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Periodic solutions with prescribed energy for some Keplerian N -body problems ¹

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ABSTRACT. – We prove the existence of periodic solutions with prescribed energy for a class of N -body type problems with Keplerian like interaction.

Key words: Periodic solutions, N -body problems.

RÉSUMÉ. – Nous prouvons l'existence de solutions périodiques d'énergie prescrite pour une classe de problèmes à N corps avec interaction de type képlérien.

1. INTRODUCTION

In this paper we seek for periodic solutions of

$$\left. \begin{aligned} \ddot{x} + V'(x) &= 0, \\ \frac{1}{2}|\dot{x}|^2 + V(x) &= h, \end{aligned} \right\} \quad (1.1)$$

Classification A.M.S.: 58 E 05, 58 F 05.

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where $x = (x_1, \dots, x_N)$, $x_j \in \mathbf{R}^k$ and

$$V(x) = \frac{1}{2} \sum_{i \neq j} V_{ij}(x_i - x_j). \quad (1.2)$$

Roughly, we deal with potentials like

$$V_{ij}(\xi) \simeq -\frac{1}{|\xi|^\alpha}, \quad 0 < \alpha < 2. \quad (1.3)$$

When $V_{ij}(\xi)$ is as in (1.3) and $\alpha = 1$, (1.2) is the interaction potential of N -bodies of masses $m_1 = \dots = m_N = 1$, and (1.1) is nothing but the Kepler N -body problem.

Periodic solutions of (1.1) with $N = 2$ have been widely investigated. See [3] and references therein.

When $N > 2$, the problem is more difficult because the lack of compactness arises in a stronger form. The breakdown of the Palais-Smale condition has been bypassed either assuming $V_{ij}(\xi) = V_{ji}(\xi)$, (cf. [5]) or using critical point at infinity and Morse theory in [4, 9], or employing critical point theory with boundary condition in [7]. Using this latter tool, solutions with fixed energy have been found in [8] for a class of $V_{ij}(\xi) \simeq -|\xi|^{-\alpha}$, $\alpha > 2$ and $h > 0$. However this does not cover the Kepler N -body problem, where, among other things, the natural value of energy is negative. When $V_{ij}(\xi) = V_{ji}(\xi)$, $V_{ij}(\xi) \simeq -|\xi|^{-\alpha}$, $0 < \alpha < 2$ and $h < 0$, the existence of periodic solutions of (1.1) has been proved in [2], but no results dealing with the general case, are known. In the present paper we address this situation and prove the existence of (generalized) solutions of (1.1) for a class of Keplerian-like K -body problem.

The usual functional framework to study (1.1) is to look for critical points of the Maupertuis-like functional:

$$I(u) = \frac{1}{2} \|\dot{u}\|_{L^2}^2 \int_0^1 (h - V(u)) dt$$

defined on

$$\Lambda = \{u \in H^{1,2}(S^1, \mathbf{R}^{kN}); \\ u_i(t) \neq u_j(t) \text{ for all } t \in \mathbf{R} \text{ and } i \neq j\}.$$

Our approach consists of 4 steps:

1° In order to control the behavior of I on $\partial\Lambda$, we consider the perturbed potentials $V_\varepsilon = V - \frac{1}{2} \cdot \varepsilon \sum_{i \neq j} |u_i - u_j|^{-2}$ and the corresponding functional I_ε .

2° In contrast with [8], I_ε is not bounded from below on Λ , because $h < 0$. To bypass this difficulty we use a device like in [1]. Namely we consider the manifold

$$M = \{u \in \Lambda; \|\dot{u}\|_{L^2}^2 = 1\}$$

and a suitable, related functional $J_\varepsilon(u)$ (see section 3) which is bounded below on M and such that the critical points of $J_\varepsilon(u)$ constrained on M correspond to critical points of $I_\varepsilon(u)$.

3° We show that the arguments used in [7, 8] to overcome the lack of Palais-Smale condition can be adapted here to obtain approximate solutions $x^\varepsilon(t)$ of (1.1) with V_ε instead of V .

4° We show that $x^\varepsilon(t) \rightharpoonup x(t)$, a weak solution of (1.1) in the sense of [3]. See also Definition 3.1 below.

We point out that the regularity of weak solutions will not be studied here. For this kind of results, when $N = 2$ and $k \geq 3$, see [10].

2. MAIN RESULT

We assume that the potential $V(x) = \frac{1}{2} \sum_{i \neq j} V_{ij}(x_i - x_j)$ satisfies the following conditions:

(V1) $V_{ij} \in C^2(\mathbf{R}^k \setminus \{0\}, \mathbf{R})$, $V_{ij}(\xi) < 0$ for all $\xi \neq 0$;

(V2) $3V'_{ij}(\xi)\xi + V''_{ij}(\xi)\xi \cdot \xi \neq 0$ for all $\xi \neq 0$;

(V3) There exists an $\alpha \in (0, 2)$ such that

$$V'_{ij}(\xi)\xi \geq -\alpha V_{ij}(\xi) \quad \text{for all } \xi \neq 0;$$

(V4) There exist $\beta \in (0, 2)$ and $r_1 > 0$ such that

$$V'_{ij}(\xi)\xi \leq -\beta V_{ij}(\xi) \quad \text{for all } 0 < |\xi| \leq r_1;$$

(V5) $V_{ij}(\xi) + \frac{1}{2} V'_{ij}(\xi)\xi \rightarrow 0$ as $|\xi| \rightarrow \infty$;

(V6) There exist $\theta \in [0, \pi/2)$ and $r_2 > 0$ such that

$$\text{ang}(V'_{ij}(\xi), \xi) \leq \theta \quad \text{for all } |\xi| \geq r_2.$$

Here

$$\text{ang}(\xi, \eta) = \begin{cases} \arccos \frac{\xi \cdot \eta}{|\xi| |\eta|}, & \text{if } |\xi| |\eta| \neq 0, \\ 0, & \text{otherwise.} \end{cases}$$

Remark 2.1. – Without loss of generality, we can assume that

$$V_{ij}(\xi) = V_{ji}(-\xi).$$

Otherwise, consider $\bar{V}_{ij}(\xi) = \frac{1}{2}(V_{ij}(\xi) + V_{ji}(-\xi))$ instead of $V_{ij}(\xi)$.

