# Annales scientifiques de l’é.n.S. 

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Annales scientifiques de l'É.N.S. $4^{e}$ série, tome 20, no 2 (1987), p. 227-239
[http://www.numdam.org/item?id=ASENS_1987_4_20_2_227_0](http://www.numdam.org/item?id=ASENS_1987_4_20_2_227_0)
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# A GENERALIZATION OF BERGER'S RIGIDITY THEOREM FOR POSITIVELY CURVED MANIFOLDS ( ${ }^{1}$ ) 

By Detlef GROMOLL and Karsten GROVE

In this paper we consider a rigidity problem for compact connected riemannian manifolds M of dimension $n \geqq 2$, with positive sectional curvature K. For convenience we normalize the metric so that $K \geqq 1$. By the classical result of Bonnet-Myers, the diameter of $M$ satisfies $\operatorname{diam}(M) \leqq \pi$, and by a theorem of Toponogov equality holds if and only if M is isometric to the unit sphere $\mathrm{S}^{n}(1)$ in $\mathbb{R}^{n+1}$. The question we are concerned with here arises from the following result of [GS], a homotopy version of which was first proved by Berger (cf. [CE] or [GKM]).

Diameter sphere theorem. - A complete riemannian manifold M of dimension $n \geqq 2$ with $\mathrm{K} \geqq 1$ and $\operatorname{diam}(\mathrm{M})>\pi / 2$ is homeomorphic to the sphere $\mathrm{S}^{n}$.

This conclusion is no longer true if the condition $\operatorname{diam}(\mathrm{M})>\pi / 2$ is relaxed to $\operatorname{diam}(\mathrm{M}) \geqq \pi / 2$. Real projective space, as well as lens spaces in general, with metrics of constant curvature 1 provide simple counterexamples. The other projective spaces with their standard metrics of curvature $1 \leqq \mathrm{~K} \leqq 4$ are simply connected examples with diameter $\pi / 2$.

In this paper we give an essentially complete classification of the manifolds $M$ with $K \geqq 1$ and $\operatorname{diam}(M)=\pi / 2$.

Theorem A. - Let M be a complete riemannian manifold of dimension $n \geqq 2$ with $\mathrm{K} \geqq 1$ and $\operatorname{diam}(\mathrm{M})=\pi / 2$. Then either
(i) M is a twisted sphere, or
(ii) $\tilde{\mathrm{M}}$, the universal covering of M , is isometric to a rank 1 symmetric space, except possibly when M has the integral cohomology ring of the Cayley plane $\mathrm{CaP}^{2}$.

Moreover in the non-simply connected case we have:

[^0]Theorem B. - Let M be as above with non-trivial fundamental group $\pi_{1}(\mathrm{M})=\Gamma$. Then either
(i) $\tilde{M}$ is isometric to $\mathrm{S}^{n}(1)$, and the action of $\Gamma$ on $\mathrm{S}^{n}(1)$ has a proper totally geodesic invariant subsphere $\mathrm{S}^{k}(1)$ in $\mathrm{S}^{n}(1)$, or
(ii) $\tilde{M}$ is isometric to $\mathbb{C} \mathbb{P}^{2 d-1}$ with its standard metric of curvature $1 \leqq \mathrm{~K} \leqq 4$, and $\Gamma$ is isomorphic to $\mathbb{Z}_{2}$ acting on $\mathbb{C} \mathrm{P}^{2 d-1}$ by the involution I ,

$$
\mathrm{I}\left[z_{1}, \ldots, z_{2 \mathrm{~d}}\right]=\left[\bar{z}_{d+1}, \ldots, \bar{z}_{2 d},-\bar{z}_{1}, \ldots,-\bar{z}_{\mathrm{d}}\right],
$$

in homogeneous coordinates of $\mathbb{C P}^{2 d-1}$.
These results were announced in $\left[\mathrm{GG}_{1}\right]$. Special cases of Theorem B were discussed in [SS] and [Sa]. For a classification of spherical space forms we refer to [W].

As the diameter sphere theorem generalizes the classical sphere theorem of Rauch, Berger, and Klingenberg, Theorem A above extends the following well-known rigidity result.

Theorem (Berger). - Let V be a complete simply connected riemannian manifold with $1 \leqq \mathrm{~K} \leqq 4$. Then V is a twisted sphere, or V is isometric to a rank 1 symmetric space.
In fact, the assumptions $1 \leqq \mathrm{~K} \leqq 4$ and V simply connected imply, although non-trivially, that the injectivity radius of V satisfies $\operatorname{inj}(\mathrm{V}) \geqq \pi / 2\left(c f .\left[\mathrm{CG}_{1}\right]\right.$ or $\left.[\mathrm{KS}]\right)$, in particular $\operatorname{diam}(\mathrm{V}) \geqq \pi / 2$.

The paper is divided into five sections. First we construct a "dual" pair of convex sets A and $\mathrm{A}^{\prime}$ in M at maximal distance ( $c f$. also [SS], [Sa], and [S]). In Section 2, using ideas of [GS], we show that the complement of a "tubular" neighborhood of $A \cup A^{\prime}$ in M is topologically a product. This implies in particular: If A and $\mathrm{A}^{\prime}$ are both contractible then M is a twisted sphere (Theorem 2.5). In the remaining cases we prove, in Section 3 , that A and $\mathrm{A}^{\prime}$ have no boundary (one of them is possibly a point), and that any geodesic perpendicular to A gives rise to a minimal connection from $A$ to $\mathrm{A}^{\prime}$, and vice versa. This leads to the construction of a riemannian submersion from the unit normal sphere at any point of $\mathrm{A}^{\prime}$ to A , and vice versa. Our study of metric fibrations in $\left[\mathrm{GG}_{2}\right]$ and $\left[\mathrm{GG}_{3}\right]$ is then used in Section 4 to deal with the simply connected case (Theorem 4.3 and Remark 4.4). In Section 5 we give a similar analysis for the covering space $\tilde{\mathrm{M}}$ of M , when M is not simply connected (Theorem $5.1,5.2,5.3$ ). Theorems A and $B$ are immediate consequences of $2.5,3.2,4.3,5.1,5.2$ and 5.3 .

We refer to [GKM] and [CE] for basic tools and results in riemannian geometry that will be used freely.

## 1. Dual convex sets

The metric distance between points $x, y \in \mathrm{M}$ is denoted by $d(x, y)$, and $d(x, \mathrm{~B})$ is the distance from $x$ to a subset $\mathrm{B} \subset \mathrm{M}$. For a smooth submanifold $\mathrm{V} \subset \mathrm{M}$ and $x \in \mathrm{~V}, \mathrm{~T}_{x} \mathrm{~V}$ and $\mathrm{T}_{x}^{\perp}$ are the tangent and normal spaces of V at $x$, respectively. As usual $\exp _{\mathbf{V}}: T^{\perp} V \rightarrow M$ is the (normal) exponential map, and $C(V)$ is the cutlocus of $V$ in $M$. $4^{e}$ SÉrie - tome $20-1987-\mathrm{N}^{\circ} 2$

All geodesics are parametrized by arc length on [0, ], unless otherwise stated, and L denotes the arc length functional. To specify the initial direction $u \in \mathrm{~T}_{x} \mathrm{M}$ of a geodesic emanating from $x$, we sometimes write $c_{u}$, i. e. $c_{u}(t)=\exp _{x}(t u)$ or $\dot{c}_{u}(0)=u$.

