# RENDICONTI del Seminario Matematico della Università di Padova

## D. BAINOV

## V. PETROV

# Oscillation and asymptotic behaviour of neutral equations with distributed delay

Rendiconti del Seminario Matematico della Università di Padova, tome 95 (1996), p. 253-261

<a>http://www.numdam.org/item?id=RSMUP\_1996\_\_95\_\_253\_0></a>

© Rendiconti del Seminario Matematico della Università di Padova, 1996, tous droits réservés.

L'accès aux archives de la revue « Rendiconti del Seminario Matematico della Università di Padova » (http://rendiconti.math.unipd.it/) implique l'accord avec les conditions générales d'utilisation (http://www.numdam.org/conditions). Toute utilisation commerciale ou impression systématique est constitutive d'une infraction pénale. Toute copie ou impression de ce fichier doit contenir la présente mention de copyright.

# $\mathcal{N}$ umdam

Article numérisé dans le cadre du programme Numérisation de documents anciens mathématiques http://www.numdam.org/ REND. SEM. MAT. UNIV. PADOVA, Vol. 95 (1996)

## Oscillation and Asymptotic Behaviour of Neutral Equations with Distributed Delay.

D. BAINOV(\*) - V. PETROV(\*\*)

ABSTRACT - Consider the neutral differential equation

$$\left[x(t) + \int_{0}^{\sigma(t)} x(t-s) d_{s} r_{1}(t, s)\right]' + \int_{0}^{\sigma(t)} x(t-s) d_{s} r_{2}(t, s) = 0.$$

The asymptotic properties of the nonoscillatory solutions of the equation are studied. Sufficient conditions are also given to guarantee that all solutions oscillate.

### 1. - Introduction.

In the recent few years a considerable number of papers were published, devoted to the oscillatory properties of first order linear neutral differential equations. Up to now equations of the following form have been investigated

$$[x(t) + px(t - \tau)]' + qx(t - \sigma) = 0,$$
  

$$[x(t) + p(t)x(t - \tau)]' + q(t)x(t - \sigma) = 0,$$
  

$$\left[x(t) + \sum_{i=1}^{k} p_i x(t - \tau_i)\right]' + \sum_{i=1}^{m} q_i x(t - \sigma_i) = 0,$$
  

$$\left[x(t) + \sum_{i=1}^{k} p_i(t)x(t - \tau_i)\right]' + \sum_{i=1}^{m} q_i(t)x(t - \sigma_i) = 0.$$

(\*) Indirizzo dell'A.: Academy of Medicine, Sofia, Bulgaria.

(\*\*) Indirizzo dell'A.: Higher Institute of Mechanical and Electrical Engineering, Centre of Mathematics, Plovdiv, Bulgaria. To these equations the papers [1]-[3], [6]-[10] were devoted. We shall note that nonautonomous neutral differential equations with distributed delay have not been studied up to now.

In the present paper the equation

(1) 
$$\left[x(t) + \int_{0}^{\sigma(t)} x(t-s) d_{s} r_{1}(t, s)\right]' + \int_{0}^{\sigma(t)} x(t-s) d_{s} r_{2}(t, s) = 0$$

is investigated with initial function  $\varphi(t) \in C([a, t_0], \mathbb{R})$ ,  $(a = \inf_{\substack{t \ge t_0}} \{t - -\sigma(t)\})$ , where the integrals in (1) are in the sense of Riemann-Stieltjes. Some ideas of [2] are developed, the asymptotic behaviour of (1) is investigated and sufficient conditions for oscillation of all solutions of (1) are obtained.

## 2. – Preliminary notes.

We shall say that conditions (A) are met if the following conditions hold:

A1) 
$$\sigma(t) \in C([t_0, \infty), (0, \infty)),$$
  
A2)  $\lim_{t \to \infty} (t - \sigma(t)) = \infty.$ 

Conditions (A) imply that  $a = \inf_{t \ge t_0} (t - \sigma(t)) > -\infty$ . Introduce conditions (B):

B1) 
$$x \in C([a, \infty), \mathbb{R}),$$
  
B2)  $x(t) + \int_{0}^{\sigma(t)} x(t-s) d_s r_1(t, s) \in C^1([t_0, \infty), \mathbb{R}).$ 

Consider equation (1) with the initial condition

(2) 
$$x(t) = \varphi(t), \quad t \in [a, t_0].$$

DEFINITION 1. The function x(t), satisfying conditions (B) is said to be a solution of the initial value problem (1)-(2) if x(t) satisfies (1) for  $t \ge t_0$  and if the relation (2) holds.