Remark 2.2. – From (V1)-(V4), it follows that

- (i) $V'_{ij}(\xi)\xi > 0$ for all $\xi \neq 0$,
(ii) For some $a > 0$,

$$V_{ij}(\xi) \leq -\frac{a}{|\xi|^\alpha} \quad \text{for all } 0 < |\xi| \leq r_1, \quad (2.2)$$

$$(iii) V_{ij}(\xi) + \frac{1}{2}V'_{ij}(\xi)\xi \rightarrow -\infty \text{ as } |\xi| \rightarrow 0. \quad (2.3)$$

To state our result, we need to introduce the concept of weak periodic solutions of (1.1) as in Definition 10.1 of [3]. Roughly, it is a special class of generalized solutions which are found as limits of non-collision solutions of approximate problems. Since we need some notations to give a precise definition of weak solutions, we will give it in the next section.

Remark 2.3. – It is shown in [3] that every weak T -periodic solution $x(t)$ satisfies

- (i) $\text{meas } \mathcal{C}(x) = 0$, where

$$\mathcal{C}(x) = \{t \in \mathbf{R}; x_i(t) \neq x_j(t) \text{ for some } i \neq j\},$$

- (ii) $x(t) \in C^2(\mathbf{R} \setminus \mathcal{C}(x), \mathbf{R}^{kN})$,

- (iii) $x(t)$ satisfies (1.1) for all $t \in \mathbf{R} \setminus \mathcal{C}(x)$,

- (iv) $\int_0^T \left[\frac{1}{2}|\dot{x}|^2 - V(x(t)) \right] dt < \infty$.

In the sequel, a solution $x(t)$ will be called a *noncollision* solutions of (1.1) if $\mathcal{C}(x) = \emptyset$.

Now we can state our main result.

THEOREM 2.1. – Suppose that (V1)-(V6) hold. Then for all $h < 0$, the problem (1.1) has a weak periodic solution.

In the following sections, we will give a proof to Theorem 2.1.

3. VARIATIONAL FORMULATION

Throughout this paper, we use the following notation:

NOTATION:

$$\begin{aligned}
 H &= H^{1,2}(S^1, \mathbf{R}^k), \\
 [u] &= \int_0^1 u(t) dt \quad \text{for } u \in H, \\
 \|u\|_2^2 &= \int_0^1 |u|^2 dt \quad \text{for } u \in L^2(S^1, \mathbf{R}^{kN}), \\
 \|u\|^2 &= \int_0^1 |\dot{u}|^2 dt + |[u]|^2 = \sum_{i=1}^N \left(\int_0^1 |\dot{u}_i|^2 dt + |[u_i]|^2 \right) \\
 &\quad \text{for all } u = (u_1, \dots, u_N) \in H^N, \\
 E &= \left\{ u = (u_1, \dots, u_N) \in H^N; \sum_{i=1}^N [u_i] = 0 \right\}, \\
 \Lambda &= \{ u \in E; u_i(t) \neq u_j(t) \text{ for all } t \text{ and all } i \neq j \}, \\
 (u|v) &= \int_0^1 uv dt \quad \text{for } u, v \in L^2(S^1, \mathbf{R}^{kN}),
 \end{aligned}$$

$\langle f|u \rangle$ = the duality product of $f \in E^*$ and $u \in E$.

For a sequence $(u^n)_{n=1}^\infty \subset E$, we write

$$u^n \rightharpoonup u^0$$

to indicate that u^n converges to u^0 weakly in E and uniformly on $[0, 1]$.

We consider the following functional, $I : \Lambda \rightarrow \mathbf{R}$,

$$I(u) = \frac{1}{2} \|\dot{u}\|_2^2 \int_0^1 (h - V(u)) dt.$$

It is well-known that critical point of $I(u)$ on Λ , such that $I(u) > 0$, would give a rise – after a suitable time scaling – to a non-collision periodic solution of (1.1). However unfortunately, it is difficult to deal with $I(u)$ directly and we need to introduce a modified functional $I_\varepsilon(u)$ for $\varepsilon \in (0, 1]$, by setting

$$V_\varepsilon(x) = V(x) - \frac{\varepsilon}{2} \sum_{i \neq j} \frac{1}{|x_i - x_j|^2} \quad \text{for } x \in \mathbf{R}^{kN},$$

$$\begin{aligned}
 I_\varepsilon(u) &= \frac{1}{2} \|\dot{u}\|_2^2 \int_0^1 (h - V_\varepsilon(u)) dt \\
 &= I(u) + \frac{\varepsilon}{4} \|\dot{u}\|_2^2 \int_0^1 \sum_{i \neq j} \frac{1}{|u_i - u_j|^2} dt.
 \end{aligned}$$

The main different feature of V_ε is that: for every sequence $(u^n) \subset \Lambda$ such that $u^n \rightharpoonup u \in \partial\Lambda$, we have

$$\int_0^1 \sum_{i \neq j} \frac{1}{|u_i^n - u_j^n|^2} dy \rightarrow \infty, \quad (3.1)$$

that is, for $\varepsilon \in (0, 1]$

$$\int_0^1 -V_\varepsilon(u^n) dt \rightarrow \infty. \quad (3.2)$$

We remark here that if $v^\varepsilon \in \Lambda$ satisfies $I'_\varepsilon(v^\varepsilon) = 0$ and $I'_\varepsilon(v^\varepsilon) > 0$, then

$$x^\varepsilon(t) = v^\varepsilon(\omega_\varepsilon t), \quad \omega_\varepsilon = \frac{2\sqrt{I_\varepsilon(v^\varepsilon)}}{\|\dot{v}^\varepsilon\|_2^2} \quad (3.3)$$

is a periodic solution of the perturbed problem:

$$\left. \begin{aligned} \ddot{x} + V'_\varepsilon(x) &= 0, \\ \frac{1}{2}|\dot{x}|^2 + V_\varepsilon(x) &= h, \end{aligned} \right\} \quad (3.4)$$

Now we can give a precise definition of a weak periodic solution $x(t)$ of (1.1).

