

COMPOSITIO MATHEMATICA

JOHN S. GRIFFIN, JR

On the rotation number of a normal curve

Compositio Mathematica, tome 13 (1956-1958), p. 270-276

http://www.numdam.org/item?id=CM_1956-1958__13__270_0

© Foundation Compositio Mathematica, 1956-1958, tous droits réservés.

L'accès aux archives de la revue « Compositio Mathematica » (<http://http://www.compositio.nl/>) implique l'accord avec les conditions générales d'utilisation (<http://www.numdam.org/conditions>). Toute utilisation commerciale ou impression systématique est constitutive d'une infraction pénale. Toute copie ou impression de ce fichier doit contenir la présente mention de copyright.

NUMDAM

Article numérisé dans le cadre du programme
Numérisation de documents anciens mathématiques
<http://www.numdam.org/>

On the Rotation Number of a Normal Curve

by

John S. Griffin, Jr.

In the mid-thirties Hopf [1] gave a proof that the rotation number of a simple closed curve is either 2π or -2π ; Whitney [2] then showed how to calculate the rotation number of any normal curve from properties of its crossing points.

From these theorems and the consideration of a few simple examples, it would seem that the differential-geometric notion of rotation number should be related to the topological notion of index, at any rate for normal curves. The object of the present note is to exhibit such a relation.

The author takes pleasure in recording his indebtedness to the remarks of Professors Samelson and H. Hopf.

1. *The Rotation Number of a Curve.* Let R be the field of real numbers. Let $\mathcal{P}$ be the Euclidean plane with a chosen rectangular coordinate system, that is, suppose that $\mathcal{P} = R \times R$. In particular, then, $\mathcal{P}$ is a two-dimensional vector space with basis vectors $e_1 = (1, 0)$ and $e_2 = (0, 1)$ and with norm defined by $\| (x, y) \| = \sqrt{x^2 + y^2}$.

Let S be the unit circle, that is the family of all vectors which have norm 1, and define $p : R \rightarrow S$ by

$$p(t) = (\cos t, \sin t)$$

for all points t of R . Now R is a covering space for S under the projection p , and hence there is the following well-known lemma: If A is any simply connected arcwise connected topological space, and $f : A \rightarrow S$ is continuous, then for any a in A and any t in R such that $p(t) = f(a)$ there is a unique continuous function $f^* : A \rightarrow R$ such that $pf^* = f$ and $f^*(a) = t$; such a function f^* is called a covering function for f . This is essentially the proposition of Hopf (1b of [1]) and thus may be taken as a basis for the measure of angles. Indeed, if $A = [a, b]$ is any closed interval and $u : A \rightarrow \mathcal{P}$ is any continuous function which never vanishes, then the angle turned by u is defined to be $v^*(b) - v^*(a)$, where

v^* is any covering function for the function $v : A \rightarrow S$ defined by

$$v(t) = \frac{u(t)}{\|u(t)\|}$$

for all real numbers t in A . Again, if c and d are any two linearly independent vectors then $\angle(c, d)$ the angle from c to d is defined to be the angle turned by u , where

$$u(t) = c + t(d - c)$$

for $0 \leq t \leq 1$.

Let f be a continuous function on a closed interval $[a, b]$ to $\mathcal{P}$. Then f is a *closed curve* if $f(a) = f(b)$, and a *simple closed curve* if furthermore $f(s) \neq f(t)$ for s different from a , b , and t . If f is a closed curve and c is a point of $\mathcal{P}$ which is not on f , then the *index* of c with respect to f is $\frac{\theta}{2\pi}$, where θ is the angle turned by u , the function u being defined to satisfy

$$u(t) = f(t) - c$$

for all points t of the interval $[a, b]$. If f is a simple closed curve then by the Jordan theorem the index of each exterior point is 0, and the indices of all interior points are equal, and have either the value $+1$ or else the value -1 . The *orientation number* ω_f of a simple closed curve f may thus be defined to be the index of any interior point of f .

A *smooth curve* is a continuous function f on a closed interval A to $\mathcal{P}$ which has a continuous non-vanishing derivative throughout A ; this derivative f' is the *tangent curve* of f . A *smooth closed curve* is a closed curve which is smooth and whose tangent curve is also closed; the *rotation number* of a smooth closed curve f is the angle turned by its tangent curve f' .