Recall that a hinge at $p$ in M is a triple $\left(c_{1}, c_{2}, \alpha\right)$ where $c_{1}$ and $c_{2}$ are geodesics in M with $c_{1}(0)=\mathrm{c}_{2}(0)=p$ and and $\Varangle\left(\dot{\mathrm{c}}_{1}(0), \dot{c}_{2}(0)\right)=\alpha$, The following version of the basic triangle comparison theorem of Toponogov will be most important to us throughout this paper:

Theorem 1.1 (Toponogov). - Suppose $\mathrm{K} \geqq 1$. Let $\left(c_{1}, c_{2}, \alpha\right)$ be a hinge in M and $\left(\bar{c}_{1}, \bar{c}_{2}, \alpha\right) a$ hinge in $\mathrm{S}^{2}(1)$ with $\mathrm{L}\left(c_{i}\right)=\mathrm{L}\left(\bar{c}_{i}\right)=l_{i}, i=1,2$.
(i) If $c_{1}$ is minimal and $l_{2}<\pi$ then

$$
d\left(c_{1}\left(l_{1}\right), c_{2}\left(l_{2}\right)\right) \leqq d\left(\bar{c}_{1}\left(l_{1}\right), \bar{c}_{2}\left(l_{2}\right)\right) .
$$

(ii) If in addition $0<\alpha<\pi$ and equality holds in (i), then there is a minimal geodesic $c_{3}$ in M from $c_{1}\left(l_{1}\right)$ to $c_{2}\left(l_{2}\right)$ such that: The triangle $\left(c_{1}, c_{2}, c_{3}\right)$ spans an immersed totally geodesic surface in M , of constant curvature 1 , in which the minimal connections from $c_{1}\left(l_{1}\right)$ to $c_{2}(t), 0 \leqq t \leqq l_{2}$, are also minimal in M .

Definition 1.2. - A subset $\mathrm{B} \subset \mathrm{M}$ is totally a-convex, $0<a \leqq \infty$, if for any pair $p_{1}$, $p_{2} \in \mathrm{~B}$ and any geodesic $c:[0, l] \rightarrow \mathrm{M}$ with $c(0)=p_{1}, c(l)=p_{2}$ and $l<a$, one has $c[0, l] \subset \mathrm{B}$.

Obviously, B is totally convex in the sense of $\left[\mathrm{CG}_{2}\right]$ if and only if it is totally $\infty$-convex.
From now on we always assume that $\mathrm{K} \geqq 1$ and $\operatorname{diam}(\mathrm{M})=\pi / 2$.
For any subset $B \subset M$ let $B^{\prime}$ denote the set of points in $M$ at maximal distance $\pi / 2$ from B, i. e.

$$
\mathrm{B}^{\prime}=\left\{x \in \mathrm{M} \left\lvert\, d(x, \mathrm{~B})=\frac{\pi}{2}\right.\right\} .
$$

We refer to $\mathbf{B}^{\prime}$ as the dual set of $\mathbf{B}$ in $\mathbf{M}$.
Proposition 1.3. - $B^{\prime}$ is totally $\pi$-convex.
Proof. - Since clearly $\mathbf{B}^{\prime}=\overline{\mathbf{B}}^{\prime}$ and $\overline{\mathbf{B}}^{\prime}=\bigcap_{p \in \mathbf{B}}\{p\}^{\prime}$, we need only consider the case $\mathrm{B}=\{p\}$. Suppose $d\left(x_{1}, p\right)=d\left(x_{2}, p\right)=\pi / 2$, and let $c$ be a geodesic from $x_{1}$ to $x_{2}$ with $\mathrm{L}(c)<\pi$. Since $x_{1}$ is at maximal distance from $p$, we can choose a minimal geodesic $c_{1}$ from $x_{1}$ to $p$ such that $\alpha=\Varangle\left(\dot{c}_{1}(0), \dot{c}(0)\right) \leqq \pi / 2$. But $\mathrm{L}(c)<\pi$ and $d\left(p, x_{2}\right)=\pi / 2$, and we obtain $\alpha=\pi / 2$ from (i) and $d(p, c(t))=\pi / 2$ for any $0 \leqq t \leqq L(c)$ from (ii) in 1.1.

The following properties of dual sets are obvious:
(i) $\mathrm{B} \subset \mathrm{B}^{\prime \prime}$,
(ii) if $\mathrm{B}_{1} \subset \mathrm{~B}_{2}$ then $\mathrm{B}_{1}^{\prime} \supset \mathrm{B}_{2}^{\prime}$,
and in particular,
(iii) $\mathrm{B}^{\prime}=\mathrm{B}^{\prime \prime \prime}$.

From now on we fix a non-empty set $B \subset M$ with $B^{\prime} \neq \varnothing$ and put $A=B^{\prime}$ (for $B$ we could choose a suitable point). Then $A^{\prime \prime}=A$, i.e.

$$
\mathrm{A}^{\prime}=\left\{x \in \mathrm{M} \left\lvert\, d(x, \mathrm{~A})=\frac{\pi}{2}\right.\right\}, \quad \mathrm{A}=\left\{x \in \mathrm{M} \left\lvert\, d\left(x, \mathrm{~A}^{\prime}\right)=\frac{\pi}{2}\right.\right\}
$$

We refer to A and $\mathrm{A}^{\prime}$ as a dual pair in M . By the structure theorem for convex sets in riemannian manifolds, we know in particular that A and $\mathrm{A}^{\prime}$ are topological manifolds with (possibly empty) boundary whose interior is smooth and totally geodesic (cf. [CG $\left.{ }_{2}\right]$ ).

Let $a=\operatorname{dim} \mathrm{A}$ and $a^{\prime}=\operatorname{dim} \mathrm{A}^{\prime}$.
PROPOSITION 1.4. $-a+a^{\prime} \leqq n-1$.
Proof. - If A or $\mathrm{A}^{\prime}$ is a point the claim is obvious. Assume $a, a^{\prime} \geqq 1$ and choose interior points $x \in \mathrm{~A}, x^{\prime} \in \mathrm{A}^{\prime}$. Let $c$ be a minimal geodesic from $x$ to $x^{\prime}$. Now if $a+a^{\prime} \geqq n$ then there exists a unit parallel field $X$ along $c$ which is tangent to $A$ at $x$ and tangent to $A^{\prime}$ at $x^{\prime}$. Since $M$ has positive curvature, $X$ gives rise to shorter curves connecting $A$ and $\mathrm{A}^{\prime}$, which is a contradiction.

Aside from the intrinsic structure of A and $\mathrm{A}^{\prime}$, their extrinsic properties are equally important. For any subset $B \subset M$ and any $\varepsilon \geqq 0$, consider

$$
{ }^{\varepsilon} \mathbf{B}=\{x \in \mathbf{M} \mid d(x, \mathbf{B}) \leqq \varepsilon\}
$$

Using the compactness of M , one easily obtains the following facts, $c f$. also [Wa].
Lemma 1.5. - There exists an $\varepsilon_{0}>0$ such that for any $\varepsilon$ with $0<\varepsilon \leqq \varepsilon_{0}$ and any closed convex set $\mathrm{C} \subset \mathrm{M}$ :
(i) For each $q \in{ }^{\varepsilon} \mathrm{C}$ there is a unique $q^{*} \in \mathrm{C}$ with $d\left(q, q^{*}\right)=d(q, \mathrm{C})$, and there is a unique minimal geodesic segment $q q^{*}$ from $q$ to $q^{*}$.
(ii) The map $q \rightarrow q^{*}$ from ${ }^{\varepsilon} \mathrm{C}$ to C is Lipschitz. Deforming ${ }^{\varepsilon} \mathrm{C}$ along the geodesic segments $q q^{*}$ to $q^{*}$ defines a strong deformation retract of ${ }^{\varepsilon} \mathrm{C}$ onto C .
(ii) $\partial^{\varepsilon} \mathrm{C}=\{x \in \mathrm{M} \mid d(x, \mathrm{C})=\varepsilon\}$ is a codimension 1 submanifold in M of class $\mathrm{C}^{1}$ and $a$ strong deformation retract of ${ }^{\varepsilon} \mathrm{C} \backslash \mathrm{C}$.