Introduce the following conditions (C):

- C1)  $r_i(t, 0) = 0, t \in [t_0, \infty), i = 1, 2.$
- C2)  $r_i(t, \sigma(t)) \in C([t_0, \infty), \mathbb{R}), i = 1, 2.$
- C3)  $r_1(t, s)$  is continuous at s = 0 for any fixed  $t \in [t_0, \infty)$ .

C4) The functions  $v_i(t) = \sup_{s \in [0, \sigma(t)]} |r_i(t, s)|, t \ge t_0, i = 1, 2$  are bounded.

C5) For any fixed  $t \ge t_0$ ,  $r_i(t, s)$  are functions of bounded variation with respect to s in  $[0, \sigma(t)]$ .  $\min_{\{\sigma(t_1), \sigma(t)\}}$ 

C6) 
$$\lim_{t_1 \to t} \int |r_i(t_1, s) - r_i(t, s)| ds = 0, \ i = 1, 2.$$

LEMMA 1. Let conditions (A) and (C) hold. Then for any initial function  $\varphi(t) \in C([a, t_0], \mathbb{R})$  the initial value problem (1)-(2) has an unique solution.

Lemma 1 is obtained as a corollary of [4]. Introduce the following conditions (D):

D1)  $r_1(t, s)$  is nonincreasing with respect to s for  $s \in [0, \sigma(t)]$ . D2)  $r_2(t, s)$  is nondecreasing with respect to s for  $s \in [0, \sigma(t)]$ . D3)  $\int_{t_0}^{\infty} r_2(t, \sigma(t)) dt = \infty$ .

DEFINITION 2. The solution x(t) of (1) is said to oscillate if there exists an increasing sequence  $\{t_n\}_1^{\infty}$ , such that  $\lim_{n \to \infty} t_n = \infty$  and  $x(t_n) =$ 

= 0,  $n \in \mathbb{N}$ . Otherwise it is said to be nonoscillatory.

DEFINITION 3. The function x(t) is said to eventually have the property K, if there exists  $t_0$  such that for  $t \ge t_0$  the function has the property K.

By Definition 3 the nonoscillatory solutions of (1) are characterized as being eventually positive or eventually negative.

Let

(3) 
$$z(t) = x(t) + \int_{0}^{\sigma(t)} x(t-s) d_s r_1(t,s) d_s$$

Then

(4) 
$$z'(t) = -\int_{0}^{\sigma(t)} x(t-s) d_s r_2(t,s).$$

We shall prove several lemmas which are essentially used in the proof of the main results.

LEMMA 2. Let conditions (A), (C) and (D) hold and let

(5)  $r_1(t, \sigma(t)) \ge p > -1.$ 

If x(t) is an eventually positive solution of (1), then x(t) is a bounded function.

**PROOF.** Let x(t) be an eventually positive solution of (1). From (4) it follows that  $z'(t) \leq 0$  eventually and z(t) is a nonincreasing function. D3) implies that z(t) is not an eventually constant function and thus either z(t) < 0 or z(t) > 0 eventually. Suppose that z(t) < 0. Then from (3), (5), C1) and D1) there follows the estimate

$$0 > x(t) + \int_{0}^{\sigma(t)} x(t-s) d_{s} r_{1}(t,s) \ge x(t) - \max_{[t-\sigma(t),t]} x(s) v_{1}(t) =$$
$$= x(t) + \max_{[t-\sigma(t),t]} x(s) r_{1}(t,\sigma(t)) > x(t) - \max_{[t-\sigma(t),t]} x(s) .$$

From the above inequalities it follows that there exists  $t_1 > t_0$ , such that for  $t > t_1$  the inequality

(6) 
$$x(t) < \max_{[t - \sigma(t), t]} x(s)$$

holds. By virtue of condition A2) we can choose  $\overline{t}$  such that  $t - \sigma(t) \ge t_0$  for  $t \ge \overline{t}$ . Then from (6) we have

(7) 
$$x(t) < \max_{[t - \sigma(t), t]} x(s).$$

Suppose that x(t) is unbounded. Then  $\limsup_{n \to \infty} x(t) = \infty$  and there exists a sequence  $\{t_n\}_{n=1}^{\infty}$ , such that  $\lim_{n \to \infty} t_n = \infty$ ,  $\lim_{n \to \infty} x(t_n) = \infty$  and  $\max_{[t_n, t_n]} x(s) = x(t_n)$ . The last inequality however contradicts (7).

