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Skorokhod Imbedding via Stochastic Integrals

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Given a Brownian motion L_t and a probability measure μ on \mathbb{R} with mean 0, a Skorokhod imbedding of μ is a stopping time T adapted to the sigma fields of L_t such that L_T has distribution μ . We give here a new method of constructing such an imbedding using results from the representation of martingales as stochastic integrals.

We first construct a Brownian motion N_t and a stopping time W such that N_W has law μ . We then show how, given an arbitrary Brownian motion L_t , one can construct a stopping time T such that L_T has law μ .

Define $p_t(y) = (2\pi t)^{-1/2} e^{-y^2/2t}$, $q_t(y) = \partial p_t(y)/\partial y = -(2\pi t)^{-1/2} (y/t) e^{-y^2/2t}$.

Let X_t be a Brownian motion, \mathbb{F}_t its filtration, and g a real-valued function.

Lemma 1. Suppose $E|g(X_1)| < \infty$. Then

a) $\sup_{|y| \leq y_0} \int |g(z)| |z-y|^k e^{-(z-y)^2/2t} dz < \infty$ for all positive k , all y_0 , all $t < 1$.

b) $g(X_1) = Eg(X_1) + \int_0^1 a(s, X_s) dX_s$, where $a(s, y) = \int q_{1-s}(z-y) g(z) dz$ for $s < 1$; furthermore $\int_0^1 a^2(s, X_s) ds < \infty$, a.s.

c) $E(g(X_1) | \mathbb{F}_s) = b(s, X_s)$ for $s < 1$, where $b(s, y) = \int p_{1-s}(z-y) g(z) dz$.

Proof. a) follows from the formula for the normal density and the fact that

$$|z-y|^k e^{-(z-y)^2/2t} \leq e^{-z^2/2} \text{ for } z \text{ large.}$$

b) Suppose first that g is bounded, has compact support, and is in C^2 .

By Clark's formula [1] applied to the functional $g(X_1)$,

$$g(X_1) = Eg(X_1) + \int_0^1 E[g'(X_1) | \mathbb{F}_s] dX_s.$$

(Another derivation of this representation is to use Ito's lemma to take care of the case $g(x) = e^{iux}$ and then use linearity and a limiting process.)

By the Markov property, if $s < 1$,

$$E[g'(X_1) | \mathbb{F}_s] = \int g'(z) p_{1-s}(X_s - z) dz .$$

An integration by parts gives the result for such g ; the result for general g follows by a limit argument.

c) By the Markov property, if $s < 1$,

$$E[g(X_1) | \mathbb{F}_s] = \int g(z) p_{1-s}(X_s - z) dz . \quad \square$$

Lemma 2. Suppose g is nondecreasing and not identically constant. Then

- a) On compact subsets of $[0,1) \times \mathbb{R}$, $a(s,y)$ is bounded above, bounded below away from 0, and uniformly Lipschitz in s and y .
- b) For each $s < 1$, $b(s,y)$ is continuous and strictly increasing as a function of y .
- c) For each $s < 1$, let $B(s,\cdot)$ be the inverse of $b(s,\cdot)$; then on compact subsets of its domain, $B(s,y)$ is uniformly Lipschitz in s and jointly continuous in s and y .

Proof. a) Suppose $|y| \leq y_0, s \leq s_0 < 1$. $a(s,y)$ is bounded above by lemma 1a. An integration by parts argument shows that $a(s,y) = \int p_{1-s}(y-z) dg(z)$, hence a is bounded below. Using the definition of $a(s,y)$, appropriate bounds on $\partial q_{1-s}/\partial s$ and $\partial q_{1-s}/\partial y$, and lemma 1a gives the uniformly Lipschitz result.

b) The definition of b shows that $b(s,\cdot)$ is continuous. Since we also have $b(s,y) = \int g(y+z) p_{1-s}(z) dz$, it follows that $b(s,\cdot)$ is nondecreasing, and in fact, strictly increasing since g is not constant. Note that this implies that the range of $b(s,\cdot)$ must be an open (possibly infinite) interval.

c) Since $b(s,\cdot)$ is continuous and strictly increasing, we can define its inverse $B(s,\cdot)$ on the range of $b(s,\cdot)$. $B(s,y)$ will be continuous in y .

Integrating by parts,

$$\partial b / \partial y = \int p_{1-s}(y-z) dg(z) ,$$

which is uniformly > 0 for s,y in a compact subset of $[0,1) \times \mathbb{R}$. $\partial b / \partial s$ is bounded above on compact sets since $\partial p_{1-s} / \partial s$ is, using lemma 1a again.

We now show that B is uniformly Lipschitz in s , s,y in a compact subset of the domain of B . Let $w = B(s+h,y)$, $x = B(s,y)$, and suppose $w \leq x$,

the other case being similar. Then

$$0 = b(s+h,w) - b(s,x) = b(s+h,w) - b(s,w) + b(s,w) - b(s,x) \leq C|h| - c(x-w),$$

$$\text{or } |x-w| \leq C|h| / c ,$$

where C and c are upper and lower bounds for $\partial b/\partial s$ and $\partial b/\partial y$, respectively.