If in the above lemma C has no boundary, everything is of course smooth, and ${ }^{\varepsilon} \mathrm{C}$ is nothing but a tubular neighborhood of C in M .

## 2. Topological duality and the non-rigid case

Following the ideas in [GS] we can now smooth either one of the distance functions $d(, \mathrm{~A})=d_{\mathrm{A}}, d\left(, A^{\prime}\right)=d_{\mathrm{A}^{\prime}}$, and construct a smooth gradient vector field on M , which for sufficiently small $\varepsilon>0$ is transversal to the boundary components $\partial^{\varepsilon} A$ and $\partial^{\varepsilon} A^{\prime}$ of $\mathbf{M}_{\varepsilon}=\mathbf{M} \backslash\left({ }^{\varepsilon} A \cup^{\varepsilon} A^{\prime}\right)$, with no zeros in $\mathbf{M}_{\varepsilon}$. For many purposes it is sufficient to have such a "gradient-like" vector field, which was observed in [G]. This simplifies some arguments. As these constructions are rather straight-forward extensions of those in [GS] (cf. also [G]) we only give a brief discussion.

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$$

Let $\mathrm{H}_{x}$ denote the set of all hinges (c. $\left.c^{\prime}, \alpha\right)$ at $x \in \mathrm{M}_{0}=\mathrm{M} \backslash\left(\mathrm{A} \cup \mathrm{A}^{\prime}\right)$, where $c, c^{\prime}$ are minimal geodesics from $x$ to $A, A^{\prime}$. We define the function $\alpha: M_{0} \rightarrow \mathbb{R}$ by

$$
\alpha(x)=\min \left\{\alpha \mid\left(c, c^{\prime}, \alpha\right) \in \mathrm{H}_{x}\right\}
$$

and conclude

$$
\begin{equation*}
\frac{\pi}{2}<\alpha \leqq \pi \tag{2.1}
\end{equation*}
$$

from 1.1 (i).
We say that $x \in \mathbf{M} \backslash \mathbf{A}$ (resp. $\mathbf{M} \backslash \mathbf{A}^{\prime}$ ) is a critical point for the (non-smooth) function $d_{\mathrm{A}}$ (resp. $d_{A^{\prime}}$ ) if for any non-zero $u \in \mathrm{~T}_{x} \mathrm{M}$ there is a minimal geodesic $c$ from $x$ to A (resp. A') such that $\Varangle(u, \dot{c}(0)) \leqq \pi / 2$. By 2.1 both $d_{\mathrm{A}}$ and $d_{\mathrm{A}^{\prime}}$ have no critical points in $\mathrm{M}_{0}$. As a consequence we obtain the following topological duality between $A$ and $A^{\prime}$ in M.

Theorem 2.2. - Let $0<\varepsilon \leqq \varepsilon_{0}$ as in Lemma 1.5. Then M is $\mathrm{C}^{1}$-diffeomorphic to ${ }^{\varepsilon} \mathrm{A} \cup_{\mathbf{F}}{ }^{\varepsilon} \mathrm{A}^{\prime}$, for some diffeomorphism $\mathrm{F}: \partial^{\varepsilon} \mathrm{A} \rightarrow \partial^{\varepsilon} \mathrm{A}^{\prime}$. In particular A (resp. $\mathrm{A}^{\prime}$ ) is a strong deformation retract of $\mathbf{M} \backslash \mathbf{A}^{\prime}($ resp. $\mathbf{M} \backslash \mathbf{A})$.

Proof. - By 2.1, for any $x \in \overline{\mathrm{M}}_{\varepsilon}$ we find a smooth non vanishing vector field $\mathrm{U}_{x}$ defined in a neighborhood $\mathrm{N}_{x}$ of $x$ in $\mathrm{M}_{0}$ with

$$
\begin{equation*}
\Varangle\left(U_{x}(y), \dot{c}(0)\right)<\frac{\pi}{2} \quad \text { and } \quad<\left(U_{x}(y), \dot{c}^{\prime}(0)\right)>\frac{\pi}{2}, \tag{2.3}
\end{equation*}
$$

for all $y \in \mathrm{~N}_{x}$ and all minimal geodesics $c, c^{\prime}$ from $y$ to $\mathrm{A}, \mathrm{A}^{\prime}$. Let $f_{i}$ be a partition of unity subordinate to the covering $\left\{\mathrm{N}_{x}\right\}$ of $\overline{\mathrm{M}}_{\varepsilon}$. Then $\mathrm{U}=\sum f_{i} \mathrm{U}_{x_{i}}\left\|\sum f_{i} \mathrm{U}_{x_{i}}\right\|$ is a smooth unit vector field on $\overline{\mathrm{M}}_{\varepsilon}$ satisfying 2.3 for all $y \in \overline{\mathrm{M}}_{\varepsilon}$. Notice that by $1.5, \mathrm{U}$ is traversal to both components $\partial^{\varepsilon} \mathrm{A}, \partial^{\varepsilon} \mathrm{A}^{\prime}$ of $\partial \mathrm{M}_{\varepsilon}$. Using 2.3 and the first variation formula, $d_{A}$ is strictly decreasing on any integral curve of U . Now there is a constant $\mathrm{T}>0$ such that any maximal integral curve $\varphi$ with $\varphi(0) \in \partial^{\varepsilon} \mathrm{A}^{\prime}$ will reach $\partial^{\varepsilon} \mathrm{A}$ before time T. Otherwise, by a limiting argument, we would find a local integral curve on which $d_{\mathrm{A}}$ is constant. Therefore we have shown $\overline{\mathbf{M}}_{\varepsilon}$ is $C^{1}$-diffeomorphic with $\partial^{\varepsilon} \mathrm{A}^{\prime} \times[0,1]$ and this is enough to complete the proof.

Remark 2.4. - It is straightforward to modify the construction of the vector field U in the proof of 2.2 so that

$$
\mathrm{U}(c(t))=\dot{c}(t), \quad \varepsilon \leqq t \leqq \frac{\pi}{2}-\varepsilon,
$$

along all minimal geodesics $c$ from $\mathrm{A}^{\prime}$ to A . This will be used in 3.5.
Theorem 2.5. - A (resp. $\mathrm{A}^{\prime}$ ) is contractible iff it is a point or has non-empty boundary. If both A and $\mathrm{A}^{\prime}$ are contractible, then M is homeomorphic to the sphere $\mathrm{S}^{n}$.