DEFINITION 3.1. – (cf. Definition 10.1 of [3]). $x(t)$ is said to be a *weak periodic solution* of (1.1) if there exist sequences $(v^n) \subset \Lambda$ and $\varepsilon_n \rightarrow 0$ such that

1° $v^n \in \Lambda$ is a critical point of I_{ε_n} such that $I_{\varepsilon_n}(v^n) > 0$, that is, if we set $x^n(t)$ as in (3.3), $x^n(t)$ is a periodic solution of (3.4).

2° There exists a constant $a > 0$ such that

$$0 < I_{\varepsilon_n}(v^n) \leq a < \infty.$$

3° $\omega_n \rightarrow \omega \neq 0$, $v^n \rightharpoonup v \in E$ and $x(t) = v(\omega t)$.

4° There exists a $t_0 \in (0, 1/\omega]$ such that

$$x_i(t_0) \neq x_j(t_0) \quad \text{for all } i \neq j.$$

As anticipated before, it has been proved in Theorem 10.7 of [3] that any weak periodic solution satisfies the properties (i)-(iv) of Remark 2.3.

Next we define for $u \in \Lambda$ with $\dot{u} \not\equiv 0$ a positive number $\rho = \rho(u) > 0$ by

$$\frac{d}{d\rho} I_\varepsilon(\rho u) = 0. \quad (3.5)$$

LEMMA 3.1. – For any $u \in \Lambda$ with $\dot{u} \not\equiv 0$, the equation (3.5) has a unique solution $\rho = \rho(u) > 0$, which is independent of $\varepsilon \in (0, 1]$ and satisfies

$$h = \int_0^1 \left[V(\rho u) + \frac{1}{2} V'(\rho u) \rho u \right] dt. \quad (3.6)$$

Proof. – For $u \in \Lambda$, a direct calculation gives us

$$\frac{d}{d\rho} I(\rho u) = \rho \|\dot{u}\|_2^2 \int_0^1 \left[h - V(\rho u) - \frac{1}{2} V'(\rho u) \rho u \right] dt.$$

Thus, for $u \in \Lambda$, with $\dot{u} \neq 0$, (3.5) is equivalent to (3.6). We set for $u \in \Lambda$, and $\rho > 0$

$$\phi_u(\rho) = \int_0^1 \left[V(\rho u) + \frac{1}{2} V'(\rho u) \rho u \right] dt.$$

From (V2), (V5) and (2.3), it follows

$$\phi'_u(\rho) > 0 \quad \text{for all } \rho \in (0, \infty), \quad (3.7)$$

$$\phi_u(\rho) \rightarrow -\infty \quad \text{as } \rho \rightarrow 0,$$

$$\phi_u(\rho) \rightarrow 0 \quad \text{as } \rho \rightarrow \infty.$$

Thus there is a unique $\rho = \rho(u) > 0$ such that $\phi_u(\rho) = h$ for all $u \in \Lambda$ and $h < 0$. ■

Remark 3.1. – In what follows, we define $\rho(u) > 0$ for all $u \in \Lambda$ by (3.6). We state some properties of $\rho(u)$.

LEMMA 3.2. – (i) $\rho(u) \in C^1(\Lambda, \mathbf{R})$;

(ii) If $u^n \rightharpoonup u \in \Lambda$, then $\rho(u^n) \rightarrow \rho(u)$;

(iii) For all $u \in \Lambda$,

$$\begin{aligned} \int_0^1 [h - V(\rho(u)u)] dt &= \frac{1}{2} \int_0^1 V'(\rho(u)u) \rho(u)u dt \\ &\geq \frac{1}{2} \left(\frac{1}{\alpha} - \frac{1}{2} \right)^{-1} (-h) \equiv C_0 > 0 \end{aligned} \quad (3.8)$$

Proof. – Properties (i) and (ii) easily follow from the implicit function theorem, using (3.6) and (3.7).

(iii) From (3.6) and (V3), we have

$$\begin{aligned} h &= \int_0^1 \left[V(\rho(u)u) + \frac{1}{2} V'(\rho(u)u) \rho(u)u \right] dt \\ &\leq -\left(\frac{1}{\alpha} - \frac{1}{2} \right) \int_0^1 V'(\rho(u)u) \rho(u)u dt, \end{aligned}$$

and (3.8) follows. ■

We set

$$M = \{ u \in \Lambda; \|\dot{u}\|_2^2 = 1 \}$$

and

$$\begin{aligned} J_\varepsilon(u) &= I_\varepsilon(\rho(u)u) \\ &= \frac{1}{2} \rho(u)^2 \int_0^1 [h - V_\varepsilon(\rho(u)u)] dt \\ &= \frac{1}{2} \rho(u)^2 \int_0^1 [h - V(\rho(u)u)] dt + \frac{\varepsilon}{4} \int_0^1 \sum_{i \neq j} \frac{1}{|u_i - u_j|^2} dt \\ &= \frac{1}{4} \rho(u)^2 \int_0^1 V'(\rho(u)u) \rho(u)u dt \\ &\quad + \frac{\varepsilon}{4} \int_0^1 \sum_{i \neq j} \frac{1}{|u_i - u_j|^2} dt. \end{aligned} \quad (3.9)$$

We remark that $\rho(u) > 0$ and (3.8) imply

$$J_\varepsilon(u) \geq \frac{C_0}{2} \rho(u)^2 > 0 \quad \text{on } M. \quad (3.10)$$

We also remark here that M is a submanifold of E of codimension 1 and

$$T_u M = \{ \varphi \in E; (\dot{u}|\dot{\varphi}) = 0 \},$$

$$(T_u M)^\perp = \text{span} \{ u - [u] \}.$$

In particular, all constant functions belong to $T_u M$ for all $u \in M$.

In what follows, for a functional $F(u) \in C^1(\Lambda, \mathbf{R})$, we denote by $F'(u)$ its gradient in Λ , and for $u \in M$ we denote by $\nabla_M F(u)$ its gradient constrained on M , i. e., $\nabla_M F(u) \in E^*$ is a vector satisfying

$$\langle \nabla_M F(u) | \varphi \rangle = \langle F'(u) | \varphi \rangle \quad \text{for all } \varphi \in T_u M,$$

$$\langle \nabla_M F(u) | \varphi \rangle = 0 \quad \text{for all } \varphi \in (T_u M)^\perp.$$

More precisely, it is given by

$$\langle \nabla_M F(u) | \varphi \rangle = \langle F'(u) | \varphi \rangle - \langle F'(u) | u - [u] \rangle (\dot{u} | \dot{\varphi}).$$

Here we state some properties of $I_\varepsilon(u)$ and $J_\varepsilon(u)$.

