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PAR JOSEPH LIOUVILLE

A. D. MICHAL

R. S. MARTIN

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*Some expansions in vector space:*By **A. D. MICHAL** and **R. S. MARTIN** ⁽¹⁾.

1. INTRODUCTION. — The general theory of linear vector spaces has been studied by several authors ⁽²⁾. The present paper is mainly concerned with the study of the properties of two expansions $B(T)$ and $D(T)$ in a special linear vector space S , closed under multiplication by numbers of a real or complex system A , and having additional properties abstracted from those of a space of linear transformations. The functions $B(T)$ and $D(T)$ are on S to S and S to A respectively. $D(T)$ is analogous to the Fredholm determinant and $B(T)$ to the first Fredholm minor. A simple derivation of some results on generalized rotations is incidentally given in Section 5.

2. POSTULATES AND DEFINITIONS. — Let A denote the system of real or the system of complex numbers.

We consider a space S consisting of a set $\{T, U, \dots\}$ of elements $T, U, \dots$ and five operations

$$(-), (\cdot), (\otimes), \|\dots\|, \{\dots\}$$

satisfying the following postulates.

1. The set $\{T, U, \dots\}$ forms a complete linear vector space with

⁽¹⁾ *National Research Fellow in Mathematics at California Institute of Technology.*

⁽²⁾ See, for example, S. BAXACH, *Fundamenta Mathematicæ*, vol. 3, 1932, p. 133-181, and M. FRÉCHET, *Espaces abstraits*, Paris, 1938. See also Fréchet's *fundamental papers on abstract spaces in*, *Rend. Circ. Mat. Palermo*, vol. 29, 1906, p. 1-74, and in *Journal de Mathématiques*, 1929, p. 71-93.

respect to addition, $\oplus$, multiplication, $\odot$, by numbers $a, b, \dots$ of A , and the norm $|\dots|$.

II. The set $\{T, U, \dots\}$ forms a ring with respect to $\oplus$ and composition, $\circ$, having a unique two-sided unit I , that is

$$I(\widehat{\circ})T = T(\widehat{\circ})I = T \quad (\text{all } T).$$

III. $|I| = 1$.

IV. The product $T \odot I$ is a bilinear operation of modulus unity on the space S^2 to S .

V. $|\dots|$ is a homogeneous linear continuous operation on S to the number system A , having the property that

$$|T(\widehat{\circ})U| = |U(\widehat{\circ})T| \quad (\text{all } T, U).$$

That the five postulates are consistent is shown by taking S to be A , the operations

$$(+), (\cdot), (\infty), \|\dots\|,$$

to be ordinary addition, multiplication, and modulus respectively, and $|a|$ to be a .

With A the real number system and with the following interpretation of the elements and operations, the set of ordered pairs of functions $(T(x, y), T(x))$ form a non-trivial instance of a space S . Let

$$T = (T(x, y), T(x)), \quad U = (U(x, y), U(x)), \\ I = (a, 1),$$

where $T(x, y)$ and $U(x, y)$ are continuous on the square $a \leq x, y \leq b$, and $T(x)$ and $U(x)$ are continuous on the interval (a, b) . Take

$$T(\widehat{+})U = (T(x, y) + U(x, y), T(x) + U(x)),$$

$$a(\cdot)T = (aT(x, y), aT(x)),$$

$$T(\widehat{\circ})U = \left(\int_a^b T(x, \sigma)U(\sigma, y) d\sigma + T(x)U(x, y) + U(y)T(x, y), T(x)U(x) \right),$$

$$\|T\| = (b-a) \max_{a \leq y \leq b} |T(x, y)| + \max_x |T(x)|,$$

$$|T| = \int_a^b T(x, x) dx.$$

We may also take

$$[T] = cT(x_1),$$

where c is a constant and x_1 is a fixed number in (a, b) .

Unless ambiguity arises we shall write $\ominus$ as simply $\div$ and omit to write $\odot$ and $\oslash$. As immediate consequences of postulate (4) we have

$$(2.1) \quad (a(\oslash)T)(\oslash)U = T(\oslash)(a(\oslash)U) = a(\oslash)(T(\oslash)U)$$

and

$$(2.2) \quad \|T(\oslash)U\| \leq \|T\| \|U\|.$$

For purposes of exposition it is convenient to make several definitions, some of whose further implications have been studied elsewhere (¹).

Definition I. — By a polynomial $p(x)$ of degree n on a vector space $V_1(A)$ to a vector space $V_2(A)$ we shall mean a continuous function $p(x)$ such that $p(x + \lambda y)$ is a polynomial of degree n in λ of the number system A , with coefficients in $V_2(A)$. If further

$$p(\lambda x) = \lambda^n p(x),$$

$p(x)$ is said to be homogeneous of degree n . It is convenient to consider a null polynomial as having any degree whatever.

Definition II. — By the modulus of a homogeneous polynomial of degree n we shall mean

$$\max_x \frac{\|p(x)\|}{\|x\|^n}$$

and shall denote it by mp .

Definition III. — We shall say that a function $f(x)$ on $V_1(A)$ to $V_2(A)$ is analytic at a point x_0 if there exists a sequence $\{h_n(x)\}$ of homogeneous polynomials ($h_n(x)$ of degree n) such that $\sum \lambda^n m h_n$ has a positive radius of convergence r , and such that for $\|x - x_0\| < r$, $\sum h_n(x - x_0)$ converges (in the norm) to $f(x)$. We shall call r the

(¹) R. S. MARTIN, *California Institute thesis*, 1932.

radius of analyticity of $f(x)$ at x_0 and shall often refer to such an $f(x)$ as analytic (x) at $x = x_0$.