This is a direct consequence of Theorem 2.2 and the following

Lemma 2.6. - Let $\mathrm{C} \subset \mathrm{M}$ be a closed convex set and let $\varepsilon>0$ be as in Lemma 1.5. Then ${ }^{\varepsilon} \mathrm{C}$ is homeomorphic (in fact $\mathrm{C}^{1}$-diffeomorphic) to the disc $\mathrm{D}^{n}$ if $\partial \mathrm{C} \neq \varnothing$.

Proof. - First note that if $\operatorname{dim} \mathrm{C}=k$ then C is homeomorphic to the disc $\mathrm{D}^{k}$. This follows from the fact the fact that the function $\psi: \mathrm{C} \rightarrow \mathbb{R}$ given by $\psi(x)=d(x, \partial \mathrm{C})$ is strictly concave since K is positive, $c f$. Theorem 1.10 of $\left[\mathrm{CG}_{2}\right]$. In particular for each $a \geqq 0$, the set

$$
\mathrm{C}^{a}=\{x \in \mathrm{C} \mid d(x, \partial \mathrm{C}) \geqq a\}
$$

is convex, and the intersection of all $\mathrm{C}^{a} \neq \varnothing$ is the unique point $s_{0}$ where $\psi$ has its maximum. In the language of $\left[\mathrm{CG}_{2}\right], s_{0}$ is the soul of C . Now according to Lemma 2.4 of $\left[\mathrm{CG}_{2}\right]$ there is $0<\delta \leqq \varepsilon / 2$ such that

$$
\mathrm{C}^{a} \subset^{\varepsilon / 2}\left(\mathrm{C}^{a^{\prime}}\right)
$$

whenever $0 \leqq a \leqq a^{\prime} \leqq \max \psi$ and $a^{\prime}-a<\delta$. Choose numbers $0=a_{0}<a_{1}<\ldots<a_{r}=\max$ $\psi$ with $a_{i+1}-a_{i}<\delta$ and consider the convex sets

$$
\mathrm{C}=\mathrm{C}^{a_{0}} \supset \mathrm{C}^{a_{1}} \supset \ldots \supset \mathrm{C}^{a_{r}}=\left\{s_{0}\right\} .
$$

Now $\mathrm{C}^{a_{i}} \complement^{\varepsilon / 2}\left(\mathrm{C}^{a_{i+1}}\right)$, and hence ${ }^{\varepsilon / 2}\left(\mathrm{C}^{a_{i}}\right) \subset^{\varepsilon}\left(\mathrm{C}^{a_{i+1}}\right)$ for $i=0, \ldots, r-1$. From 1.5 we then get in particular that for each $q \in \partial^{\varepsilon / 2}\left(\mathrm{C}^{a_{i}}\right)$ there is a closest point $q^{*} \in \mathrm{C}^{a_{i+1}}$ and a unique minimal geodesic from $q$ to $q^{*}$, which intersects $\partial^{\delta / 2}\left(\mathrm{C}^{a_{i+1}}\right)$ at the unique closest point from $q$. The connecting minimal geodesics give rise to a $\mathrm{C}^{1}$-diffeomorphism ${ }^{\varepsilon / 2}\left(\mathrm{C}^{a_{i+1}}\right) \rightarrow{ }^{\varepsilon / 2}\left(\mathrm{C}^{a_{i}}\right)$. Thus we have the following sequence of diffeomorphisms

$$
{ }^{\varepsilon} \mathrm{C} \sim^{\varepsilon / 2}\left(\mathrm{C}^{a_{0}}\right) \sim^{\varepsilon / 2}\left(\mathrm{C}^{a_{1}}\right) \sim \ldots \sim^{\varepsilon / 2}\left(\mathrm{C}^{a_{r}}\right)==^{\varepsilon / 2}\left(s_{0}\right) \sim \mathrm{D}^{n} .
$$

See also [S] for a slightly different proof of Theorem 2.5.
Remark 2.7. - We like to mention that the arguments used in Theorem 2.2 are by now known to also provide a simple and direct proof of the diffeomorphism statement $[\mathrm{P}]$ in the «Soul Theorem" of $\left[\mathrm{CG}_{2}\right]$ : The distance function $d_{\mathrm{S}}$ from a soul S in a complete noncompact manifold M with nonnegative curvature has no critical points outside S . This follows since any $x \in \mathrm{M} \backslash \mathrm{S}$ lies in the boundary of a compact totally convex set C with $\mathrm{S} \subset$ int C , by the basic construction in $\left[\mathrm{CG}_{2}\right]$.

## 3. Normal holonomy of dual sets

From now on we assume that $M$ is not homeomorphic to the sphere $\mathrm{S}^{n}$. In view of Theorem 2.5 this means, at least one of the two dual sets, in this section say A , is not contractible. In particular $\partial \mathbf{A}=\varnothing$ and A is not a point. We will show first that necessarily also $\partial \mathrm{A}^{\prime}=\varnothing$. Then we will prove: The cut locus $\mathrm{C}(\mathrm{A})$ of A in M is the dual set $\mathrm{A}^{\prime}$, and vice versa. The arguments involved will finally lead to the construction of a riemannian submersion from each unit normal sphere of one dual set onto the other. This is a crucial step toward rigidity.
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We begin with the following observation, $c f$. also the proof of Proposition 1.3. For a piecewise smooth curve $\sigma:[0, l] \rightarrow \mathrm{M}$, parallel transport along $\sigma$ is denoted by $\tau_{\sigma}^{t}: \mathrm{T}_{\sigma(0)} \mathrm{M} \rightarrow \mathrm{T}_{\sigma(t)} \mathrm{M}$.

Lemma 3.1. - Let $c:[0, l] \rightarrow \mathrm{A}$ be a geodesic and $c_{u}$ a minimal geodesic from $c(0)$ to $\mathrm{A}^{\prime}$. Then $\tau_{c}^{t}(u)$ defines a minimal geodesic from $c(t)$ to $c_{u}(\pi / 2) \in \mathrm{A}^{\prime}$ for $0 \leqq t \leqq l$. The set of these geodesics form an immersed totally geodesic surface in $M$ of constant curvature 1 .

Proof. - It is sufficient to consider $l<\pi$, and since clearly $\Varangle(u, \dot{c}(0))=\pi / 2$, our claim is a direct consequence of 1.1 (ii) applied to the hinge $\left(c_{u}, c, \pi / 2\right)$.

Now Proposition 1.4, Theorem 2.5 and Lemma 3.1 yield
Theorem 3.2. - If $n=2$ then M is either homeomorphic to $\mathrm{S}^{2}$ or isometric to $\mathbb{R} \mathrm{P}^{2}$ with constant curvature 1 .

Since any smooth curve is a limit of broken geodesics, another immediate consequence of 3.1 is

Corollary 3.3. - Let $\sigma:[0, l] \rightarrow \mathrm{A}$ be a piecewise smooth curve in A and suppose the unit vector $u \in \mathrm{~T}_{\sigma(0)}^{\perp} \mathrm{A}$ defines a minimal geodesic $c_{u}$ to $\mathrm{A}^{\prime}$, i.e. $c_{u}(\pi / 2) \in \mathrm{A}^{\prime}$. Then $\tau_{\sigma}^{t}(u)$ defines a minimal geodesic from $\sigma(t)$ to $c_{u}(\pi / 2)$ for all $0 \leqq t \leqq l$.

