lambda$ such that $\Phi\left(X^{\prime}\right)=N^{\prime}\left[x_{i}:=\mathbf{C}_{[m]} \mathbf{I}\right]$ and let $X_{L}^{\prime}$ be its left inverse, existing for the first part of this lemma: $X_{\mathrm{L}}^{\prime}=\left\langle\Psi_{1}^{\prime}, \Psi_{2}^{\prime}, \ldots, \Psi_{n}^{\prime}\right\rangle$. We maintain that the sequence $X_{L}=\left\langle\Psi_{1}^{\prime}, \Psi_{2}^{\prime}, \ldots, \Psi_{i-1}^{\prime}, \mathbf{C}_{[m]} \mathbf{I}, \Psi_{i}^{\prime}, \Psi_{i+1}^{\prime}, \ldots, \Psi_{n}^{\prime}\right\rangle$ is a left inverse for $X$. In fact:

$$
\begin{aligned}
& \left(X^{\prime} y\right) \Psi_{1}^{\prime} \Psi_{2}^{\prime} \ldots \Psi_{i-1}^{\prime}=(X y) \Psi_{1}^{\prime} \Psi_{2}^{\prime} \ldots \Psi_{i-1}^{\prime}\left(\mathbf{C}_{[m]} \mathbf{l}\right) \\
& (X y) \Psi_{1}^{\prime} \Psi_{2}^{\prime} \ldots \Psi_{i-1}^{\prime}\left(\mathbf{C}_{[m]}\right] \Psi_{i}^{\prime} \ldots \Psi_{n}^{\prime}=\left(X^{\prime} y\right) \Psi_{1}^{\prime} \Psi_{2}^{\prime} \ldots \Psi_{i-1}^{\prime} \Psi_{i}^{\prime} \ldots \Psi_{n}^{\prime} \geqslant y .
\end{aligned}
$$

The proof can be generalized in a obvious way to the case of terms nonhomogeneous for more than one variable.

Lemma 2.1.4: Every $\lambda$-term of $\Lambda$, distinct from I and having the direct approximation in $\mathscr{L}$, has an infinite number of non convertible left inverses.

Proof: Let $X$ be a $\lambda$-term satisfying the hypothesis of this lemma. If some of the $\lambda$-terms of the not empty sequence $X_{L}$, obtained by the construction of lemma 2.1.3, are arbitrary we can obtain an infinite number of left inverses choosing them in infinite ways.

Instead if each $\Psi_{i}$ has been substituted by a suitable combinator, we can obtain an infinite number of left inverses as follows. Let $\mathbf{U}_{k}^{m}$ be a selector occurring in $X_{L}$ (from proof of lemma 2.1 .3 it is clear that in $X_{L}$ we have surely some selectors), i. e.:

$$
X_{L}=\left\langle\Psi_{1}, \Psi_{2}, \ldots, \Psi_{i-1}, \mathbf{U}_{k}^{m}, \Psi_{i+1}, \ldots, \Psi_{k}\right\rangle
$$

It is easy to prove that

$$
X_{L}^{\prime}=\left\langle\Psi_{1}, \Psi_{2}, \ldots, \Psi_{i-1}, \mathbf{U}_{k}^{m+n}, \Psi_{i+1}, \ldots, \Psi_{h}, \Phi_{1}, \ldots, \Phi_{n}\right\rangle
$$

where $\Phi_{i}(1 \leqslant i \leqslant n)$ are generic $\lambda$-terms, is another left inverse for $X$, nonconvertible to $X_{L}$ :
$X_{L}^{\prime}(X y) \geqslant(X y) \Psi_{1} \Psi_{2} \ldots \Psi_{i-1} \mathbf{U}_{k}^{m+n} \Psi_{i+1} \ldots \Psi_{n} \Phi_{1} \Phi_{2} \ldots \Phi_{n} \geqslant$

$$
\geqslant\left(\lambda t_{1} t_{2} \ldots t_{n} \cdot y\right) \Phi_{1} \Phi_{2} \ldots \Phi_{n} \geqslant y .
$$

Definition 2.1.6: A $\lambda$-term $X$ of $\Lambda$ is of type $\Sigma$ if the set $\mathscr{A}(X) \cap \mathscr{L}$ is not empty.

Remark 1: For any Böhm tree $B T(X)$ of a $\lambda$-term $X$ of type $\Sigma$ (shortly B. T. of type $\Sigma$ ), there is at least a terminal node $\sigma$, such that:
$i)$ the first component of the vector $b(\bar{\sigma})$ occurs as head variable only in the label of $\sigma$;
ii) every head variable in the label of a not terminal node of the path $\bar{\sigma}$, is bound.

