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NEW COUNTEREXAMPLES TO STRICHARTZ ESTIMATES FOR THE WAVE EQUATION ON A 2D MODEL CONVEX DOMAIN

BY OANA IVANOVICI, GILLES LEBEAU & FABRICE PLANCHON

ABSTRACT . — We prove that the range of Strichartz estimates on a model 2D convex domain may be further restricted compared to the known counterexamples from [3, 4]. Our new family of counterexamples is built on the parametrix construction from [7] and revisited in [8]. Interestingly enough, it is sharp in at least some regions of phase space.

RÉSUMÉ (Nouveaux contre-exemples aux estimations de Strichartz pour l'équation des ondes dans un domaine convexe modèle bidimensionnel)

Nous démontrons que le domaine de validité des estimations de Strichartz sur un domaine convexe modèle bidimensionnel peut être encore restreint par rapport aux contre-exemples déjà connus [3, 4]. Notre nouvelle famille de contre-exemples s'appuie sur la construction de parametrix élaborée dans [7] et revisitée dans [8]. Cette construction est en sus optimale dans certaines régions de l'espace des phases.

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1. INTRODUCTION AND MAIN RESULTS

Let us consider the wave equation on a domain Ω with boundary \mathcal{A} ,

$$(1) \quad \begin{cases} \partial_t^2 u - \Delta u = 0; & x \in \Omega \\ u|_{t=0} = u_0; & \partial_t u|_{t=0} = u_1; \\ Bu = 0; & x \in \mathcal{A}; \end{cases}$$

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Here, Δ stands for the Laplace-Beltrami operator on Ω , the boundary condition could be either Dirichlet ($u|_{\partial\Omega} = 0$) or Neumann ($B = \partial$, where ν is the unit normal to the boundary.) We will take $B = \text{Id}$ but the argument may be adapted to Neumann.

The so called Strichartz estimates aim at quantifying dispersive properties of the solutions to this linear wave equation: for given data in the natural energy space, the solution will have better decay for suitable time averages. This is of value for several applications, of which we quote only two:

- nonlinear problems, where Strichartz may be used as a tool to improve on Sobolev embeddings and allow for better nonlinear mapping properties of solutions;
- localization properties of (clusters of) eigenfunctions of the Laplacian (through square function estimates for the wave equation which are closely related to Strichartz estimates).

On any compact Riemannian manifold with empty boundary, the solution to (1) is such that, at least for a suitable $\delta < 1$, for all $h < 1$,

$$(2) \quad \|h^{-k} (hD_t) u\|_{L^q([t_0; t_0+h])L^r} \leq C (\|u(0; x)\|_{L^2} + \|hD_t u\|_{L^2});$$

where $\chi \in C_0^\infty$ is a smooth truncation in a neighborhood of t . Let d be the spatial dimension of Ω , then rescaling dictates that $d(1-2\delta) = 1-r$ where $(q; r)$ is a so-called admissible pair:

$$(3) \quad \frac{1}{q} \leq \frac{(d-1)}{2} \frac{1}{2} \frac{1}{r}; \quad q > 2;$$

On non compact manifolds, one would have to assume suitable geometric assumptions to allow these estimates to hold globally: when (2) holds for $\delta < 1$, it is said to be a global in time Strichartz estimate. For \mathbb{R}^d with flat metric, the solution $u_{\mathbb{R}^d}(t; x)$ to (1) with initial data $(u_0 = \phi_{x_0}; u_1 = 0)$ has an explicit representation formula

$$u_{\mathbb{R}^d}(t; x) = \frac{1}{(2)^d} \int_{\mathbb{S}^{d-1}} \cos(tj \cdot \nu) e^{i(x \cdot x_0 + t \nu \cdot x)} d\nu$$

and by usual stationary phase methods one gets dispersion:

$$(4) \quad \|h^{-k} (hD_t) u_{\mathbb{R}^d}(t; \cdot)\|_{L^r(\mathbb{R}^d)} \leq C(d) h^{-d} \min\{1, (h-t)^{(d-1)/2}\};$$

Interpolation between (4) and energy estimates, together with a duality argument, routinely provides (2) ([14], [11], [2]). On any (compact) Riemannian manifold without boundary $(\Omega; g)$ one may follow the same path, replacing the exact formula by a parametrix, which may be constructed locally (in time and space) within a small ball, thanks to finite speed of propagation ([9], [10]). By routine computations, one may deduce from the semi-classical estimate (2) standard estimates involving mixed Lebesgue-Besov norms on the left-hand side and Sobolev spaces on the right-hand side; these are better suited to dealing with nonlinear problems.

