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HIGHER ORDER FRAMES AND LINEAR CONNECTIONS

by YUEN Ping Cheng

Introduction.

In the first part of this paper we develop some elementary properties of semi-holonomic k -frames parallel to those of holonomic k -frames. Our definition of a semi-holonomic k -frame is essentially equivalent to the one originally given by Ehresmann [1b]; our formulation, however, leads us easily to define a canonical 1-form θ_k on the principal fibre bundle $\bar{H}^k(V_n)$ of semi-holonomic k -frames on a differentiable manifold V_n . If we restrict θ_k to the principal sub-bundle $H^k(V_n)$ of holonomic k -frames on V_n , we obtain the canonical 1-form given by Kobayashi [3]. Our main result is the "Holonomy Theorem" where we give a geometrical interpretation of the holonomy conditions in terms of the canonical 1-form. This result will be useful for studying the integrability of higher order G -structures. These preliminary results served originally as an introductory part to a forthcoming paper which deals with the structure tensors of higher order regular G -structures and higher order geometric structures.

The second part of this paper deals with the higher order linear connections. Let V_n be a differentiable manifold. A linear connection of order k on V_n is an infinitesimal connection on the principal fibre bundle $\bar{H}^k(V_n)$. Its torsion form is defined to be the exterior covariant derivative of θ_k . There is a one-to-one correspondence between the set of linear connections of order k (resp. quasi-holonomic linear connections of order k without torsion) on V_n and the set of invariant sections of the canonical projection $\bar{H}^{k+1}(V_n) \rightarrow H^1(V_n)$. We show further that a linear connection of order k on V_n is locally flat if and only if it can be obtained by successive prolongations of a first order linear connection without torsion and curvature. Some of these results have been summarized in [6] and are prepublished in French, in the first part of the author's thesis [7]. If V_n is a differentiable manifold, $T_x(V_n)$ is the tangent vector space of V_n at x .

Part I

HIGHER ORDER FRAMES

1. Semi-holonomic frames.

Let V_n be an n -dimensional C^∞ -differentiable manifold. A *first order frame* (or a *1-frame*) of V_n at the point x is an invertible 1-jet of $\mathbf{R}^n$ into V_n with source $0 \in \mathbf{R}^n$ and target $x \in V_n$. The manifold of all 1-frames of V_n , denoted by $H^1(V_n)$, forms a principal fibre bundle over V_n with natural projection π_0^1 which assigns to each 1-jet its target, the structure group being $L_n^1 = GL(n, \mathbf{R})$. The trivial bundle $H^1(\mathbf{R}^n) \approx \mathbf{R}^n \times L_n^1$ can be identified with the group of all affine transformations on $\mathbf{R}^n$. There is a distinguished element in $H^1(\mathbf{R}^n)$, namely the 1-frame e_1 of $\mathbf{R}^n$ defined by the 1-jet of the identity mapping of $\mathbf{R}^n$ onto $\mathbf{R}^n$ with source 0.

Let $b: H^1(\mathbf{R}^n) \rightarrow H^1(V_n)$ be a local isomorphism. It induces a local diffeomorphism f of $\mathbf{R}^n$ into V_n with $f \circ \pi_0^1 = \pi_0^1 \circ b$ (pseudo-products); we will denote all natural projections by the same symbol π with indices. We say that b is *1-admissible* if the domain of b contains e_1 and $b(e_1) = j_0^1 f$. (Here $j_0^1 f$ denotes the 1-jet of f with source 0).

The manifold of 1-jets $j_{e_1}^1 b$, where b is a 1-admissible local isomorphism of $H^1(\mathbf{R}^n)$ into $H^1(V_n)$, will be denoted by $\bar{H}^2(V_n)$. There are two natural bundle structures on $\bar{H}^2(V_n)$:

i) $\bar{H}^2(V_n)$ forms a principal fibre bundle over $H^1(V_n)$ with natural projection π_1^2 and structure group $\bar{M}_n^2$ consisting of all 1-jets of 1-admissible local isomorphisms of $H^1(\mathbf{R}^n)$ into $H^1(\mathbf{R}^n)$ with source and target e_1 . The structure group $\bar{M}_n^2$ acts on $\bar{H}^2(V_n)$ on the right by the composition of jets. Moreover $\pi_1^2(j_{e_1}^1 b) = b(e_1) = j_0^1 f$.

ii) $\bar{H}^2(V_n)$ forms a principal fibre bundle over V_n with projection $\pi_0^2 = \pi_0^1 \circ \pi_1^2$ and structure group $\bar{L}_n^2$. Here $\bar{L}_n^2$ is the fibre of $\bar{H}^2(\mathbf{R}^n)$ over the origin $0 \in \mathbf{R}^n$. The multiplication in $\bar{L}_n^2$ is given by: if $g_1 = j_{e_1}^1 b_1 \in \bar{L}_n^2$ and $g_2 = j_{e_1}^1 b_2 \in \bar{L}_n^2$, then the pseudo-product $b_1 \circ b_2$ is a 1-admissible local isomorphism and $g_1 \cdot g_2 = j_{e_1}^1 (b_1 \circ b_2)$ depends only on $j_{e_1}^1 b_1$ and $j_{e_1}^1 b_2$. Notice there is again a distinguished element in $\bar{H}^2(\mathbf{R}^n) \approx \mathbf{R}^n \times \bar{L}_n^2$,

namely the element e_2 defined by the 1-jet of the identity mapping of $H^1(\mathbf{R}^n)$ onto $H^1(\mathbf{R}^n)$ with source e_1 . An element $z \in \bar{H}^2(V_n)$ will be called a *semi-holonomic 2-frame* of V_n at the point $x = \pi_0^2(z)$.

We define by recurrence the principal fibre bundle $\bar{H}^k(V_n)$ of semi-holonomic k -frames of V_n . Let us assume that we have defined the principal fibre bundle $\bar{H}^{k-1}(V_n)$ of semi-holonomic $(k-1)$ -frames of V_n , with base space V_n , structure group $\bar{L}_n^{k-1}$ and projection π_{k-2}^{k-1} on $\bar{H}^{k-2}(V_n)$. A local isomorphism $u: \bar{H}^{k-1}(\mathbf{R}^n) \rightarrow \bar{H}^{k-1}(V_n)$ is said $(k-1)$ -admissible if:

i) v is $(k-2)$ -admissible, where v is the local isomorphism of $\bar{H}^{k-2}(\mathbf{R}^n)$ into $\bar{H}^{k-2}(V_n)$ induced by u , such that $v \circ \pi_{k-2}^{k-1} = \pi_{k-2}^{k-1} \circ u$.

ii) $u(e_{k-1}) = j_{e_{k-2}}^1 v$, where e_{k-1} (resp. e_{k-2}) is the distinguished element in $\bar{H}^{k-1}(\mathbf{R}^n)$ (resp. $\bar{H}^{k-2}(\mathbf{R}^n)$).

The set $\bar{H}^k(V_n)$ of 1-jets of the form $j_{e_{k-1}}^1 u$, where u is a $(k-1)$ -admissible local isomorphism of $\bar{H}^{k-1}(\mathbf{R}^n)$ into $\bar{H}^{k-1}(V_n)$, forms a principal fibre bundle over V_n with structure group $\bar{L}_n^k$; the underlying set of $\bar{L}_n^k$ is just the fibre of $\bar{H}^k(\mathbf{R}^n)$ over $0 \in \mathbf{R}^n$. The space $\bar{H}^k(V_n)$ can also be regarded as a principal fibre bundle over $\bar{H}^{k-1}(V_n)$ with structure group $\bar{M}_n^k = \text{Ker}(\bar{L}_n^k \rightarrow \bar{L}_n^{k-1})$. An element z of $\bar{H}^k(V_n)$ will be called a *semi-holonomic k -frame* of V_n at the point x , where x is the projection of z into V_n .

For $m < k$, the natural projection π_m^k of $\bar{H}^k(V_n)$ onto $\bar{H}^m(V_n)$ is compatible with the surjective homomorphism of $\bar{L}_n^k$ onto $\bar{L}_n^m$. The distinguished element e_k in $\bar{H}^k(\mathbf{R}^n) = \mathbf{R}^n \times \bar{L}_n^k$ is defined by the 1-jet of the identity mapping of $\bar{H}^{k-1}(\mathbf{R}^n)$ with source e_{k-1} .

2. Canonical form on $\bar{H}^k(V_n)$.

An element $u \in \bar{H}^k(V_n)$ can be written as $u = j_{e_{k-1}}^1 b$, where b is a $(k-1)$ -admissible local isomorphism of $\bar{H}^{k-1}(\mathbf{R}^n)$ into $\bar{H}^{k-1}(V_n)$; it determines a linear isomorphism $\tilde{u}$ of $\bar{E}^{k-1} = T_{e_{k-1}}(\bar{H}^{k-1}(\mathbf{R}^n))$ onto $T_u(\bar{H}^{k-1}(V_n))$ with $u' = \pi_{k-1}^k(u) \in \bar{H}^{k-1}(V_n)$. Since $\bar{H}^{k-1}(\mathbf{R}^n) \approx \mathbf{R}^n \times \bar{L}_n^{k-1}$, we have a canonical decomposition $\bar{E}^{k-1} = \mathbf{R}^n \oplus \bar{\mathcal{Q}}_n^{k-1}$, where $\bar{\mathcal{Q}}_n^{k-1}$ is the Lie algebra of $\bar{L}_n^{k-1}$. From now on, we will identify $\mathbf{R}^n$ with a vector subspace of $\bar{E}^{k-1}$ given by the canonical decomposition. Since $\tilde{u}$ is a linear isomorphism, $\tilde{u}(\mathbf{R}^n)$ is an n -dimensional vector subspace of $T_u(\bar{H}^{k-1}(V_n))$.

transversal to the fibres, called the *horizontal n -plane* associated to the k -frame u .

Let v be the projection of u under π_m^k . The following diagram

$$\begin{array}{ccc} \bar{E}^{k-1} & \xrightarrow{\tilde{u}} & T_u(\bar{H}^{k-1}(V_n)) \\ \downarrow & & \downarrow \\ \bar{E}^{m-1} & \xrightarrow{\tilde{v}} & T_v(\bar{H}^{m-1}(V_n)) \end{array}$$

is commutative, where v' is the projection of v under π_{m-1}^m and where the vertical arrows are the natural projections.

Consider a vector $Z \in T_u(\bar{H}^k(V_n))$. Its image $Z' = T\pi_{k-1}^k(Z)$ under the tangential map $T\pi_{k-1}^k$ is tangent to $\bar{H}^{k-1}(V_n)$ at the point $u' = \pi_{k-1}^k(u)$.

The $\bar{E}^{k-1}$ -valued differential 1-form θ_k defined by

$$\theta_k(Z) = \tilde{u}^{-1}(T\pi_{k-1}^k(Z))$$

will be called the *canonical form* on $\bar{H}^k(V_n)$. For $m < k$, we have the following commutative diagram

$$\begin{array}{ccc} T(\bar{H}^k(V_n)) & \xrightarrow{\theta_k} & \bar{E}^{k-1} \\ \downarrow & & \downarrow \\ T(\bar{H}^m(V_n)) & \xrightarrow{\theta_m} & \bar{E}^{m-1} \end{array}$$

where the vertical arrows are the natural projections.

The Lie group $\bar{L}_n^k$ acts naturally on $\bar{E}^{k-1}$ on the left. Each element g of $\bar{L}_n^k$ defines a linear isomorphism $\tilde{g}$ of $\bar{E}^{k-1}$ onto $T_{g'}(\bar{H}^{k-1}(\mathbf{R}^n))$ with $g' = \pi_{k-1}^k(g)$. The right translation $R_g^{-1} = R_{(g')^{-1}}$ determines a linear isomorphism TR_g^{-1} of $T_{g'}(\bar{H}^{k-1}(\mathbf{R}^n))$ onto $\bar{E}^{k-1}$. If we put $\rho(g) = TR_g^{-1} \circ \tilde{g}$, we obtain a linear representation ρ of $\bar{L}_n^k$ on the vector space $\bar{E}^{k-1}$. For $m < k$,

$$\begin{array}{ccc} \bar{E}^{k-1} & \xrightarrow{\rho(g)} & \bar{E}^{k-1} \\ \downarrow & & \downarrow \\ \bar{E}^{m-1} & \xrightarrow{\rho(\pi_m^k(g))} & \bar{E}^{m-1} \end{array}$$

is a commutative diagram, where the vertical arrows are the natural projections.

PROPOSITION 1.1. *The canonical form θ_k is a pseudo-tensorial 1-form on $\bar{H}^k(V_n)$ of type $(\rho, \bar{E}^{k-1})$, i.e.*

$$\theta_k(TR_g(Z)) = \rho(g^{-1})\theta_k(Z)$$

for all $Z \in T(\bar{H}^k(V_n))$ and $g \in \bar{L}_n^k$.

3. Holonomic Frames.

A diffeomorphism $f: V_n \rightarrow V'_n$ induces a principal fibre bundle isomorphism $f^{(k)}$ of $\bar{H}^k(V_n)$ onto $\bar{H}^k(V'_n)$. This isomorphism $f^{(k)}$ possesses the following properties:

i) $\pi_m^k \circ f^{(k)} = f^{(m)} \circ \pi_m^k$ for all $0 \leq m < k$;

ii) $f^{(k)}$ is compatible with the canonical forms, i.e. $f^{(k)*}\theta'_k = \theta_k$, where θ_k (resp. θ'_k) is the canonical form on $\bar{H}^k(V_n)$ (resp. $\bar{H}^k(V'_n)$).

THEOREM 1.2. *Let ϕ be a local diffeomorphism of $\bar{H}^k(V_n)$ into $\bar{H}^k(V'_n)$. Then locally $\phi = f^{(k)}$ for some local diffeomorphism f of V_n into V'_n , if and only if ϕ is compatible with the canonical forms, i.e. $\phi^*\theta'_k = \theta_k$.*

It remains to show that the condition is sufficient. For this we will proceed by induction on k .

LEMMA 1.3. *Let ϕ be a local diffeomorphism of $H^1(V_n)$ into $H^1(V'_n)$ with $\phi^*\theta'_1 = \theta_1$. Then we can locally write $\phi = f^{(1)}$ for some local diffeomorphism f of V_n into V'_n .*

Consider a tangent vector $Z \in T_u(H^1(V_n))$ with $T\pi_0^1(Z) = 0$. The condition $\phi^*\theta'_1 = \theta_1$ implies that $T\pi_0^1(T\phi(Z)) = 0$. Thus ϕ sends a tangent space to the fibre of $H^1(V_n)$ onto a tangent space to the fibre of $H^1(V'_n)$. This means that locally ϕ is a fibre map and induces a map f of V_n into V'_n satisfying $f \circ \pi_0^1 = \pi_0^1 \circ \phi$. We want to show that $\phi = f^{(1)}$. Thus we want to show that for any u with $\pi_0^1(u) = x$ we have $\phi(u) = j_x^1 f \circ u$. Let $\xi \in \mathbb{R}^n$. Choose a vector $Z \in T_u(H^1(V_n))$ with $T\pi_0^1(Z) = \tilde{u}(\xi)$. Then $(j_x^1 f \circ \tilde{u})(\xi) = (Tf \circ \tilde{u})(\xi) = (Tf \circ T\pi_0^1)(Z) = (T\pi_0^1 \circ T\phi)(Z)$. On the other hand, $(\widetilde{\phi(u)})^{-1} \circ T\pi_0^1 \circ T\phi(Z) = (\tilde{u}^{-1} \circ T\pi_0^1)(Z) = \xi$. Thus

$\phi(u) = j_x^1 f \circ u$ holds proving the lemma.