The Böhm tree of figure 5 is of type $\Sigma$, because the terminal nodes $\langle 2\rangle$ and $\langle 11\rangle$ satisfy the conditions of the remark 1 .


Figure 5. - A Böhm tree of type $\Sigma$.

Theorem 2.1.1: A $\lambda$-term $X$ has at least a left inverse if and only if it is of type $\Sigma$.

Proof: If $X$ is of type $\Sigma$, there is at least an approximation $N^{\prime} \subseteq \Phi(X)$ belonging to $\mathscr{L}$, so for theorem 2.1 and lemma 2.1.3 $X$ has at least a left inverse.

Now, let us suppose, per absurdum, that the $\lambda$-term $X$ not of type $\Sigma$ has a left inverse. If $X$ is not of type $\Sigma$ one of the conditions of remark 1 is not satisfied.

If for any path $\bar{\sigma}$ of $B T(X)$ the condition $i$ ) of remark 1 does not hold, then in $(X y)$ the free variable $y$, if it occurs, always occurs applied to a positive number of arguments, which cannot be eliminated using only $\beta$-reductions. Instead if for any path for which condition $i$ ) of remark 1 holds, there is some non-terminal node whose label has as head variable a free variable, then there is no $\lambda$-term $Y$ such that in $Y(X y)$ this free variable can be erased to obtain $y$.

### 2.2. Right Invertibility

Definition 2.2.1: Let $A, A^{\prime}$ be two B. T., different from $\Omega$. We say that $A^{\prime}$ is an initial extension of $A\left(A \underset{i-\text { ext }}{\longrightarrow} A^{\prime}\right)$ if $A^{\prime}$ results from $\bar{A}$ by adding to its root a son with label $\underline{\Omega}$ (see fig. 6)


Figure 6. - Two Böhm trees $\mathbf{A}$ and $\mathbf{A}^{\prime}$ such that $\mathbf{A} \xrightarrow[i-\mathrm{ext}]{ } \mathbf{A}^{\prime}$.
Definition 2.2.2: We call Right Invertible Term Generator Set the subset $\mathscr{R} \subset \mathscr{N}$ inductively defined as follows:
i) $\mathbf{I} \in \mathscr{R}$
ii) $N \in \mathscr{R}$ and $B T(N) \xrightarrow[i-\mathrm{ext}]{ } B T\left(N^{\prime}\right) \Rightarrow N^{\prime} \in \mathscr{R}$.

Lemma 2.2.1: Every $\lambda$-term $X$ of $\Lambda$, whose direct approximation $\Phi(X)$ is in $\mathscr{R}$ has one and only one right inverse $X_{R}$.

Proof: " One " part. Let $X$ be $\lambda x \cdot x X_{1} X_{2} \ldots X_{h}$, with $X_{i}(1 \leqslant i \leqslant h)$ unsolvable; we take as $X_{R}$ the $\lambda$-term $\mathbf{U}_{1}^{h+1} \equiv \lambda x_{0} x_{1} \ldots x_{h}$. $x_{0}$. It's trivial that $X\left(X_{R} y\right) \geqslant y$, so $X_{R}$ is a right inverse for $X$.
" Only one" part. Let us suppose, per absurdum, that $X=\lambda z . z X_{1} \ldots X_{h}$,
with $X_{i}(1 \leqslant i \leqslant h)$ unsolvable, has a right inverse $X_{R}^{\prime}=\lambda x_{0} x_{1} \ldots x_{n} \cdot x_{j} Y_{1} Y_{2} \ldots Y_{t}$ distinct from $X_{R}=\lambda x_{0} x_{1} \ldots x_{h}, x_{0}$.