5. THE POLYNOMIALS $B_n(T)$ and $a_n(T)$. — Let T be in S . Let $a_0 = 1$ and $B_0 = 0$ where 0 is the zero element of S . Define a sequence of numbers $\{a_n(T)\}$ and a sequence of elements $\{B_n(T)\}$ of S by means of the recurrence relations

$$(3.1) \quad B_n(T) = a_{n-1}(T)T - B_{n-1}(T)T,$$

$$(3.2) \quad a_n(T) = \frac{1}{n} [B_n(T)].$$

We have

$$(3.3) \quad B_n(T) = \sum_{r=1}^n (-1)^{r-1} a_{n-r}(T) T^r,$$

$$(3.4) \quad n a_n(T) = \sum_{r=1}^n (-1)^{r-1} a_{n-r}(T) [T^r].$$

Solving (3.4) (whose determinant is $n!$) we have

$$(3.5) \quad a_n(T) = \frac{1}{n!} \begin{vmatrix} [T] & [T^2] & \dots & \cdot & [T^n] \\ n-1 & [T] & \dots & \cdot & [T^{n-1}] \\ 0 & n-2 & \dots & \cdot & [T^{n-2}] \\ \cdot & \dots & \dots & \cdot & \dots \\ 0 & 0 & \dots & 1 & [T] \end{vmatrix} \quad (n > 0).$$

Furthermore

$$(3.6) \quad B_n(T) = \frac{1}{(n-1)!} \begin{vmatrix} T & T^2 & \dots & T^{n-1} & T^n \\ n-1 & [T] & \dots & [T^{n-2}] & [T^{n-1}] \\ 0 & n-2 & \dots & [T^{n-3}] & [T^{n-2}] \\ \cdot & \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 1 & [T] \end{vmatrix} \quad (n > 0),$$

as can be seen by expanding (3.6) in its first row and using (3.3) and (3.5).

THEOREM 3.1. — $B_n(T)$ is a homogeneous polynomial of degree n on the space S to the space $\bar{S}$. The modulus of $B_n(T)$ satisfies the inequality

$$(3.7) \quad m B_n \leq \frac{(\gamma+1)(\gamma+2)\dots(\gamma+n-1)}{(n-1)!} \quad (n > 0),$$

where γ is the modulus of the operation $[\dots]$. Similarly $a_n(T)$ is a homogeneous polynomial of degree n on S to A and

$$(3.8) \quad m a_n \leq \frac{\gamma(\gamma+1)(\gamma+2)\dots(\gamma+n-1)}{n!} \quad (n \geq 0).$$

Proof : The polynomial property of $a_n(T)$ and $B_n(T)$ is evident for $n=1$, for then $a_1(T)=[T]$ and $B_1(T)=T$. Assuming the theorem true for $n-1$, the continuity of $B_n(T)$ follows from the inequality

$$\begin{aligned} \|B_n(T) - B_n(U)\| &\leq \|a_{n-1}(T)T - a_{n-1}(U)T\| + \|a_{n-1}(U)T - a_{n-1}(U)U\| \\ &\quad + \|B_{n-1}(U)T - B_{n-1}(T)T\| + \|B_{n-1}(U)U - B_{n-1}(U)T\| \\ &\leq (\|a_{n-1}(T) - a_{n-1}(U)\| + \|B_{n-1}(T) - B_{n-1}(U)\|) \|T\| \\ &\quad + (\|a_{n-1}(U)\| + \|B_{n-1}(U)\|) \|T - U\| \end{aligned}$$

and that of $a_n(T)$ from the fact that $[\dots]$ is a linear continuous operation.

Observing that $a_{n-1}(T + \lambda U)$ and $B_{n-1}(T + \lambda U)$ are polynomials in λ on A to A and A to S respectively we see at once from (3.1) that $B_n(T + \lambda U)$ is a polynomial in λ on A to S , say $\sum \lambda^r K_r$. Then

$$a_n(T + \lambda U) = \frac{1}{n} \left[\sum \lambda^r K_r \right] = \sum \lambda^r \left[\frac{K_r}{n} \right]$$

is a polynomial in λ on A to A . The homogeneity is obvious from (3.1) and (3.2).

The proof of the inequalities (3.7) and (3.8) is by induction and the use of the postulates.

4. THE EXPANSIONS $B(T)$ AND $D(T)$. — THEOREM 4.1 :

$$B(T) \equiv \sum_1^\infty B_n(T) \quad \text{and} \quad D(T) \equiv \sum_0^\infty a_n(T)$$

are functions on S to S and S to A respectively analytic at $T=0$. Their radii of analyticity are not less than unity.

Proof :

$$\sum \lambda^n m B_n \quad \text{and} \quad \sum \lambda^n m a_n$$

are dominated respectively by

$$\sum_1^{\infty} \lambda^n \frac{(\gamma+1) \dots (\gamma+n-1)}{(n-1)!} = \lambda(1-\lambda)^{-(\gamma+1)} \quad (|\lambda| < 1)$$

and

$$\sum_0^{\infty} \lambda^n \frac{\gamma(\gamma+1) \dots (\gamma+n-1)}{n!} = (1-\lambda)^{-\gamma} \quad (|\lambda| < 1).$$

THEOREM 4. II. — *If $|\lambda| < 1$ then*

$$(4.1) \quad D(\lambda I) = (1+\lambda)^l$$

and

$$(4.2) \quad B(\lambda I) = \lambda(1+\lambda)^{l-1} I$$

where

$$l = [1].$$

Proof: From the homogeneity of $a_n(T)$ we have

$$a_n(\lambda I) = \lambda^n a_n(I)$$

and from (3.4)

$$(4.3) \quad n a_n(I) = l \sum_{r=1}^n (-1)^{r-1} a_{n-r}(I).$$

The recursion formula (4.3) together with the condition $a_0 = 1$ determine the successive coefficients b_n in the expansion of $(1+\lambda)^l$, for differentiating

$$(4.4) \quad (1+\lambda)^l = \sum b_n \lambda^n$$

we obtain

$$\sum n b_n \lambda^{n-1} = l(1+\lambda)^{l-1} = l \left(\sum b_n \lambda^n \right) \frac{1}{1+\lambda} = l \left(\sum b_n \lambda^n \right) \sum (-1)^r \lambda^r.$$