On a manifold with boundary, the geometry of light rays becomes much more complicated, and one may no longer think that one is slightly bending flat trajectories. There may be gliding rays (along a convex boundary) or grazing rays (tangential to a

convex obstacle) or combinations of both. Strichartz estimates outside a strictly convex obstacle were obtained in [12] and turned out to be similar to the free case (see [6] for the more complicated case of the dispersion). Strichartz estimates with losses were obtained later on general domains, [1], using short time parametrices constructions from [13], which in turn were inspired by works on low regularity metrics [15]. Most of these works focus either on compact domains with boundary or exterior domains, although one may combine existing results to deal with unbounded domains with suitable control over geometry at infinity.

In our work [7], a parametrix for the wave equation inside a model of strictly convex domain was constructed that provided optimal decay estimates, uniformly with respect to the distance of the source to the boundary, over a time length of constant size. This involves dealing with an arbitrarily large number of caustics and retain control of their order. Our dispersion estimate from [7] is optimal and immediately yields by the usual argument Strichartz estimates with a range of (q, r) such that

$$\frac{1}{q} \leq \frac{(d-1)}{2} \frac{1}{4} \frac{1}{2} \frac{1}{r} ; \quad q > 2;$$

where, informally, the new factor, when compared to (3), is related to the loss in the dispersion estimate from [7], when compared to (4). On the other hand, earlier works [3, 4] proved that Strichartz estimates on strictly convex domains can hold only if, where $r > 4$, $(1/q, 1/r)$ are below a line connecting the pair $(1/q, 1/r)$ (from free space) and $(1/q, 0)$ such that

$$\frac{1}{q_1} = \frac{(d-1)}{2} \frac{1}{2} \frac{1}{4} \quad \text{and} \quad \frac{1}{q_1} = \frac{(d-1)}{2} \frac{1}{12} \frac{1}{2}.$$

We will restate the exact result later on as we provide a simplified proof for it. Our main purpose in the present work is to improve upon the negative results in dimension $d = 2$; improvements on the positive side were obtained in [8]. In particular, for suitable microlocalized solutions we close the gap between known estimates and known counterexamples, providing a near complete picture in a specific location in phase space. Before stating our main results, we start by describing our convex model domain. Our Friedlander model is the half-space $\Omega_d = \{(x, y) \mid x > 0; y \in \mathbb{R}^{d-1}\}$ with the metric g_F inherited from the following Laplace operator $\Delta_F = \partial_x^2 + (1+x)\Delta_{\mathbb{R}^{d-1}}$, with Dirichlet boundary condition on $x = 0$. The domain $(\Omega_d; g_F)$ is easily seen to be a strictly convex set, as a first order approximation of the unit disk $D(0; 1)$ in polar coordinates (r, θ) : set $r = 1 - x/2$, $\theta = y$.

We start by stating our results for $d = 2$ and later provide the general statement in higher dimensions, using the same reduction as [4] to take advantage of the 2D setting.

Theorem 1. — Strichartz estimates (2) may hold true on the domain $(\Omega; g_F)$ only if possible pairs $(q; r)$ are such that

$$(5) \quad \frac{1}{q} \leq \frac{1}{6} + \frac{1}{2} \left(\frac{1}{10} - \frac{1}{2} + \frac{1}{r} \right) :$$

In particular, for $r = +\infty$, we have $q > 5$.

Remark 1.1. — Theorem 1 improves on the results from [3]: the range of admissible pairs is further restricted as $l=12$ is replaced by $l=10$ in the admissibility condition. Moreover, we no longer have a restricted range of q , unlike [3].