1° It follows from (3.5) that

$$\langle I'_\varepsilon(\rho(u)u) | u \rangle = 0 \quad \text{for all } u \in \Lambda. \quad (3.11)$$

2° For $u \in \Lambda$ and $\varphi \in E$,

$$\begin{aligned}\langle J'_\varepsilon(u)|\varphi\rangle &= \rho(u)\langle I'_\varepsilon(\rho(u)u)|\varphi\rangle + \langle I'_\varepsilon(\rho(u)u)|u\rangle\langle\rho'(u)|\varphi\rangle \\ &= \rho(u)\langle I'_\varepsilon(\rho(u)u)|\varphi\rangle,\end{aligned}$$

that is,

$$J'_\varepsilon(u) = \rho(u)I'_\varepsilon(\rho(u)u). \quad (3.12)$$

3° For $u \in E$, define $f_u \in E^*$ by

$$\langle f_u|\varphi\rangle = (\dot{u}|\dot{\varphi}).$$

Then $\nabla_M J_\varepsilon(u)$ can be written as

$$\begin{aligned}\nabla_M J_\varepsilon(u) &= J'(u) - \nu f_u \\ &= \rho(u)I'_\varepsilon(\rho(u)u) - \nu f_u\end{aligned} \quad (3.13)$$

with $\nu = \langle J'_\varepsilon(u)|u - [u]\rangle$.

4° Assume $\nabla_M J_\varepsilon(u) = 0$ for $u \in M$. By 1° and 3°, we have

$$\begin{aligned}0 &= \langle \nabla_M J_\varepsilon(u)|u\rangle \\ &= \rho(u)\langle I'_\varepsilon(\rho(u)u)|u\rangle - \nu = -\nu.\end{aligned}$$

Hence $I'_\varepsilon(\rho(u)u) = 0$.

Thus we have

LEMMA 3.3. – *Let $u^\varepsilon \in M$ be a critical point of J_ε on M , that is, $\nabla_M J_\varepsilon(u^\varepsilon) = 0$. Then*

- (i) $I'_\varepsilon(\rho_\varepsilon u^\varepsilon) = 0$, where $\rho_\varepsilon = \rho(u^\varepsilon)$.
- (ii) Set $\omega_\varepsilon^2 = 4I_\varepsilon(\rho_\varepsilon u^\varepsilon)/\rho_\varepsilon^4$ and $x^\varepsilon(t) = \rho_\varepsilon u^\varepsilon(\omega_\varepsilon t)$. Then $x^\varepsilon(t)$ is a noncollision solution of (3.4). ■

Remark 3.2. – Since $\rho_\varepsilon > 0$ and (3.10) holds, ω_ε is well-defined and $\omega_\varepsilon > 0$.

In the following sections, we shall find a critical point u^ε of J_ε on M .

4. A CRITICAL POINT LEMMA

It is known that $J_\varepsilon(u)$ does not satisfy the Palais-Smale condition on M (cf. [4, 7, 8]). To overcome this difficulty, we follow the procedure of [7, 8] (see also [6]). We set

$$g(u) = \sum_{i=1}^N |u_i - u_j|^2 \quad \text{for } u \in E,$$

$$M^b = \{u \in M; g(u) \leq b\}.$$

The following is nothing but Lemma 2.1 of [8] in our setting.

LEMMA 4.1. – Assume that there are constants c and $\tilde{c}$ with $c < \tilde{c}$ and $b \in \mathbf{R}$ such that

(H1) If $(u^n) \subset M$ satisfies $u^n \rightharpoonup u^0 \in \partial\Lambda$ and $g(u^n)$ is bounded, then

$$J_\varepsilon(u^n) \rightarrow \infty.$$

(H2) $\nabla_M g(u) \neq 0$ for all $g(u) = b$, $J_\varepsilon(u) = c$.

(H3) If $(u^n) \subset M$ satisfies $J_\varepsilon(u^n) \rightarrow c$, $\limsup g(u^n) \leq b$ and $\nabla_M J_\varepsilon(u^n) \rightarrow 0$, then (u^n) possesses a convergent subsequence.

(H4) If $(u^n) \subset M$ satisfies $J_\varepsilon(u^n) \rightarrow c$, $g(u^n) \rightarrow b$ and

$$\nabla_M J_\varepsilon(u^n) - \lambda_n \nabla_M g(u^n) \rightarrow 0$$

for some $\lambda_n \geq 0$, then (u^n) possesses a convergent subsequence.

(H5) $\nabla_M J_\varepsilon(u) \neq \lambda \nabla_M g(u)$ for all $u \in M$ with $J_\varepsilon(u) = c$, $g(u) = b$ and for all $\lambda > 0$.

(H6) For any $\delta > 0$ with $c + \delta < \tilde{c}$, the set

$$\{u \in M; J_\varepsilon(u) \leq c + \delta\} \cup (\{u \in M; J_\varepsilon(u) \leq \tilde{c}\} \cap \{u \in M; g(u) \geq b\})$$

is not deformable in M into

$$\{u \in M; J_\varepsilon(u) \leq c - \delta\} \cup (\{u \in M; J_\varepsilon(u) \leq \tilde{c}\} \cap \{u \in M; g(u) \geq b\}).$$

Then $J_\varepsilon(u)$ has a least one critical point $u \in M$ such that $J_\varepsilon(u) = c$ and $g(u) \leq b$. ■

We are going to verify the conditions (H1)-(H6) for suitable c , $\tilde{c}$, $b > 0$. First of all, we remark by (3.1) and (3.9) that if $u^n \rightharpoonup u^0 \in \partial\Lambda$ then

$$J_\varepsilon(u^n) \geq \frac{\varepsilon}{4} \int_0^1 \sum_{i \neq j} \frac{1}{|u_i - u_j|^2} dt \rightarrow \infty. \quad (4.1)$$

Therefore (H1) holds. Moreover, since

$$\langle \nabla_M g(u) | [u] \rangle = 2g(u) = 2b \neq 0 \quad \text{and} \quad [u] \in T_u M$$

for all $g(u) = b > 0$,

$$\nabla_M g(u) \neq 0 \quad \text{for all } g(u) = b > 0.$$

That is, (H2) holds for all $b > 0$ and $\tilde{c} \in \mathbf{R}$.