Equating coefficients of λ^n we see that $b_0 = 1$ and that b_n satisfies the recursion formulæ (4.3) for $a_n(I)$. Hence

$$b_n = a_n(I).$$

Furthermore from (3.3) we see that

$$B_n(I) = \beta_n I$$

where

$$\beta_n = \sum_{r=1}^n (-1)^{n-r} a_{n-r}(1) \quad (\beta_n = 0).$$

Since $\beta_0 = 0$ and since

$$\lambda(1+\lambda)^{l-1} = \left(\sum_n a_n(1)\lambda^n \right) \left(\sum_n (-1)^n \lambda^{n+1} \right)$$

it follows that β_n is precisely the coefficient of λ^n in the expansion of

$$\lambda(1+\lambda)^{l-1}.$$

COROLLARY 1. — *There exist spaces S in which the radii of analyticity about $T = 0$ of $B(T)$ and $D(T)$ are unity.*

By a proper choice of the constant c in the instance of a space S given in section (2) we may secure that l is not a positive integer or zero.

Since $\|I\| = 1$ we have that

$$m a_n \geq |a_n(1)|$$

and

$$m B_n \geq |\beta_n|.$$

Hence the radii of convergence of the power series $\sum m a_n \lambda^n$ and $\sum m B_n \lambda^n$ are respectively at most equal to the radii of convergence of $\sum |a_n(1)| \lambda^n$ and $\sum |\beta_n| \lambda^n$. The latter two series, however, have the same radius of convergence as $\sum a_n(1) \lambda^n$ and $\sum \beta_n \lambda^n$, namely unity. Combining this result with Theorem 4.1. we have the corollary.

COROLLARY 2. — *If the real part of $[I]$ is positive then $D(-1) = 0$.*

We have

$$a_n(-1) = (-1)^n b_n$$

where b_n is given by (4.4).

If the real part of l is positive then the series $\sum (-1)^n b_n$ is known to converge. Hence using Abel's theorem on convergence up to the unit circle we have

$$\sum a_n(-1) = \lim_{\lambda \rightarrow -1+0} \sum b_n \lambda^n = \lim_{\lambda \rightarrow -1+0} (1+\lambda)^l = 0.$$

COROLLARY 3. — *If the real part of $[I]$ is negative then the series $\Sigma a_n(-I)$ representing $D(-I)$ is divergent.*

COROLLARY 4. — *If $[I] \equiv 0$, then $D(-I) = I$.*

We observe that for fixed T , $B(\lambda T)$ and $D(\lambda T)$ are analytic functions of λ near $\lambda = 0$ on A to S and A to A respectively and that their radii of analyticity are not less than $\frac{1}{\|T\|}$.

THEOREM 4.III. — *If $\{E_n\}$ is a sequence of elements of S such that $E \equiv \Sigma E_n$ converges in the norm, then ΣTE_n and $\Sigma E_n T$ converge in the norm and are equal to TE and ET respectively.*

Proof: Let

$$G_m = \sum_{n=1}^m E_n,$$

then

$$\left\| \sum_{n=1}^m TE_n - TE \right\| = \|T(G_m - E)\| \leq \|T\| \cdot \|G_m - E\|.$$

Since by hypothesis $\|G_m - E\|$ approaches zero with $\frac{1}{m}$, the first part of the theorem is proved. The proof of the second part is similar.

THEOREM 4.IV. — *If $E(T) = \Sigma E_n(T)$, where $E_n(T)$ is a homogeneous polynomial of degree n , is a function on S to S analytic at $T = 0$, then $TE(T)$ and $E(T)T$ are analytic on S to S and their radii of analyticity are at least as large as that of $E(T)$.*

Proof: That $TE_n(T)$ is a homogeneous polynomial of degree $n+1$ is shown by a similar argument to that employed in the proof of Theorem 3.I From the inequality

$$\frac{\|TE_n(T)\|}{\|T\|^{n+1}} \leq \frac{\|T\|}{\|T\|} \frac{\|E_n(T)\|}{\|T\|^n} \leq m E_n$$

and Theorem 4.III the rest of Theorem 4.IV follows The proof is similar for $E(T)T$.

§. INVERSES AND ROTATIONS. — In this section we shall not make use

of postulate 5 for the space S . Hence throughout this section S will denote a space that satisfies the first four postulates.

Definition. — By a left-hand (right hand) inverse to an element T of S we shall understand an element T_1 such that

$$T_1(\otimes)T = I \quad (T(\otimes)T_1 = I).$$

A two-sided inverse T^{-1} we shall call an inverse of T .

THEOREM 5. I. — *If T of S has at least one right hand inverse and at least one left hand inverse then it has unique right and left hand inverses and they are identical.*

Proof : Let T_1 be any left hand inverse and T_2 any right hand inverse of T . From

$$T(\otimes)T_2 = I,$$

we have

$$T_2 = I(\otimes)T_2 = T_1(\otimes)T(\otimes)T_2 = T_1(\otimes)I = T_1.$$

COROLLARY 1. — *If T has an inverse, then it is unique.*

COROLLARY 2. — *If $T_1, T_2, \dots, T_n$ of S have inverses, then*

$$T_1(\otimes)T_2(\otimes)\dots(\otimes)T_n$$

has an inverse, namely

$$T_n^{-1}(\otimes)T_{n-1}^{-1}(\otimes)\dots(\otimes)T_1^{-1}.$$

COROLLARY 3. — *If T has an inverse T^{-1} then T^{-1} has an inverse, namely T .*

THEOREM 5. II. — *If $\|T\| < 1$, then $I + T$ has an (unique) inverse, namely*

$$I + \sum_{n=1}^{\infty} (-1)^n T^n.$$

Proof : By successive applications of (2.2) we have

$$\|(-1)^n T^n\| \leq \|T\|^n.$$

It follows from the completeness of S that $\sum_{n=1}^{\infty} (-1)^n T^n$ is in S . By an evident calculation and the use of Theorem 4.III, it is seen that

$$1 + \sum_{n=1}^{\infty} (-1)^n T^n$$

is an inverse of $1 + T$, which by Corollary 1 of the preceding theorem is unique.