Since, from the definition of right inverse,

$$
\left(X_{R}^{\prime} y\right) X_{1} \ldots X_{h} \geqslant y
$$

we must have $n \leqslant h$, otherwise we cannot eliminate the $n-h$ initial abstractions.
Since from theorem 2.1.1 it follows that $X_{R}^{\prime}$ is of type $\Sigma$, the head variable $x_{j}$ of $X_{R}^{\prime}$ must be exactly $x_{0}$ if $t=0$, different from $x_{0}$ and bound if $t \neq 0$. In the first case we must have $n=h$, otherwise $y$ remains applied to a positive number of $\lambda$-terms, which cannot be eliminated to give $y$, hence $X_{R}^{\prime}=X_{R}$, contrary to the hypothesis. In the second case, we should have, for some $X_{j}$ unsolvable:

$$
X_{j} Y_{1}^{\prime} \ldots Y_{t}^{\prime} X_{n+1} \ldots X_{n} \geqslant y
$$

where:

$$
Y_{i}^{\prime}=Y_{i}\left[x_{0}:=y, x_{1}:=X_{1}, \ldots, x_{n}:=X_{n}\right] \quad \text { for } \quad 1 \leqslant i \leqslant t
$$

and this is an absurdum.
Definition 2.2.3: We say that a $\lambda$-term $\bar{X}$ of $\Lambda$ is of type $\Xi$ if the set $\mathscr{A}(X) \cap \mathscr{R}$ is not empty.

Example: The $\lambda$-terms whose $B$. T. is shown in figure 7 are of type $\Xi$, because they have as approximation the $\lambda$ - $\underline{\text {-term }} \lambda x_{0} \cdot x_{0} \underline{\Omega \Omega}$.


Figure 7. - A Böhm tree of $\lambda$-terms of type $\Xi$.

Remark 2: If $X$ is of type $\Xi$, it has the form $\lambda x . x X_{1} \ldots X_{h}$.
Theorem 2.2.1: A $\lambda$-term $X$ has at least a righ inverse if and only if it is of type $\Xi$.

Proof: If $X$ is a $\lambda$-term of type $\Xi, \mathscr{I}_{R}(X)$ is not empty from lemma 2.2.1 and theorem 2.1. Now let us suppose $X$ not of type $\Xi$; then $X$ can have in its head more than one abstraction: $X=\lambda x_{0} x_{1} \ldots x_{n} \cdot x_{i} X_{1} \ldots X_{h}$ and/or $X$ can have as head variable a free variable $X=\lambda x_{0} x_{1} \ldots x_{n} \cdot y X_{1} \ldots X_{h}$. In the first case the $n+1$ initial abstractions cannot be eliminated using $\beta$-reductions; in the second case the free variable cannot be erased.

Corollary: The only $\lambda$-term having left and right inverse is the combinator $I$.

Definition 2.2.4: We say that a $\lambda$-term $X$ is $\Omega$-like if either:
i) $X$ is unsolvable, or
ii) $X$ is solvable and its head variable is free.

We say $X$ not $\Omega$-like on the contrary.
Lemma 2.2.2: Let $X$ be a $\lambda$-term:
i) if $X$ is $\Omega$-like, for any $\lambda$-term $Y$, the application $(X Y)$ is also an $\Omega$-like term.
ii) if $X$ is $\Omega$-like, for any variable $y$ different from the head variable of $X$, if any, there are no $h \lambda$-terms $Y_{1}, Y_{2}, \ldots, Y_{h}$ such that:

$$
X Y_{1} Y_{2} \ldots Y_{h} \geqslant y
$$

iii) if $X$ is not $\Omega$-like there are $h \lambda$-terms $Y_{1}, Y_{2}, \ldots, Y_{h}$ such that:

$$
X Y_{1} Y_{2} \ldots Y_{h} \geqslant \mathbf{I}
$$

Proof: Both assertions i) and ii) are trivially true for $X$ unsolvable. Let us suppose $X$ solvable with head variable free: $X=\lambda x_{1} x_{2} \ldots x_{k} \cdot a X_{1} \ldots X_{h}$, then the head variable $a$ cannot be eliminated using only $\beta$-reductions, so ( $X Y$ ) is solvable with head variable $a$, moreover it is impossible to reduce $X$ to a free variable $y$ different from $a$.

To prove assertion iii), let us suppose $X=\lambda x_{1} x_{2} \ldots x_{k}, x_{j} X_{1} \ldots X_{s}$, with $x_{j}$ bound. If we choose $h=k, Y_{i}=\Psi_{i}$, where $\Psi_{i}$ is a generic $\lambda$-term, for $1 \leqslant i<j$ and $j<i \leqslant h$, and $Y_{j}=\mathbf{U}_{s+1}^{s+1}$, where $\mathbf{U}_{s+1}^{s+1} \equiv \lambda x_{0} x_{1} \ldots x_{s} \cdot x_{s}$, it is trivially true that $X Y_{1} \ldots Y_{h} \geqslant \mathbf{I}$.