Pick a unit normal vector $u \in \mathrm{~T}_{p}^{\perp} \mathrm{A}$ with $c_{u}(\pi / 2)=p^{\prime} \in \mathrm{A}^{\prime}$. Consider the closure E of the set of unit normal vectors to A obtained from $u$ by parallel translation along piecewise smooth paths $\sigma$ in A with $\sigma(0)=p$. Then $\pi: \mathrm{E} \rightarrow \mathrm{A}$ is a sub bundle of the unit normal bundle $\pi: \mathrm{T}_{1}^{\perp} \mathrm{A} \rightarrow \mathrm{A}$ of A in M . To see this let $\mathrm{E}_{q}=\{u \in \mathrm{E} \mid \pi(u)=q\}$ and observe that $\mathrm{E}_{p}$ is the orbit through $u$ of the closure of the normal holonomy group $\Phi_{p}$ at $p$. Furthermore, we have $\mathrm{E}_{q}=\tau_{\sigma}^{l}\left(\mathrm{E}_{p}\right)$ for any $\sigma:[0, l] \rightarrow \mathrm{A}$ from $p$ to $q$. Note in particular that the fiber $\mathrm{E}_{q}$ is a compact homogeneous space.

As a first application of this construction we obtain
Proposition 3.4. - If $\mathrm{A}^{\prime}$ is contractible then $\mathrm{A}^{\prime}=\left\{p^{\prime}\right\}$ is a point and $\mathrm{C}(\mathrm{A})=\left\{p^{\prime}\right\}$, $\mathrm{C}\left(p^{\prime}\right)=\mathrm{A}$.

Proof. - Let $p^{\prime} \in \mathrm{A}^{\prime}$ be arbitrary and $c_{u}$ a minimal geodesic from some $p \in \mathrm{~A}$ to $p^{\prime}$. Consider the bundle $\pi: \mathrm{E} \rightarrow \mathrm{A}$ constructed from $u$ as above. We now claim that $E=T_{1}^{\perp} A$. Since $A^{\prime}$ is contractible the total space $T_{1}^{\perp} A$ is homeomorphic to $S^{n-1}$ by 2.6 and 2.2. Thus if $\mathrm{T}_{1}^{\perp} \mathrm{A} \backslash \mathrm{E} \neq \varnothing$ we see that $\pi: \mathrm{E} G \mathrm{~T}_{1} \mathrm{~A} \rightarrow \mathrm{~A}$ is homotopic to a constant, i. e. there is a homotopy $\mathrm{H}: \mathrm{E} \times[0,1] \rightarrow \mathrm{A}$ with $\mathrm{H}_{0}=\pi$ and $\mathrm{H}_{1}(\mathrm{E})=\{q\}$. Now $\pi \circ \mathrm{id}_{\mathrm{E}}=\mathrm{H}_{0}$, so by the homotopy lifting property of $\pi: \mathrm{E} \rightarrow \mathrm{A}$ we obtain a homotopy $\tilde{\mathrm{H}}: \mathrm{E} \times[0,1] \rightarrow \mathrm{E}$ with $\tilde{\mathrm{H}}_{0}=\mathrm{id}_{\mathrm{E}}$ and $\tilde{\mathrm{H}}_{1}(\mathrm{E}) \subset \mathrm{E}_{q}$. This is clearly impossible since E is a closed manifold, which is not a point. Now by 3.3 any $v \in \mathrm{E}$ defines a minimal geodesic to $p^{\prime}$. This shows that any unit normal vector to $A$ defines a minimal geodesic to $p^{\prime}$. Thus $\mathrm{A}^{\prime}=\left\{p^{\prime}\right\}, \mathrm{C}(\mathrm{A})=\left\{p^{\prime}\right\}$, and then clearly also $\mathrm{C}\left(p^{\prime}\right)=\mathrm{A}$.

As a second application of the holonomy construction above we get similarly
Proposition 3.5. - If $\mathrm{A}^{\prime}$ is not contractible, in particular $\partial \mathrm{A}^{\prime}=\Phi$, then $\mathrm{C}(\mathrm{A})=\mathrm{A}^{\prime}$ and $\mathrm{C}\left(\mathrm{A}^{\prime}\right)=\mathrm{A}$.

Proof. - Consider a bundle $\pi: \mathrm{E} \rightarrow \mathrm{A}$ as before. The diffeomorphism $\mathrm{F}: \partial^{\varepsilon} \mathrm{A} \rightarrow \partial^{\varepsilon} \mathrm{A}^{\prime}$ in 2.2 obtained from the flow of the vector field $U$ of 2.4 induces a diffeomorphism $\hat{F}: T_{1}^{\perp} A \rightarrow T_{1}^{\perp} A^{\prime}$ of the unit normal bundles of $A$ and $A^{\prime}$, via the normal exponential maps. By construction, $\hat{\mathrm{F}}$ imbeds E into the normal sphere $\mathrm{S}_{p^{\prime}}$ of $\mathrm{A}^{\prime}$ at $p^{\prime}$. Thus $\pi: \mathrm{E} \rightarrow \mathrm{A}$ factors through the sphere $\mathrm{S}_{p^{\prime}}$, and we conclude as in 3.4 that $\hat{\mathrm{F}}(\mathrm{E})=\mathrm{S}_{p^{\prime}}$. This proves that $\mathrm{C}\left(\mathrm{A}^{\prime}\right)=\mathrm{A}$, and then also $\mathrm{C}(\mathrm{A})=\mathrm{A}^{\prime}$.

We have seen in 3.4 and 3.5 that for any $p^{\prime} \in \mathrm{A}^{\prime}$ there is a fibration

$$
\pi_{\mathrm{A}}: \quad \mathrm{S}_{p^{\prime}} \rightarrow \mathrm{A}, \quad u^{\prime} \rightarrow \exp \left(\frac{\pi}{2} \cdot u^{\prime}\right)
$$

of the unit normal sphere $\mathrm{S}_{p^{\prime}}$ of $\mathrm{A}^{\prime}$ at $p^{\prime}$ over A . These fibrations impose additional geometric restrictions on A , and by symmetry also on $\mathrm{A}^{\prime}$ if $\mathrm{A}^{\prime} \neq\left\{p^{\prime}\right\}$. The basic reason for this is contained in