To prove the theorem for k we may assume that it has been established for $k-1$. Let $Z \in T_u(\bar{H}^k(V_n))$ with $T\pi_{k-1}^k(Z) = 0$. The condition $\phi^*\theta'_k = \theta_k$ implies $(T\pi_{k-1}^k \circ T\phi)(Z) = 0$. Thus ϕ is a local fibre map with respect to the fibrations $\bar{H}^k(V_n) \rightarrow \bar{H}^{k-1}(V_n)$ and $\bar{H}^k(V'_n) \rightarrow \bar{H}^{k-1}(V'_n)$. There exists a local diffeomorphism ψ of $\bar{H}^{k-1}(V_n)$ into $\bar{H}^{k-1}(V'_n)$ such that $\psi \circ \pi_{k-1}^k = \pi_{k-1}^k \circ \phi$. Since $\pi_{k-1}^{k*} \theta_{k-1} = T\pi_{k-2}^{k-1} \circ \theta_k$ (resp. $\pi_{k-1}^{k*} \theta'_{k-1} = T\pi_{k-2}^{k-1} \circ \theta'_k$), we have

$$\begin{aligned} (\pi_{k-1}^{k*}(\psi^*\theta'_{k-1}))(Z) &= (\theta'_{k-1} \circ T\psi \circ T\pi_{k-1}^k)(Z) \\ &= (\theta'_{k-1} \circ T\pi_{k-1}^k \circ T\phi)(Z) \\ &= (\pi_{k-1}^{k*} \theta'_{k-1})(T\phi(Z)) \\ &= (T\pi_{k-2}^{k-1} \circ \theta'_k \circ T\phi)(Z) \\ &= (T\pi_{k-2}^{k-1} \circ \theta_k)(Z) \\ &= (\pi_{k-1}^{k*} \theta_{k-1})(Z) \end{aligned}$$

for all $Z \in T_u(\bar{H}^k(V_n))$. As π_{k-1}^k is surjective, we deduce that $\psi^*\theta'_{k-1} = \theta_{k-1}$. By the induction hypothesis, there exists a local diffeomorphism f of V_n into V'_n such that locally $\psi = f^{(k-1)}$. We have thus $f^{(k-1)} \circ \pi_{k-1}^k = \pi_{k-1}^k \circ \phi$ locally. Now we are going to show that locally $\phi = f^{(k)}$. An element $u \in \bar{H}^k(V_n)$ determines a linear isomorphism $\tilde{u}: \bar{E}^{k-1} \rightarrow T_u(\bar{H}^{k-1}(V_n))$ with $u' = \pi_{k-1}^k(u)$. Two elements u and v of $\bar{H}^k(V_n)$ are identical if and only if $\tilde{u} = \tilde{v}$. It suffices therefore to show that $\widetilde{\phi(u)} = \widetilde{f^{(k)}(u)}$ for all $u \in \bar{H}^k(V_n)$. Let $\xi \in \bar{E}^{k-1}$. Choose a tangent vector $Z \in T_u(\bar{H}^k(V_n))$ with $\theta_k(Z) = \xi$. We have

$$\theta_k(Z) = (\phi^*\theta'_k)(Z) = (\theta'_k \circ T\phi)(Z) = (\widetilde{\phi(u)})^{-1} \circ T\pi_{k-1}^k \circ T\phi(Z).$$

On the other hand, $\xi = \theta_k(Z) = (\tilde{u}^{-1} \circ T\pi_{k-1}^k)(Z)$. It follows that for all $\xi \in \bar{E}^{k-1}$,

$$\begin{aligned} \widetilde{\phi(u)}(\xi) &= (T\pi_{k-1}^k \circ T\phi)(Z) = (Tf^{(k-1)} \circ T\pi_{k-1}^k)(Z) \\ &= (Tf^{(k-1)} \circ \tilde{u})(\xi) = \widetilde{f^{(k)}(u)}(\xi). \end{aligned}$$

We have therefore $\phi = f^{(k)}$ locally and our theorem is proved.

COROLLARY 1.4. *Let ϕ be a principal fibre bundle isomorphism of $\bar{H}^k(V_n)$ onto $\bar{H}^k(V'_n)$. Let f be the diffeomorphism of V_n onto V'_n induced by ϕ . Then $\phi = f^{(k)}$ if and only if $\phi^* \theta'_k = \theta_k$.*

Consider a local diffeomorphism f of an open neighbourhood of $0 \in \mathbf{R}^n$ onto an open set of V_n . It induces a $(k-1)$ -admissible local isomorphism $f^{(k-1)}: \bar{H}^{k-1}(\mathbf{R}^n) \rightarrow \bar{H}^{k-1}(V_n)$. It follows that $u = j_{e_{k-1}}^1 f^{(k-1)}$ is an element of $\bar{H}^k(V_n)$. We say that $u \in \bar{H}^k(V_n)$ is a *holonomic k -frame* of V_n if u can be written as $u = j_{e_{k-1}}^1 f^{(k-1)}$ for some local diffeomorphism f of $\mathbf{R}^n$ into V_n . A k -frame u of V_n is holonomic if and only if one can find a representative for u compatible with the canonical forms. The set of holonomic k -frames of V_n forms a principal fibre subbundle $H^k(V_n)$ of $\bar{H}^k(V_n)$. Its structure group is the subgroup L_n^k of $\bar{L}_n^k$ consisting of holonomic elements. Notice there is a group isomorphism between L_n^k and the group of all invertible k -jets of $\mathbf{R}^n$ into $\mathbf{R}^n$ with source and target 0. The space $H^k(V_n)$ can also be regarded as a principal fibre bundle over $H^{k-1}(V_n)$ with structure group $M_n^k = \bar{M}_n^k \cap L_n^k$, kernel of the surjective homomorphism $L_n^k \rightarrow L_n^{k-1}$.

4. Relations between $\bar{H}^k(V_n)$, $\bar{P}^k(V_n)$ and $\bar{J}^{k-1}(H^1(V_n))$.

Let W and Y be two C^∞ -differentiable manifolds. We will denote by $\bar{J}^k(W, Y)$ the differentiable manifold of semi-holonomic k -jets of W into Y . For the definition of semi-holonomic jets, see the works of Ehresmann. For $m < k$, let p_m^k be the canonical projection of $\bar{J}^k(W, Y)$ onto $\bar{J}^m(W, Y)$. A jet $X \in \bar{J}^k(W, Y)$ is invertible if and only if $p_1^k(X)$ is invertible. Let $\bar{\Pi}^k(W, Y)$ denote the set of invertible jets in $\bar{J}^k(W, Y)$. This set is then the inverse image of $\bar{\Pi}^1(W, Y)$ by the submersion p_1^k . Since $\bar{\Pi}^1(W, Y)$ is an open submanifold of $\bar{J}^1(W, Y) \equiv J^1(W, Y)$, it follows that $\bar{\Pi}^k(W, Y)$ is an open submanifold of $\bar{J}^k(W, Y)$. Moreover, $p_m^k: \bar{\Pi}^k(W, Y) \rightarrow \bar{\Pi}^m(W, Y)$ is a submersion.

A semi-holonomic k -frame (resp. holonomic k -frame) of V_n in the sense of Ehresmann is an invertible semi-holonomic k -jet (resp. invertible holonomic k -jet) of $\mathbf{R}^n$ into V_n with source $0 \in \mathbf{R}^n$. The set $\bar{P}^k(V_n)$ (resp.

$P^k(V_n)$) of semi-holonomic k -frames (resp. holonomic k -frames) of V_n in the sense of Ehresmann has a principal fibre bundle structure over V_n , the structure group being the group of all invertible semi-holonomic k -jets (resp. holonomic k -jets) of $\mathbf{R}^n$ into $\mathbf{R}^n$ with source and target $0 \in \mathbf{R}^n$. An element $u \in \bar{P}^k(V_n)$ can then be written as $u = j_0^1 f$, where f is a differentiable mapping of $\mathbf{R}^n$ into $\bar{P}^{k-1}(V_n)$ satisfying the condition:

$$j_0^1(p_{k-2}^{k-1} \circ f) = f(0).$$

Here we have also denoted by p_{k-2}^{k-1} the canonical projection of $\bar{P}^{k-1}(V_n)$ onto $\bar{P}^{k-2}(V_n)$.

THEOREM 1.5. *There exists a canonical diffeomorphism ν_k of $\bar{H}^k(V_n)$ onto $\bar{P}^k(V_n)$ satisfying the properties:*

- (1) ν_k is a fibre map, i.e. $p_0^k \circ \nu_k = \pi_0^k$;
- (2) for $m < k$,

$$\begin{array}{ccc} \bar{H}^k(V_n) & \xrightarrow{\nu_k} & \bar{P}^k(V_n) \\ \pi_m^k \downarrow & & \downarrow p_m^k \\ \bar{H}^m(V_n) & \xrightarrow{\nu_m} & \bar{P}^m(V_n) \end{array}$$

is a commutative diagram;

(3) ν_k , restricted to $H^k(V_n)$, is a diffeomorphism of $H^k(V_n)$ onto $P^k(V_n)$.

We prove the theorem by induction on k . For $k=1$, $H^1(V_n)$ is identical with $P^1(V_n)$ and ν_1 is just the identity map. Let $u = j_{e_1}^1 b$ be an arbitrary element in $\bar{H}^2(V_n)$. If η_1 denotes the «zero section»^{*} of $H^1(\mathbf{R}^n)$ the mapping $u \mapsto \nu_2(u) = j_0^1(\nu_1 \circ b \circ \eta_1)$ defines a diffeomorphism of $\bar{H}^2(V_n)$ onto $\bar{P}^2(V_n)$, because the composition of jets is a differentiable map. Let us assume there exists ν_{k-1} such that, for all $z \in \bar{H}^{k-1}(V_n)$, $\nu_{k-1}(z) = (j_z^1, \nu_{k-1}) \circ z \circ (j_0^1 \eta_{k-2})$ where $z' = \pi_{k-2}^{k-1}(z)$ and η_{k-2} is the «zero section» of the trivial bundle $\bar{H}^{k-2}(\mathbf{R}^n) \approx \mathbf{R}^n \times \bar{L}_n^{k-2}$. Consider then an arbitrary element $y = j_{e_{k-1}}^1 g$ in $\bar{H}^k(V_n)$. If η_{k-1} is the «zero section» of $\bar{H}^{k-1}(\mathbf{R}^n) = \mathbf{R}^n \times \bar{L}_n^{k-1}$, $g' = \nu_{k-1} \circ g \circ \eta_{k-1}$ defines a local diffeomorphism of $\mathbf{R}^n$ to $\bar{P}^{k-1}(V_n)$. Since $j_0^1(p_{k-2}^{k-1} \circ g') = g'(0)$, the 1-jet $j_0^1 g'$, which

^{*}) corresponding to $\mathbf{R}^n \times \{e\}$, where e is the unit element.

is independent of the choice of g for y , is an element in $\bar{P}^k(V_n)$. The mapping $y \mapsto \nu_k(y) = j_0^1 g'$ defines a diffeomorphism ν_k of $\bar{H}^k(V_n)$ onto $\bar{P}^k(V_n)$. It is easy to check that ν_k has the desired properties.

Consider the case where $V_n = \mathbb{R}^n$. Let us recall that the underlying set of $\bar{L}_n^k$ is just the fibre of $\bar{H}^k(\mathbb{R}^n)$ over the origin 0 . Since the multiplication in $\bar{L}_n^k$ is given by the composition of jets, the restriction of ν_k to $\bar{L}_n^k$ defines a group isomorphism of $\bar{L}_n^k$ onto the group of all invertible semi-holonomic k -jets of $\mathbb{R}^n$ into $\mathbb{R}^n$ with source and target 0 . It is easy to see that the diffeomorphism ν_k of the above theorem is compatible with this group isomorphism. We have therefore the following corollary:

COROLLARY 1.6. *The principal fibre bundle $\bar{H}^k(V_n)$ (resp. $H^k(V_n)$) is canonically isomorphic to $\bar{P}^k(V_n)$ (resp. $P^k(V_n)$).*

Let E be a locally trivial fibre bundle over V_n . We will denote by $J^k E$ the differentiable manifold of k -jets of local sections of E . Let $\tilde{J}^2 E = J^1(J^1 E)$. The k -th non-holonomic prolongation of E is defined by induction:

$$\tilde{J}^k E = J^1(\tilde{J}^{k-1} E).$$

We define also the semi-holonomic prolongation $\bar{J}^k E$ by restricting ourselves to those local sections such that, for all $0 < m < k$, the local section σ of V_n into $\tilde{J}^m E$ satisfies the condition: $j_x^1(\pi_{m-1}^m \sigma) = \sigma(x)$, where π_{m-1}^m is the natural projection of $\tilde{J}^m E$ onto $\tilde{J}^{m-1} E$. We have

$$J^k E \subset \bar{J}^k E \subset \tilde{J}^k E.$$

THEOREM 1.7. *There exists a canonical diffeomorphism μ_k of $\bar{H}^k(V_n)$ onto $\bar{J}^{k-1}(H^1(V_n))$ satisfying the following properties:*

- (1) for $k=1$, μ_1 is just the identity map of $H^1(V_n)$;
- (2) μ_k is a fibre map; more explicitly

$$\begin{array}{ccc} \bar{H}^k(V_n) & \xrightarrow{\mu_k} & \bar{J}^{k-1}(H^1(V_n)) \\ \downarrow & & \downarrow \\ V_n & \xrightarrow{id} & V_n \end{array}$$

is a commutative diagram;

(3) for $0 < m < k$, the following diagram

$$\begin{array}{ccc} \bar{H}^k(V_n) & \xrightarrow{\mu_k} & \bar{J}^{k-1}(H^1(V_n)) \\ \downarrow & & \downarrow \\ \bar{H}^m(V_n) & \xrightarrow{\mu_m} & \bar{J}^{m-1}(H^1(V_n)) \end{array}$$

commutes.