In Section 5, we verify (H3) and (H4) which are local versions of Palais-Smale condition, and in Section 6 we will get (H5) and (H6).

5. PALAIS-SMALE CONDITION

To verify (H3), (H4), some lemmas are in order. First we need some properties of $\rho(u)$.

LEMMA 5.1. – *For $c > 0$, there are $k_1 = k_1(c) > 0$ and $k_2 = k_2(c) > 0$ independent of $\varepsilon \in (0, 1]$ such that for $u \in M$*

$$(i) \ J_\varepsilon(u) \leq c \text{ implies } \rho(u) \leq k_1(c),$$

$$(ii) \ J_\varepsilon(u) \geq c \text{ implies } \rho(u) \geq k_2(c).$$

Proof. – (i) follows from (3.10) easily. We prove (ii) here. We argue indirectly and assume there are sequences $(u^n) \subset M$ and $(\varepsilon_n) \subset (0, 1]$ such that

$$J_{\varepsilon_n}(u^n) \geq c \quad \text{and} \quad \rho_n \equiv \rho(u^n) \rightarrow 0.$$

We set $w^n = \rho_n u^n$. Since $\rho^n \rightarrow 0$ and

$$c \leq J_{\varepsilon_n}(u^n) = \frac{1}{2} \rho_n^2 \int_0^1 \left[h - V(w^n) + \frac{\varepsilon_n}{4} \sum_{i \neq j} \frac{1}{|w_i^n - w_j^n|^2} \right] dt,$$

it follows

$$\int_0^1 \left[h - V(w^n) + \frac{\varepsilon_n}{4} \sum_{i \neq j} \frac{1}{|w_i^n - w_j^n|^2} \right] dt \rightarrow \infty.$$

In particular, for some $i \neq j$, one has

$$\min_{t \in [0, 1]} |w_i^n(t) - w_j^n(t)| \rightarrow 0.$$

On the other hand, $\|\dot{w}^n\|_2 = \rho_n \rightarrow 0$ and hence

$$\max_{t \in [0, 1]} |w_i^n(t) - w_j^n(t)| \rightarrow 0.$$

Then $w_i^n - w_j^n \rightarrow 0$ uniformly in $[0, 1]$ and therefore, by (3.6) and (2.3)

$$h = \int_0^1 \left[V(w^n) + \frac{1}{2} V'(w^n) w^n \right] dt \rightarrow -\infty.$$

This is a contradiction. ■

Recall that $\sum_{i=1}^N [u_i] = 0$ for $u \in E$. Therefore M^b is a bounded set of E for all b . Thus using also (4.1), we infer

LEMMA 5.2. – For $\varepsilon \in (0, 1]$, suppose $(u^n) \subset M$ satisfies for $b > 0, c > 0$

(i) $u^n \in M^b$, i. e., $g(u^n) \leq b$,

(ii) $J_{\varepsilon_n}(u^n) \leq c$.

Then (u^n) has a subsequence – still denoted by u^n – such that

$$u^n \rightharpoonup u^0 \in \Lambda. \quad \blacksquare$$

Next we prove (H3) and (H4).

LEMMA 5.3. – Suppose $\varepsilon \in (0, 1]$. Then

(i) (H3) holds for all $b > 0$ and $c > 0$,

(ii) (H4) holds for all $b > 0$ and $c > 0$.

Proof. – (i) We assume

$$u^n \in M^b,$$

$$J_{\varepsilon}(u^n) \rightarrow c > 0,$$

$$\nabla_M J_{\varepsilon}(u^n) \rightarrow 0 \quad \text{strongly in } E^*.$$

Our goal is to prove there is a strongly convergent subsequence of (u^n) such that $u^n \rightarrow u^0 \in M$. By Lemma 5.2, (u^n) possesses a weakly convergent subsequence $u^n \rightharpoonup u^0 \in \Lambda$. Thus it suffices to show the convergence is strong, that is, $\|\dot{u}^n\|_2 \rightarrow \|\dot{u}^0\|_2$, i. e., $\|\dot{u}^0\|_2 = 1$.

First, by Lemma 5.1, we remark that

$$\rho_n \equiv \rho(u^n) \in [k_1, k_2],$$

where $k_1, k_2 > 0$ are independent of n and hence $\rho_n \rightarrow \rho_0 = \rho(u^0) \neq 0$.

Since $\nabla_M J_{\varepsilon}(u^n) \rightarrow 0$, by (3.13) there exists a sequence $(\nu_n) \subset \mathbf{R}$ such that

$$\rho_n I'_{\varepsilon}(\rho_n u^n) - \nu_n f_{u^n} \rightarrow 0 \quad \text{strongly in } E^*.$$

Taking a scalar product with u^n , we infer $\nu_n \rightarrow 0$ by (3.11). Thus,

$$I'_{\varepsilon}(\rho_n u^n) \rightarrow 0 \quad \text{strongly in } E^*.$$

In particular, we have $\langle I'_\varepsilon(\rho_n u^n) | u^0 \rangle \rightarrow 0$, *i. e.*,

$$\rho_n (\dot{u}^n | \dot{u}^0) \int_0^1 [h - V_\varepsilon(\rho_n u^n)] dt - \frac{1}{2} \rho_n^2 \int_0^1 V'_\varepsilon(\rho_n u^n) u^0 dt \rightarrow 0.$$

Then

$$\rho_0 \|\dot{u}^0\|_2^2 \int_0^1 [h - V_\varepsilon(\rho_0 u^0)] dt - \frac{1}{2} \rho_0^2 \int_0^1 V'_\varepsilon(\rho_0 u^0) u^0 dt = 0. \quad (5.1)$$

On the other hand, by (3.11), $\langle I'_\varepsilon(\rho_n u^n) | u^n \rangle = 0$, *i. e.*,

$$\rho_n \int_0^1 [h - V_\varepsilon(\rho_n u^n)] dt - \frac{1}{2} \rho_n^2 \int_0^1 V'_\varepsilon(\rho_n u^n) u^0 dt = 0.$$

Taking a limit as $n \rightarrow \infty$, we have

$$\rho_0 \int_0^1 [h - V_\varepsilon(\rho_0 u^0)] dt - \frac{1}{2} \rho_0^2 \int_0^1 V'_\varepsilon(\rho_0 u^0) u^0 dt = 0. \quad (5.2)$$

Comparing (5.1) and (5.2) and recalling (3.8), we have $\|\dot{u}^0\|_2 = 1$, *i. e.*, $u^n \rightarrow u^0 \in \Lambda$ strongly in E .