In [8], we obtained the following positive results:

Theorem 2 ([8]). — Strichartz estimates (2) hold true on $(\Omega; g_F)$ for $(q; r)$ such that

$$(6) \quad \frac{1}{q} \leq \frac{1}{6} + \frac{1}{2} \left(\frac{1}{9} - \frac{1}{2} + \frac{1}{r} \right) :$$

In particular, for $r = +\infty$, we have $q > 5 + 1 = 7$.

A gap remains between negative results ($l=10$ in (5)) and positive results ($l=9$ in (6)).

Remark 1.2. — Besides the full Laplacian, both \mathcal{L} and $x + (\mathcal{L})^{-1}(\mathcal{L})$ commute with the wave flow. In [8] we obtain that, whenever the data is moreover restricted to $j @ j \leq h^{-1}$ and $x + (\mathcal{L})^{-1}(\mathcal{L}) \leq h^{1=3}$, then Strichartz estimates hold for $q > 5$. Hence, in this region of phase space, Theorem 1 is optimal except for the endpoint $q = 5$.

Counterexamples in [3] were constructed by carefully propagating a cusp starting in a suitable position around $(a; 0) \in \Omega$, with $a \leq h^{1=2}$. Here we start with a smoothed out cusp, which may be seen as a wave packet around $x \leq h^{1=3}$ and let it propagate, estimating the resulting solution with the parametrix and proving it saturates the bound with a set of exponents satisfying (5). Our special solution may be seen as a sum of consecutive wave reflections, and at any given point in space-time we see at most one of these waves. Each wave has its peak around a specific location related to the number of reflections, and we can estimate the area $(\text{ir}(x; y))$ where the amplitude of the wave remains close to its peak value, allowing to lower bound any of its physical Lebesgue norms. The time norm is then estimated taking advantage of the separation between any two different wave reflections.

From the 2D construction, we can easily follow the strategy from [4], and construct a good approximated- d -dimensional wave by tensor product: retain our 2D wave in a given spatial tangential direction and multiply by a Gaussian of width $h^{1=2}$ in all other tangential directions. Such a wave packet will then provide a special solution that saturates some- d -dimensional estimates. However, it turns out that we do not recover better counterexamples than the ones from [4]: in fact, we recover the exact same set of exponents, albeit for a slightly different class of examples. As such we

state the result and its proof for the sake of completeness as well as providing a much simpler argument than both [3, 4].

Theorem 3. — For $d = 3; 4; 5$, Strichartz estimates (2) may hold true on the domain $(d; q; r)$ only if possible pairs $(q; r)$ are such that

$$\frac{1}{q} \leq \frac{d-1}{2} - \frac{1}{12} \frac{4-r}{24-r} \leq \frac{1}{2} - \frac{1}{r} :$$

Note that we get the same dimension restriction out of necessity: we have an additional condition $r > 4$ that restricts meaningful ranges to lower dimensions.

Finally, we comment on dealing with only a model case: Theorem 1 should be seen as a better version of the results from [3]. Counterexamples from [3] do not directly provide counterexamples for a generic convex domain, and it required further treatment in [4]. We believe that the present construction is a lot simpler than that of [3], mostly thanks to the use of the exact parametrix from [8]. As such, constructing a generic counterexample will be easier, using in turn the parametrix obtained in [5] and following the present work as a blueprint. In fact, we suggest to any interested reader to start with the present paper, followed by [8], [5] and only afterward, if inclined to, [3], [4] and [7].

In the remaining of the paper, $A \lesssim B$ means that there exists a constant C such that $A \leq CB$ and this constant may change from line to line but is independent of all parameters. It will be explicit when (very occasionally) needed. Similarly, $A \approx B$ means both $A \lesssim B$ and $B \lesssim A$.