We prove the theorem by induction on k . For $k=1$, $J^0(H^1(V_n)) = H^1(V_n)$ by definition and μ_1 is just the identity map of $H^1(V_n)$. Let $u = j_{e_1}^1 b$ be an arbitrary element of $\bar{H}^2(V_n)$. Consider the local diffeomorphism f of $\mathbf{R}^n$ into V_n defined by the condition: $\pi_0^1 \circ b = f \circ \pi_0^1$. If η_1 is the «zero section» of $H^1(\mathbf{R}^n) \approx \mathbf{R}^n \times L_n^1$, the mapping

$$x \mapsto \sigma(x) = b \circ \eta_1 \circ f^{-1}(x)$$

defines a local section σ of V_n into $H^1(V_n)$. If we put $\mu_2(u) = j_x^1 \sigma$ with $x = \pi_0^1(u)$, the mapping $u \mapsto \mu_2(u)$ defines an injection of $\bar{H}^2(V_n)$ into $\bar{J}^1(H^1(V_n))$. This differentiable mapping μ_2 is surjective. In fact let σ be a local section of V_n into $H^1(V_n)$ with $j_x^1 \sigma \in \bar{J}^1(H^1(V_n))$. The target $\sigma(x)$ can be written as $\dot{\sigma}(x) = j_0^1 f$ for some local diffeomorphism f of $\mathbf{R}^n$ into V_n . Let b be the local isomorphism of $H^1(\mathbf{R}^n)$ into $H^1(V_n)$ defined by the conditions:

$$\text{i) } \pi_0^1 \circ b = f \circ \pi_0^1;$$

$$\text{ii) } b \circ \eta_1 = \sigma \circ f.$$

It is easy to check that b is 1-admissible and $j_x^1 \sigma = \mu_2(j_{e_1}^1 b)$. The mapping μ_2 gives then a diffeomorphism of $\bar{H}^2(V_n)$ onto $\bar{J}^1(H^1(V_n))$ with the desired properties. Now, let us assume there exists μ_{k-1} and μ_{k-2} such that, for all $u \in \bar{H}^{k-1}(V_n)$, we have

$$\mu_{k-1}(u) = (j_u^1, \mu_{k-2}) \circ u \circ (j_0^1 \eta_{k-2}) \circ \omega^{-1}$$

with $u' = \pi_{k-2}^{k-1}(u)$, $\omega = \pi_1^k(u)$ and where η_{k-2} is the «zero section» of $\bar{H}^{k-2}(\mathbf{R}^n) = \mathbf{R}^n \times \bar{L}_n^{k-2}$. Let $z = j_{e_{k-1}}^1 b$ be an arbitrary element of $\bar{H}^k(V_n)$. Let f be the local diffeomorphism of $\mathbf{R}^n$ into V_n induced by b . If we denote by η_{k-1} the «zero section» of $\bar{H}^{k-1}(\mathbf{R}^n) = \mathbf{R}^n \times \bar{L}_n^{k-1}$, then

$$b' = \mu_{k-1} \circ b \circ \eta_{k-1} \circ f^{-1}$$

defines a local section of V_n into $\bar{J}^{k-2}(H^1(V_n))$ and $j_x^1 b'$ determines an element $\mu_k(z)$ of $\bar{J}^{k-1}(H^1(V_n))$ independent of the choice of the representative b for z . It is easy to verify that $z \mapsto \mu_k(z)$ defines a diffeomorphism μ_k of $\bar{H}^k(V_n)$ onto $\bar{J}^{k-1}(H^1(V_n))$ satisfying the required conditions of the theorem.

COROLLARY 1.8 [4c] $\bar{P}^k(V_n)$ and $\bar{J}^{k-1}(H^1(V_n))$ are canonically diffeomorphic.

5. Local coordinate systems in $\bar{H}^k(V_n)$.

Let $\{x^1, x^2, \dots, x^n\}$ be the natural coordinate system in $\mathbf{R}^n$. Let U be a coordinate neighbourhood in V_n with a local coordinate system $\{y^1, y^2, \dots, y^n\}$. Consider an element $u \in H^1(V_n)$ with projection

$$\pi_0^1(u) = y = (y^1, y^2, \dots, y^n) \in U.$$

The 1-frame u is completely determined by the linear isomorphism

$$\tilde{u}: T_0(\mathbf{R}^n) \longrightarrow T_y(V_n).$$

In terms of local coordinates, $\tilde{u}$ can be expressed by

$$\tilde{u}: v_i \longrightarrow \sum_m y_i^m \bar{v}_m \quad (1 \leq i \leq n, 1 \leq m \leq n),$$

where $v_i = (\frac{\partial}{\partial x^i})_0$, $\bar{v}_m = (\frac{\partial}{\partial y^m})_y$ and $\det(y_i^m) \neq 0$.

The 1-frame u is therefore completely determined by the set of local coordinates (y^i, y_k^j) with $\det(y_k^j) \neq 0$. Thus we can take $\{y^i, y_k^j\}$ as a local coordinate system in $(\pi_0^1)^{-1}(U) \subset H^1(V_n)$. Similarly, we have a global coordinate system $\{x^i, x_k^j\}$ in $H^1(\mathbf{R}^n)$, with respect to which the distinguished element is given by $e_1 = (0, \delta_k^j)$.

The $n + n^2$ vectors $\{s_i = (\frac{\partial}{\partial x^i}) e_1, s_k^j = (\frac{\partial}{\partial x_k^j}) e_1\}$ form a basis for $E^1 = T_{e_1}(H^1(\mathbf{R}^n))$, and the $n + n^2$ local vector fields $\{\frac{\partial}{\partial y^i}, \frac{\partial}{\partial y_k^j}\}$ are linearly independent. Once again, any 2-frame v is completely determined by the linear isomorphism $\tilde{v}$ associated to v . In terms of local coordinates, we have

$$\tilde{v}: E^1 \longrightarrow T_u(H^1(V_n)) \quad \text{with} \quad \pi_1^2(v) = u = (y^i, y_k^j)$$

give a necessary and sufficient condition for u to be a holonomic k -frame. Let us recall that the horizontal n -plane defined by u is just the image of the $\mathbf{R}^n$ -component of $\bar{E}^{k-1} = \mathbf{R}^n \oplus \bar{\mathcal{Q}}_n^{k-1}$ under the linear isomorphism $\tilde{u}$. It is tangent to $H^{k-1}(V_n)$ at the point $u' = \pi_{k-1}^k(u)$, if u is holonomic.

For $k=1$, there is no distinction between semi-holonomic frames and holonomic frames. For $k \geq 2$, $H^k(V_n) \subset \bar{H}^k(V_n)$.

PROPOSITION 1.9. *An element u of $\bar{H}^2(V_n)$ is a holonomic 2-frame if and only if the 2-form $d\theta_1$ vanishes on the horizontal n -plane associated to u .*

Let $r_1, r_2, \dots, r_n$ be a basis for $\mathbf{R}^n$. The canonical form θ_1 on $H^1(V_n)$ can be expressed as follows:

$$\theta_1 = \sum \theta^i r_i.$$

In terms of a local coordinate system $\{y^i, y_j^i\}$ in $H^1(V_n)$, the components θ^i of θ_1 are given by

$$\theta^i = \sum_j z_j^i dy^j,$$

where (z_j^i) is the inverse matrix of (y_j^i) . By exterior differentiation, we get

$$d\theta^i = \sum \frac{\partial z_j^i}{\partial y_q^m} dy_q^m \wedge dy^j.$$

Let $u = (a^i, a_j^i, a_{jk}^i) \in \bar{H}^2(V_n)$. The horizontal n -plane Q_u associated to u is generated by the n vectors

$$X_i = \sum \left(a_i^j \left(\frac{\partial}{\partial y^j} \right)_u + \frac{1}{2!} a_{ki}^j \left(\frac{\partial}{\partial y_k^j} \right)_u \right) \quad (1 \leq i \leq n),$$

with $u' = \pi_1^2(u) = (a^i, a_j^i)$. The 2-form $d\theta_1$ vanishes on Q_u if and only if

$$d\theta^i(X_j, X_k) = \sum \left(\frac{\partial z_m^i}{\partial y_q^p} \right)_u \begin{vmatrix} \frac{1}{2!} a_{qj}^p & a_j^m \\ \frac{1}{2!} a_{qk}^p & a_k^m \end{vmatrix}$$

is zero for all $1 \leq i, j, k \leq n$. Since $(z_j^i) = (y_j^i)^{-1}$, we have the relation $z_p^i y_k^p = \delta_k^i$. By differentiation, we get

$$\left(\frac{\partial z_m^i}{\partial y_q^p}\right)_u = -b_m^q b_p^i$$

where $(b_j^i) = (a_j^i)^{-1}$. It follows that

$$\begin{aligned} d\theta^i(X_j, X_k) &= -\frac{1}{2!} \sum (b_m^q b_p^i (a_k^m a_{qj}^p - a_j^m a_{qk}^p)) \\ &= -\frac{1}{2!} \sum (b_p^i (a_{jk}^p - a_{kj}^p)) \end{aligned}$$

Since $\det(b_j^i) \neq 0$, we conclude that $d\theta^i(X_j, X_k) = 0$ for all $1 \leq i, j, k \leq n$ if and only if the a_{jk}^i are symmetrical with respect to their lower indices. Thus our proposition is proved.

For the general case where $k > 2$, we have the following «Holonomy Theorem»:

THEOREM 1.10. *An element $u \in \bar{H}^k(V_n)$ is a holonomic k -frame if and only if the following conditions are satisfied:*

- i) *the horizontal n -plane Q_u associated to u is tangent to the submanifold $H^{k-1}(V_n)$ of $\bar{H}^{k-1}(V_n)$;*
- ii) *the 2-form $d\theta_{k-1}$ vanishes on Q_u .*

Let us assume that u is a holonomic k -frame. We can then write $u = j_{e_{k-1}}^1 f^{(k-1)}$ for some local diffeomorphism f of $\mathbf{R}^n$ into V_n . If θ_{k-1} and $\hat{\theta}_{k-1}$ are respectively the canonical form on $\bar{H}^{k-1}(V_n)$ and $\bar{H}^{k-1}(\mathbf{R}^n)$, we have $f^{(k-1)*}\theta_{k-1} = \hat{\theta}_{k-1}$. It follows that $f^{(k-1)*}d\theta_{k-1} = d\hat{\theta}_{k-1}$. Now, the 2-form $d\hat{\theta}_{k-1}$ vanishes on the $\mathbf{R}^n$ -component of $\bar{E}^{k-1} = \mathbf{R}^n \oplus \bar{\mathcal{L}}_n^{k-1}$. As a consequence, $d\theta_{k-1}$ vanishes on Q_u . The first condition is obviously necessary.

It remains to show that the conditions are sufficient. The first condition implies that $u' = \pi_{k-1}^k(u)$ is a holonomic $(k-1)$ -frame, and that we can find a local coordinate system $\{y^i, y_{j_1}^i, \dots, y_{j_1 \dots j_k}^i\}$ in $\bar{H}^k(V_n)$ such that $u = (0, a_{j_1}^i, \dots, a_{j_1 \dots j_k}^i)$ where $a_{j_1 \dots j_m}^i$ are symmetrical with respect to their lower indices for $2 \leq m \leq k-1$ and $a_{j_1 \dots j_k}^i$ is symmetrical with respect to the first $k-1$ lower indices. By a change of local coordinate systems, we can even suppose that $a_j^i = \delta_j^i$ and $a_{j_1 \dots j_m}^i = 0$ for

$2 \leq m \leq k-1$.

Let $\{x^1, x^2, \dots, x^n\}$ be the natural coordinate system in $\mathbf{R}^n$. By iteration, we define a global coordinate system $\{x^i, x_{j_1}^i, \dots, x_{j_1 \dots j_m}^i\}$ in $\bar{H}^m(\mathbf{R}^n)$. Let $z^\alpha = x_{j_1 \dots j_p}^i$ with $\alpha = i n^p + j_p n^{p-1} + \dots + j_1$. The vectors

$$t_\alpha = \left(\frac{\partial}{\partial z^\alpha} \right) e_{k-2} \quad (1 \leq \alpha \leq n^{k-1} + n^{k-2} + \dots + n)$$

form a basis for $\bar{E}^{k-2}$ and we can write

$$\theta_{k-1} = \sum_\alpha \theta^\alpha t_\alpha.$$

An element $v = (y^i, y_{j_1}^i, \dots, y_{j_1 \dots j_{k-1}}^i) \in \bar{H}^{k-1}(V_n)$ defines a linear isomorphism $\tilde{v}$ of $\bar{E}^{k-2}$ onto $T_v(\bar{H}^{k-2}(V_n))$ with $v' = \pi_{k-2}^{k-1}(v)$. In terms of local coordinate systems, $\tilde{v}$ is given by

$$\tilde{v}: t_\alpha \longrightarrow \sum_\beta A_\alpha^\beta \bar{t}_\beta$$

where $1 \leq \alpha, \beta \leq n^{k-1} + n^{k-2} + \dots + n$, $\bar{t}_\alpha = \left(\frac{\partial}{\partial \bar{z}^\alpha} \right)_v$, with $\bar{z}^\alpha = y_{j_1 \dots j_p}^i$. The matrix $A = (A_\alpha^\beta)$ is of the form

$$A = \begin{pmatrix} A_j^i & A_j^\omega \\ 0 & J \end{pmatrix} \quad \begin{matrix} 1 \leq i, j \leq n \\ n < \omega \leq n^{k-1} + n^{k-2} + \dots + n \end{matrix}$$

where J is the matrix corresponding to the linear isomorphism Tv' . We have therefore $y_{j_1 \dots j_m}^i = A_{j_m}^\beta$ with $\beta = i n^{m-1} + j_{m-1} n^{m-2} + \dots + j_1$. Let $B = (B_\alpha^\beta)$ be the inverse matrix of $A = (A_\alpha^\beta)$. The components θ^α of θ_{k-1} can be expressed by

$$\theta^\alpha = \sum_\beta B_\beta^\alpha d\bar{z}^\beta.$$

By exterior differentiation, we get

$$d\theta^\alpha = \sum \left(\frac{\partial B_\beta^\alpha}{\partial \bar{z}^\gamma} \right) d\bar{z}^\gamma \wedge d\bar{z}^\beta + \sum \left(\frac{\partial B_\beta^\alpha}{\partial y_{j_1 \dots j_{k-1}}^i} \right) dy_{j_1 \dots j_{k-1}}^i \wedge d\bar{z}^\beta.$$

Since $\sum B_\mu^\alpha A_\nu^\mu = \delta_\nu^\alpha$, we obtain by differentiation

$$\frac{\partial B_\beta^\alpha}{\partial \bar{z}^\gamma} = -\sum B_\mu^\alpha B_\beta^\nu \left(\frac{\partial A_\nu^\mu}{\partial \bar{z}^\gamma} \right),$$

$$\frac{\partial B_{\beta}^{\alpha}}{\partial y_{j_1 \dots j_{k-1}}^i} = -\sum B_{\mu}^{\alpha} B_{\beta}^{\nu} \left(\frac{\partial A_{\nu}^{\mu}}{\partial y_{j_1 \dots j_{k-1}}^i} \right),$$

hence

$$d\theta^{\alpha} = -\sum B_{\mu}^{\alpha} B_{\beta}^{\nu} \left(\frac{\partial A_{\nu}^{\mu}}{\partial \bar{z}^{\gamma}} \right) d\bar{z}^{\gamma} \wedge d\bar{z}^{\beta} - \sum B_{\mu}^{\alpha} B_{\beta}^{\nu} \left(\frac{\partial A_{\nu}^{\mu}}{\partial y_{j_1 \dots j_{k-1}}^i} \right) dy_{j_1 \dots j_{k-1}}^i \wedge d\bar{z}^{\beta}.$$

Let $u = (0, \delta_j^i, 0, \dots, a_{j_1 \dots j_k}^i)$ and let Q_u be the horizontal n -plane of $\bar{H}^{k-1}(V_n)$ associated to u . Q_u is generated by the n vectors

$$X_p = \left(\frac{\partial}{\partial y^p} \right)_u + \frac{1}{k!} \sum a_{j_1 \dots j_{k-1} p}^i \left(\frac{\partial}{\partial y_{j_1 \dots j_{k-1}}^i} \right)_u,$$

where $u' = \pi_{k-1}^k(u)$ and $1 \leq p \leq n$.