(ii) Next we assume $(u^n) \subset M$ satisfies

$$g(u^n) \rightarrow b > 0, \quad (5.3)$$

$$J_\varepsilon(u^n) \rightarrow c > 0, \quad (5.4)$$

$$\nabla_M J_\varepsilon(u^n) - \mu_n \nabla_M g(u^n) \rightarrow 0, \quad (5.5)$$

with $\mu_n \geq 0$.

By Lemma 5.2, we may assume $u^n \rightarrow u^0 \in \Lambda$ and again it suffices to show $\|\dot{u}^0\|_2 = 1$. Again we note that

$$\rho_n \rightarrow \rho_0 \neq 0.$$

By the definition of ∇_M and (5.5), there exists $(\nu_n) \subset \mathbf{R}$ such that

$$\rho_n I'_\varepsilon(\rho_n u^n) - \mu_n g'(u^n) + \nu_n f_{u^n} \rightarrow 0 \quad \text{strongly in } E^*. \quad (5.6)$$

Taking a product of (5.6) and u^n , we get from (3.11)

$$-\mu_n \langle g'(u^n) | u^n \rangle + \nu_n \langle f_{u^n} | u^n \rangle \rightarrow 0,$$

i. e.,

$$-2\mu_n g(u^n) + \nu_n \rightarrow 0. \quad (5.7)$$

Taking a product of (5.6) and $[u^n]$, we also get

$$\rho_n \langle I'_\varepsilon(\rho_n u^n) | [u^n] \rangle - 2\mu_n g(u^n) \rightarrow 0. \quad (5.8)$$

Since $\rho_n u^n \rightharpoonup \rho_0 u^0 \in \Lambda$ uniformly in $[0, 1]$ and weakly in E , we can see $\langle I'_\varepsilon(\rho_n u^n) | [u^n] \rangle$ stays bounded as $n \rightarrow \infty$. Thus by (5.3), (5.7), (5.8), μ_n and ν_n stay bounded as $n \rightarrow \infty$. Therefore we may assume $\mu = \lim_{n \rightarrow \infty} \mu_n$ and $\nu = \lim_{n \rightarrow \infty} \nu_n$ exist. Here we remark

$$\nu = \lim_{n \rightarrow \infty} \nu_n = 2b \lim_{n \rightarrow \infty} \mu_n \geq 0. \quad (5.9)$$

As in the proof of (i), we take scalar products of (5.6) and u^n (resp. u^0) and take limits as $n \rightarrow \infty$. Then we have

$$\rho_0^2 \int_0^1 [h - V_\varepsilon(\rho_0 u^0)] dt - \rho_0^3 \int_0^1 V'_\varepsilon(\rho_0 u^0) u^0 dt - 2b\mu + \nu = 0$$

and

$$\begin{aligned} & \rho_0^2 \|\dot{u}^0\|_2^2 \int_0^1 [h - V_\varepsilon(\rho_0 u^0)] dt - \rho_0^3 \\ & \times \int_0^1 V'_\varepsilon(\rho_0 u^0) u^0 dt - 2b\mu + \nu \|\dot{u}^0\|_2^2 = 0. \end{aligned}$$

Recalling (3.8) and (5.9), we get $\|\dot{u}^0\|_2 = 1$. ■

6. SOLUTIONS OF (3.4)

Next we deal with (H5) and (H6). The arguments of the proofs are similar to those of [8].

LEMMA 6.1. – *For any $0 < c_1 < c_2$ there exists $B_0 = B_0(c_1, c_2) > 0$ independent of $\varepsilon \in (0, 1]$ such that*

$$\nabla_M J_\varepsilon(u^n) \neq \lambda \nabla_M g(u)$$

for all $\lambda > 0$ and $u \in M$ with $J_\varepsilon(u) \in [c_1, c_2]$, $g(u) \geq B_0$.

Proof. – Arguing indirectly, we assume that there exist $(\varepsilon_n) \subset (0, 1]$, $(u^n) \subset M$ and $(\lambda_n) \subset (0, \infty)$ such that

$$\nabla_M J_{\varepsilon_n}(u^n) = \lambda_n \nabla_M g(u^n), \quad (6.1)$$

$$J_{\varepsilon_n}(u^n) \in [c_1, c_2], \quad (6.2)$$

$$g(u^n) \rightarrow \infty. \quad (6.3)$$

We set $z^n = g(u^n)^{-1/2} [u^n]$. Clearly (z^n) is a bounded sequence and we may assume $z^0 = \lim_{n \rightarrow \infty} z^n$ exists. We remark $g(z^0) = 1$ and $z^0 \in T_{u^n} M$ for all n . We will show

$$\langle \nabla_M J_{\varepsilon_n}(u^n) | z^0 \rangle \leq 0, \quad (6.4)$$

$$\langle \nabla_M g(u^n) | z^0 \rangle > 0, \quad (6.5)$$

for large n . Clearly they are incompatible with (6.1) and $\lambda_n > 0$. By (6.2) and Lemma 5.1, we have

$$\rho_n \equiv \rho(u^n) \in [k_1(c_1), k_2(c_2)].$$

Note that if $z_i^0 \neq z_j^0$, then $|[u_i^n] - [u_j^n]| \rightarrow \infty$. For such $i \neq j$, we have from (6.3)

$$\begin{aligned} |\rho_n(u_i^n(t) - u_j^n(t))| &\geq \rho_n|[u_i^n] - [u_j^n]| - 2\rho_n\|\dot{u}^n\|_2 \\ &\geq k_1(c_1)|[u_i^n] - [u_j^n]| - k_2(c_2) \\ &\rightarrow \infty \quad \text{as } n \rightarrow \infty, \end{aligned} \quad (6.6)$$

$$\begin{aligned} &|g(u^n)^{-1/2} \rho_n(u_i^n(t) - u_j^n(t)) - \rho_n(z_i^0 - z_j^0)| \\ &\leq k_2(c_2)g(u^n)^{-1/2}\|\dot{u}^n\|_2 + 2k_2(c_2)|z^n - z^0| \rightarrow 0 \end{aligned} \quad (6.7)$$

as $n \rightarrow \infty$ uniformly in t .