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2. The half-wave propagator: spectral analysis and parametrix construction

2.1. Digression on Airy functions . — Before dealing with the Friedlander model, we recall a few notations, where Ai denotes the standard Airy function (see e.g. [16] for well-known properties of the Airy function), $\text{Ai}(x) = \frac{1}{2} \int_{\mathbb{R}} e^{i(\frac{1}{3}x^3 - tx)} dt$:

$$(7) \quad A_{\pm}(z) = e^{\pm i\pi/3} \text{Ai}(e^{\pm i\pi/3} z) = e^{\pm 2i\pi/3} \text{Ai}(e^{\pm 2i\pi/3} z); \text{ for } z \in \mathbb{C};$$

then one checks that $\text{Ai}(z) = A_+(z) + A_-(z)$ (see [16, (2.3)]). The next lemma is proved in the appendix and requires the classical notion of asymptotic expansion: a function $f(w)$ admits an asymptotic expansion for $w \rightarrow \infty$ when there exists a (unique) sequence $(c_n)_n$ such that, for any n ,

$$\lim_{w \rightarrow \infty} w^{-(n+1)} (f(w) - \sum_{j=0}^n c_j w^j) = 0 :$$

We will denote $f(w) \sim \sum_{n=0}^{\infty} c_n w^n$.

Lemma1. — De ne $L(\lambda) = \lambda + i \log(A(\lambda)) = A_+(\lambda)$ for $\lambda \in \mathbb{R}$, then L is real analytic and strictly increasing. We also have

$$(8) \quad L(0) = \frac{4}{3}; \quad \lim_{\lambda \rightarrow 1^-} L(\lambda) = 0; \quad L(\lambda) = \frac{4}{3} \lambda^{3/2} + \frac{1}{2} B(\lambda^{3/2}); \quad \text{for } \lambda > 1;$$

with the following asymptotic expansion for B , with $b_1 > 0$ and $(b_k)_{k \geq 1} \in \mathbb{R}^{\mathbb{N}}$,

$$(9) \quad B(u) \underset{u \rightarrow 1}{\sim} \sum_{k \geq 1} b_k u^{-k};$$

Finally, let $\lambda_{k,0} > 1$ denote the zeros of the Airy function in decreasing order,

$$(10) \quad L(\lambda_{k,0}) = 2^{-k}; \quad L'(\lambda_{k,0}) = 2 \int_0^{\lambda_{k,0}} \text{Ai}^2(x - \lambda_{k,0}) dx;$$

2.2. Spectral analysis of the Friedlander model . — Recall

$$\Delta = f(x; y) \Delta \mathbb{R}^2 \text{ ; } x > 0; y \in \mathbb{R} \text{ and } \mathcal{F} = \mathcal{L}^2 + (1+x)\mathcal{L}^2$$

with Dirichlet boundary condition. After a Fourier transform in the y variable, the operator \mathcal{F} is now $\mathcal{L}^2 + (1+x)^2$. For $\epsilon > 0$, this operator is a positive self-adjoint operator on $L^2(\mathbb{R}_+)$, with compact resolvent and we have explicit eigenfunctions and eigenvalues (the proof of the next lemma is, again, postponed to the appendix):

Lemma2. — There exist orthonormal eigenfunctions $e_k(x; \lambda)$ $\lambda_{k,0} > 0$ with their corresponding eigenvalues $\lambda_k(\lambda) = j^2 + \lambda_{k,0} j^{4/3}$, which form an Hilbert basis of $L^2(\mathbb{R}_+)$. These eigenfunctions have an explicit form

$$(11) \quad e_k(x; \lambda) = \frac{1}{\sqrt{2}} \frac{j^{1/3}}{L'(\lambda_{k,0})} \text{Ai}(j^{2/3} x - \lambda_{k,0});$$

where $L'(\lambda_{k,0})$ is given by (10), which yields $\|e_k(\cdot; \lambda_{k,0})\|_{L^2(\mathbb{R}_+)} = 1$.

In a classical way, for $a > 0$, the Dirac distribution $\delta_{x=a}$ on \mathbb{R}_+ may be decomposed as

$$\delta_{x=a} = \sum_{k \geq 1} e_k(x; \lambda_{k,0}) e_k(a; \lambda_{k,0});$$

Then if we consider a data at time $t = s$ such that $u_0(x; y) = \delta_{x=a; y=b}$, where $h \in (0; 1)$ is a small parameter and $\lambda \in C_0^1([1/2; 2])$, we can write the (localized in λ) Green function associated to the half-wave operator on \mathbb{R}_+ as

$$(12) \quad G_h((x; y; t); (a; b; s)) = \sum_{k \geq 1} \int_{\mathbb{R}} e^{-i(t-s)\lambda_k(\lambda)} \frac{1}{L'(\lambda_{k,0})} e^{i(y-b)\lambda_k(\lambda)} (h) e_k(x; \lambda_{k,0}) e_k(a; \lambda_{k,0}) d\lambda;$$