The nullity of $d\theta_{k-1}^{\alpha}$ on Q_u implies that $d\theta^{\alpha}(X_p, X_q) = 0$ for all $1 \leq p, q \leq n$ and $1 \leq \alpha \leq n^{k-1} + n^{k-2} + \dots + n$. We have then

$$\begin{aligned} 0 &= d\theta^{\alpha}(X_p, X_q) \\ &= \sum B_{\mu}^{\alpha}(u') B_{\beta}^{\nu}(u') \left(\frac{\partial A_{\nu}^{\mu}}{\partial y_{j_1 \dots j_{k-1}}^i} \right)_u \left| \begin{array}{cc} \frac{1}{k!} a_{j_1 \dots j_{k-1} p}^i & A_p^{\beta}(u') \\ \frac{1}{k!} a_{j_1 \dots j_{k-1} q}^i & A_q^{\beta}(u') \end{array} \right| \\ &= \frac{1}{k!} \sum B_{\mu}^{\alpha}(u') \partial_{\beta}^{\mu} (a_{j_1 \dots j_{k-2} 2 q p}^i - a_{j_1 \dots j_{k-2} p q}^i) \end{aligned}$$

with $\beta = i n^{k-2} + \dots + j_1$. Since $\det(B_{\beta}^{\alpha}(u')) \neq 0$, we obtain

$$a_{j_1 \dots j_{k-2} p q}^i = a_{j_1 \dots j_{k-2} q p}^i.$$

It follows that the $a_{j_1 \dots j_k}^i$ are symmetrical with respect to their lower indices and thus u is a holonomic k -frame.

Let us call $u \in \bar{H}^k(V_n)$ a *quasi-holonomic k -frame* if the horizontal n -plane Q_u of $\bar{H}^{k-1}(V_n)$ associated to u is tangent to the submanifold $H^{k-1}(V_n)$. We will denote by $\check{H}^k(V_n)$ the set of quasi-holonomic k -frames. We have obviously $H^k(V_n) \subset \check{H}^k(V_n) \subset \bar{H}^k(V_n)$. From the above theorem a quasi-holonomic k -frame u is a holonomic one if and only if $d\theta_{k-1}^{\alpha}$ vanishes on the horizontal n -plane Q_u associated to u .

7. Some remarks on $\bar{H}^k(\mathbf{R}^n)$.

In the preceding paragraphs, $\mathbf{R}^n \times \bar{L}_n^k$ has been identified with $\bar{H}^k(\mathbf{R}^n)$. In this identification, a couple $(x, g) \in \mathbf{R}^n \times \bar{L}_n^k$ is identified with the element $t_x^{(k)}(g) \in \bar{H}^k(\mathbf{R}^n)$, where t_x denotes the translation in $\mathbf{R}^n$ sending the origin 0 to the point x . The tangent space $\bar{E}^k$ to $\bar{H}^k(\mathbf{R}^n)$ at the distinguished element e_k has a canonical Lie algebra structure. Let us say a few words on this Lie algebra structure. Let $u = (x, g) \in \bar{H}^k(\mathbf{R}^n)$. The translation t_x in $\mathbf{R}^n$ induces an automorphism $t_x^{(k)}$ of $\bar{H}^k(\mathbf{R}^n)$ which commutes with the right translations of $\bar{L}_n^k$ on $\bar{H}^k(\mathbf{R}^n)$, i.e.

$$t_x^{(k)} \circ R_b = R_b \circ t_x^{(k)}$$

for all $b \in \bar{L}_n^k$. In particular, $t_x^{(k)} \circ R_g = R_g \circ t_x^{(k)}$ gives a diffeomorphism of $\bar{H}^k(\mathbf{R}^n)$ onto itself that we will denote by t_u . We call a vector field on $\bar{H}^k(\mathbf{R}^n)$ *invariant* if it is invariant with respect to all diffeomorphisms of the form t_u , where u is an arbitrary element of $\bar{H}^k(\mathbf{R}^n)$. There is a one-to-one correspondence between $\bar{E}^k$ and the set of invariant vector fields on $\bar{H}^k(\mathbf{R}^n)$. If X, Y are two invariant vector fields on $\bar{H}^k(\mathbf{R}^n)$, so is the bracket $[X, Y]$. The vector space $\bar{E}^k$, endowed with this multiplication, becomes a Lie algebra over the field of real numbers. The Lie algebra $\bar{\mathcal{L}}_n^k$ of $\bar{L}_n^k$ is a Lie subalgebra of $\bar{E}^k = \mathbf{R}^n \oplus \bar{\mathcal{L}}_n^k$.

To every differentiable map f of a differentiable manifold W into $\bar{H}^k(\mathbf{R}^n)$, we can associate a differential 1-form $\omega_f = f^{-1}df$ with values in the Lie algebra $\bar{E}^k$ defined by $\omega_f(X) = (T t_{f(x)}^{-1} \circ T f)(X)$ for all X in $T_x(W)$. In particular, if $W = \bar{H}^k(\mathbf{R}^n)$ and if f is the identity map of $\bar{H}^k(\mathbf{R}^n)$, we get a differential 1-form ω on $\bar{H}^k(\mathbf{R}^n)$ with values in $\bar{E}^k$, called the *invariant form* on $\bar{H}^k(\mathbf{R}^n)$.

PROPOSITION 1.11. *The invariant form ω on $\bar{H}^k(\mathbf{R}^n)$ satisfies the equation*

$$d\omega + [\omega, \omega] = 0.$$

We recall that the form $[\omega, \omega]$ is defined by $[\omega, \omega](X, Y) = [\omega(X), \omega(Y)]$ for all vector fields X, Y on $\bar{H}^k(\mathbf{R}^n)$. Since the module of vector fields on $\bar{H}^k(\mathbf{R}^n)$ is generated by the invariant vector

fields, it suffices to prove the equation for two invariant vector fields X and Y . We have

$$\begin{aligned} d\omega(X, Y) &= X\omega(Y) - Y\omega(X) - \omega([X, Y]) \\ &= -\omega([X, Y]) = -[\omega(X), \omega(Y)] \end{aligned}$$

proving the proposition.

REMARK: We have adopted the following convention for the exterior product:

$$(\alpha \wedge \beta)(X_1, X_2, \dots, X_{p+q}) = \sum (-1)^\varepsilon \alpha(X_{i_1}, \dots, X_{i_p}) \beta(X_{i_{p+1}}, \dots, X_{i_{p+q}}),$$

where the summation runs over all permutations $i_1, \dots, i_p, i_{p+1}, \dots, i_{p+q}$ of $\{1, 2, \dots, p+q\}$ and where ε denotes the signature of the corresponding permutation. With this convention, we have the following formula: if α is a p -form, then

$$\begin{aligned} d\alpha(X_1, \dots, X_{p+1}) &= \sum_{i=1}^{p+1} (-1)^{i+1} X_i \alpha(X_1, \dots, \hat{X}_i, \dots, X_{p+1}) \\ &\quad + \sum_{i < j} (-1)^{i+j} \alpha([X_i, X_j], X_1, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_{p+1}). \end{aligned}$$

Kumpera pointed out to me that the above Lie algebra structure on $\bar{E}^k$ comes from a canonical Lie group structure on $\bar{H}^k(\mathbf{R}^n)$. Since $(x, g) \in \mathbf{R}^n \times \bar{L}_n^k$ is identified with $t_x^{(k)}(g) = t_x^{(k)} \circ R_g(e_k) = R_g \circ t_x^{(k)}(e_k)$, we have $(t_x^{(k)} \circ R_g) \circ (t_{x'}^{(k)} \circ R_{g'}) = t_x^{(k)} \circ t_{x'}^{(k)} \circ R_g \circ R_{g'} = t_{x+x'}^{(k)} \circ R_{g \cdot g'}$. Let ${}^t\bar{L}_n^k$ denote the underlying set of $\bar{L}_n^k$ endowed with the following multiplication: $g * h = hg$ where $g * h$ denotes the product in ${}^t\bar{L}_n^k$ and hg denotes the product in $\bar{L}_n^k$. With the identification $\bar{H}^k(\mathbf{R}^n) = \mathbf{R}^n \times \bar{L}_n^k$, $\bar{H}^k(\mathbf{R}^n)$ becomes a Lie group isomorphic to $\mathbf{R}^n \times {}^t\bar{L}_n^k$. Moreover, if $u = (x, g)$, $u' = (x', g')$, then

$$\begin{aligned} uu' &= (x+x', g'g) = t_{x+x'}^{(k)} R_{g'g}(e_k) \\ &= (t_x^{(k)} \circ R_g) \circ (t_{x'}^{(k)} \circ R_{g'})(e_k) \\ &= (t_x^{(k)} \circ R_g)(u') = t_u(u'), \end{aligned}$$

where t_u is the diffeomorphism defined in the opening paragraph of this section. In fact, t_u is no other than the left translation defined by u in

the Lie group $\bar{H}^k(\mathbf{R}^n)$. The Lie algebra structure on $\bar{E}^k$ defined above is precisely the Lie algebra of the Lie group $\bar{H}^k(\mathbf{R}^n)$. The invariant form ω is simply the Maurer-Cartan form of the Lie group $\bar{H}^k(\mathbf{R}^n)$.

Part II

HIGHER ORDER CONNECTIONS

1. Linear connections of order k .

An infinitesimal connection Γ^k in the principal fibre bundle of semi-holonomic k -frames $\bar{H}^k(V_n)$ over V_n will be called a *linear connection of order k* of V_n . Let ω_k be its connection form. We will sometimes say that ω_k is a linear connection of order k of V_n . If D is the exterior covariant differentiation relative to ω_k , the tensorial 2-form $\Theta_k = D\theta_k$ (resp. $\Omega_k = D\omega_k$) will be called the *torsion form* (reps. *curvature form*) of Γ^k or ω_k . For $Y, Z \in T(\bar{H}^k(V_n))$, $g \in \bar{L}_n^k$, we have

$$\Theta_k(TR_g(Y), TR_g(Z)) = \rho(g^{-1})\Theta_k(Y, Z).$$

where ρ is the linear representation of $\bar{L}_n^k$ on $\bar{E}^{k-1}$ defined in Part I. If Y or Z is a vertical vector, then $\Theta_k(Y, Z) = 0$.

The linear representation ρ induces a representation of $\bar{\mathcal{Q}}_n^k$ on $\bar{E}^{k-1}$: if $A \in \bar{\mathcal{Q}}_n^k$, $\xi \in \bar{E}^{k-1}$, we put

$$A\xi = \lim_{t \rightarrow 0} \frac{1}{t} (\rho(a_t)\xi - \xi)$$

where $a_t = \exp tA$ is the 1 -parameter group of transformations of $\bar{L}_n^k$ generated by A . In particular, if ξ is vertical, i.e. $\xi \in \bar{\mathcal{Q}}_n^{k-1}$, we have

$$A\xi = -[T\pi_{k-1}^k(A), \xi].$$

THEOREM II.1 (structure equations) *Let ω_k be a linear connection of order k . Then*

$$\Omega_k = d\omega_k + \omega_k \wedge \omega_k$$

$$\Theta_k = d\theta_k + \omega_k \wedge \theta_k + 3[T\pi_{k-1}^k \circ \omega_k, T\pi_{k-1}^k \circ \omega_k].$$

The first structure equation is well known. Let us show the second structure equation:

$$\begin{aligned}\Theta_k(X, Y) &= d\theta_k(X, Y) + \omega_k(X)\theta_k(Y) - \omega_k(Y)\theta_k(X) \\ &\quad + 3[T\pi_{k-1}^k \circ \omega_k(X), T\pi_{k-1}^k \circ \omega_k(Y)]\end{aligned}$$

for all vectors $X \in T_u(\bar{H}^k(V_n))$ and $Y \in T_u(\bar{H}^k(V_n))$. It is sufficient to verify the equality in the following three special cases:

i) X and Y are horizontal. In this case, $\omega_k(X) = 0$, $\omega_k(Y) = 0$ and the equation reduces to the definition of Θ_k .

ii) X and Y are vertical. Let $X = A_u^*$ and $Y = B_u^*$, where A^* and B^* are the fundamental vector fields on $\bar{H}^k(V_n)$ corresponding to $A = \omega_k(X)$ and $B = \omega_k(Y)$ respectively. We have

$$\begin{aligned}\Theta_k(X, Y) &= 0; \\ d\theta_k(X, Y) &= X\theta_k(B^*) - Y\theta_k(A^*) - \theta_k([A^*, B^*]_u) \\ &= -[T\pi_{k-1}^k(A), T\pi_{k-1}^k(B)]; \\ \omega_k(X)\theta_k(Y) &= A\theta_k(B_u^*) \\ &= -[T\pi_{k-1}^k(A), T\pi_{k-1}^k(B)]; \\ \omega_k(Y)\theta_k(X) &= -[T\pi_{k-1}^k(B), T\pi_{k-1}^k(A)];\end{aligned}$$

and

$$[T\pi_{k-1}^k \circ \omega_k(X), T\pi_{k-1}^k \circ \omega_k(Y)] = [T\pi_{k-1}^k(A), T\pi_{k-1}^k(B)].$$

The equality holds.

iii) X is vertical and Y is horizontal. Let $X = A_u^*$ with $A = \omega_k(X) \in \bar{\mathcal{Q}}_n^k$. We can extend Y to an invariant horizontal vector field $\tilde{Y}$ on $\bar{H}^k(V_n)$.