Thus from (6.6)-(6.7), we can see

$$\text{ang}(\rho_n(u_i^n(t) - u_j^n(t)), z_i^0 - z_j^0) \rightarrow 0,$$

$$\min_{t \in [0, 1]} |\rho_n(u_i^n(t) - u_j^n(t))| \rightarrow \infty$$

as $n \rightarrow \infty$ uniformly in t . Thus by (V6)

$$\begin{aligned} \langle \nabla_M J_{\varepsilon_n}(u^n) | z \rangle &= \rho_n \langle I'_\varepsilon(\rho_n u^n) | z \rangle \\ &= -\frac{1}{2} \rho_n^2 \int_0^1 \left[\sum_{i \neq j} V_{ij}(\rho_n(u_i^n - u_j^n))(z_i^0 - z_j^0) \right. \\ &\quad \left. + \frac{\varepsilon_n}{4} \sum_{i \neq j} \frac{(u_i^n - u_j^n)(z_i^0 - z_j^0)}{|u_i^n - u_j^n|^4} \right] dt \\ &< 0 \end{aligned}$$

for large n . Thus we get (6.4). On the other hand,

$$\langle \nabla_M g(u^n) | z^0 \rangle = g(u^n)^{1/2} \langle g'(z^n) | z^0 \rangle \rightarrow \infty.$$

Therefore we get (6.5). Thus (6.1) cannot take place. ■

As in [7, 8], we define admissible sets. Let $\mathcal{H}$ be the set of deformations of Λ in E into the space of constant functions $\mathbf{R}^{kN}$;

$$\mathcal{H} = \{ \eta \in C([0, 1] \times \Lambda, E); \eta(0, \cdot) = \text{id}, \eta(1, \Lambda) \subset \mathbf{R}^{kN} \}.$$

We also use the notation, for $i \neq j$,

$$\Gamma_{ij} = \{ u \in E; u_i(t) = u_j(t) \text{ for some } t \}.$$

DEFINITION 6.1. – Let A be a closed subset of Λ . We say A is *admissible* if for any $\eta \in \mathcal{H}$ there exists $u \in A$ such that for any $i \neq j$ there exists a sequence $i_1, \dots, i_m \in \{1, \dots, N\}$ satisfying

$$1^\circ i_1 = i, i_m = j;$$

$$2^\circ i_k \neq i_{k+1} \text{ for all } k = 1, \dots, m-1;$$

$$3^\circ \eta([0, 1] \times \{u\}) \cap \Gamma_{i_k i_{k+1}} \neq \emptyset \text{ for all } k = 1, \dots, m-1.$$

We denote by $\mathcal{A}$ the class of admissible sets.

It is shown in [7, 8] that there is a compact admissible set, which does not contain constant functions, and

(A1) If $A \subset B$ and $A \in \mathcal{A}$, then $B \in \mathcal{A}$,

(A2) If B is a deformation of $A \in \mathcal{A}$ in Λ , then $B \in \mathcal{A}$.

We set

$$\mathcal{A}_M = \{ A \subset M; A \in \mathcal{A} \}.$$

Plainly $\mathcal{A}_M \neq \emptyset$, indeed it contains any radial projection on M of $A \in \mathcal{A}$ with $A \cap \{u \in \Lambda; \dot{u} \equiv 0\} = \emptyset$.

The following property is important for our argument.

LEMMA 6.2. – *There exists $B_1 > 0$ such that*

$$\{u \in M; g(u) \geq B_1\} \notin \mathcal{A}_M.$$

Proof. – It suffices to show for any $A \in \mathcal{A}_M$ there exists $u \in A$ such that $g(u) \leq 2N(N-1)^3$.

Let $\eta_0 \in \mathcal{H}$ be a deformation such that

$$\eta_0(s, u) = [u] + (1-s)(u - [u]).$$

By the definition of admissible sets, there is a $u \in A$ such that for any $i \neq j$ there exists a sequence $i_1, \dots, i_m$ satisfying the properties 1°-3° of Definition 6.1. We remark that we may assume $m \leq N$.

By 3° of Definition 6.1, $\eta_0([0, 1] \times \{u\}) \cap \Gamma_{i_k i_{k+1}} \neq \emptyset$ for all $k = 1, \dots, m-1$. Thus for some $s_k \in [0, 1]$ and t_k , we have

$$[u_{i_k} - u_{i_{k+1}}] + (1 - s_k)(u_{i_k}(t_k) - u_{i_{k+1}}(t_k) - [u_{i_k} - u_{i_{k+1}}]) = 0.$$

Thus

$$|[u_{i_k} - u_{i_{k+1}}]| \leq (1 - s_k) \|\dot{u}_{i_k} - \dot{u}_{i_{k+1}}\|_2 \leq \sqrt{2}.$$

Therefore

$$|[u_i - u_j]| \leq \sum_{k=1}^{m-1} |[u_{i_k} - u_{i_{k+1}}]| \leq \sqrt{2}(N-1).$$

Since the pair (i, j) with $i \neq j$ is arbitrary, we have

$$g(u) = \sum_{i \neq j} |[u_i - u_j]|^2 \leq 2N(N-1)^3.$$

We also have

LEMMA 6.3. – *For any given $b' > 0$ there is a $\gamma = \gamma(b') > 0$ independent of $\varepsilon \in (0, 1]$ such that*

$$\{u \in M; J_\varepsilon(u) \leq \gamma\} \subset \{u \in M; g(u) \geq b'\}.$$

Proof. – We argue indirectly and assume there are sequences $(u^n) \subset M$ and $(\varepsilon_n) \subset (0, 1]$ such that

$$J_{\varepsilon_n}(u^n) \rightarrow 0,$$

$$g(u^n) \leq b'.$$

By (3.10), we have

$$\rho_n \equiv \rho(u^n) \rightarrow 0.$$

Since $M^{b'}$ is bounded in E , we can see

$$\rho_n u^n \rightarrow 0 \text{ strongly in } E.$$

But this is incompatible with (3.6) and (2.3). ■

COROLLARY 6.4. – *Let $B_1 > 0$ be a number given in Lemma 6.2. Then*

$$\{u \in M; J_\varepsilon(u) \leq \gamma(B_1)\} \cup \{u \in M; g(u) \geq B_1\} = \{u \in M; g(u) \geq B_1\}.$$