2.3. Airy-Poisson formula . — We briefly recall a variant of the Poisson summation formula, introduced to deal with a parametrix construction for the general case of a generic strictly convex domain in [5] and used in [8] to improve Strichartz estimates in the model case. It will turn out to be crucial to analyze the spectral sum defining G_h and map it to a sum over reflections of waves.

Lemma 3. — In $D^q(\mathbb{R}^1)$, one has

$$\sum_{N \geq 2} \sum_{k \geq N} e^{iNL} \hat{f}(k) = 2 \sum_{k \geq N} \frac{1}{L^q \hat{f}(k)} \hat{f}(k):$$

In other words, for $\hat{f} \in C_0^1$,

$$(13) \quad \sum_{N \geq 2} \sum_{k \geq N} e^{iNL} \hat{f}(k) d! = 2 \sum_{k \geq N} \frac{1}{L^q \hat{f}(k)} \hat{f}(k):$$

The lemma is easily proved using the usual Poisson summation formula followed by the change of variable $x = L(\cdot)$ and we provide details in the appendix.

3. Counterexamples

As recalled in the introduction, counterexamples in [3] were constructed by carefully propagating a cusp starting at a distance $a^{1=2}$ from the boundary. In this section, a is a parameter to be optimized later on, which is to be thought as the distance between the boundary and the peak value of the data (and later, repeatedly in time, of the solution itself). Recall that a (2D) Strichartz estimate is

$$(14) \quad \|u\|_{L^q([0,t_0];L^r)} \leq h \|u_0\|_{L^2};$$

where $h = d(1=2 \ 1=r) \ 1=q$ with $d = 2$ (scaling condition). We also define h to be such that $1=q = (1=2 \ 1=r)$ and recall that in free space, $h = (d \ 1)=2 = 1=2$.

3.1. Rescaled variables. — Let a be small enough, such that $a^{2=3} \leq a \leq 1$. From our knowledge from the parametrix construction in [7] (see also [8]), where the source point is $(x = a; y = 0)$, we rescale as follows: set $h = a^{3=2} = h$ and let $M_a = a^{1=2}$,

$$(15) \quad t = a^{1=2}T; \quad x = aX; \quad y = \frac{p}{t} \sqrt{1+a+a^{3=2}Y}; \quad U(T; X; Y) = u(t; x; y):$$

If $F(X; Y) = f(aX; a^{3=2}Y \ \frac{p}{T} \sqrt{1+a})$, then

$$\|F(X; Y)\|_{L^r_{X>0;Y}} = a^{5=(2r)} \|f\|_{L^r_{X>0;Y}}$$

and

$$\|U(T; X; Y)\|_{L^q([0;M_a];L^r)} = a^{1=(2q) \ 5=(2r)} \|u\|_{L^q([0;1];L^r)}:$$

Since $h = M_a^{3 \ 1}$, in rescaled variables, (14) becomes

$$M_a^{1=q \ 5=r} \|U\|_{L^q([0;M_a];L^r)} \leq (M_a^3)^{1=q \ 2=r} a^{5=4} \|u_0\|_{L^2}$$

hence we are reduced to

$$(16) \quad \|U\|_{L^q([0;M_a];L^r)} \leq M_a^{1=q \ 2=r} M_a^{1=2 \ 1=r \ 2=q} \|u_0\|_{L^2}:$$