We have then

$$d\theta_k(X, Y) = X\theta_k(\tilde{Y}) - Y\theta_k(A^*) - \theta_k([A^*, \tilde{Y}]_u).$$

Since $\theta_k(A^*)$ is constant, $Y\theta_k(A^*) = 0$. As $\tilde{Y}$ is an invariant horizontal vector field, $[A^*, \tilde{Y}] = 0$. Let $a_t = \exp tA$ be the 1-parameter group of transformations of $\bar{L}_n^k$ generated by $A \in \bar{\mathcal{Q}}_n^k$.

$$\begin{aligned}d\theta_k(X, Y) &= A_u^* \theta_k(\tilde{Y}) \\ &= \lim_{t \rightarrow 0} \frac{1}{t} (\rho(a_t^{-1})\theta_k(\tilde{Y}) - \theta_k(\tilde{Y}))\end{aligned}$$

$$= -A \theta_k(Y).$$

Now, $\omega_k(Y) = 0$, $\Theta_k(X, Y) = 0$ and $\omega_k(X) \theta_k(Y) = A \theta_k(Y)$. The equality therefore holds.

The projection π_m^k of $\bar{H}^k(V_n)$ onto $\bar{H}^m(V_n)$ being compatible with the natural surjection of $\bar{L}_n^k$ onto $\bar{L}_n^m$ ($m < k$), any linear connection ω_k (of order k) induces a linear connection ω_m of order m , given by

$$\pi_m^{k*} \omega_m = T \pi_m^k \circ \omega_k.$$

PROPOSITION II.2 Any linear connection ω_k of order k induces canonically a linear connection ω_m of order $m < k$ given by

$$\pi_m^{k*} \omega_m = T \pi_m^k \circ \omega_k.$$

We have the relations:

$$\pi_m^{k*} \Omega_m = T \pi_m^k \circ \Omega_k,$$

$$\pi_m^{k*} \Theta_m = T \pi_{m-1}^{k-1} \circ \Theta_k.$$

Let us verify only the last formula. We know that

$$\pi_m^{k*} \theta_m = \theta_m \circ T \pi_m^k = T \pi_{m-1}^{k-1} \circ \theta_k.$$

As a consequence, $\pi_m^{k*} d \theta_m = T \pi_{m-1}^{k-1} \circ d \theta_k$. From the second structure equation, we obtain

$$\begin{aligned} \pi_m^{k*} \Theta_m &= \pi_m^{k*} d \theta_m + \pi_m^{k*} \omega_m \wedge \pi_m^{k*} \theta_m \\ &\quad + 3 [T \pi_{m-1}^m \circ \pi_m^{k*} \omega_m, T \pi_{m-1}^m \circ \pi_m^{k*} \omega_m] \\ &= T \pi_{m-1}^{k-1} \circ d \theta_k + T \pi_m^k \circ \omega_k \wedge T \pi_{m-1}^{k-1} \circ \theta_k \\ &\quad + 3 [T \pi_{m-1}^k \circ \omega_k, T \pi_{m-1}^k \circ \omega_k] \\ &= T \pi_{m-1}^{k-1} \circ (d \theta_k + \omega_k \wedge \theta_k + 3 [T \pi_{k-1}^k \circ \omega_k, T \pi_{k-1}^k \circ \omega_k]) \\ &= T \pi_{m-1}^{k-1} \circ \Theta_k. \end{aligned}$$

COROLLARY II.3 If the torsion form (resp. the curvature form) of ω_k vanishes identically on $T(\bar{H}^k(V_n))$, the induced connection ω_m ($m < k$) is without torsion (resp. without curvature).

Let ω_k be a linear connection of V_n . We say that ω_k is quasi-bo-

lomorphic if the connection form ω_k , restricted to $T(H^k(V_n))$, defines a connection in the principal fibre bundle $H^k(V_n)$ over V_n . If ω_k is quasi-holonomic, all induced connections ω_m ($m < k$) are quasi-holonomic. The canonical connection in $\bar{H}^k(\mathbf{R}^n) = \mathbf{R}^n \times \bar{L}_n^k$ is quasi-holonomic.

2. Second order linear connections.

Let u be an element of $\bar{H}^2(V_n)$. Consider a coordinate neighbourhood U of $a_0 = \pi_0^2(u)$ with a system of local coordinates $\{x^1, x^2, \dots, x^n\}$. The 2-frame u can be represented by a set of local coordinates (x^i, x_j^i, x_{jk}^i) with $\det(x_j^i) \neq 0$. Let U' be another coordinate neighbourhood of a_0 with a system of local coordinates $\{y^1, y^2, \dots, y^n\}$. The same u is represented by (y^i, y_j^i, y_{jk}^i) . The changes of local coordinates are given by

$$y^i = y^i(x)$$

$$y_j^i = \sum \left(\frac{\partial y^i}{\partial x^m} \right) x_j^m$$

$$y_{jk}^i = \sum \left(\frac{\partial^2 y^i}{\partial x^j \partial x^k} \right) x_m^i + \sum \left(\frac{\partial y^p}{\partial x^j} \right) \left(\frac{\partial y^q}{\partial x^k} \right) x_{pq}^i.$$

An element $g \in \bar{L}_n^2$ can be represented by $u = (a_j^i, a_{jk}^i)$ with $\det(a_j^i) \neq 0$. In terms of these coordinates, the multiplication in $\bar{L}_n^2$ is given by

$$(a_j^i, a_{jk}^i) \cdot (b_j^i, b_{jk}^i) = \left(\sum a_m^i b_j^m, \sum a_m^i b_{jk}^m + \sum a_{pq}^i b_{jk}^p b_k^q \right).$$

The action of $\bar{L}_n^2$ on $\bar{H}^2(V_n)$ is given by

$$(x^i, x_j^i, x_{jk}^i) (a_j^i, a_{jk}^i) = (x^i, \sum x_m^i a_j^m, \sum x_m^i a_{jk}^m + \sum x_{pq}^i a_j^p a_k^q).$$

Let α be the automorphism of $\bar{L}_n^2$ defined by $\alpha(a_j^i, a_{jk}^i) = (a_j^i, a_{kj}^i)$. It is evident that α leaves fixed every element in L_n^2 . Moreover, $\alpha^2 = \text{identity}$. We have immediately

PROPOSITION II.4 *There exists an involutive automorphism α of $\bar{L}_n^2$ such that L_n^2 is the subgroup of all the fixed points of α .*

THEOREM II.5 *The homogeneous space $\bar{L}_n^2 / L_n^2$ is weakly reductive: there exists a vector subspace $\mathfrak{M}$ of $\bar{\mathcal{Q}}_n^2$ such that*

$$\bar{\mathcal{Q}}_n^2 = \mathcal{Q}_n^2 \oplus \mathfrak{M} \text{ (direct sum),}$$

$$ad(L_n^2)\mathfrak{M} \subset \mathfrak{M},$$

where $\mathfrak{L}_n^2$ (resp. $\overline{\mathfrak{L}}_n^2$) is the Lie algebra of L_n^2 (resp. $\overline{L}_n^2$).

This result is an immediate consequence of the following lemma proved in [2].

LEMMA II.6 Let α be an involutive automorphism of a Lie group $\overline{G}$. The set of fixed points of α forms a Lie subgroup G of $\overline{G}$. Moreover, the homogeneous space $\overline{G}/G$ is weakly reductive: there exists a vector subspace $\mathfrak{M}$ of the Lie algebra $\overline{\mathfrak{G}}$ of $\overline{G}$ such that

$$\overline{\mathfrak{G}} = \mathfrak{G} \oplus \mathfrak{M} \text{ (direct sum)}$$

$$ad(G)\mathfrak{M} \subset \mathfrak{M}$$

where $\mathfrak{G}$ is the Lie algebra of G . The vector space $\mathfrak{M}$ can be given by

$$\mathfrak{M} = \{X \in \overline{\mathfrak{G}} : T\alpha(X) = -X\}.$$

Let $\mathfrak{M}$ be the vector subspace of $\overline{\mathfrak{L}}_n^2$ defined by the above lemma. If $X \in \mathfrak{M}$, $Y \in \mathfrak{M}$, $T\alpha([X, Y]) = [T\alpha(X), T\alpha(Y)] = [-X, -Y] = [X, Y]$ showing that $[X, Y] \in \mathfrak{L}_n^2$, i.e. $[\mathfrak{M}, \mathfrak{M}] \subset \mathfrak{L}_n^2$. We have therefore the following result.

COROLLARY II.7 The homogeneous space $\overline{L}_n^2/L_n^2$ is a symmetric space.

For the rest of this section, we fix once for all a decomposition $\overline{\mathfrak{L}}_n^2 = \mathfrak{L}_n^2 \oplus \mathfrak{M}$, where $\mathfrak{M}$ is the vector subspace defined in the theorem II.5. We denote by i the canonical injection of $H^2(V_n)$ into $\overline{H}^2(V_n)$.

Let $\bar{\omega}_2$ be a connection form in $\overline{H}^2(V_n)$. We can write $i^*\bar{\omega}_2 = \omega_2 + t$, where ω_2 (resp. t) is the $\mathfrak{L}_n^2$ -component (resp. $\mathfrak{M}$ -component) of $i^*\bar{\omega}_2$. Since $ad(L_n^2)\mathfrak{M} \subset \mathfrak{M}$, ω_2 defines a connection in the principal fibre bundle $H^2(V_n)$ over V_n and t is a $\mathfrak{M}$ -valued tensorial 1-form on $H^2(V_n)$, called the *quasi-holonomic form* of $\bar{\omega}_2$. Inversely, the couple (ω_2, t) determines a connection $\bar{\omega}_2$ in $\overline{H}^2(V_n)$. In fact, if $\xi \in T_u(\overline{H}^2(V_n))$ with $u \in H^2(V_n)$, we can write $\xi = \xi' + \xi''$, where ξ' is a horizontal vector with respect to the connection ω_2 and ξ'' is a vertical vector. Let us put $\bar{\omega}_2(\xi) = t(\xi') + u^{-1}(\xi'')$. Now, if $\xi \in T_v(\overline{H}^2(V_n))$ where $v \notin H^2(V_n)$, there exist $u \in H^2(V_n)$ and $g \in \overline{L}_n^2$ such that $v = ug$ and $\xi = TR_g(\xi')$ for

some $\xi \in T_u(\bar{H}^2(V_n))$. It is easy to check that $\bar{\omega}_2(\bar{\xi}) = \text{ad}(g^{-1})\bar{\omega}_2(\xi)$ does not depend on the choice of u and g . The mapping $\xi \rightarrow \bar{\omega}_2(\xi)$ gives the required connection form on $\bar{H}^2(V_n)$. Besides, $i^*\bar{\omega}_2 = \omega_2 + t$. We have thus established the following result.

PROPOSITION II.8 *There is a one-to-one correspondence between the set of all second order connections $\bar{\omega}_2$ of V_n and the set of all couples (ω_2, t) , where ω_2 is a connection form in $H^2(V_n)$ and t is a $\mathbb{M}$ -valued tensorial 1-form on $H^2(V_n)$; the correspondence is given by*

$$i^*\bar{\omega}_2 = \omega_2 + t.$$

COROLLARY II.9 *A linear connection $\bar{\omega}_2$ is quasi-holonomic if and only if its associated quasi-holonomic form t vanishes identically on $H^2(V_n)$.*

Let ϕ be a tensorial form on $\bar{H}^2(V_n)$. From the structure equation

$$\bar{D}\phi = d\phi + \bar{\omega}_2 \wedge \phi$$

where $\bar{D}\phi$ is the exterior covariant derivative of ϕ with respect to $\bar{\omega}_2$, we deduce that

$$\begin{aligned} i^*(\bar{D}\phi) &= i^*d\phi + i^*\bar{\omega}_2 \wedge i^*\phi \\ &= d(i^*\phi) + i^*\bar{\omega}_2 \wedge i^*\phi \\ &= d(i^*\phi) + \omega_2 \wedge i^*\phi + t \wedge i^*\phi. \end{aligned}$$

The induced form $i^*\phi$ is a tensorial form on $H^2(V_n)$. If D is the exterior covariant differentiation with respect to ω_2 , we have

$$D(i^*\phi) = d(i^*\phi) + \omega_2 \wedge i^*\phi.$$

Thus

$$i^*(\bar{D}\phi) = D(i^*\phi) + t \wedge i^*\phi.$$

Let $\bar{\Omega}_2$ (resp. Ω_2) be the curvature form of $\bar{\omega}_2$ (resp. ω_2). From the structure equation

$$\bar{\Omega}_2 = d\bar{\omega}_2 + [\bar{\omega}_2, \bar{\omega}_2]$$

we have

$$\begin{aligned} i^*\bar{\Omega}_2 &= i^*(d\bar{\omega}_2) + i^*([\bar{\omega}_2, \bar{\omega}_2]) \\ &= d(i^*\bar{\omega}_2) + [i^*\bar{\omega}_2, i^*\bar{\omega}_2] \end{aligned}$$

$$= \Omega_2 + D t + [t, t]$$

The form $D t + [t, t]$ is a tensorial 2-form on $H^2(V_n)$. We may call it the *quasi-holonomic curvature* of $\bar{\omega}_2$.

From the structure equation

$$\bar{\Theta}_2 = d\theta_2 + \bar{\omega}_2 \wedge \theta_2 + 3 [T\pi_1^2 \circ \bar{\omega}_2, T\pi_1^2 \circ \bar{\omega}_2]$$

we have

$$\begin{aligned} i^* \bar{\Theta}_2 &= i^* d\theta_2 + i^* \bar{\omega}_2 \wedge i^* \theta_2 + 3 [T\pi_1^2 \circ i^* \bar{\omega}_2, T\pi_1^2 \circ i^* \bar{\omega}_2] \\ &= \Theta_2 + t \wedge i^* \theta_2 + 3 [T\pi_1^2 \circ (\omega_2 + t), T\pi_1^2 \circ (\omega_2 + t)]. \end{aligned}$$

The form

$$\begin{aligned} T &= t \wedge i^* \theta_2 + 3 [T\pi_1^2 \circ (\omega_2 + t), T\pi_1^2 \circ (\omega_2 + t)] \\ &\quad - 3 [T\pi_1^2 \circ \omega_2, T\pi_1^2 \circ \omega_2] \end{aligned}$$

is a tensorial 2-form on $H^2(V_n)$, which may be called the *quasi-holonomic torsion* of $\bar{\omega}_2$.

If $\bar{\omega}_2$ is quasi-holonomic, its associated quasi-holonomic form t vanishes identically on $H^2(V_n)$. Therefore, the quasi-holonomic curvature and the quasi-holonomic torsion of $\bar{\omega}_2$ are zero.

3. $\mathfrak{G}$ -connections.

Let u be an arbitrary element of L_n^1 . There exists a unique automorphism f of the vector space $\mathbf{R}^n$ such that $u = j_0^1 f$. The induced map $f^{(k-1)}: \bar{H}^{k-1}(\mathbf{R}^n) \rightarrow \bar{H}^{k-1}(\mathbf{R}^n)$ is a $(k-1)$ -admissible isomorphism, and $j_{e_{k-1}}^1 f^{(k-1)} \in L_n^k$. The mapping $u \mapsto \iota^k(u) = j_{e_{k-1}}^1 f^{(k-1)}$ gives a canonical identification of L_n^1 with a subgroup of L_n^k (hence of $\bar{L}_n^k$). For $m < k$, $\iota^m = \pi_m^k \circ \iota^k$.