Theorem 3.6. - For any $p^{\prime} \in \mathrm{A}^{\prime}$, the fibration $\pi_{\mathrm{A}}: \mathrm{S}_{p^{\prime}} \rightarrow \mathrm{A}$ is a riemannian submersion.
Proof. - By definition $\pi_{\mathrm{A}}$ is clearly smooth. Now let $v \in \mathrm{~T}_{p} \mathrm{~A}$ be a unit tangent vector and choose $u^{\prime} \in \mathrm{S}_{p^{\prime}}$ with $\pi_{\mathrm{A}}\left(u^{\prime}\right)=c_{u^{\prime}}(\pi / 2)=p$. From 3.1 we see that the geodesic $c_{v}$ in A together with the geodesic $c_{u^{\prime}}$ determine a geodesic $\gamma_{w}$ in $S_{p^{\prime}}$ with $\pi_{\mathrm{A}}{ }^{\circ} \gamma_{w}=c_{v^{\prime}}$. This shows that $\pi_{\mathrm{A}}$ is a submersion. Since $w \in \mathrm{~T}_{u^{\prime}}\left(\mathrm{S}_{p^{\prime}}\right)$ is of unit length, all we need to prove is that $w$ is perpendicular to the fiber $\pi_{\mathrm{A}}^{-1}(p)$ in $\mathrm{S}_{p^{\prime}}$ at $u^{\prime}$. Let $\varphi:(-\varepsilon, \varepsilon) \rightarrow \pi_{\mathrm{A}}^{-1}(p)$ be a smooth curve with $\dot{\varphi}(0) \in \mathrm{T}_{u^{\prime}}\left(\mathrm{S}_{p^{\prime}}\right)$. Then $\varphi$ gives rise to a Jacobifield $Y$ along $c_{u^{\prime}}$ with $\mathrm{Y}(0)=0$ and $Y^{\prime}(0)=\varphi^{\prime}(0)$. Similarly $w$ determines a Jacobifield $X$ along $c_{u^{\prime}}$ with $X(0)=0$ and $\mathrm{X}^{\prime}(0)=w$ in $\mathrm{T}_{p^{\prime}}^{\perp} \mathrm{A}^{\prime}$. In fact $\mathrm{X}(t)=\sin t \cdot \mathrm{~W}$, where W is a parallel field along $c_{u^{\prime}}$ determined by $\mathrm{W}(\pi / 2)=v$. If we let $\mathscr{W}$ denote the vector space of parallel fields W along $c_{u^{\prime}}$ with $\mathrm{W}(\pi / 2) \in \mathrm{TA}$, then since $\mathrm{Y}(\pi / 2)=0$, clearly $\langle\mathrm{Y}, \mathrm{W}\rangle=0$ for all $\mathrm{W} \in \mathscr{W}$. Therefore also $\left\langle Y, X^{\prime}\right\rangle=0=\left\langle Y, X^{\prime \prime}\right\rangle$ and hence $\left\langle\mathrm{Y}^{\prime}, \mathrm{X}^{\prime}\right\rangle=0$. In particular

$$
\left\langle\mathrm{Y}^{\prime}(0), \mathrm{X}^{\prime}(0)\right\rangle=\langle\dot{\varphi}(0), w\rangle
$$

i. e. $w$ is perpendicular to any vector tangent to the fiber.

Although we will not use it in what follows, we like to point out an interesting and almost immediate consequence of the results in this section.

Remark 3.7. - Using that $S_{p^{\prime}}$ is isometric to the unit sphere $S^{n-a^{\prime}-1}$ we find that all geodesics in A are periodic with maximal period $\pi$. It then follows that all geodesics in $M$ through $A$ are periodic, and hence from $[B B]$ that the rational cohomology ring of $\tilde{M}$ is generated by one element.

We will, however, make use of the following much stronger and more difficult result.
Remark 3.8. - Suppose A is simply connected. Topologically, the fibers of $\pi_{\mathrm{A}}: \mathrm{S}_{p^{\prime}} \rightarrow \mathrm{A}$ are homotopy spheres $\sum^{k}, k=1,3$ or 7 , and $k=7$ can occur only when $S_{p^{\prime}}=S^{15}[B]$. Except for that case, our work in $\left[\mathrm{GG}_{2}\right]$ and $\left[\mathrm{GG}_{3}\right]$ then implies that $\pi_{\mathrm{A}}: \mathrm{S}_{p^{\prime}} \rightarrow \mathrm{A}$ is metrically congruent to a Hopf fibration. In particular, $A$ is isometric to a rank 1 symmetric space with $1 \leqq K \leqq 4$ and $\operatorname{diam}(\mathrm{A})=\pi / 2$.

We are now ready to complete the metric classification of non-spherical manifolds with $\mathrm{K} \geqq 1$ and diameter $\pi / 2$.

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## 4. Rigidity in the simply connected case

In this section we assume that $M$ is simply connected and not homeomorphic to $S^{n}$. In particular $n \geqq 3$, and the dual sets A and $\mathrm{A}^{\prime}$ in M are totally geodesic closed submanifolds, totally $\pi$-convex, one of them possibly a point. It is an immediate consequence of 3.1 that all geodesics in $\mathrm{A}, \mathrm{A}^{\prime}$ are periodic with common (not smallest) period $2 \pi$.

Lemma 4.1. - Any closed geodesic of lenth $<2 \pi$ in $A, \mathrm{~A}^{\prime}$ is homotopically trivial in $\mathrm{A}, \mathrm{A}^{\prime}$.

Proof. - Let $c$ be a closed geodesic of length $l$ in A, i. e. $\dot{c}(l)=\dot{c}(0)$. If $l<2 \pi$, then $l=2 \pi / k$ for some integer $k \geqq 2$, in particular $l \leqq \pi$. Let $p=c(0), q=c\left(t_{0}\right)$ for some $t_{0} \in(0, l)$, and consider the two (not normal) geodesics $\gamma_{i}$ in A defined by

$$
\gamma_{0}(s)=c\left(s t_{0}\right), \quad \gamma_{1}(s)=c\left(l-s\left(l-t_{0}\right)\right)
$$

and $0 \leqq s \leqq 1$. Now let $\left\{\gamma_{t}\right\}, 0 \leqq t \leqq 1$, be a homotopy of smooth curves in $\mathbf{M}$ from $\gamma_{0}$ to $\gamma_{1}$. Since any geodesic in M from $p$ to $q$ of length $>\pi$ has index $\geqq n-1 \geqq 2$ we conclude from (degenerate) Morse theory (cf. $\left[\mathrm{CG}_{1}\right]$ ) that we may assume $\mathrm{L}\left(\gamma_{t}\right) \leqq \pi$ for $0 \leqq t \leqq 1$. If for some $t$, we have $\gamma_{t}[0,1] \cap \mathrm{A}^{\prime} \neq \varnothing$, then clearly $\gamma_{t}$ is a geodesic of length $\pi$ and $\gamma_{t}$ on $[0,1 / 2]$ is a minimal geodesic from $p$ to $\mathrm{A}^{\prime}$. It then follows from 3.1 that $q=\gamma_{t}(1)=c(\pi)$. By choosing $t_{0}$ so that $c(\pi) \neq c\left(t_{0}\right)=q$ we conclude that for all $0 \leqq t \leqq 1$ necessarily $\gamma_{t}[0,1] \subset \mathbf{M} \backslash \mathbf{A}^{\prime}$. Now 2.2 implies that $\gamma_{0}$ and $\gamma_{1}$ are homotopic in $\mathbf{A}$, or equivalently, $c$ is homotopically trivial in $\mathbf{A}$.

Proposition 4.2. - $A$ and $\mathrm{A}^{\prime}$ are simply connected.
Proof. - Suppose A is not simply connected. Let $c:[0, l] \rightarrow$ A be a closed geodesic in A of minimal length in its free homotopy class. Then $l=2 \pi$ by 4.1 and $\operatorname{dim} A=a=1$ by standard comparison and the minimality of $c$, i. e. $A=c[0,2 \pi]$ is a simple closed geodesic of length $2 \pi$. This is impossible because $A$ is totally $\pi$-convex and $\operatorname{diam}(M)=\pi / 2$.

We are now in a position to prove
Theorem 4.3. - If M is simply connected and not homeomorphic to $\mathrm{S}^{n}$, then M is isometric to a symmetric space of rank 1 , except possibly when $\mathrm{M}=\mathrm{M}^{16}$ has the integral cohomology ring of $\mathbb{C a P}^{2}$.