3.2. Setup for the parametrix . — Let us consider our model equation,

$$(\partial_x^2 - (\partial_x + (1 + x)\partial_x))u(t; x; y) = 0 \quad \text{on } x > 0; y \in \mathbb{R}$$

with Dirichlet boundary condition $u|_{x=0} = 0$. We will seek solutions u under the following form, where the Fourier variable associated to y is rescaled with $\eta = h^{-1}y$,

$$u(t; x; y) = \frac{1}{2\pi h} \int_{\mathbb{R}} e^{i(\eta h)y} v(t; x; \eta) d\eta;$$

where $\eta \in C_0^1$, $\eta = 1$ for $3/4 \leq \eta \leq 6/5$ and $\eta = 0$ outside $[1/2, 2]$. Therefore, as a function of y , u is band-limited and its Fourier variable $\eta = h^{-1}y$. If we set $\tilde{y} = h^{-1}y$ and $v_-(t; x) = v(t; x; \tilde{y})$, v_- is a solution to

$$(\partial_x^2 - (\partial_x + (1 + x)\partial_x))v_-(t; x) = 0 \quad \text{for } x > 0;$$

with $v_-|_{x=0} = 0$. Recalling from Lemma 2 that the eigenmodes are $e_k(x; \tilde{y}^{-1})$ and using (11), we select a datum $v_0 = v_0(x; a; \tilde{y}^{-1})$ (to be suitably chosen later), decompose it over the eigenmodes and write the corresponding half-wave propagator, with an additional spectral cut-off $\chi_0(\eta) = \chi_1(\eta^{-2/3})$,

$$\begin{aligned} v_-(t; x) &= \sum_{k > 1} e^{i(t-\tilde{y}^{-1})(1 + \eta^{-2/3})\eta^{-1/2}} \chi_0(\eta) \chi_1(\eta^{-2/3}) e_k(x; \tilde{y}^{-1}) \\ &= \sum_{k > 1} \frac{2^{-2/3}}{L^Q(\eta)} e^{i(t-\tilde{y}^{-1})(1 + \eta^{-2/3})\eta^{-1/2}} \chi_0(\eta) \chi_1(\eta^{-2/3}) \text{Ai}(\tilde{y}^{-2/3} x - \eta) \\ &= \sum_{k > 1} \frac{2^{-2/3}}{L^Q(\eta)} e^{i(t-\tilde{y}^{-1})(1 + \eta^{-2/3})\eta^{-1/2}} \chi_0(\eta) \chi_1(\eta^{-2/3}) \text{Ai}(\tilde{y}^{-2/3} z - \eta) v_0(z; a; \tilde{y}^{-1}) dz \end{aligned} \tag{17}$$

It turns out to be convenient to localize v_- with respect to the Laplacian. Recall that

$$\partial_x^2 \frac{\chi_0(\eta)}{\chi_1(\eta^{-2/3})} e_k(x; \tilde{y}^{-1}) = \partial_x^2 \frac{\chi_0(\eta)}{1 + \eta^{-2/3}} e_k(x; \tilde{y}^{-1});$$

which explains why we added a spectral cut-off $\chi_1(\eta^{-2/3})$, with $\chi_1(\eta) = 0$ for $\eta < 1$ and $\chi_1(\eta) = 1$ for $0 < \eta < 1$. We also insert $\chi_0(\eta) = 1$ for $\eta > 2$, $\chi_0(\eta) = 0$ for $\eta < 1$: obviously $\chi_0(\eta) = 1$ for all η , as $\eta^{-1} > 2$. With both cut-offs, the sum over k in (17) is reduced to a finite sum $k \leq h^{-1}$, owing to the asymptotics of the zeroes of the Airy function, which are strictly positive and behave like $k^{2/3}$ for large k . Alternatively, we may use the Green function formula (12) and apply it to our datum v_0 (after inserting the same spectral cut-off in the Green function). We point out that our choice of $+$ sign in the half-wave propagator is arbitrary and does not play any important role beside setting a direction of propagation (to the left of the x axis in the upper plane) when returning to $U(t; x; y)$.