Suppose now there exist an operation $'$, which we shall call transposition, with the following three properties :

- (a) $'T$ is a linear operation on S to S ,
- (b) $'T'U = '(UT)$,
- (c) $''(T) = T$.

It follows immediately from the properties (b) and (c) that $'1 = 1$. From (b) and this result it follows that if T has an inverse then the transposed of T has an inverse given by the transposed of the inverse of T .

Definition. — If $1 - \lambda T$ has an inverse $1 + \lambda \Gamma(\lambda)$, then $\Gamma(\lambda)$ will be called the resolvent of λT .

THEOREM 5.III. — Suppose $1 - \lambda T$ and $1 - (\lambda + \mu)T$ have inverses, then if $\Gamma(\lambda)$ is the resolvent of λT it follows that $\Gamma(\lambda + \mu)$ is the resolvent of $\mu \Gamma(\lambda)$.

Proof: By hypothesis

$$(1 - \lambda T)(1 + \lambda \Gamma(\lambda)) = 1.$$

From this relation we obtain

$$(5.1) \quad (1 - \lambda T) \Gamma(\lambda) = T.$$

Consider an element J defined by

$$(5.2) \quad J = (1 - \mu \Gamma(\lambda))(1 + \mu \Gamma(\lambda + \mu)).$$

On applying (5.1) twice successively to $(1 - \lambda T)J$ we obtain

$$(1 - \lambda T)J = (1 - (\lambda + \mu)T)(1 + \mu \Gamma(\lambda + \mu)) = 1 - \lambda T.$$

Since $I - \lambda T$ has an inverse it follows that $J = I$ and hence the theorem is proved.

Definition of a rotation. — If $I + T$ has an inverse given by $I + {}^*T$ then T will be called a rotation.

THEOREM 5. IV. — *If T is a rotation and if $(\lambda - 1)T$ has a resolvent $\Gamma(\lambda - 1)$ then $-\lambda T$ has a resolvent and*

$$(5.3) \quad \Gamma(\lambda - 1) = - {}^*T(-\lambda).$$

Proof: Since T is a rotation

$$(5.4) \quad {}^*T = - \Gamma(-1).$$

By hypothesis and the previous theorem we have

$$(5.5) \quad (I - \lambda \Gamma(\lambda - 1))(I + \lambda {}^*T) = I.$$

Applying the properties of transposition, the transposed of (5.5) becomes

$$(5.6) \quad (I + \lambda T)(I - \lambda \Gamma(\lambda - 1)) = I.$$

Hence the inverse of $I - (-\lambda)T$ exists and we have

$$(5.7) \quad (I - (-\lambda)T)(I - \lambda \Gamma(-\lambda)) = I.$$

By Corollary 1 to Theorem 5. I

$${}^*T(\lambda - 1) = - \Gamma(-\lambda).$$

From this result (5.3) follows immediately.

Corollary. — *If T is a rotation and $I + \frac{1}{3} T$ has an inverse then*

$$H = \Gamma\left(-\frac{1}{3}\right)$$

is defined and

$$H = - {}^*H.$$

THEOREM 5. V. — *If T is a rotation such that $I + \frac{1}{3} T$ has an inverse, then T is the resolvent of $\frac{1}{3} H$ where H satisfies the relation*

$${}^*H = - H.$$

Proof: Take $\lambda = \frac{1}{3}$ in (5.7) and apply the previous corollary.

THEOREM 5.VI. — *If $I - \frac{1}{3}T$ has an inverse and if*

$$(5.8) \quad {}^tT = -T$$

then the resolvent $\Lambda\left(\frac{1}{3}\right)$ of $\frac{1}{3}T$ is a rotation.

Proof: By hypothesis we have

$$(5.9) \quad \left(I + \frac{1}{3}\Lambda\left(\frac{1}{3}\right)\right)\left(I - \frac{1}{3}T\right) = I.$$

Transposing and making use of (5.8) we obtain

$$(5.10) \quad \left(I + \frac{1}{3}T\right)\left(I + \frac{1}{3}\Lambda\left(\frac{1}{3}\right)\right) = I.$$

Since by hypothesis $I - \frac{1}{3}T$ has an inverse and since $I + \frac{1}{3}T$ is the transposed of $I - \frac{1}{3}T$ it follows that $I + \frac{1}{3}T$ has an inverse, namely,

$$I - \frac{1}{3}\Lambda\left(-\frac{1}{3}\right).$$

Hence from (5.10) we have

$$(5.11) \quad \Lambda\left(\frac{1}{3}\right) = -\Lambda\left(-\frac{1}{3}\right).$$

Since $\Lambda\left(\frac{1}{3}\right)$ and $\Lambda\left(-\frac{1}{3}\right)$ exist we can apply Theorem 5.III and obtain

$$\left(I - \Lambda\left(\frac{1}{3}\right)\right)\left(I - \Lambda\left(-\frac{1}{3}\right)\right) = I.$$

With the aid of (5.11) we can write this relation in the form

$$\left(I + \Lambda\left(\frac{1}{3}\right)\right)\left(I - \Lambda\left(\frac{1}{3}\right)\right) = I.$$

This proves the theorem.

6. A LEMMA ON SEQUENCES OF REAL NUMBERS DEFINED BY RECURRENT INEQUALITIES. — The results of the following lemma are necessary for the development of the succeeding sections.