Proof. - First suppose $\mathrm{A}, \mathrm{A}^{\prime}$ is a dual pair, and say $\mathrm{A}^{\prime}=\left\{p^{\prime}\right\}$. By 3.4, all geodesics in $M$ starting at $p^{\prime}$ are simple loops of length $\pi$. The generalized version of the Bott-Samelson Theorem in [Be] then implies that $M$ has the integral cohomology ring of a projective space $\mathrm{P}^{m}, m \geqq 2$. Consider the riemannian submersion $\pi_{\mathrm{A}}: \mathrm{S}_{p^{\prime}} \rightarrow \mathrm{A}$ in 3.6. By the main results of $\left[\mathrm{GG}_{2}\right]$, $\left[\mathrm{GG}_{3}\right](c f .3 .8), \pi_{\mathrm{A}}$ is isometrically equivalent to a Hopf fibration $\mathrm{S}^{k m-1} \rightarrow \mathrm{P}^{m-1}(k)$, except possibly when $\mathrm{S}_{p^{\prime}}=\mathrm{S}^{15}$ and $\pi_{\mathrm{A}}$ has fibers diffeomorphic to $\mathbf{S}^{7}$, in our case. In this last case, $\mathrm{M}^{16}$ has the integral cohomology ring of the Cayley plane $\mathbb{C a P}^{2}$. In all the other cases we will now prove that $M$ is isometric to standard $P^{m}(k)$ with diameter $\pi / 2$.

In the model space, for $p_{0}^{\prime} \in \mathrm{P}^{m}(k)$, we have

$$
\mathrm{A}_{0}=\left\{p_{0}^{\prime}\right\}^{\prime}=\mathrm{C}\left(p_{0}^{\prime}\right)=\mathrm{P}^{m-1}(k)
$$

and $\pi_{\mathrm{A}_{0}}: \mathrm{S}_{p_{0}^{\prime}} \rightarrow \mathrm{A}_{0}$ in 3.6 is a standard Hopf fibration. According to 3.8, we have the commutative diagram

$$
\begin{aligned}
& \mathrm{S}_{p^{\prime}} \longrightarrow \mathrm{S}_{p_{0}^{\prime}}=\mathrm{S}^{k m-1} \\
& \pi_{\mathrm{A}} \\
& \mathrm{~A} \int_{\imath}^{\pi_{\mathrm{A}_{0}}} \\
& \mathrm{~A}_{0}=\mathrm{P}^{m-1}(k)
\end{aligned}
$$

with isometries $\mathbf{1}, \mathrm{l}_{0}$. Clearly,

$$
f: \quad \mathrm{M} \rightarrow \mathrm{P}^{m}(k), \quad \exp _{p^{\prime}}(t u) \rightarrow \exp _{p_{0}^{\prime}}\left(t \mathrm{t}_{0} u\right)
$$

$0 \leqq t \leqq \pi / 2$, is a well defined continuous map and $\left.f\right|_{\mathbf{A}}=\mathbf{1}$. By definition, $f$ maps minimal geodesics in M from $p^{\prime}$ to $p \in \mathrm{~A}$ to minimal geodesics in $\mathrm{P}^{m}(k)$ from $p_{0}^{\prime}$ to $f(p)$. The set of all such geodesics in $\mathrm{P}^{m}(k)$ form a totally geodesic submanifold isometric to the sphere $\mathrm{S}^{k}(1 / 2)$ with diameter $\pi / 2$. We claim that the same statement holds in M . In fact let $\mathrm{B} \subset \mathrm{A}$ be the dual set of $p$ in A . Then $\mathrm{B}=\mathrm{A} \cap\{p\}^{\prime}$ is a totally geodesic, $\pi$-convex submanifold of M isometric to standard $\mathrm{P}^{m-2}(k)$. Note that $\{p\}^{\prime \prime}=\{p\}$. All this depends on A being isometric to standard $\mathrm{P}^{m-1}(k)$. Now $\mathrm{B}^{\prime} \subset \mathrm{M}$ is a totally geodesic, totally $\pi$-convex submanifold of $M$ which contains the set of minimal geodesics from $p$ to $p^{\prime}$. Moreover, for any $q \in B, \pi_{B^{\prime}}: S_{q} \rightarrow B^{\prime}$ is a riemannian submersion from the unit normal sphere $S_{q}=S^{2 k-1}(1)$ to $B^{\prime}$. Again by $3.8, B^{\prime}$ is isometric to $S^{k}(1 / 2)$ and coincides with the set of minimal geodesics from $p$ to $p^{\prime}$. It is now an immediate consequence that $f$ maps $\mathrm{M} \backslash \mathrm{A}$ isometrically onto $\mathrm{P}^{m}(k) \backslash \mathrm{A}_{0}$, and therefore $f$ is globally isometric.

To complete the proof, we need to find a dual pair $\mathrm{A}, \mathrm{A}^{\prime}=\left\{p^{\prime}\right\}$. If $\mathrm{A}, \mathrm{A}^{\prime}$ is a dual pair, A symmetric, then $\{p\}^{\prime \prime}=\{p\}$ for any $p \in \mathrm{~A}$, as we have seen, and we are done. By 3.8 it only remains to analyze the possibility $\operatorname{dim} \mathrm{A}=\operatorname{dim} \mathrm{A}^{\prime}=8$ and $\operatorname{dim} \mathrm{M}=24$. Fix $p \in \mathrm{~A}, p^{\prime} \in \mathrm{A}^{\prime}$ and consider the set of minimal geodesics from $p$ to $p^{\prime}$. By construction of $\pi_{\mathrm{A}}, \pi_{\mathrm{A}^{\prime}}$ we see that in this case the closure G of the normal holonomy group at $p^{\prime}$ acts on $S_{p}{ }^{\prime}=S^{15}$, and the orbits are exactly the fibres of $\pi_{A}$. But such an action does not exist. A simple argument in our context can be given as follows: Let $h \in \mathrm{G}$ have a fixed point $x=h x$. Then the differential $h_{*}$ is the identity on the normal space $v_{x}$ of the orbit $\mathrm{G} x$ at $x$, and thus $h=\mathrm{id}$ on the great sphere $\exp \left(v_{x}\right)$. Now let $y \in \mathrm{~S}_{p^{\prime}}$ be arbitrary. The intersection of $\exp \left(v_{x}\right)$ and $\exp \left(v_{y}\right)$ contains a point $z$, for dimension reasons. But $z=h z$ and $y \in \exp \left(v_{z}\right)$, so by the above also $y=h y$, and we conclude that $h \equiv \mathrm{id}$. Therefore, G would act freely on $S_{p^{\prime}}$, which is impossible, since the fibers are 7-spheres and thus not diffeomorphic to a Lie group.

Remark 4.4. - It is clear from the above proof, that part (ii) of Theorem A in the introduction holds without any restriction, if the only Riemannian fibration from the euclidian sphere $S^{15}(1)$ with fiber $S^{7}$ is the Hopf fibration, up to congruence.
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## 5. Rigidity in the non-simply connected case

In this section we assume that $M$ is not simply connected. Let $\tilde{M} \rightarrow M$ be the universal riemannian covering of $\mathbf{M}$. Clearly, $\tilde{\mathbf{M}}$ satisfies $K \geqq 1$ and $\pi / 2 \leqq \operatorname{diam}(\tilde{\mathbf{M}}) \leqq \pi$.

We first observe
Theorem 5.1. - If M is not simply connected and say $\mathrm{A}^{\prime}=\left\{p^{\prime}\right\}$, then M is isometric to real projective space $\mathbb{R} \mathrm{P}^{n}$ of constant curvature 1 .