If $f : [a, b] \rightarrow \mathcal{P}$ is a closed curve, the *multiplicity* of a point c of $\mathcal{P}$ is the number (possibly infinite) of points s such that $a \leq s < b$ and $f(s) = c$. A *crossing point* of f is a point c of multiplicity 2 such that if $f(s) = c$ then f has a derivative at s , and furthermore if $f(s) = c$ and $f(t) = c$ but $s < t$ then $f'(s)$ and $f'(t)$ are linearly independent unless $s = a$ and $t = b$, in which case $f'(s) = f'(t)$. A smooth curve is *normal* if there are but a finite number of points whose multiplicity is greater than 1, and each of these is a crossing point. As shown by Whitney [2], any smooth closed curve f may be deformed into a normal curve by a homotopy which modifies both f and f' only a very little, and which in particular leaves the rotation number of f unchanged.

A class of curves which arise in the study of normal curves are the broken curves: Let $f: [a, b] \rightarrow \mathcal{P}$ be a closed curve; f is *broken* if there are points c_i , $a = c_0 < c_1 < \dots < c_n = b$, such that for $i = 1, 2, \dots, n$ $f|_{[c_{i-1}, c_i]}$ is a smooth curve, say with tangent curve τ_i ; furthermore for $i = 1, 2, \dots, n-1$, the vectors $\tau_i(c_i)$ and $\tau_{i+1}(c_i)$ are linearly independent; and finally either the vectors $\tau_1(a)$ and $\tau_n(b)$ are equal, or else they are linearly independent. The *corner points* of f are the points $c_1, \dots, c_{n-1}$ together with a if $\tau_1(a) \neq \tau_n(b)$.

The concept of rotation number may be extended to the class of broken curves by making proper allowance for corner points: if α_i is the angle turned by τ_i then the rotation number of f is

$$\sum_{i=1}^n \alpha_i + \sum_{i=1}^{n-1} \angle [\tau_i(c_i), \tau_{i+1}(c_i)] + \beta$$

where $\beta = \angle [\tau_n(b), \tau_1(a)]$ if a is a corner point, and $\beta = 0$ otherwise.

In the paper mentioned above Hopf showed that the rotation number of a simple closed curve is always 2π or else -2π , and he gave a rule to determine the sign. Since it is implicit in his proof that this sign is the sign of the orientation number, his theorem may be rephrased as follows:

If f is a simple closed curve, either smooth or broken, then the rotation number of f is $2\pi \omega_f$.

2. Circuits in a Closed Curve. Let $[a, b]$ be a closed interval, and let $f: [a, b] \rightarrow \mathcal{P}$ be a closed curve. It may happen that there is a proper sub-interval $[c, d]$ of $[a, b]$ such that $f|_{[c, d]}$ is also a closed curve; if so, then $f(c) = f(d)$, and therefore the function g defined by

$$g(t) = f(t + a) \quad \text{for } 0 \leq t \leq c - a$$

and

$$g(t) = f(t + d) \quad \text{for } c - a \leq t \leq (c - a) + (b - d)$$

is continuous, and hence is also a closed curve. Now $f|_{[c, d]}$ or g may be easier to deal with than f , as for example if $f|_{[c, d]}$ were a simple closed curve; hence the study of f might be facilitated by this sort of decomposition.

These considerations may easily be formalized. First let us agree that if A is a union of a finite number of closed intervals, say

$$A = \cup_{i=1}^n [a_i, b_i],$$

and f is a continuous function on A to $\mathcal{P}$ such that $f(b_i) = f(a_{i+1})$ for $i = 1, 2, \dots, n-1$ then

$$f \sim : [0, \sum_{i=1}^n (b_i - a_i)] \rightarrow \mathcal{P}$$

is defined by

$$f \sim (t) = f(t + a_i)$$

for $0 \leq t \leq b_1 - a_1$ if $i = 1$, and for $\sum_{j=1}^{i-1} b_j - a_i \leq t \leq \sum_{j=1}^i b_j - a_i$ for $1 < i < n$. Thus in the above example $g = (f|_{[a, c] \cup [a, b]}) \sim$.