An invariant section of the fibration $\bar{H}^{k+1}(V_n) \rightarrow H^1(V_n)$, i.e. a lift ϕ_{k+1} of $H^1(V_n)$ into $\bar{H}^{k+1}(V_n)$ compatible with the canonical homomorphism $\iota^{k+1}: L_n^1 \rightarrow \bar{L}_n^{k+1}$, will be called an $\mathfrak{G}$ -connection of order k of V_n . It is given by a reduction of the structure group of $\bar{H}^{k+1}(V_n)$ from $\bar{L}_n^{k+1}$ to L_n^1 . There is a one-to-one correspondence between the set of all $\mathfrak{G}$ -connections (of order k) of V_n and the set of all semi-holonomic connections (of order k) defined in the sense of Ehresmann on the principal

bundle $H^1(V_n)$. [4c].

We say that an $\mathfrak{G}$ -connection ϕ_{k+1} is *symmetrical* or *holonomic* (resp. *quasi-holonomic*) if

$$\phi_{k+1}(H^1(V_n)) \subset H^{k+1}(V_n) \text{ (resp. } \phi_{k+1}(H^1(V_n)) \subset \check{H}^{k+1}(V_n)).$$

If ϕ_{k+1} is symmetrical (resp. quasi-holonomic), all projections $\phi_{m+1} = \pi_{m+1}^{k+1} \circ \phi_{k+1}$ of ϕ_{k+1} are symmetrical.

Consider an open set U of V_n with a system of local coordinates $\{x^1, x^2, \dots, x^n\}$. In terms of the induced local coordinates, a lift ϕ_{k+1} of $H^1(V_n)$ into $\tilde{H}^{k+1}(V_n)$ can be expressed by

$$(x^i, x_j^i) \rightarrow (x^i, x_j^i, \dots, x_{j_1 j_2 \dots j_{k+1}}^i).$$

If ϕ_{k+1} is invariant, the functions $x_{j_1 j_2}^i, \dots, x_{j_1 \dots j_{k+1}}^i$ can be written in the form

$$\begin{aligned} x_{j_1 j_2}^i &= \sum \Gamma_{m_1 m_2}^i x_{j_1}^{m_1} x_{j_2}^{m_2} \\ x_{j_1 j_2 j_3}^i &= \sum \Gamma_{m_1 m_2 m_3}^i x_{j_1}^{m_1} x_{j_2}^{m_2} x_{j_3}^{m_3} \\ &\dots \dots \dots \\ x_{j_1 j_2 \dots j_{k+1}}^i &= \sum \Gamma_{m_1 m_2 \dots m_{k+1}}^i x_{j_1}^{m_1} x_{j_2}^{m_2} \dots x_{j_{k+1}}^{m_{k+1}} \end{aligned}$$

where $\Gamma_{m_1 m_2}^i, \dots, \Gamma_{m_1 m_2 \dots m_{k+1}}^i$ are differentiable functions defined on U . These are the *Christoffel symbols* of the $\mathfrak{G}$ -connection ϕ_{k+1} . They are not entirely arbitrary; they have to satisfy certain conditions when we change the local coordinates system. It is clear that ϕ_{k+1} is symmetrical if and only if all the Christoffel symbols are symmetrical with respect to their lower indices.

Let us consider some particular cases:

case (i): $k=1$.

Let Γ_{rs}^i (resp. $\bar{\Gamma}_{rs}^i$) be the Christoffel symbols of a first order $\mathfrak{G}$ -connection ϕ_2 relative to a coordinate neighbourhood U (resp. $\bar{U}$) with a local coordinates system $\{x^1, x^2, \dots, x^n\}$ (resp. $\{\bar{x}^1, \bar{x}^2, \dots, \bar{x}^n\}$). If $U \cap \bar{U} \neq \emptyset$, we obtain easily the classical formula for the Christoffel symbols of a linear connection

$$\Gamma_{jk}^i = \sum \bar{\Gamma}_{\beta\gamma}^\alpha \left(\frac{\partial \bar{x}^\beta}{\partial x^j} \right) \left(\frac{\partial \bar{x}^\gamma}{\partial x^k} \right) \left(\frac{\partial x^i}{\partial \bar{x}^\alpha} \right) + \sum \left(\frac{\partial^2 \bar{x}^\alpha}{\partial x^j \partial x^k} \right) \left(\frac{\partial x^i}{\partial \bar{x}^\alpha} \right).$$

The quantities Γ_{jk}^i define then a linear connection of V_n . On the other hand, if $u \in H^1(V_n)$, the lift $\phi_2(u)$ of u determines a horizontal n -plane $Q_{\phi_2(u)}$ of $H^1(V_n)$ at u . Since ϕ_2 is compatible with $\iota^2: L_n^1 \rightarrow \bar{L}_n^2$, it is easy to check that the distribution $u \mapsto Q_{\phi_2(u)}$ defines an infinitesimal connection on $H^1(V_n)$, thus a linear connection ω_1 of V_n . The quantities Γ_{jk}^i are simply the classical Christoffel symbols of the associated linear connection ω_1 . In fact, if $X_j = \sum x_j^i \left(\frac{\partial}{\partial x^i} \right)_x$ ($1 \leq j \leq n$) is a basis for $T_x(V_n)$, with $x \in U$, the horizontal lift of X_j at $u = (x^i, x_j^i) \in H^1(V_n)$ with respect to ω_1 , is given by

$$X_j^* = \sum x_j^i \left(\frac{\partial}{\partial x^i} \right)_u + \sum x_{jk}^i \left(\frac{\partial}{\partial x^i} \right)_u$$

where $x_{jk}^i = -\sum \Gamma_{rs}^i x_j^r x_k^s$. Let $r_i^j = \left(\frac{\partial}{\partial x_j^i} \right) e_1$ ($1 \leq i, j \leq n$) be a basis for $\mathcal{L}_n^1$.

The components of $\omega_1 = \sum \omega_j^i r_i^j$ can be expressed by

$$\omega_j^i = \sum y_k^i (dx_j^k + \sum C_{mp}^k x_j^p dx^m)$$

where (y_k^i) is the inverse matrix of (x_k^i) and C_{mp}^k are the classical Christoffel symbols of the linear connection ω_1 . Consequently, $\omega_j^i(X_k^*) = 0$ for all indices $1 \leq i, j, k \leq n$. It follows that

$$x_{jk}^i = -\sum \Gamma_{rs}^i x_j^r x_k^s = -\sum C_{rs}^i x_j^r x_k^s.$$

Since $\det(x_j^i) \neq 0$, we have $\Gamma_{jk}^i = C_{jk}^i$.

PROPOSITION II.10 [4a] (i) *There is a one-to-one correspondence between the set of first order linear connections of V_n and the set of invariant sections of $H^1(V_n)$ into $\bar{H}^2(V_n)$.*

(ii) *Two linear connections of V_n have the same torsion if and only if the images of $H^1(V_n)$ by the corresponding invariant sections are contained in a principal subbundle of $\bar{H}^2(V_n)$ having the structure group L_n^2 .*

It remains to prove the second part of the proposition. Let $\phi_2, \bar{\phi}_2$

be two invariant sections of $H^1(V_n)$ into $\bar{H}^2(V_n)$. In terms of local coordinates, these $\bar{G}$ -connections are given by

$$\begin{aligned}(x^i, x_j^i) &\longrightarrow \phi_2(x^i, x_j^i) = (x^i, x_j^i, -\sum \Gamma_{rs}^i x_j^r x_k^s), \\(x^i, x_j^i) &\longrightarrow \bar{\phi}_2(x^i, x_j^i) = (x^i, x_j^i, -\sum \bar{\Gamma}_{rs}^i x_j^r x_k^s).\end{aligned}$$

where $\Gamma_{jk}^i, \bar{\Gamma}_{jk}^i$ are the corresponding Christoffel symbols. As $\phi_2(x^i, x_j^i)$ and $\bar{\phi}_2(x^i, x_j^i)$ are on the same fibre of $\bar{H}^2(V_n)$, there exists an element $(\delta_j^i, g_{jk}^i) \in \bar{M}_n^2 = \text{Ker}(\bar{L}_n^2 \rightarrow \bar{L}_n^1)$ such that

$$(x^i, x_j^i, -\sum \bar{\Gamma}_{rs}^i x_j^r x_k^s) = (x^i, x_j^i, -\sum \Gamma_{rs}^i x_j^r x_k^s)(\delta_j^i, g_{jk}^i).$$

It follows that

$$\sum \bar{\Gamma}_{rs}^i x_j^r x_k^s = \sum \Gamma_{rs}^i x_j^r x_k^s - \sum x_m^i g_{jk}^m,$$

Consequently, we have

$$(*) \quad \sum (\bar{\Gamma}_{rs}^i - \bar{\Gamma}_{sr}^i) x_j^r x_k^s = \sum (\Gamma_{rs}^i - \Gamma_{sr}^i) x_j^r x_k^s - \sum x_m^i (g_{jk}^m - g_{kj}^m).$$

If the two linear connections have the same torsion, that is if $\Gamma_{rs}^i - \Gamma_{sr}^i = \bar{\Gamma}_{rs}^i - \bar{\Gamma}_{sr}^i$, we have $\sum x_m^i (g_{jk}^m - g_{kj}^m) = 0$. Since $\det(x_m^i) \neq 0$, we get $g_{jk}^m = g_{kj}^m$, which shows that $(\delta_j^i, g_{jk}^i) \in M_n^2 = \bar{M}_n^2 \cap L_n^2$. Hence the condition is necessary.

If ϕ_2 and $\bar{\phi}_2$ map $H^1(V_n)$ into the same principal subbundle of $\bar{H}^2(V_n)$ having the structure group L_n^2 , we still have the formula (*) with $g_{jk}^m = g_{kj}^m$. Consequently,

$$\sum (\bar{\Gamma}_{rs}^i - \bar{\Gamma}_{sr}^i) x_j^r x_k^s = \sum (\Gamma_{rs}^i - \Gamma_{sr}^i) x_j^r x_k^s.$$

Since $\det(x_j^i) \neq 0$, we get

$$\bar{\Gamma}_{rs}^i - \bar{\Gamma}_{sr}^i = \Gamma_{rs}^i - \Gamma_{sr}^i.$$

Hence the connections have the same torsion, proving that the condition is sufficient.

Case (ii): $k = 2$

An element of $\bar{L}_n^3$ can be represented by a set of coordinates $(a_j^i, a_{jk}^i, a_{jkm}^i)$ with $\det(a_j^i) \neq 0$. The multiplication is given by

$$(a_j^i, a_{jk}^i, a_{jkm}^i) \cdot (b_j^i, b_{jk}^i, b_{jkm}^i) = (\sum a_r^i b_j^r, \sum (a_{rs}^i b_j^r b_k^s + a_r^i b_{jk}^r),$$

$$\sum (a_{rst}^i b_j^r b_k^s b_m^t + a_{rs}^i b_{jk}^r b_m^s + a_{rs}^i b_k^r b_{jm}^s + a_{rs}^i b_j^r b_{km}^s + a_r^i b_{jkm}^r).$$

If $u = (x^i, x_j^i, x_{jk}^i, x_{jkm}^i) \in \bar{H}^3(V_n)$, the action of $\bar{L}_n^3$ on $\bar{H}^3(V_n)$ can be expressed by

$$(x^i, x_j^i, x_{jk}^i, x_{jkm}^i)(a_j^i, a_{jk}^i, a_{jkm}^i) = (x^i, \sum x_r^i a_j^r, \sum (x_{rs}^i a_j^r a_k^s + x_r^i a_{jk}^r), \\ \sum (x_{rst}^i a_j^r a_k^s a_m^t + x_{rs}^i a_{jk}^r a_m^s + x_{rs}^i a_k^r a_j^s a_m^t + x_{rs}^i a_j^r a_{km}^s + x_r^i a_{jkm}^r)).$$

Consider an $\mathfrak{E}$ -connection ϕ_3 of order 2. In terms of local coordinates, ϕ_3 is given by

$$(x^i, x_j^i) \longrightarrow (x^i, x_j^i, -\sum \Gamma_{rs}^i x_j^r x_k^s, -\sum \bar{\Gamma}_{rst}^i x_j^r x_k^s x_m^t)$$

where $\Gamma_{rs}^i, \bar{\Gamma}_{rst}^i$ are the Christoffel symbols. If $\bar{\Gamma}_{rs}^i, \bar{\Gamma}_{rst}^i$ are the Christoffel symbols of ϕ_3 in an other local coordinates system, we have

$$\Gamma_{jk}^i = \sum \bar{\Gamma}_{\beta\gamma}^a (\frac{\partial \bar{x}^\beta}{\partial x^j})(\frac{\partial \bar{x}^\gamma}{\partial x^k})(\frac{\partial x^i}{\partial \bar{x}^a}) + \sum (\frac{\partial^2 \bar{x}^a}{\partial x^j \partial x^k})(\frac{\partial x^i}{\partial \bar{x}^a}), \\ \bar{\Gamma}_{jkm}^i = \sum (\frac{\partial x^r}{\partial \bar{x}^j})(\frac{\partial x^s}{\partial \bar{x}^k})(\frac{\partial x^t}{\partial \bar{x}^m}) \{ \Gamma_{rst}^a (\frac{\partial \bar{x}^i}{\partial x^a}) - (\frac{\partial^3 \bar{x}^i}{\partial x^r \partial x^s \partial x^t}) + \\ \Gamma_{rs}^a (\frac{\partial^2 \bar{x}^i}{\partial x^a \partial x^t}) + \Gamma_{rt}^a (\frac{\partial^2 \bar{x}^i}{\partial x^s \partial x^a}) + \Gamma_{st}^a (\frac{\partial^2 \bar{x}^i}{\partial x^r \partial x^a}) \}.$$

By direct computations, we have the following result:

PROPOSITION II.11 *Let $\Gamma_{jk}^i, \bar{\Gamma}_{jkm}^i$ be the Christoffel symbols of a second order $\mathfrak{E}$ -connection of V_n . If the induced first order $\mathfrak{E}$ -connection is symmetrical, then the following quantities*

$$A_{jkm}^i = \Gamma_{jkm}^i - \Gamma_{kjm}^i,$$

$$B_{jkm}^i = \Gamma_{jkm}^i - \Gamma_{mkj}^i,$$

$$C_{jkm}^i = \Gamma_{jkm}^i - \Gamma_{jmk}^i$$

are respectively the components of a $(1, 3)$ -tensor on V_n . The given $\mathfrak{E}$ -connection is symmetrical if and only if these three tensors are zero.

4. Linear connections and $\mathfrak{E}$ -connections.

The Lie group $\bar{L}_n^{k+1}$ (resp. L_n^{k+1}) acts linearly on $\bar{E}^k$ (resp. $E^k = T_{e_k}(H^k(\mathbf{R}^n))$) on the left. We denote by $\bar{S}^k T$ (resp. $S^k T$) the associa-

ted vector bundle of $\bar{H}^{k+1}(V_n)$ (resp. $H^{k+1}(V_n)$) with standard fibre $\bar{E}^k$ (resp. E^k) and structure group $\bar{L}_n^{k+1}$ (resp. L_n^{k+1}). For $k=0$, $S^0 T = T(V_n)$.