Proof. - Since $\mathrm{A}^{\prime}=\left\{p^{\prime}\right\}$ is totally $\pi$-convex, the fiber $\pi^{-1}\left(p^{\prime}\right)$ consists of two points $\tilde{p}_{1}$ and $\tilde{p}_{2}$ with $d\left(\tilde{p}_{1}, \tilde{p}_{2}\right)=\pi$. Therefore $\pi_{1}(\mathbf{M}) \cong \mathbb{Z}_{2}$, and $\tilde{\mathbf{M}}$ is isometric to the sphere $S^{n}(1)$ by Toponogov's Diameter Theorem. Hence $M$ is isometric to $\mathbb{R} P^{n}$.

Now let $\tilde{\mathrm{A}}, \tilde{\mathrm{A}}^{\prime}$ be the inverse image of $\mathrm{A}, \mathrm{A}^{\prime}$ under the covering projection $\tilde{\mathrm{M}} \rightarrow \mathrm{M}$. In the case left, $\tilde{\mathrm{A}}$ and $\tilde{\mathrm{A}}^{\prime}$ are connected, totally geodesic and totally $\pi$-convex closed submanifolds of $\tilde{\mathbf{M}}$, with dimensions $a, a^{\prime} \geqq 1$. Observe that for any $\tilde{x} \in \tilde{\mathrm{M}}$, we have $\max \left\{d_{\tilde{\mathrm{A}}}(\tilde{x}), d_{\tilde{\mathrm{A}}},(\tilde{x})\right\} \leqq \pi / 2$, and using the notation from Section 2 ,

$$
(\tilde{\mathrm{A}})^{\prime}=\tilde{\mathrm{A}}^{\prime} \quad \text { and } \quad\left(\tilde{\mathrm{A}}^{\prime}\right)^{\prime}=\tilde{\mathrm{A}}
$$

Hence, by arguments exactly like those in the proof of 2.2 , it follows that $\tilde{\mathbf{M}}$ is the disjoint union

$$
\tilde{\mathbf{M}}={ }^{\varepsilon} \tilde{\mathrm{A}} \cup \tilde{\mathbf{M}}_{\varepsilon} \cup^{\varepsilon} \tilde{\mathrm{A}}^{\prime} .
$$

The closure of $\tilde{\mathbf{M}}_{\varepsilon}$ is diffeomorphic to the product $\partial^{\varepsilon} \tilde{\mathrm{A}} \times[0,1]$. This leads to the following reduction.

Theorem 5.2. - If $\mathbf{M}$ is not simply connected and $\operatorname{diam}(\tilde{\mathrm{M}})>\pi / 2$, then $\tilde{\mathrm{M}}$ is isometric to $\mathrm{S}^{n}(1)$, and the induced orthogonal action of $\pi_{1}(\mathrm{M})$ on $\mathbb{R}^{n+1}$ has a proper invariant subspace.

Proof. - As in the proofs of 4.1 and 4.2 we see that $\tilde{\mathrm{A}}$ (resp. $\widetilde{\mathrm{A}}^{\prime}$ ) is either simply connected or a closed geodesic of length $2 \pi$. In the latter case we conclude diam $(\tilde{\mathrm{M}})=\pi$, since $\tilde{\mathrm{A}}$ is totally $\pi$-convex, and hence by Toponogov's Diameter Theorem, $\tilde{\mathrm{M}}$ is isometric to $S^{n}(1)$. Otherwise, using the above topological description of $\tilde{M}$, a simple transversality argument shows for the inclusion $i_{\tilde{A}}: \tilde{\mathrm{A}} \rightarrow \tilde{\mathrm{M}}$, that in homotopy

$$
\left(i_{\tilde{\mathrm{A}}}\right)_{*}: \quad \pi_{q}(\tilde{\mathrm{~A}}) \rightarrow \pi_{q}(\tilde{\mathrm{M}})
$$

is injective for $q \leqq n-a^{\prime}-2$, and surjective for $q \leqq n-a^{\prime}-1$. An analogous conclusion holds for $\left(i_{\tilde{\mathbf{A}}^{\prime}}\right)_{*}$. This implies that $a+a^{\prime}=n-1$, since by the Main Theorem in [GS], M is homeomorphic to $S^{n}$. Then by 3.6 , both $\tilde{A}$ and $\tilde{A}^{\prime}$ are of constant curvature 1 , and hence isometric to $S^{a}(1)$ and $S^{a^{\prime}}(1)$, respectively. Again by Toponogov's Diameter Theorem $\tilde{\mathrm{M}}$ is isometric to $S^{n}(1)$. Moreover, in either of the above cases $\tilde{\mathrm{A}}, \tilde{\mathrm{A}}^{\prime}$ is a $\pi_{1}(\mathrm{M})$-invariant pair of orthogonal (complementary) great spheres in $S^{n}(1)$. This completes the proof (cf. also 5.1).

It remains to consider the case $\operatorname{diam}(\tilde{\mathrm{M}})=\pi / 2$. In this case $\tilde{\mathrm{M}}$ has the integral cohomology ring of a projective space $\mathrm{P}^{m}(k), m \geqq 2$, by 4.3. In particular, $\operatorname{dim} \mathrm{M}$ is
even. By Synge's Theorem $\pi_{1}(M) \cong \mathbb{Z}_{2}$, and there is a fixed point free orientation reversing isometric involution $\mathrm{I}: \tilde{\mathrm{M}} \rightarrow \tilde{\mathrm{M}}$ and $\mathrm{M}=\tilde{\mathbf{M}} / \tilde{x} \sim \mathrm{I}(\tilde{x})$. Such a map does not exist for cohomological reasons when $m$ is even. In the remaining cases $\tilde{\mathbf{M}}$ is isometric to a standard projective space by 4.3. It is however well-known [W] that the isometry group of the quaternionic projective space $\mathrm{P}^{m}(4)=\mathscr{H} \mathrm{P}^{m}$ is connected and hence contains no orientation reversing element.

Now we are only left with a question about possible fixed point free isometric involutions on $\mathrm{P}^{m}(2)=\mathbb{C} \mathrm{P}^{m}$, for $m=2 d-1$ odd and with quotients of diameter $\pi / 2$. It is not difficult to see from our constructions that any quotient of $\mathbb{C} \mathrm{P}^{2 d-1}$ by a fixed point free involution actually has diameter $\pi / 2$. By induction on $d$, any two such quotients are isometric. As far as existence is concerned, the map

$$
\text { I: } \mathbb{C} \mathrm{P}^{2 d-1} \rightarrow \mathbb{C} \mathrm{P}^{2 d-1},\left[z_{1}, \ldots, z_{2 d}\right] \rightarrow\left[\bar{z}_{d+1}, \ldots, \bar{z}_{2 d},-\bar{z}_{1}, \ldots,-\bar{z}_{d}\right]
$$

in homogeneous coordinates is a fixed point free isometric involution on $\mathbb{C} \mathrm{P}^{\mathbf{2 d - 1}}$.
Summarizing the last conclusions we have
Theorem 5.3. - If M is not simply connected and not of constant curvature 1 , then M is isometric to $\mathbb{C} \mathrm{P}^{2 d-1} / \mathrm{I}$.

This finally completes the proofs of Theorems A and B in the introduction.

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(Manuscrit reçu le 12 mai 1986, révisé le 7 janvier 1987).

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[^0]:    ${ }^{(1)}$ This work was partially supported by the National Science Foundation (Grant MCS 7802679A03) and the Danish Natural Science Research Council (511-8169, 10060).