Let z(t) > 0 eventually. Since z(t) is a nonincreasing function, there exists the finite limit  $\lim_{t\to\infty} z(t) = c \ge 0$ . We shall prove that  $\liminf_{t\to\infty} x(t) = 0$ . Suppose that this is not true, i.e.  $d = \liminf_{t\to\infty} x(t) > 0$ . There exists  $\overline{t} \ge \overline{t}$  such that x(t) > d/2 for  $t \ge \overline{t}$ . From (4) and D2) it follows that

$$z'(t) \leq -\min_{[t-\sigma(t), t]} x(s) r_2(t, \sigma(t)).$$

By virtue of A2) we can choose  $\tilde{t}$  such that  $t - \sigma(t) > \overline{t}$  for  $t \ge \tilde{t}$ . Then

256

from the above estimate we have

$$z'(t) < -\frac{d}{2}r_2(t, \sigma(t)), \quad t \ge \tilde{t}.$$

Integrate the last inequality from  $\tilde{t}$  to t and obtain

$$z(t) \leq z(\tilde{t}) - \frac{d}{2} \int_{t}^{\tilde{t}} r_2(s, \sigma(s)) ds.$$

D3) implies that  $\lim_{t\to\infty} z(t) = -\infty$ , which contradicts the inequality z(t) > 0 eventually. Thus  $\liminf_{t\to\infty} x(t) = 0$ . Suppose that x(t) is an unbounded function. As above we choose a sequence  $\{t_n\}_1^\infty$  with the respective properties. Since  $\liminf_{t\to\infty} x(t) = 0$ , there exists a sequence  $\{\tau_k\}_1^\infty$ , such that  $\lim_{k\to\infty} \tau_k = \infty$  and  $\lim_{k\to\infty} x(\tau_k) = 0$ . Let  $n, k \in \mathbb{N}$  be large enough and such that  $t_n > \tau_k$ . Then the following estimate is valid:

$$z(t_n) - z(\tau_k) > x(t_n) - x(\tau_k) + \int_0^{\sigma(t_n)} x(t_n - s) d_s r_1(t_n, s) \ge$$
$$\ge x(t_n) - x(\tau_k) + \max_{[t_n - \sigma(t_n), t_n]} x(s) r_1(t_n, \sigma(t_n)) \ge x(t_n) - x(\tau_k) + px(t_n)$$

Thus we have

$$z(t_n) - z(\tau_k) > x(t_n)(1+p) - x(\tau_k).$$

The choice of the sequences  $\{t_n\}$  and  $\{\tau_k\}$  and (5) imply that  $z(t_n) - z(\tau_k) > 0$  and since  $t_n > \tau_k$ , we get to a contradiction with the fact that z(t) is an eventually nonincreasing function.

LEMMA 3 ([5]). Let  $p, \tau \in C([t_0, \infty), (0, \infty))$  and  $\lim_{t\to\infty} (t - \tau(t)) = \infty$ . If

$$\liminf_{t\to\infty}\int_{t-\tau(t)}^t p(s)\,ds>\frac{1}{e},$$

then the inequality

$$y'(t) + p(t)y(t - \tau(t)) \leq 0$$

has no eventually positive solutions.

257

).

### 3. – Main results.

THEOREM 1. Let conditions (A), (C), (D) and (5) hold. Then each non-oscillatory solution x(t) of (1) tends to 0 as  $t \to \infty$ .