Now we define minimax values c_ε^* by

$$c_\varepsilon^* = \inf_{A \in \mathcal{A}_M} \sup_{u \in A} J_\varepsilon(u).$$

By the definition of c_ε^* , it is clear from (A1)-(A2) that for any $\delta > 0$

$$\{u \in M; J_\varepsilon(u) \leq C_\varepsilon^* + \delta\} \in \mathcal{A}_M. \quad (6.8)$$

Thus we see from Corollary 6.4 that

$$\gamma(B_1) \leq c_\varepsilon^* + \delta.$$

Fix $C^* > c_1^*$ and let $B_2 = B_0(\gamma(B_1), C^*)$ [let $B_0(\cdot, \cdot)$ be given in Lemma 6.1] and set

$$d = \max\{B_1, B_2\}.$$

LEMMA 6.5. – $J_\varepsilon|_M$ has a critical point u^ε such that

- (i) $J_\varepsilon(u^\varepsilon) \in [\gamma(B_1), C^*]$,
- (ii) $u^\varepsilon \in M^d$.

Proof. – Set

$$\begin{aligned} c_\varepsilon = \inf \{ & c \in \mathbf{R}; \{u \in M; J_\varepsilon(u) \leq c\} \\ & \cup \{u \in M; g(u) \geq d\} \in \mathcal{A}_M \}. \end{aligned}$$

Then clearly

$$c_\varepsilon \leq c_\varepsilon^* < C^* \quad \text{for all } \varepsilon \in (0, 1].$$

From Corollary 6.4 it follows

$$\begin{aligned} & \{u \in M; J_\varepsilon(u) \leq \gamma(B_1)\} \cup \{u \in M; g(u) \geq d\} \\ & \subset \{u \in M; g(u) \leq B_1\} \cup \{u \in M; g(u) \geq d\} \\ & = \{u \in M; g(u) \geq d\}. \end{aligned}$$

Since $\{u \in M; g(u) \geq d\} \notin \mathcal{A}_M$, (A1) yields

$$\{u \in M; J_\varepsilon(u) \leq \gamma(B_1)\} \cup \{u \in M; g(u) \geq d\} \notin \mathcal{A}_M.$$

Thus we have

$$\gamma(B_1) < c_\varepsilon \quad \text{for all } \varepsilon \in (0, 1].$$

Now it is easy to see all assumptions (H1)-(H6) of Lemma 4.1 are satisfied with $c = c_\varepsilon$, $\tilde{c} = C^*$ and $b = d$. ■

7. LIMITING PROCESS

In previous sections, we have shown that for any $\varepsilon \in (0, 1]$ there exists a critical point u^ε such that

$$\nabla_M J_\varepsilon(u^\varepsilon) = 0,$$

$$J_\varepsilon(u^\varepsilon) = c_\varepsilon,$$

$$u^\varepsilon \in M^d.$$

We set

$$\rho_\varepsilon \equiv \rho(u^\varepsilon)$$

$$v^\varepsilon(t) = \rho_\varepsilon u^\varepsilon(t),$$

$$\omega_\varepsilon^2 = \frac{\int_0^1 [h - V_\varepsilon(v^\varepsilon)] dt}{\frac{1}{2} \rho_\varepsilon^2} = \frac{J_\varepsilon(u^\varepsilon)}{\frac{1}{4} \rho_\varepsilon^4}$$

From the arguments of Sections 5 and 6 one deduces:

$$c_\varepsilon \in [\gamma(B_1), C^*] \quad (7.1)$$

$$\rho(u^\varepsilon) \in [k_1(\gamma(B_1)), k_2(C^*)], \quad (7.2)$$

$$\omega_\varepsilon^2 \in \left[\frac{4\gamma(B_1)}{k_2(C^*)^4}, \frac{C^*}{k_1(\gamma(B_1))^4} \right]. \quad (7.3)$$

Since $u^\varepsilon \in M^d$ and M^d is a bounded subset of E , then, up to a subsequence,

$$u^\varepsilon \rightharpoonup u. \quad (7.4)$$

Moreover, by (7.2), it follows that

$$\rho_\varepsilon \rightarrow \rho \neq 0, \quad (7.5)$$

while, by (7.3), $\omega_\varepsilon \rightarrow \omega$. We set

$$x(t) = \rho u(\omega t).$$

LEMMA 7.1. – *There exists a $t_0 \in (0, 1]$ such that*

$$x_i(t_0) \neq x_j(t_0) \quad \text{for all } i \neq j. \quad (7.6)$$

Proof. – By (7.4) and (7.5), $v^\varepsilon \rightharpoonup v := \rho u$. Since

$$J_\varepsilon(u^\varepsilon) = \frac{1}{2} \rho_\varepsilon^2 \int_0^1 [h - V_\varepsilon(z^\varepsilon)] dt,$$

we have by (7.1) and (7.2)

$$\int_0^1 [h - V_\varepsilon(v^\varepsilon)] dt = \frac{2J_\varepsilon(u^\varepsilon)}{\rho_\varepsilon^2} \in \left[\frac{2\gamma(B_1)}{k_2(C^*)^2}, \frac{2C^*}{k_1(\gamma(B_1))^2} \right]$$

for all $\varepsilon \in (0, 1]$. It is easy to see that, *via* the Fatou's Lemma, this implies the existence of $t_0 \in (0, 1]$ satisfying (7.6). ■

Proof of Theorem 2.1 completed. – It suffices to note that $v_\varepsilon \rightharpoonup v$, $v = \rho u$ and properties 1°-3° of Definition 3.1 are satisfied, while, property 4° is nothing but Lemma 7.1. ■

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