A *circuit* in a closed curve $f : A \rightarrow \mathcal{P}$ is a restriction of f to a subset B of A which is a union of a finite number of closed intervals, say

$$B = \cup_{i=1}^n [a_i, b_i],$$

and such that $f(b_i) = f(a_{i+1})$ for each i and $f|_B$ is a simple closed curve. A *decomposition* of f is a family of circuits $\phi_1, \phi_2, \dots, \phi_n$, such that if $\phi_i = f|_{B_i}$ for each i then $A = \cup_{i=1}^n B_i$ and $B_i \cap B_j$ is discrete unless $i = j$.

LEMMA. *If $f : A \rightarrow \mathcal{P}$ is a normal curve then there is a decomposition of f into circuits; if $\phi_1, \dots, \phi_n$ is any such decomposition then the rotation number of f is the sum of the rotation numbers of the curves ϕ_i .*

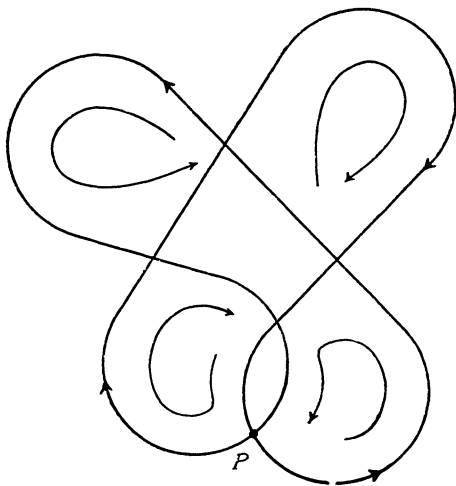
PROOF. Let C be the family of all curves satisfying all the hypotheses of the lemma except possibly smoothness: members of C may be broken but they must be closed and have only a finite number of points of multiplicity greater than 1, all these being crossing points. For $g : A \rightarrow \mathcal{P}$ a member of C , let S_g be the family of all points s of A such that $g(s)$ is the image of at least one point other than s . Clearly S_g is always finite; the end-points of A are members of S_g , and S_g has no other members if and only if g is simple.

An induction on the number of members of S_g now yields the desired decomposition. Trivially for any member g of C for which S_g has exactly two points there is a decomposition. Suppose therefore that there is a decomposition for any $g \in C$ such that S_g has at most n points, and let $f : [a, b] \rightarrow \mathcal{P}$ be a member of C such that S_f has exactly $n + 1$ points, say $s_0, s_1, \dots, s_n$. Let $\mathcal{J}$ be the family of all intervals $[s_i, s_j]$ such that $f(s_i) = f(s_j)$, and partially order $\mathcal{J}$ by inclusion. Since $\mathcal{J}$ is finite, there is a minimal member, say $[s_p, s_q]$. Clearly $f|_{[s_p, s_q]}$ is a circuit, and if

$$g = (f|_{[a, s_p] \cup [s_q, b]}) \sim$$

then $g \in C$ and S_g has at most n points; it follows that g , and hence f , has a decomposition into circuits.

Observe that neither the decomposition nor even the number of circuits is unique for a given curve. For example, the algorithm implicit in the above argument yields a decomposition of the curve in the accompanying figure into two circuits, each with one corner



at P ; but this curve can also be decomposed into four circuits as indicated by the arrows.

To return to the proof, it remains to show that if $\phi_1, \dots, \phi_n$ is a decomposition of the normal curve $f: A \rightarrow P$ into circuits, and r_i is the rotation number of ϕ_i , then $\sum_i r_i$ is the rotation number of f .

Suppose that for each i ϕ_i is defined on the intervals $I_0^i, I_1^i, \dots, I_{p(i)}^i$, where for each j

$$I_j^i = [a_j^i, b_j^i];$$

thus we are assuming that

$$A = \cup_{i,j} I_j^i,$$

that for each j

$$b_j^i \neq a_{j+1}^i \quad \text{but} \quad f(b_j^i) = f(a_{j+1}^i),$$

that each ϕ_i is a simple closed curve, and that I_j^i and I_k^h have at most one common point unless $i = h$ and $j = k$. Note that it may happen that I_j^i is to the right of I_k^h even though $j < k$, as for example in two of the four circuits indicated in the figure.