LEMMA. — *Let $\{r_n\}$ be a sequence of non-negative real numbers such that Σr_n converges. Let two sequences of non-negative real numbers $\{e_n\}$ and $\{f_n\}$ satisfy the recurrent inequalities*

$$(6.1) \quad ne_n \geq 2^{\lambda} (\lambda(e_{n-1} + f_{n-1}) + r_{n-1}),$$

$$(6.2) \quad f_n \leq \lambda(e_{n-1} + f_{n-1}) + r_{n-1},$$

$$e_n = f_n = 0,$$

where $\lambda \geq 0$. Then if $0 \leq \lambda \leq 1$, $\Sigma e_n x^n$ and $\Sigma f_n x^n$ have radii of convergence at least unity. If furthermore $0 \leq \lambda < 1$, Σe_n and Σf_n converge and their sums tend to zero with Σr_n .

Proof: Since e_n, f_n, r_n are non-negative it is clearly sufficient to prove the lemma for the case where the inequalities (6.1) and (6.2) are replaced by the corresponding equalities.

Assume first that $\lambda > 0$, $0 \leq \lambda \leq 1$. From the hypotheses on $\{r_n\}$ it is clear that $\Sigma r_n x^n$ converge uniformly and absolutely for $|x| \leq 1$ and hence defines an analytic function $R(x)$ of x in the interior of the unit circle.

Consider the differential equation

$$(6.3) \quad u'(x) = \frac{u}{1-\lambda x} (\lambda u(x) + R(x)).$$

Let $E(x) \equiv \Sigma E_n x^n$ be the unique analytic solution satisfying the initial condition $E(0) = 0$. Let

$$(6.4) \quad F(x) \equiv \sum F_n x^n = x \frac{E'(x)}{\lambda}.$$

We have at once

$$(6.5) \quad \frac{E'(x)}{\lambda} = \lambda(E(x) + F(x)) + R(x),$$

$$(6.6) \quad \frac{F(x)}{x} = \lambda(E(x) + F(x)) + R(x).$$

Equating the coefficients of x^{n-1} and observing that $F(0) = E(0) = 0$

we have

$$(6.7) \quad \begin{cases} nE_n = \lambda(1-\lambda)E_{n-1} - F_{n-1} + r_{n-1}, \\ F_n = \lambda(E_{n-1} - F_{n-1}) + r_{n-1}, \\ E_0 = F_0 = 0. \end{cases}$$

Since the coefficients of differential equation (6.3) are analytic within the unit circle it follows that the solution $E(x)$, and hence $F(x)$, is analytic within the unit circle. For $|x| < 1$ we may write the solution $E(x)$ in the form

$$(6.8) \quad E(x) = (1-\lambda x)^{-2} \int_0^1 (1-\lambda t)^{-2} R(t) dt.$$

Furthermore for $0 \leq \lambda < 1$ the sums of the coefficients of x^n in the expansions of $(1-\lambda x)^{-2}$ and $(1-\lambda x)^{-2-1}$ are absolutely convergent. Since the result of Cauchy multiplication of two power series the sums of whose coefficients are absolutely convergent is a power series having the same property, and since the property is preserved under term by term integration, it follows from (6.8) that $\sum E_n$ is convergent.

On differentiating (6.8) and applying a similar argument we see that $\sum F_n$ is convergent.

Applying Abel's theorem on continuity on the circle of convergence we have that $R(x)$ and $E(x)$ are continuous on the left at $x=1$.

Hence

$$\sum E_n = (1-\lambda)^{-2} \int_0^1 (1-\lambda t)^{-2} R(t) dt.$$

Since

$$\begin{aligned} R(t) &\geq R(1) = 0 \quad (0 \leq t \leq 1), \\ \sum E_n &\geq M(\lambda, \lambda) R(1) = M(\lambda, \lambda) \sum r_n. \end{aligned}$$

By a similar argument we prove that

$$\sum F_n \geq N(\lambda, \lambda) \sum r_n.$$

Assume now that $\lambda=0$. The recurrence relations (6.7) become

$$(6.9) \quad \begin{cases} E_n = 0, \\ F_n = \lambda F_{n-1} + r_{n-1}. \end{cases}$$

We simply observe that the coefficients in the power series

expansion of

$$F(x) = \frac{x R(x)}{1 - Lx}$$

are given by (6.9). The rest of the argument is similar to that for $\mu > 0$.

7. FRÉCHET DIFFERENTIABILITY OF $B(T)$ AND $D(T)$. — If the number system A of a vector space $V_1(A)$ is the complex number system it can be shown by a general argument that a function $f(x) = \sum_{n=0}^{\infty} h_n(x)$ analytic (r) at $x=0$ on $V_1(A)$ to a complete $V_2(A)$ has for $|x| < r$ a Fréchet differential $(1) \hat{z}f(x)$ given by $\sum_{n=1}^{\infty} \hat{z}h_n(x)$ which, as a function of x , is also analytic (r) at $x=0$. For the special analytic functions $B(T)$ and $D(T)$ it is possible to give a direct proof of their term by term differentiability for an *unrestricted number system* A .

THEOREM 7.1. — *The functions $D(T) \equiv \sum a_n(T)$ and $B(T) \equiv \sum B_n(T)$ have Fréchet differentials $\hat{z}D$ and $\hat{z}B$ given for $|T| < 1$ respectively by $\sum \hat{z}a_n(T)$ and $\sum \hat{z}B_n(T)$. These last two series define analytic functions of T whose radii of analyticity are at least unity.*

Proof: By Theorem 3.1 and by a theorem on the differentials of polynomials proved elsewhere ⁽²⁾, it follows that $a_n T$ and $B_n(T)$ possess differentials for all T in S .

From the definition of a Fréchet differential we have that $\varepsilon_n(T, \delta T)$ and $\varepsilon_n(T, \delta T)$ defined by

$$\begin{aligned} (7.1) \quad & \begin{cases} \|\delta T\| \varepsilon_n = \Delta a_n(T) - \hat{z}a_n(T) & (\delta T \neq 0), \\ \varepsilon_n = 0 & (\delta T = 0); \end{cases} \\ (7.2) \quad & \begin{cases} \|\delta T\| \varepsilon_n = \Delta B_n(T) - \hat{z}B_n(T) & (\delta T \neq 0), \\ \varepsilon_n = 0 & (\delta T = 0) \end{cases} \end{aligned}$$

where

$$\Delta f(T) = f(T + \delta T) - f(T).$$

⁽¹⁾ FRÉCHET, *La notion de différentielle dans l'Analyse générale* (Ann. Ec. Norm. sup., 4, XLII, 1925, p. 293-313).