PROPOSITION II.12 *The vector bundle $\bar{S}^k T$ (resp. $S^k T$) is canonically isomorphic to the vector bundle $T(\bar{H}^k(V_n))/\bar{L}_n^k$ (resp. $T(H^k(V_n))/L_n^k$).*

An element $u \in \bar{H}^{k+1}(V_n)$ determines a linear isomorphism $\tilde{u}$ of $\bar{E}^k$ onto $T_{u,}(\bar{H}^k(V_n))$ with $u' = \pi_k^{k+1}(u)$. On the other hand, u can be considered as a linear isomorphism of $\bar{E}^k$ onto the fibre $(\bar{S}^k T)_x$ over x , where x is the projection of u on V_n . We have then a linear isomorphism $\tilde{u}_0 u^{-1}$ of $(\bar{S}^k T)_x$ onto $T_{u,}(\bar{H}^k(V_n))$. If v is another element of $\bar{H}^{k+1}(V_n)$ with projection $x = \pi_0^{k+1}(v)$, we can write $v = ug$ for a unique $g \in \bar{L}_n^{k+1}$. Similarly, we have a linear isomorphism $\tilde{v}_0 v^{-1} : (\bar{S}^k T)_x \rightarrow T_{v,}(\bar{H}^k(V_n))$, where $v' = \pi_k^{k+1}(v)$. Now, $v = u \circ \rho(g)$ and $\tilde{v} = T R_{g,0} \tilde{u}_0 \rho(g)$ with $g' = \pi_k^{k+1}(g) \in \bar{L}_n^k$. Consequently, $\tilde{v}_0 v^{-1} = T R_{g,0} \tilde{u}_0 u^{-1}$. Since $\bar{H}^{k+1}(V_n) \rightarrow \bar{H}^k(V_n)$ is surjective, we get an isomorphism of $\bar{S}^k T$ onto $T(\bar{H}^k(V_n))/\bar{L}_n^k$. Similarly, one establishes an isomorphism of $S^k T$ onto $T(H^k(V_n))/L_n^k$.

P. Libermann showed that $T(\bar{H}^k(V_n))/\bar{L}_n^k$ (resp. $T(H^k(V_n))/L_n^k$) is canonically isomorphic to $\bar{J}^k T$ (resp. $J^k T$), the k -th semi-holonomic (resp. holonomic) prolongation of the vector bundle $T(V_n)$. Thus, we have an isomorphism of $\bar{S}^k T$ (resp. $S^k T$) onto $\bar{J}^k T$ (resp. $J^k T$).

$H^{k+1}(V_n)$ being a principal fibre subbundle of $\bar{H}^{k+1}(V_n)$ and the action of L_n^{k+1} on E^k being the restriction of that of $\bar{L}_n^{k+1}$ on $\bar{E}^k$, the vector bundle $S^k T$ can be considered as a vector subbundle of $\bar{S}^k T$.

The projection π_{m+1}^{k+1} of $\bar{H}^{k+1}(V_n)$ onto $\bar{H}^{m+1}(V_n)$ induces a surjection p_m^k of $\bar{S}^k T$ onto $\bar{S}^m T$. Moreover, the restriction of p_m^k to each fibre of $\bar{S}^k T$ is linear. Similarly, we have a projection of $S^k T$ onto $S^m T$ for $m < k$.

An $\mathcal{G}$ -connection $\phi_{k+1} : H^1(V_n) \rightarrow \bar{H}^{k+1}(V_n)$ induces a splitting of the following exact sequence of vector bundles

$$0 \longrightarrow \bar{N}^k \longrightarrow \bar{S}^k T \longrightarrow T(V_n) \longrightarrow 0$$

where $\bar{N}^k$ is the kernel of the projection $\bar{S}^k T \rightarrow T(V_n)$. More precisely, we have the following result:

THEOREM II.13 *There exists a one-to-one correspondence between the set of $\mathcal{E}$ -connections of order k of V_n and the set of splittings of the exact sequence of vector bundles over V_n :*

$$0 \longrightarrow \bar{N}^k \longrightarrow \bar{S}^k T \longrightarrow T(V_n) \longrightarrow 0.$$

Let us first prove two lemmas:

LEMMA II.14 *Let $\bar{E}^k = \mathbf{R}^n \oplus \bar{\mathcal{Q}}_n^k$ be the canonical decomposition of $\bar{E}^k$ defined by the canonical connection in $\bar{H}^k(\mathbf{R}^n) = \mathbf{R}^n \times \bar{L}_n^k$. For every other decomposition of $\bar{E}^k$ of the form $\bar{E}^k = Q^k \oplus \bar{\mathcal{Q}}_n^k$, there exists a unique $g \in \bar{M}^{k+1} = \text{Ker}(\bar{L}_n^{k+1} \rightarrow L_n^1)$ such that $\rho(g)(\mathbf{R}^n) = Q^k$.*

We prove the lemma by induction on k . For $k=1$, we have the canonical decomposition $E^1 = \mathbf{R}^n \oplus \mathcal{Q}_n^1$. Let $E^1 = Q^1 \oplus \bar{\mathcal{Q}}_n^1$ be another decomposition of E^1 . Consider a local section σ_1 of $H^1(\mathbf{R}^n) \rightarrow \mathbf{R}^n$ such that $\sigma_1(0) = e_1$ and $T\sigma_1(\mathbf{R}^n) = Q^1$. Let f be the admissible local isomorphism of $H^1(\mathbf{R}^n)$ into $H^1(\mathbf{R}^n)$ defined by the condition: $f \circ \eta_1 = \sigma_1$, where η_1 is the «zero section» of $H^1(\mathbf{R}^n) = \mathbf{R}^n \times L_n^1 \rightarrow \mathbf{R}^n$. The 1-jet $j_{e_1}^1 f = g$ defines an element $g \in \bar{M}_n^2 = \text{Ker}(\bar{L}_n^2 \rightarrow L_n^1)$ satisfying the property: $\rho(g)(\mathbf{R}^n) = Q^1$. Uniqueness follows from the fact that the neutral element is the only element of $\bar{M}_n^2$ leaving stable the two components of $E^1 = \mathbf{R}^n \oplus \mathcal{Q}_n^1$.

Let us assume that the lemma is proved for $m \leq k-1$. If $\bar{E}^k = Q^k \oplus \bar{\mathcal{Q}}_n^k$ is a decomposition of $\bar{E}^k$, we may consider a local section σ_k of $\bar{H}^k(\mathbf{R}^n) \rightarrow \mathbf{R}^n$ satisfying the conditions: $\sigma_k(0) = e_k$ and $T\sigma_k(T_0(\mathbf{R}^n)) = Q^k$. Now,

$$\bar{E}^{k-1} = T\pi_{k-1}^k(\bar{E}^k) = T\pi_{k-1}^k(Q^k) \oplus T\pi_{k-1}^k(\bar{\mathcal{Q}}_n^k) = T\pi_{k-1}^k(Q^k) \oplus \bar{\mathcal{Q}}_n^{k-1}.$$

From the induction hypothesis, there is a unique $g' \in \bar{M}^k = \text{Ker}(\bar{L}_n^k \rightarrow L_n^1)$ such that $\rho(g')(\mathbf{R}^n) = T\pi_{k-1}^k(Q^k)$. Let h be the admissible local isomorphism of $\bar{H}^k(\mathbf{R}^n)$ into $\bar{H}^k(\mathbf{R}^n)$ defined by the condition: $h \circ \eta_k = R_{g'} \circ \sigma_k$ where η_k is the «zero section» of $\bar{H}^k(\mathbf{R}^n) = \mathbf{R}^n \times \bar{L}_n^k \rightarrow \mathbf{R}^n$. The 1-jet $j_{e_k}^1 h$ defines an element g of $\bar{M}^{k+1} = \text{Ker}(\bar{L}_n^{k+1} \rightarrow L_n^1)$ such that $\rho(g)(\mathbf{R}^n) = Q^k$. Suppose that there is another $\bar{g} \in \bar{M}^{k+1}$ satisfying the condition: $\rho(\bar{g})(\mathbf{R}^n) = Q^k$. We have then $\rho(\pi_{k-1}^{k+1}(\bar{g}))(\mathbf{R}^n) = T\pi_{k-1}^k(Q^k)$. Consequently, $g' = \pi_{k-1}^{k+1}(\bar{g})$. We can write $\bar{g} = gm_0$ where m_0 is an ele-

ment of $\text{Ker}(\bar{L}_n^{k+1} \rightarrow \bar{L}_n^k)$. Since the neutral element is the only element of $\text{Ker}(\bar{L}_n^{k+1} \rightarrow \bar{L}_n^k)$ leaving stable the two components of $\bar{E}^k = \mathbf{R}^n \oplus \bar{\mathcal{Q}}_n^k$, we conclude that $\bar{g} = g$ proving the uniqueness of g .

LEMMA II.15 *The Lie group $\iota^{k+1}(L_n^1)$ is the largest subgroup of $\bar{L}_n^{k+1}$ which leaves invariant the two direct summands of $\bar{E}^k = \mathbf{R}^n \oplus \bar{\mathcal{Q}}_n^k$.*

It is easy to check that $\iota^{k+1}(L_n^1)$ leaves invariant the two direct summands of $\bar{E}^k = \mathbf{R}^n \oplus \bar{\mathcal{Q}}_n^k$. Now, consider an element $g \in \bar{L}_n^{k+1}$ such that $\rho(g)(\mathbf{R}^n) = \mathbf{R}^n$. Let $g_0 = \pi_1^{k+1}(g)$. The action of $\iota^{k+1}(g_0) \cdot g^{-1}$ on $\mathbf{R}^n \subset \bar{E}^k$ is trivial. Consequently, we have $g = \iota^{k+1}(g_0) \in \iota^{k+1}(L_n^1)$ in virtue of the preceding lemma.

Let us go back to the proof of the theorem. We have seen that there is a mapping F of the set of $\mathcal{E}$ -connections of order k of V_n into the set of splittings of the exact sequence of vector bundles over V_n :

$$0 \longrightarrow \bar{N}^k \longrightarrow \bar{S}^k T \longrightarrow T(V_n) \longrightarrow 0.$$

This mapping F is injective. Let us consider two $\mathcal{E}$ -connections ϕ_{k+1} and ψ_{k+1} which induce the same splitting

$$F(\phi_{k+1}) = F(\psi_{k+1}): T(V_n) \rightarrow \bar{S}^k T.$$

If $y \in T(V_n)$, we can write $y = q_1(u, \xi)$, where $u \in H^1(V_n)$, $\xi \in \mathbf{R}^n$ and q_1 is the natural projection of $H^1(V_n) \times \mathbf{R}^n$ onto $T(V_n)$. The condition $F(\phi_{k+1})(y) = F(\psi_{k+1})(y)$ implies that

$$q_{k+1}(\phi_{k+1}(u), \xi) = q_{k+1}(\psi_{k+1}(u), \xi),$$

where we have denoted by q_{k+1} the natural projection of $\bar{H}^{k+1}(V_n) \times \bar{E}^k$ onto $\bar{S}^k T$. From the above lemma, we deduce that $\phi_{k+1}(u) = \psi_{k+1}(u)$ for all $u \in H^1(V_n)$. Let us show that F is surjective. Consider a splitting of the exact sequence

$$0 \longrightarrow \bar{N}^k \longrightarrow \bar{S}^k T \longrightarrow T(V_n) \longrightarrow 0$$

given by the lift $\sigma: T(V_n) \rightarrow \bar{S}^k T$. Let x be an arbitrary element of V_n . An element u of the fibre of $\bar{H}^{k+1}(V_n)$ over x determines a linear isomorphism of $\bar{E}^k$ onto $(\bar{S}^k T)_x$. The image $u^{-1}(\sigma(T_x(V_n)))$ is a vector subspace of $\bar{E}^k$. More exactly, we have $\bar{E}^k = u^{-1}(\sigma(T_x(V_n))) \oplus \bar{\mathcal{Q}}_n^k$. From

the lemma II.14, there exists a $g \in \bar{M}^{k+1} = \text{Ker}(\bar{L}_n^{k+1} \rightarrow L_n^1)$ such that $\rho(g)(\mathbf{R}^n) = u^{-1}(\sigma(T_x(V_n)))$. The element $v = ug \in \bar{H}^{k+1}(V_n)$ defines therefore a linear isomorphism of $\bar{E}^k = \mathbf{R}^n \oplus \bar{\mathcal{Q}}_n^k$ onto $(\bar{S}^k T)_x$, mapping $\mathbf{R}^n$ onto $\sigma(T_x(V_n))$. Every element of $\bar{H}^{k+1}(V_n)$ lying on the fibre over x and having the same property is of the form vg_0 with $g_0 \in \iota^{k+1}(L_n^1)$. Since x is arbitrary, we obtain in this way a principal subbundle of $\bar{H}^{k+1}(V_n)$ with structure group $\iota^{k+1}(L_n^1)$, hence the $\mathfrak{E}$ -connection that we are looking for.