This proves that B is uniformly Lipschitz in s , and it follows immediately

that B is jointly continuous. \square

Now let μ be a probability measure on \mathbb{R} and suppose $\int |x| d\mu(x) < \infty$ and $\int x d\mu(x) = 0$. Let $F(x) = \mu(-\infty, x]$, let $F^{-1}(y) = \inf\{x: F(x) \geq y\}$, let $\Phi(x) = \int_{-\infty}^x p_1(y) dy$, and let $g(x) = F^{-1}(\Phi(x))$. Then $g(X_1)$ has distribution μ and $Eg(X_1) = 0$.

Define $M_t = \int_0^t a(s, X_s) dX_s$, where $a(s, y)$ is given by lemma 1 for $s < 1$, $a(s, y) = 1$ for $s \geq 1$. Note $M_1 = g(X_1)$ has law μ , and if $s < 1$, $M_s = b(s, X_s)$. Let $R(t) = \int_0^t a^2(s, X_s)$, define $S(t) = \inf\{r: R(r) \geq t\}$, and let $N_t = M_{S(t)}$. Since the quadratic variation of the continuous martingale N is t , N is a Brownian motion.

$N_{R(1)} = M_1$, which has law μ . Letting $W = R(1)$, it suffices to show that $R(1)$ is a stopping time of the N_t process.

Proposition 3. (cf. Yershov, [2]). $(W \geq u)$ is in the right continuous completion of $\sigma(N_s; s \leq u)$.

Proof. Since $W = R(1) = \lim_{s \uparrow 1} R(s)$ by monotone convergence, it suffices to consider $R(s)$, $s < 1$. $(R(s) \geq u) = (s \geq S(u))$.

It is not hard to see that $S(t)$ satisfies the equation

$$\frac{dS(t)}{dt} = a^{-2}(S(t), X_{S(t)})$$

if $S(t) < 1$. But $X_{S(t)} = B(S(t), M_{S(t)}) = B(S(t), N_t)$. Thus, for each ω , $S(t)$ satisfies the ordinary differential equation

$$(1) \quad \frac{dS(t)}{dt} = a^{-2}(S(t), B(S(t), N_t)) .$$

For each ω , $\{(S(t), N_t): S(t) \leq s\}$ is contained in a compact subset of the domain of B . This, lemma 2, and a theorem on uniqueness of solutions of

differential equations [3, pp.1-6] show that there is a unique solution $S(t)$ to (1) up to the first t for which $S(t) = s$. Moreover, this solution may be constructed via Picard iteration. But then $(s \geq S(u))$ is in the right continuous completion of $\sigma(N_s; s \leq u)$ as required. \square

Suppose now that L is any Brownian motion. We construct an L -measurable stopping time T such that L has law μ . Let $V(t)$ be the unique solution to

$$\frac{dV(t)}{dt} = a^{-2}(V(t), B(V(t), L_t))$$

for each ω . (Since L_t has the same law as N_t , $\{(V(t), L_t): V(t) \leq s\}$ will be in a compact subset of the domain of B , a.s.) Let $U(t) = V^{-1}(t)$, $t < 1$ and let $T = U(1) = \sup_{s < 1} U(s)$. Clearly the law of (L, T) is the same as the law of (N, W) , and so L_T has distribution μ .

$T^{1/2}$ will satisfy certain moment conditions if μ does. For example, suppose $\Psi: [0, \infty) \rightarrow [0, \infty)$ is continuous, $\int \Psi(|x|) d\mu(x) < \infty$, and for some $\epsilon > 0$, $\Psi^{1/(1+\epsilon)}$ is convex and increasing. By Doob's inequality applied to the submartingale $\Psi^{1/(1+\epsilon)}(|M_s|)$, $E \sup_{s \leq 1} \Psi(|M_s|) < \infty$ since $E \Psi(|M_1|) < \infty$. Then by Burkholder's inequality, $E \Psi(W^{1/2}) < \infty$.

If Y_t is a d -dimensional Brownian motion, $d \geq 2$, it is known that there are measures μ for which one cannot find a stopping time T with μ the law of Y_T : just take μ atomic and recall that d -dimensional Brownian motion does not hit points. However, one can always find $f: \mathbb{R} \rightarrow \mathbb{R}^d$ such that the law of $f(X_1)$ is μ , X_t a 1-dimensional Brownian motion. (The coordinate functions of f are not assumed to be nondecreasing.) One can then use lemma 1 to find a vector-valued function $A: [0, 1) \times \mathbb{R} \rightarrow \mathbb{R}^d$ such that $f(X_1) = Ef(X_1) + \int_0^1 A(s, X_s) dX_s$.

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