⁽²⁾ MARTIN, *loc. cit.*

are continuous functions of δT at $\delta T = 0$. In order to show Fréchet differentiability for $\|T\| < 1$ it is clearly sufficient to prove that for $\|T\| < 1$ $\Sigma \Delta a_n(T)$ and $\Sigma \Delta B_n(T)$ converge and that

$$\varepsilon(T, \delta T) = \Sigma \varepsilon_n(T, \delta T)$$

and

$$\varepsilon'(T, \delta T) = \Sigma \varepsilon'_n(T, \delta T)$$

converge for

$$\|T\| + \|\delta T\| < 1$$

and represent continuous functions of δT at $\delta T = 0$.

From the recurrence formulae (3.1) and (3.2), and from the evident identity

$$\Delta(U(T)V(T)) = (\Delta U(T))V(T) + U(T + \delta T)\Delta V(T),$$

we have

$$(7.3) \quad n \Delta a_n(T) = (\Delta a_{n-1}(T))\{T\} + a_{n-1}(T + \delta T)\|\delta T\| \\ - [(\Delta B_{n-1}(T))T + B_{n-1}(T + \delta T)\delta T],$$

$$(7.4) \quad \Delta B_n(T) = (\Delta a_{n-1}(T))T + a_{n-1}(T + \delta T)\delta T \\ - (\Delta B_{n-1}(T))T - B_{n-1}(T + \delta T)\delta T.$$

Taking norms of (7.3) and (7.4) we obtain

$$n\|\Delta a_n(T)\| \leq \gamma \{(\|\Delta a_{n-1}(T)\| + \|\Delta B_{n-1}(T)\|)\|T\| \\ + (\|a_{n-1}(T + \delta T)\| + \|B_{n-1}(T + \delta T)\|)\|\delta T\|\}, \\ \|\Delta B_n(T)\| \leq \{(\|\Delta a_{n-1}(T)\| + \|\Delta B_{n-1}(T)\|)\|T\| \\ + (\|a_{n-1}(T + \delta T)\| + \|B_{n-1}(T + \delta T)\|)\|\delta T\|\},$$

where γ is the modulus of the operation $\{\dots\}$. By Theorem 3.1 the quantities

$$r_n = (\|a_n(T + \delta T)\| + \|B_n(T + \delta T)\|)\|\delta T\|$$

are for $\|T\| + \|\delta T\| < 1$ the terms of an absolutely convergent series.

Hence from the preceding Lemma taking

$$e_n = \|\Delta a_n(T)\|, \quad f_n = \|\Delta B_n(T)\|, \quad \lambda = \|T\|, \quad \mu = \gamma$$

and r_n as defined above we have that $\Sigma \|\Delta a_n(T)\|$ and $\Sigma \|\Delta B_n(T)\|$ converge and tend to zero with Σr_n and hence with $\|\delta T\|$.

Making use of the formulae, valid when a, U, V are differentiable

$$\begin{aligned}\delta(a \circ U) &= (\delta a) \circ U, \\ \delta(U \otimes V) &= (\delta U) \otimes V + U \otimes \delta V, \\ \delta[U] &= [\delta U]\end{aligned}$$

we have again from (3.1) and (3.2)

$$(7.5) \quad n \delta a_n(T) = (\delta a_{n-1}(T)) [T] + a_{n-1}(T) [\delta T] \\ - [(\delta B_{n-1}(T)) T + B_{n-1}(T) \delta T],$$

$$(7.6) \quad \delta B_n(T) = (\delta a_{n-1}(T)) T + a_{n-1}(T) \delta T \\ - (\delta B_{n-1}(T)) T + B_{n-1}(T) \delta T.$$

Subtracting (7.5) from (7.3) and (7.6) from (7.4) we obtain, using (7.1) and (7.2)

$$(7.7) \quad n \|\delta T\| \varepsilon_n = \|\delta T\| \varepsilon_{n-1} [T] + (\Delta a_{n-1}(T)) [\delta T] \\ - [\|\delta T\| \varepsilon_{n-1} T + (\Delta B_{n-1}(T)) \delta T]$$

and

$$(7.8) \quad \|\delta T\| \varepsilon_n = \|\delta T\| \varepsilon_{n-1} T + (\Delta a_{n-1}(T)) \delta T - [\|\delta T\| \varepsilon_{n-1} T + (\Delta B_{n-1}(T)) \delta T].$$

Taking norms of (7.7) and (7.8) we obtain the inequalities

$$(7.9) \quad n \|\varepsilon_n\| \leq \gamma (\|\varepsilon_{n-1}\| \|T\| + \|\Delta a_{n-1}\| + \|\varepsilon_{n-1}\| \|T\| + \|\Delta B_{n-1}\|),$$

$$(7.10) \quad \|\varepsilon_n\| \leq \|\varepsilon_{n-1}\| \|T\| + \|\Delta a_{n-1}\| + \|\varepsilon_{n-1}\| \|T\| + \|\Delta B_{n-1}\|.$$

Again Applying the Lemma to (7.9) and (7.10) and using what we have just proved for $\Sigma \|\Delta a_n\|$ and $\Sigma \|\Delta B_n\|$ we obtain the result that $\Sigma \|\varepsilon_n\|$ and $\Sigma \|\varepsilon'_n\|$ converge and tend to zero with $\delta \|T\|$.