Theorem 2.2.2: Let $X$ be a $\lambda$-term of type $\Xi: X=\lambda z . z X_{1} \ldots X_{h}$. If every $X_{i}$ is $\Omega$-like, then $X$ has one and only one right inverse, else $X$ has an infinite number of right inverses.

Proof: Let us suppose $X=\lambda z . z X_{1} \ldots X_{h}$ with $X_{i}(1 \leqslant i \leqslant h) \Omega$-like. We
must prove that $X$ has only the right inverse given in the proof of lemma 2.2.1: $X_{R}=\lambda x_{0} \ldots x_{h}, x_{0}$.

The existence of another inverse $X_{R}^{\prime}$ should cause an absurdum, in fact being $X_{R}^{\prime}=\lambda x_{0} x_{1} \ldots x_{n} \cdot x_{j} Y_{1} \ldots Y_{h}$ of type $\Sigma$ because of theorem 2.1.1, its head variable must be bound and different from $x_{0}$ (see proof of lemma 2.2.1), then we should have, for some $X_{i} \Omega$-like and some $Z_{1}, Z_{2}, \ldots, Z_{k}$ :

$$
X_{i} Z_{1} \ldots Z_{k} \geqslant y
$$

and this is an absurdum because of lemma 2.2.2, case $i i$ ).
Now let us suppose that at least one $\lambda$-term $X_{i}$ is not $\Omega$-like. For lemma 2.2.2, case $i i i$ ), there exist $h \lambda$-terms $Y_{1}, Y_{2}, \ldots, Y_{h}$ such that:

$$
X_{i} Y_{1} Y_{2} \ldots Y_{h} \geqslant \mathbf{I}
$$

Let $\mathscr{S}(X)$ be the set inductively defined as follows:
i) $X_{R}=\lambda x_{0} \ldots x_{h} \cdot x_{0}$ is in $\mathscr{S}(X)$
ii) if $Y$ is in $\mathscr{S}(X)$ and $Y^{\prime}$ is a term obtained by substituting in the $B T(Y)$ to the terminal node $x_{0}$ the subtree:

then $Y^{\prime}$ is in $\mathscr{S}(X)$.
It is obvious that $\mathscr{S}(X)$ has an infinite number of elements, which are all right inverses of $X$.

## 3. LEFT AND RIGHT INVERTIBILITY IN THE GRAPH MODEL $\mathbf{P}_{\omega}$

H. Barendregt [1, p. 496-500], reformulating in terms of Böhm trees the Hyland's characterization of the equality in the graph model $\mathbf{P}_{\omega}$, has shown that

$$
\mathbf{P}_{\omega} \vDash X=Y \Leftrightarrow B T(X)=B T(Y) .
$$

So we can say that the above results about invertibility on $\mathscr{N}$ (or $\mathscr{B}$ ) can be carried on $\mathbf{P}_{\omega}$. Now let $f$ and $g$ be the following functions

$$
\begin{array}{ll}
f: \mathbf{P}_{\omega} \rightarrow 2^{\mathbf{P}_{\omega}} & f(X)=\mathscr{I}_{L}(X) \\
g: \mathbf{P}_{\omega} \rightarrow 2^{\mathbf{P}_{\omega}} & g(X)=\mathscr{I}_{R}(X),
\end{array}
$$

since both $\mathbf{P}_{\omega}$ and $2^{\mathbf{P}_{\omega}}$ are complete lattices [1, p. 19], it is of some interest to investigate whether $f$ and $g$ are monotonic functions, i. e.
whether

$$
\begin{array}{llll}
\text { whether } & \mathscr{I}_{L}(X) \subseteq \mathscr{I}_{L}(Y) & \text { whenever } & X \sqsubseteq Y \\
\text { and whether } & \mathscr{I}_{R}(X) \subseteq \mathscr{I}_{R}(Y) & \text { whenever } & X \sqsubseteq Y,
\end{array}
$$

being $\check{\approx}$ the order relation on $\mathbf{P}_{\omega}$. H. Barendregt [1, p. 228-240, 496-500] has shown that

$$
\mathbf{P}_{\omega} \vDash X \check{\approx} Y \Leftrightarrow B T(X) \eta_{\sqsubseteq} B T(Y),
$$

where $\eta_{\subseteq}$ is the order relation defined as it follows.
Definition 3.1: Let $A$ be a B. T. and $\alpha$ one of its nodes having label $\lambda x_{1} \ldots x_{n} \cdot y$. The B. T. $A^{\prime}$ is an $\eta$-expansion of $A$ at $\alpha$ if it results from $A$ by replacing the subtree $A_{\alpha}$, which has the form

by the subtree $A_{\alpha}^{\prime}$ having the form


In the sequel if $\alpha$ is the root of $A$, we call the $\eta$-expansion at $\alpha$ head $\eta$-expansion, if $\alpha$ is a terminal node of $A$ we call it terminal $\eta$-expansion.