PROOF. Let x(t) be an eventually positive solution of (1). From Lemma 2 it follows that the function x(t) is bounded. Then b = $= \limsup_{t \to \infty} x(t) < \infty$ . We shall prove that b = 0. Suppose that this is not true and choose  $\varepsilon > 0$  so that  $\varepsilon < (b(1 + p))/(2 - p)$ . There exists a sequence  $\{t_n\}_1^{\infty}$  such that  $\lim_{n \to \infty} t_n = \infty$  and  $\lim_{n \to \infty} x(t_n) = b$ . Then we can choose  $\overline{t} \ge t_0$  and N so that  $|x(t_n) - b| < \varepsilon$  for n > N and  $x(t) - b < \varepsilon$  for  $t > \overline{t}$ . Since x(t) is a bounded function, z(t) is bounded too. Then the fact that z(t) is a nonincreasing function implies the existence of the finite limit  $\lim_{t \to \infty} x(t) = c$ . As in the proof of Lemma 2 it is shown that  $\liminf_{t \to \infty} \tau_k = \infty$  and  $\lim_{k \to \infty} x(\tau_k) = 0$ . There exists K such that for k > K we have  $x(\tau_k) < \varepsilon$ . From the sequences  $\{t_n\}_1^{\infty}$  and  $\{\tau_k\}_1^{\infty}$  choose the pair  $\tau_j$ ,  $t_i$  so that j > K, i > N,  $\tau_j < t_i$  and  $t_i - \sigma(t_i) > t_0$ . Then the following estimate is valid:

$$\begin{aligned} z(t_i) - z(\tau_j) &= x(t_i) - x(\tau_j) + \\ &+ \int_0^{\sigma(t_i)} x(t_i - s) \, d_s \, r_1(t_i, \, s) - \int_0^{\sigma(\tau_j)} x(\tau_j - s) \, d_s \, r_1(\tau_j, \, s) \ge \\ &\ge x(t_i) - x(\tau_j) + \int_0^{\sigma(t_i)} x(t_i - s) \, d_s \, r_1(t_i, \, s) \ge \\ &\ge x(t_i) - x(\tau_j) + \max_{[t_i - \sigma(t_i), \, t_i]} x(s) \, r_1(t_i, \, \sigma(t_i)) \ge \\ &\ge b - \varepsilon - \varepsilon + p(b + \varepsilon) > 0 \,. \end{aligned}$$

(The last inequality follows from the choice of  $\varepsilon$ .) Thus, for  $\tau_j < t_i$  we obtained that  $z(\tau_j) < z(t_i)$ , which contradicts the fact that the function z(t) is nonincreasing. Hence  $\limsup_{t \to \infty} x(t) = 0$  and  $\lim_{t \to \infty} x(t) = 0$ . If x(t) is an eventually negative solution of (1), then since (1) is a linear equation, -x(t) is an eventually positive solution of (1), which implies that in this case as well  $\lim_{t \to \infty} x(t) = 0$ .

In the same way the following theorem is proved:

THEOREM 2. Let conditions (A), (C), D2) and D3) hold and let  $r_1(t, s)$  be nondecreasing with respect to s for  $s \in [0, \sigma(t)]$ .

If  $r_1(t, \sigma(t)) \leq p < 1$ , then each nonoscillatory solution of (1) tends to 0 as  $t \to \infty$ .

REMARK 1. Theorem 1 generalizes or generalizes and extends a number of known results, for instance Theorem 3 iv) ([2]), Theorem 1 ([10]), Theorem 5 ([7]), Corollary 3b ([1]).

REMARK 2. The condition  $r_1(t, \sigma(t)) \leq p < 1$  in Theorem 2 is essential. We shall illustrate this fact with the following example:

EXAMPLE 1 [8]. Consider the equation

(8) 
$$[x(t) + x(t-2)]' + q(t)x(t) = 0,$$

where

$$q(t) = rac{(1/t^2) + 1/(t-2)^2}{\psi(t) + 1/t}$$

and  $\psi(t)$  is the 4-periodic function

$$\psi(t) = \begin{cases} 0, & t \in [0, 1], \\ t - 1, & t \in (1, 2], \\ 1, & t \in (2, 3], \\ 4 - t, & t \in (3, 4]. \end{cases}$$

Clearly, equation (8) is a particular case of (1), moreover  $r_1(t, \sigma(t)) \equiv 1$ . It is immediately verified that  $x(t) = \psi(t) + 1/t$  is a nonoscillatory solution of (8), yet the limit  $\lim_{t \to \infty} x(t)$  does not exist. On the other hand all

conditions of Theorem 2, except the condition  $r_1(t, o(t)) \leq p < 1$  are met.