Let α_j^i be the angle turned by f' on the interval I_j^i , and let β_j^i , $j = 0, 1, 2, \dots, p(i)$, represent the angles at the corners of ϕ_i : if $j < p(i)$

$$\beta_j^i = \angle (f'(b_j^i), f'(a_{j+1}^i))$$

and

$$\beta_{p(i)}^i = \star (f'(b_{p(i)}^i), f'(a_0^i))$$

unless a_0^i and $b_{p(i)}^i$ are the left and right end points of A , in which case leave $\beta_{p(i)}^i$ undefined. One then has

$$r_i = \sum_j \alpha_j^i + \sum_j \beta_j^i,$$

and hence

$$\sum_i r_i = \sum_i \sum_j \alpha_j^i + \sum_i \sum_j \beta_j^i.$$

Since f is smooth, the rotation number of f is $\sum_i \sum_j \alpha_j^i$, and it remains to see that the second sum vanishes. Here the crucial fact is that the corners of members of the decomposition occur in pairs: corners arise from crossing points and therefore must have mates. Let then $c_1, c_2, \dots, c_n$ be the images of the points b_j^i under f (excluding the right end-point b_j^i of A if the left end point of A is a_0^i), and let the pair (i, j) belong to σ_k if and only if $f(b_j^i) = c_k$; it follows that

$$\sum_i \sum_j \beta_j^i = \sum_{k=1}^n \sum_{(i,j) \in \sigma_k} \beta_j^i.$$

And now finally for each k

$$\sum_{(i,j) \in \sigma_k} \beta_j^i = 0:$$

if $(i, j) \in \sigma_k$ there is exactly one member (h, m) of σ_k distinct from (i, j) and

$$f(b_j^i) = f(b_m^h) = c_k,$$

and furthermore

$$f(a_{j+1}^i) = f(a_{m+1}^h) = c_k$$

(unless $j+1 = p(i)$ respectively $m+1 = p(h)$, in which case $j+1$ respectively $m+1$ must be replaced with 0). Since c_k is of multiplicity two,

$$b_j^i = a_{m+1}^h \quad \text{and} \quad b_m^h = a_{j+1}^i;$$

since

$$\beta_j^i = \star (f'(b_j^i), f'(a_{j+1}^i))$$

and

$$\beta_m^h = \star (f'(b_m^h), f'(a_{m+1}^h))$$

it follows that $\beta_j^i = -\beta_m^h$.

3. The Subdivision of a Normal Curve. The proposed relationship now follows.

THEOREM. *A normal curve f may be decomposed into a finite*

number of circuits; if $\phi_1, \dots, \phi_n$ is such a decomposition, and ω_i is the orientation number of ϕ_i , then the rotation number of f is $2\pi \sum_i \omega_i$, and the index with respect to f of a point P not on f is $\sum_i a_i \omega_i$, where a_i is 1 or 0 according as P is interior or exterior to ϕ_i .

PROOF. In virtue of the lemma and the proposition of Hopf, it remains only to consider the index of a point P not on f .

Using the notation of § 2, let $s_i, i = 0, 1, \dots, m$ be the points of s_f , and suppose that

$$s_0 < s_1 < \dots < s_m;$$

and let $\phi_i = f|_{B_i}$, so that each interval $[s_j, s_{j+1}]$ is a subset of exactly one of the sets B_i . Now the index of any point c of $\mathcal{P}$ which is not on f is the angle turned by the curve α divided by 2π , where

$$\alpha(t) = f(t) - c;$$

so if

$$\beta_j = \alpha|_{[s_j, s_{j+1}]}$$

then the index of c with respect to f is the sum of the angles turned by the curves β_j , again divided by 2π . On the other hand, the index of c with respect to ϕ_i is the angle turned by γ_i divided by 2π , where

$$\gamma_i(t) = \phi_i(t) - c.$$

The angle turned by γ_i is the sum of the angles turned by those β_j for which $[s_j, s_{j+1}] \subset B_i$. Therefore the index of c with respect to f is the sum of the indices of c with respect to the curves ϕ_i ; each of these, however, is ω_i or 0 according as c is interior or exterior to ϕ_i . Thus the latter part of the theorem is proved.

The University of Michigan.

(Oblatum 6-3-56).

REFERENCES.

H. HOPF,

- [1] Über die Drehung der Tangenten und Sehnen ebener Kurven. *Compositio Math.* 2 (1935), pp. 50—62.

H. WHITNEY,

- [2] On regular closed curves in the plane. *Compositio Math.* 4 (1937), pp. 276—284.