Definition 3.2: Let $A, A^{\prime}$ be two Böhm trees. $A^{\prime}$ is a (possibly) infinite $\eta$-expansion of $A$ (shortly $A \leqslant_{\eta} A^{\prime}$ ) if it results from $A$ by the application of a (possibly infinite) sequence of $\eta$-expansions.

Definition 3.3: Let $A, A^{\prime}$ be two Böhm trees. $A \eta_{\sqsubseteq} A^{\prime}$ if there exists a Böhm tree $B$, which is a (possibly) infinite $\eta$-expansion of $A$, such that $B \sqsubseteq A^{\prime}$, i. e. $A \leqslant_{\eta} B \sqsubseteq A^{\prime}$.

In the sequel if $A \eta_{\sqsubseteq} B$, i. e. $A \leqslant_{\eta} A^{\prime} \sqsubseteq B$ for some $A^{\prime}$, and no terminal (head) $\eta$-expansion is applied to $A$ in order to obtain $A^{\prime}$, we say that $B$ results from $A$ without terminal (head) $\eta$-expansions.

Lemma 3.1: Let $X, Y$ be two $\lambda$-terms for which $B T(X) \eta_{\sqsubseteq} B T(Y)$ and let $X$ be of type $\Xi . Y$ is of type $\Xi$ if and only if $B T(Y)$ results from $B T(X)$ without head $\eta$-expansions.

Proof: Obvious.
Theorem 3.1: The function $g$ is not monotonic.
Proof: Let $X$ be a $\lambda$-term of type $\Xi$ and let $Y$ be a $\lambda$-term for wnus $B T(X) \eta_{\sqsubseteq} B T(Y)$. If $B T(Y)$ results from $B T(X)$ by some head $\eta$-expansion, from lemma 3.1 it follows that $\mathscr{I}_{R}(Y)$ is empty so $\mathscr{I}_{R}(X) \nsubseteq \mathscr{I}_{R}(Y)$, being $\mathscr{I}_{R}(X)$ not empty.

Notice that also in the case in which $B T(Y)$ results from $B T(X)$ without head $\eta$-expansions we can have $\mathscr{I}_{R}(X) \nsubseteq \mathscr{I}_{R}(Y)$. For example if

$$
X=\lambda x_{0} \cdot x_{0}\left(\lambda x_{1} \cdot x_{1}\right) \quad \text { and } \quad Y=\lambda x_{0} \cdot x_{0}\left(\lambda x_{1} x_{2} \cdot x_{1} x_{2}\right)
$$

we have that $X_{R}=\lambda t_{0} t_{1} \cdot t_{1} t_{0}$ is a right inverse for $X$ but not for $Y$.
Lemma 3.2: Let $X, Y$ be two $\lambda$-terms for which $B T(X) \leqslant_{\eta} B T(Y)$ and let $X$ be of type $\Sigma . Y$ is of type $\Sigma$ if and only if there exists $A \in \mathscr{A}(X) \cap \mathscr{L}$ such that $B T(Y)$ results from $B T(A)$ without terminal $\eta$-expansions.

Proof: Obvious.
Theorem 3.2: The function $f$ is not monotonic.
Proof: Obvious from lemma 3.2.
Notice that also in the case in which $Y$ is of type $\Sigma$ as $X$, we can have $\mathscr{I}_{L}(X) \nsubseteq \mathscr{I}_{L}(Y)$. For example if

$$
X=\lambda x_{0} x_{1} x_{2} \cdot x_{1}\left(x_{2} x_{0}\right) \quad \text { and } \quad Y=\lambda x_{0} x_{1} x_{2} \cdot x_{1}\left(\lambda x_{3} \cdot x_{2} x_{0} x_{3}\right)
$$

we have that $X_{L}=\lambda z . z \mathbf{I I}$ is a left inverse for $X$ but not for $Y$.

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[^0]:    $\left(^{*}\right)$ Received in December 1981, revised in June 1982.
    $\left({ }^{1}\right)$ Istituto di Scienze dell'Informazione, Università degli Studi di Torino, Corso M. D'Azeglio $n^{\circ} 42$, Torino.