The question whether the assertion of Theorem 2 is still valid without the condition  $r_1(t, \sigma(t)) \leq p < 1$ , if D3) is replaced with the more restrictive condition  $r_2(t, \sigma(t)) \geq m > 0$ ,  $t \geq t_0$ , is open. For example, this is true (Theorem 2 ([2])) for the equation

$$[x(t) + p(t)x(t - \tau)]' + q(t)x(t - \sigma) = 0,$$

where p, q are continuous, nonnegative functions and  $\tau$ ,  $\sigma \ge 0$ . (In

this case D3) reduces to  $\int_{t_0}^{\infty} q(t) dt = \infty$  and the condition  $r_2(t, \sigma(t)) \ge m > 0$  reduces to  $q(t) \ge q > 0$ .) Define the function  $\tau(t)$ 

$$\tau(t) = \sup \{ s \in [0, \sigma(t)] / r_2(t, s) = 0 \}, \quad t \ge t_0.$$

THEOREM 3. Let conditions (A), (C), (D) and (5) hold and let  $\tau(t) \in C([t_0, \infty), (0, \infty))$ . If

(9) 
$$\liminf_{t\to\infty}\int_{t-\tau(t)}^{t}r_2(s,\,\sigma(s))\,ds>\frac{1}{e}\,,$$

then each solution of (1) is oscillatory.

PROOF. Suppose that (1) has at least one nonoscillatory solution x(t). Without loss of generality, let x(t) be eventually positive. From Theorem 1 it follows that  $\lim_{t\to\infty} x(t) = 0$ . (3), (5) and D1) imply that  $\lim_{t\to\infty} z(t) = 0$ . On the other hand, z(t) is an eventually nonincreasing nonconstant function. Hence z(t) > 0 eventually. (3) implies that z(t) < x(t) and then from (1) we have

$$z'(t) + \int_{0}^{\sigma(t)} z(t-s) d_s r_2(t,s) \leq 0.$$

By virtue of the definition of  $\tau(t)$ , the last inequality takes the form

$$0 \ge z'(t) + \int_{\tau(t)}^{\sigma(t)} z(t-s) d_s r_2(t,s) \ge z'(t) + z(t-\tau(t)) r_2(t,\sigma(t)).$$

Thus we obtained that the eventually positive function z(t) is a solution of the inequality

$$y'(t) + r_2(t, \sigma(t)) y(t - \tau(t)) \leq 0$$
.

Then, by condition (9) we get to a contradiction with the assertion of Lemma 3.  $\blacksquare$ 

REMARK 3. Theorem 3 generalizes Theorem 5 ([2]).

260

Acknowledgments. The authors would like to thank the referee for her/his very helpful comments and suggestions. The present investigation was partially supported by the Bulgarian Ministry of Education, Science and Technologies under grant MM-422.

### REFERENCES

- Q. CHUANXI M. KULENOVIC G. LADAS, Oscillations of neutral equations with variable coefficients, Radovi Matematicki, 5 (1989), pp. 321-331.
- [2] M. GRAMMATIKOPOULOS G. LADAS Y. SFICAS, Oscillation and asymptotic behaviour of neutral equations with variable coefficients, Radovi Matematicki, 2 (1986), pp. 279-303.
- [3] E. GROVE G. LADAS A. MEIMARIDOU, A necessary and sufficient condition for the oscillation of neutral equations, J. Math. Anal. Appl., 126 (1987), pp. 341-354.
- [4] J. HALE, Forward and backward continuation for neutral functional differential equations, J. Diff. Equations, 9 (1971), pp. 168-181.
- [5] R. KOPLATADZE T. CHANTURIJA, On the oscillatory and monotone solutions of the first order differential equations with deviating arguments, Differentcial'nye Uravnenija, 18 (1982), 1463-1465.
- [6] M. KULENOVIC G. LADAS A. MEIMARIDOU, Necessary and sufficient conditions for oscillation of neutral differential equations, J. Austral. Math. Soc., Ser. B, 28 (1987), pp. 362-375.
- [7] G. LADAS Y. SFICAS, Oscillations of neutral delay differential equations, Canadian Math. Bull., 29 (1986), pp. 438-445.
- [8] V. PETROV, On a problem stated by Gyori and Ladas, Mathematica Balkanica, vol. 9 (to appear).
- [9] J. RUAN, Oscillations of neutral differential difference equations with several retarded arguments, Sciential Sinica (A), 10 (1986), pp. 1132-1144.
- [10] SV. STANEK, Oscillation behaviour of solutions of neutral delay differential equations, Casopis pro Pestovany Matematiky, 115 (1990), pp. 92-99.

Manoscritto pervenuto in redazione il 12 agosto 1993 e, in forma revisionata, il 25 agosto 1994.