The vector bundle $T(\bar{H}^k(V_n))/\bar{L}_n^k$ is isomorphic to $\bar{S}^k T$. We have therefore a one-to-one correspondence between the set of linear connections of order k of V_n and the set of splittings of the exact sequence of vector bundles

$$0 \longrightarrow \bar{N}^k \longrightarrow \bar{S}^k T \longrightarrow T(V_n) \longrightarrow 0.$$

From the preceding result, we have

THEOREM II.16 *There is a one-to-one correspondence between the set of linear connections of order k and the set of $\mathfrak{E}$ -connections of the same order.*

Consider an $\mathfrak{E}$ -connection $\phi_{k+1}: H^1(V_n) \rightarrow \bar{H}^{k+1}(V_n)$. Let $\phi_k = \pi_k^{k+1} \circ \phi_{k+1}$. If $u \in H^1(V_n)$, $\phi_{k+1}(u)$ determines a horizontal n -plane of $\bar{H}^k(V_n)$ at $\phi_k(u) \in \bar{H}^k(V_n)$. We obtain thus a field of n -planes of $\bar{H}^k(V_n)$ defined on $\phi_k(H^1(V_n))$. It is easy to check that this local field is invariant with respect to the right translations defined by the elements of $\iota^k(L_n^1)$ on $\bar{H}^k(V_n)$. Consequently, we can extend it to a global field of n -planes of $\bar{H}^k(V_n)$ invariant with respect to the right translations of $\bar{L}_n^k$ on $\bar{H}^k(V_n)$. We obtain thus a linear connection ω_k of order k of V_n . This correspondence $\phi_{k+1} \rightarrow \omega_k$ is exactly the one we have established in the above theorem. For $k=1$, we have a one-to-one correspondence between the set of symmetrical linear connections of V_n and the set of invariant sections of $H^1(V_n)$ into $H^2(V_n)$ (cf. Prop. I.9 and Prop. II.10). Let us assume that there is a one-to-one correspondence between the set of symmetrical $\mathfrak{E}$ -connections of order m ($m \leq k-1$) and the set of quasi-holonomic linear connections of the same order having zero torsion. If ϕ_{k+1} is a

symmetrical $\mathfrak{E}$ -connection of order k , the corresponding linear connection ω_k is quasi-holonomic and without torsion (cf. Theorem I.10). Inversely let ω_k be a quasi-holonomic linear connection having zero torsion and let ϕ_{k+1} be the corresponding $\mathfrak{E}$ -connection established in the above theorem. The connection projection ω_{k-1} (of order $k-1$) of ω_k is a quasi-holonomic connection without torsion. From the induction hypothesis, the corresponding $\mathfrak{E}$ -connection ϕ_k is symmetrical. It is easy to check that $\phi_k = \pi_k^{k+1} \circ \phi_{k+1}$. Hence $\phi_{k+1}(H^1(V_n)) \subset H^{k+1}(V_n)$ from the «Holonomy Theorem». We have thus established the following result:

COROLLARY II.17 *There is a one-to-one correspondence between the set of symmetrical $\mathfrak{E}$ -connections and the set of quasi-holonomic linear connections without torsion.*

5. Pseudo-connections and multi-connections.

A pseudo-connection of order k of V_n is a couple (ψ_{k+1}, Ψ_{k+1}) , where Ψ_{k+1} is a homomorphism of $\bar{L}_n^k$ into $\bar{L}_n^{k+1}$ and ψ_{k+1} is a differentiable lift of $\bar{H}^k(V_n)$ into $\bar{H}^{k+1}(V_n)$ such that

$$\psi_{k+1}(ug) = \psi_{k+1}(u) \Psi_{k+1}(g)$$

for all $u \in \bar{H}^k(V_n)$ and $g \in \bar{L}_n^k$. It follows that Ψ_{k+1} is a lift of $\bar{L}_n^k$ into $\bar{L}_n^{k+1}$. The condition of compatibility implies that an invariant vector field of $\bar{H}^k(V_n)$ can be lifted to an invariant vector field of $\bar{H}^{k+1}(V_n)$. We obtain thus an infinitesimal connection in the principal fibre bundle $\bar{H}^{k+1} \rightarrow \bar{H}^k(V_n)$, or equivalently, a splitting of the exact sequence of vector bundles over V_n

$$0 \longrightarrow \bar{N}_k^{k+1} \longrightarrow \bar{S}^{k+1}T \longrightarrow \bar{S}^kT \longrightarrow 0$$

where $\bar{N}_k^{k+1}$ is the kernel of $\bar{S}^{k+1}T \rightarrow \bar{S}^kT$.

Consider a pseudo-connection (ψ_{k+1}, Ψ_{k+1}) of V_n . The lift ψ_{k+1} of $\bar{H}^k(V_n)$ into $\bar{H}^{k+1}(V_n)$ defines an absolute parallelism on $\bar{H}^k(V_n)$. If $Z \in T_u(\bar{H}^k(V_n))$, we put $\alpha(Z) = \widetilde{\psi_{k+1}(u)}^{-1}(Z)$. The mapping $Z \rightarrow \alpha(Z)$ defines a differentiable 1-form α on $\bar{H}^k(V_n)$ with values in $\bar{E}^k$. There is an induced linear representation of $\bar{L}_n^k$ on $\bar{E}^k$ given by

$$\sigma = \rho \circ \Psi_{k+1},$$

where we have denoted by ρ the linear representation of $\bar{L}_n^{k+1}$ on $\bar{E}^k$. If $Z \in T(\bar{H}^k(V_n))$, we have $\alpha(TR_g(Z)) = \sigma(g^{-1})\alpha(Z)$, i.e. α is a pseudotensorial 1-form on $\bar{H}^k(V_n)$, called the *pseudo-connection form* of (ψ_{k+1}, Ψ_{k+1}) .

A *multi-connection* of order k of V_n is given by a sequence of pseudo-connections (ψ_{m+1}, Ψ_{m+1}) , $m = 1, 2, \dots, k$ such that $\Psi_{m+1} \circ \iota^m = \iota^{m+1}$. The composite map $\phi_{k+1} = \psi_{k+1} \circ \psi_k \circ \dots \circ \psi_2$ defines an $\mathfrak{E}$ -connection of V_n . Inversely, given a sequence of homomorphisms $\Psi_{m+1}: \bar{L}_n^m \rightarrow \bar{L}_n^{m+1}$ such that $\Psi_{m+1} \circ \iota^m = \iota^{m+1}$ ($m = 1, 2, \dots, k$), an $\mathfrak{E}$ -connection $\phi_{k+1}: H^1(V_n) \rightarrow \bar{H}^{k+1}(V_n)$ determines a multi-connection of order k of V_n .

We are going to define a natural sequence of group homomorphisms

$$L_n^1 \xrightarrow{\Lambda_2} \bar{L}_n^2 \xrightarrow{\Lambda_3} \dots \xrightarrow{\Lambda_{k+1}} \bar{L}_n^{k+1} \rightarrow \dots$$

satisfying the conditions: $\pi_{k+1}^{k+1} \circ \Lambda_{k+1} = \text{identity}$, $\Lambda_{k+1} \circ \iota^k = \iota^{k+1}$ for $k = 2, 3, \dots$. We put $\Lambda_2 = \iota^2$, the canonical injection of L_n^1 into $\bar{L}_n^2$. It induces a lift of $H^1(\mathbf{R}^n) = \mathbf{R}^n \times L_n^1$ into $\bar{H}^2(\mathbf{R}^n) = \mathbf{R}^n \times \bar{L}_n^2$. We will denote this lift by the same symbol Λ_2 . Let $u = j_{e_1} f \in \bar{L}_n^2$, where f is an admissible local isomorphism of $H^1(\mathbf{R}^n)$ into $H^1(\mathbf{R}^n)$. Consider the local isomorphism b of $\bar{H}^2(\mathbf{R}^n)$ into $\bar{H}^2(\mathbf{R}^n)$ defined by the condition:

$$b \circ \eta_2 = R_u \circ \Lambda_2 \circ R_u^{-1} \circ f \circ \eta_1,$$

where $u' = \pi_1^2(u)$ and η_i ($i = 1, 2$) are the «zero sections». The 1-jet $j_{e_2}^1 b$ depends uniquely on u and the mapping $u \mapsto \Lambda_3(u) = j_{e_2}^1 b$ defines a group homomorphism of $\bar{L}_n^2$ into $\bar{L}_n^3$ satisfying the required conditions. Let us assume that we have defined homomorphisms $\Lambda_2, \Lambda_3, \dots, \Lambda_k$ satisfying the required conditions. Let $v = j_{e_{k-1}}^1 b \in \bar{L}_n^k$, where b is an admissible local isomorphism of $\bar{H}^{k-1}(\mathbf{R}^n)$ into $\bar{H}^{k-1}(\mathbf{R}^n)$. Consider the admissible local isomorphism g of $\bar{H}^k(\mathbf{R}^n)$ into $\bar{H}^k(\mathbf{R}^n)$ defined by the condition:

$$g \circ \eta_k = R_v \circ \Lambda_k \circ R_v^{-1} \circ b \circ \eta_{k-1}$$

with $v' = \pi_{k-1}^k(v)$ and η_i ($i = k-1, k$) are the «zero sections». It is easy to check that the mapping $v \mapsto \Lambda_{k+1}(v) = j_{e_k}^1 g$ defines a group homomorphism of $\bar{L}_n^k$ into $\bar{L}_n^{k+1}$ with the desired properties. We obtain thus a natural sequence of group homomorphisms

$$L_n^1 \xrightarrow{\Lambda_2} \bar{L}_n^2 \longrightarrow \dots \longrightarrow \bar{L}_n^k \xrightarrow{\Lambda_{k+1}} \bar{L}_n^{k+1} \longrightarrow \dots$$

PROPOSITION II.18 *There is a one-to-one correspondence between the set of $\mathfrak{E}$ -connections of order k of V_n and the set of multi-connections of the form $\{(\lambda_m, \Lambda_m)\}_{2 \leq m \leq k}$, where the Λ_m are the homomorphisms of the natural sequence.*

6. Prolongations of linear connections.

We have seen that a linear connection of order 1 of V_n can be given by an invariant section ϕ_2 of $H^1(V_n)$ into $\bar{H}^2(V_n)$. We are going to construct a lift of $\phi_2(H^1(V_n))$ into $\bar{H}^3(V_n)$. Let $u = j_{e_1}^1 f \in \phi_2(H^1(V_n))$, where f is an admissible local isomorphism of $H^1(\mathbf{R}^n)$ into $H^1(V_n)$. Let b be the admissible local isomorphism of $\bar{H}^2(\mathbf{R}^n)$ into $\bar{H}^2(V_n)$ defined by: $b \circ \eta_2 = \phi_2 \circ f \circ \eta_1$. The mapping $u \mapsto \phi_2^3(u) = j_{e_1}^1 b$ defines a lift of $\phi_2(H^1(V_n))$ into $\bar{H}^3(V_n)$. The composite mapping $\phi_3 = \phi_2^3 \circ \phi_2$ defines an invariant section of $H^1(V_n)$ into $\bar{H}^3(V_n)$. The $\mathfrak{E}$ -connection ϕ_3 obtained by this way or the corresponding linear connection of order 2 will be called the first prolongation of ϕ_2 . The principal subbundle $\phi_3(H^1(V_n))$ of $\bar{H}^3(V_n)$, possesses the following property: for every $v \in \phi_3(H^1(V_n))$, there exists an admissible local isomorphism g of $\bar{H}^2(\mathbf{R}^n)$ into $\bar{H}^2(V_n)$ such that $v = j_{e_2}^1 g$ and that g maps the (local) zero section of $\bar{H}^2(\mathbf{R}^n)$ into $\phi_2(H^1(V_n))$. By means of this property, we can construct a lift ϕ_3^4 of $\phi_3(H^1(V_n))$ into $\bar{H}^4(V_n)$ and the composite mapping $\phi_4 = \phi_3^4 \circ \phi_3$ defines an $\mathfrak{E}$ -connection of order 3, called the second prolongation of ϕ_2 . Notice that the projections of ϕ_4 are respectively ϕ_3 and ϕ_2 . By iterations, we construct the k -th prolongation of ϕ_2 .

If we consider only the prolongations of linear connections of order 1 of V_n , we do not obtain all the linear connections of higher order of V_n . A linear connection of order k is called *simple* if it is the $(k-1)$ -th prolongation of a first order linear connection of V_n .

Let ω_k (resp. ω'_k) be a linear connection of order k of V_n (resp. V'_n). We will say that ω_k is *equivalent* to ω'_k if there exists a diffeomorphism f of V_n onto V'_n such that $f^{(k)*} \omega'_k = \omega_k$.

A linear connection ω_k is called *locally flat* if it is locally equivalent to the canonical connection in the trivial bundle $\bar{H}^k(\mathbf{R}^n) = \mathbf{R}^n \times \bar{L}_n^k$.

THEOREM II.19 *A linear connection of order k is locally flat if and only if it is simple, without torsion and without curvature.*

It is well known that a first order connection is locally flat if and only if its torsion and curvature are zero. For $k > 1$, the conditions are obviously necessary, because the canonical connection in $\bar{H}^k(\mathbf{R}^n)$ is simple, without torsion and without curvature. Let us show that the conditions are sufficient. Consider such a linear connection ω_k . The connection projection ω_1 of order 1 of ω_k is locally flat, because its torsion and its curvature are both zero. Since ω_k is simple, we can obtain ω_k by taking the successive prolongations of ω_1 . Let ϕ_{k+1} be the invariant section of $H^1(V_n)$ into $\bar{H}^{k+1}(V_n)$ corresponding to ω_k . We put $\phi_k = \pi_k^{k+1} \circ \phi_{k+1}$. For all $y \in H^1(V_n)$, the horizontal n -plane of $\bar{H}^k(V_n)$ associated to the $(k+1)$ -frame $\phi_{k+1}(y)$ is tangent to $\phi_k(H^1(V_n))$, because ω_k is simple. From the «Holonomy Theorem», we have $\phi_{k+1}(H^1(V_n)) \subset H^{k+1}(V_n)$. On the other hand, the nullity of the curvature form of ω_k implies that the distribution of n -planes of $\bar{H}^k(V_n)$ defined by ω_k is involutive. Let W be the maximal integral submanifold passing through $u \in \phi_k(H^1(V_n))$. We have $W \subset \phi_k(H^1(V_n))$. The canonical form θ_k (resp. $\hat{\theta}_k$) of $\bar{H}^k(V_n)$ (resp. $\bar{H}^k(\mathbf{R}^n)$), restricted to W (resp. $Q = \eta_k(\mathbf{R}^n)$), will be denoted by θ_W (resp. $\hat{\theta}_Q$). These forms θ_W and $\hat{\theta}_Q$ have their values in $\mathbf{R}^n \subset \bar{E}^{k-1}$. Consider the 1-form $\beta = p_1^* \theta_W - p_2^* \hat{\theta}_Q$ on the product manifold $W \times Q$, where p_i ($i=1, 2$) are the projections on W and Q respectively. In terms of a basis $\{a^1, a^2, \dots, a^n\}$ for $\mathbf{R}^n$, the components β_i of β are linearly independent. Consider now the module $\mathfrak{M}$ of vector fields X on $W \times Q$ such that $\beta_i(X) = 0$ for $i=1, 2, \dots, n$. If $X \in \mathfrak{M}$, $Y \in \mathfrak{M}$, we have

$$d\beta(X, Y) = X\beta(Y) - Y\beta(X) - \beta([X, Y]) = -\beta([X, Y]).$$

On the other hand, $d\beta(X, Y) = 0$. Consequently, $[X, Y] \in \mathfrak{M}$ showing that $\mathfrak{M}$ is involutive. Therefore, there exists a maximal integral submanifold M of dimension n passing through $(u, e_k) \in W \times Q$. For any non-zero vector Z tangent to $p_2^{-1}(e_k)$, $\beta(Z) \neq 0$. We can find an open neighbourhood U of e_k in Q and a differentiable section λ of U into $W \times Q$ such that we

have $\lambda(U) \subset M$. Let $h = p_1 \circ \lambda$. The form β vanishes identically on M , we have $\lambda^* \beta = 0$, showing that $\hat{\theta}_Q = h^* \theta_W$. We can now extend h to a local isomorphism $\check{h}$ of $\bar{H}^k(\mathbf{R}^n)$ into $\bar{H}^k(V_n)$ satisfying $\hat{\theta}_k = \check{h}^* \theta_k$. In virtue of theorem I.2, we can find an open neighbourhood N (resp. N') of $0 \in \mathbf{R}^n$ (resp. $x = \pi_0^k(u) \in V_n$) and a diffeomorphism f of N onto N' such that locally $\check{h} = f^{(k)}$. Consequently, ω_k is locally flat.

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