Taking norms of (7.5) and (7.6), dividing by $\|T\|^{n-1}$ and taking the maximum of both sides quâ T we have

$$(7.11) \quad n(m \delta a_n) \leq \gamma_1 (m \delta a_{n-1}) + (m \delta B_{n-1}) + (m a_{n-1} + m B_{n-1}) \|\delta T\|,$$

$$(7.12) \quad (m \delta B_n) \leq (m \delta a_{n-1}) + (m \delta B_{n-1}) + (m a_{n-1} + m B_{n-1}) \|\delta T\|.$$

Let τ_1 be a positive number less than unity. Multiply both sides of (7.11), (7.12) by τ_1^{n-1} and apply the Lemma taking

$$c_n = \tau_1^{n-1} m \delta a_n, \quad f_n = \tau_1^{n-1} m \delta B_n, \quad \lambda = \tau_1, \quad \mu = \gamma$$

and

$$r_n = r_1^{n-1} (m a_{n-1} + m B_{n-1}) \|\delta T\|.$$

Since by Theorem 4.1, Σr_n converges it follows at once that

$$\Sigma r_1^{n-1} (m \delta a_n)$$

and

$$\Sigma r_1^{n-1} (m \delta B_n)$$

have radii of convergence not less than unity. Thus $\Sigma \delta a_n$ and $\Sigma \delta B_n$ represent functions analytic ($r \geq 1$) at $T = 0$.

Finally from the convergence of $\Sigma \|\varepsilon_n\|$ and $\Sigma \|\varepsilon'_n\|$, and the completeness of the space S we have that $\Sigma \varepsilon_n$ and $\Sigma \varepsilon'_n$ converge in the norm, and that $\|\Sigma \varepsilon_n\|$ and $\|\Sigma \varepsilon'_n\|$ tend to zero with $\|\delta T\|$. Summing (7.1) and (7.2) we have for $\|T\| + \|\delta T\| < 1$

$$\Delta D(T) = \Sigma \delta a_n(T) = \|\delta T\| \varepsilon(T, \delta T),$$

$$\Delta B(T) = \Sigma \delta B_n(T) = \|\delta T\| \varepsilon'(T, \delta T).$$

This completes the proof of the theorem.

8. THE INVERSE OF $I + T$ FOR $\|T\| < 1$. THEOREM 8.1. — *If $\|T\| < 1$ then*

$$I = \frac{B(T)}{D(T)}$$

is an inverse to $I + T$.

Proof: We have for $\|T\| < 1$

$$(8.1) \quad D(T)T = B(T) = B(T)T = 0,$$

for from the definitions of $D(T)$ and $B(T)$, the recurrence formulae (3.1) and (3.2), Theorem 4.III and the vanishing of $B_0(T)$ we have

$$D_0(T)T = B_0(T)T = \sum_{n=1}^{\infty} (a_n(T)T - B_n(T)T) = \sum_{n=1}^{\infty} B_{n-1}(T) = B(T).$$

By a simple calculation we see from (8.1) that the theorem is proved for those values of T for which $D(T) \neq 0$. For all T for which $\|T\| < 1$ and $D(T) \neq 0$ we have by Theorem 5.II

$$(8.2) \quad \frac{B(T)}{D(T)} = \sum_{n=1}^{\infty} (-1)^{n-1} T^n.$$

Let T_1 be any chosen T such that $\|T_1\| < 1$. From the remark preceding Theorem 4.111 we have that

$$D(\lambda T_1) = \sum_0^{\infty} \lambda^n a_n(T_1)$$

is an analytic function on A to A for

$$|\lambda| < \frac{1}{\|T_1\|}.$$

From the recursion formula (3.2) we have

$$(8.3) \quad \lambda \frac{d}{d\lambda} D(\lambda T_1) = \sum_0^{\infty} n \lambda^n a_n(T_1) = \sum_0^{\infty} \lambda^n [B_n(T_1)] \\ = \sum_0^{\infty} [B_n(\lambda T_1)] = [B(\lambda T_1)].$$

For all λ in A such that $|\lambda| < \frac{1}{\|T_1\|}$ and $D(\lambda T_1) \neq 0$ we have using (8.3) and (8.2) with $T = \lambda T_1$

$$(8.4) \quad \frac{\sum_0^{\infty} n \lambda^{n+1} a_n(T_1)}{\sum_0^{\infty} \lambda^n a_n(T_1)} = \sum_0^{\infty} (-1)^n \lambda^n [T_1^{n+1}] = 0.$$

Since we clearly have

$$|(-1)^n [T_1^{n+1}]| \leq \gamma \|T_1\|^{n+1}$$

it follows that

$$\sum_0^{\infty} (-1)^n \lambda^n [T_1^{n+1}]$$

defines an analytic function of λ for $|\lambda| < \frac{1}{\|T_1\|}$.

The left hand side of (8.4) regarded as a function of a general complex variable λ is analytic in the region $|\lambda| < \frac{1}{\|T_1\|}$ except possibly for poles, and vanishes for λ in A and in the above region except at the zeros of $D(\lambda T_1)$, that is, it has zeros which are not isolated. It

follows (1) that (8.4) is an identity for complex λ in the region $|\lambda| < \frac{1}{\|T_1\|}$. Let C be a circle of radius φ ($1 < \varphi < \frac{1}{\|T_1\|}$) whose center is at the origin and whose circumference passes through none of the zeros (if any) of $\sum_n \lambda^n a_n(T_1)$. Integrating (8.4) around C we have

$$\int_C \frac{\frac{d}{dt} \left(\sum_n \lambda^n a_n(T_1) \right)}{\sum_n \lambda^n a_n(T_1)} dt = 0.$$

It follows immediately from a well known theorem that $\sum_n \lambda^n a_n(T_1)$ has no zeros inside C . Placing $\lambda = 1$ we see that $D(T_1) \neq 0$. But T_1 is any T in the region $\|T\| < 1$. The argument of the first part of the proof is therefore valid for all T in $\|T\| < 1$.

Corollary 1. — For any chosen T_1 , if $|\lambda| < \frac{1}{\|T_1\|}$, then $D(\lambda T_1)$ is not zero.

Corollary 2. — For $\|T\| < 1$

$$(8.5) \quad \log D(T) = \sum_{n=1}^{\infty} (-1)^{n-1} \frac{\|T^n\|}{n}.$$

Proof: Integrate (8.4) from 0 to 1.

9. THE PRODUCT THEOREM FOR $D(T)$. THEOREM 9.1. — *The differential of the polynomial $a_n(T)$ is given by*

$$(9.1) \quad \delta a_n(T) = a_{n-1}(T) [\delta T] - [B_{n-1}(T) \delta T] \quad (n > 0).$$

Proof: We first establish by induction the formula, evident for $n = 1$,

$$(9.2) \quad \delta a_n(T) = \sum_{r=0}^{n-1} (-1)^r a_{n-r-1}(T) [T^r \delta T].$$

(1) E. GOURSAT, *Cours d'Analyse mathématique*, 4^e édition, t. II, p. 98.

Differentiation of (3.1) gives

$$(9.3) \quad n \partial a_n(T) = \sum_{i=0}^{n-1} (-1)^i (\partial x_{n-i-1}) [T^{i+1}] \\ + \sum_{j=0}^{n-1} (-1)^j (j+1) a_{n-i-1} [T^j \partial T].$$

Assuming (9.2) for $(1, 2, \dots, n-1)$, substituting the result in the first sum on the right hand side of (9.3), reversing the summations and making use of (3.4), we have

$$n \partial a_n(T) = \sum_{r=0}^{n-1} (-1)^r (n-r-1) a_{n-r-1} [T^r \partial T] \\ + \sum_{i=0}^{n-1} (-1)^i (j+1) a_{n-i-1} [T^i \partial T]$$

which gives (9.2)

From (3.3) we have

$$(9.4) \quad [B_{n-1}(T) \partial T] = \sum_{r=1}^{n-1} (-1)^{r+1} a_{n-r-1} [T^r \partial T].$$

The theorem follows by adding (9.2) and (9.4).

With the aid of Theorems 7.1 and 9.1 we obtain the corollary.

COROLLARY. — *The differential $\partial D(T)$ is given for $\|T\| < 1$ by*

$$\partial D(T) = D(T) [\partial T] - [B(T) \partial T].$$

THEOREM 9. II. — *If $\|T\| < 1$, $\|U\| < 1$ and if for $0 \leq \lambda \leq 1$*

$$\|\lambda(T+U) + \lambda^2 TU\| < 1$$

then

$$(9.5) \quad D(T+U+TU) = D(T) D(U).$$

Proof : By successive use of a theorem (1) (proved elsewhere) on the differentials of a function of a function in vector spaces, by the

(1) M. FRÉCHET, *Annales sc. de l'École Normale supérieure*, vol. 42, 1925.
See also R. S. MARTIN, *loc. cit.*

corollary to Theorem 9.1 and by Corollary 1 to Theorem 8.1 we have for $|\lambda| \leq 1$

$$\frac{d}{d\lambda} \log D(\lambda T) = [T] - \left[\frac{B(\lambda T)}{D(\lambda T)} T \right]$$

which may be written in the convenient form

$$(9.6) \quad \frac{d}{d\lambda} \log D(\lambda T) = [\bar{T}(\lambda T) T],$$

where

$$\bar{T}(\lambda T) = I - \frac{B(\lambda T)}{D(\lambda T)},$$

is the inverse of $I + \lambda T$. Similarly

$$(9.7) \quad \frac{d}{d\lambda} \log D(\lambda U) = [\bar{U}(\lambda U) U].$$

Let $W(\lambda)$ be defined by means of

$$(9.8) \quad I + W(\lambda) = (I + \lambda T)(I + \lambda U).$$

Then

$$(9.9) \quad \frac{d}{d\lambda} \log D(W(\lambda)) = \left[\frac{dW}{d\lambda} \right] - \left[\frac{B(W)}{D(W)} \frac{dW}{d\lambda} \right] = \left[\bar{W} \frac{dW}{d\lambda} \right],$$

where $\bar{W}$ is the inverse of $I + W(\lambda)$. By Corollary 2 to Theorem 5.1

$$\bar{W} = \bar{U} \bar{T}.$$

Differentiating (9.8) we have

$$\frac{dW}{d\lambda} = (I + \lambda T)U + T(I + \lambda U).$$

Placing the last two results in (9.9) and making spécial use of postulate 5 for the space S , we have

$$\frac{d}{d\lambda} \log D(W(\lambda)) = [\bar{T}T] + [\bar{U}U].$$

Hence by (9.6) and (9.7)

$$(9.10) \quad \frac{d}{d\lambda} \log D(W(\lambda)) = \frac{d}{d\lambda} \log D(\lambda T) + \frac{d}{d\lambda} \log D(\lambda U).$$

Since the derivatives in (9.10) are in the ordinary sense we may integrate from 0 to 1 and take exponentials. This gives (9.5).

COROLLARY. — If $|T| < \sqrt{2} - 1$ and $|U| < \sqrt{2} - 1$ then the conclusions (9.5) hold.

10. *Concluding Remarks.* — If the elements T of the space S are matrices (t_j^i) of a finite order s and if

$$|T| = \sum_{i=1}^s t_i^i$$

then a_r is precisely the coefficient of λ^r in the determinant

$$D = |\delta_j^i + \lambda t_j^i| \quad (1)$$

and B_r is given by $a_r I - A_r$ where A_r is the coefficient of λ^r in the adjoint of D so that for $r > s$, $B_r = 0$. The equation (3.3) for $n = s + 1$ with the condition $B_{s+1} = 0$ is equivalent to the theorem that T satisfies its characteristic equation. In the case of a general space S , if T is such a point that $D(T)$ and $B(T)$ converge, then $|B_r| \rightarrow 0$ with $\frac{1}{r}$ and one may, if he so chooses, regard the limiting form of (3.3) as the generalization of the algebraic theorem.

(1) Where $\delta_j^i = \begin{cases} 1 & \text{if } i=j, \\ 0 & \text{if } i \neq j. \end{cases}$