Using the Airy-Poisson formula (13), we transform the sum of eigenmodes (over k) into a sum over $N \in \mathbb{Z}$; its summands will be later seen to be waves corresponding to

the number of reflections on the boundary, indexed by N :

$$v(t; x; \sim^{-1}) = \sum_{N \geq 0} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \int_{z > 0} e^{iNL} e^{j(t-)(1+ \sim^{-2=3})^{1=2}} \phi_0(\cdot) \phi_1(\sim^{-2=3} \cdot) \text{Ai}(\sim^{-2=3} x) \text{Ai}(h^{-2=3} z) v_0(z; a; 1=) dz d\cdot$$

Recall that

$$\text{Ai}(\sim^{-2=3} x) = \frac{1}{2 \sim^{-1=3}} \int_{\mathbb{R}} e^{i(-)(\sim^{-3=3} + (x \sim^{-2=3}))} d\cdot$$

If we rescale with $\sim^{-2=3}$, we get

$$v(t; x; \sim^{-1}) = \frac{1}{(2 \sim^{-2})^2} \sum_{N \geq 0} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \int_{z > 0} e^{i(-) e_N} \phi_0(\sim^{-2=3} \cdot) \phi_1(\cdot) v_0(z; a; \sim^{-1}) dz ds d\cdot$$

where

$$e_N = \frac{3}{3} + (x) + \frac{s^3}{3} + s(z) N \sim^{-L}(\sim^{-2=3}) + t^p \frac{1}{1+}$$

and therefore, with $N = e_N + y$, we find

$$u(t; x; y) = \frac{1}{(2 \sim^{-3})^3 h} \sum_{N \geq 0} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \int_{z > 0} e^{j(=h) N} \phi_0(\sim^{-2=3} \cdot) \phi_1(\cdot) \frac{1}{h^2} (\cdot) v_0(z; a; =h) dz ds d\cdot$$

Let us rescale now like we did in (15), $t = a^{1=2} T$, $x = aX$, $y = t^p \frac{1}{1+a} + a^{3=2} Y$, with moreover

$$s = aE; \quad s = a^{1=2} S; \quad = a^{1=2}; \quad z = aZ;$$

then $u(t; x; y)$ becomes $U(T; X; Y)$, where, for $= a^{3=2} = h$ as before, we have

$$(18) \quad U(T; X; Y) = \frac{1}{(2 \sim^{-3})^3 h} \sum_{N \geq 0} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \int_{z > 0} e^{j(Y + N)} V_0(Z; \cdot) a(E)^2 (\cdot) dZ dS d\cdot$$

where $a(E) = \phi_0(\sim^{-2=3} \sim^{-2=3} E) \phi_1(aE)$. Here the phase function is given by

$$N = \frac{3}{3} + (X E) + \frac{S^3}{3} + S(Z E) \frac{N}{L} ((\sim^{-2=3} E) + p \frac{T(E \sim^{-1})}{1 + aE} p \frac{1}{1 + a})$$

The last term comes from the time propagator and takes into account the change of variable in y that includes a time translation.

We conclude this introduction to the parametrix with an important lemma, in effect reducing the sum over N in (18) to a finite sum (with a very large number of terms).

Lemma 4. — Assume V_0 is a smooth function and $V_0(Z; \cdot) \in L^1 L^1_Z$. In the sum defining $U(T; X; Y)$ in (18), the only significant contributions arise from N 's such that $|jN| \leq h^{-1=3}$.

Proof. — We will rely on non stationary phase in either E , S or \dots . We have $\mathcal{Q}_N = S^2 + Z E$ and $\mathcal{Q}_N = \dots + X E$. If either $|jS_j| > 3N^{1=100}E^{1=2}$ or $|j_j| > 3N^{1=100}E^{1=2}$, integration by parts in one of these variables, say S , provides a factor $|j_j|^{-1}$. $N^{-1=50} \dots^{-1=3}$ using the lower bound on E from its support. By non stationary phase, we get both enough decay to sum in N and a bound $kV_k L_{\frac{1}{2}} O(\dots)$ (the $(E; \dots)$ integral is bounded by support considerations and the Z integral is bounded from $V_0 \geq L^1$). Using (8) to expand $L(\dots)$,

$$\mathcal{Q}_N = \left(\frac{T}{(1+aE)^p (1+a)^p} \frac{(1+aE + \frac{p}{1+aE} \frac{p}{1+a} \dots)}{(1+aE + \frac{p}{1+aE} \frac{p}{1+a} \dots)} \right) S \quad 2NE^{1=2} \dots \frac{3}{4} B^0 (E^{3=2}) ;$$

where the B^0 term is small compared to 1, if $E^{3=2}$ is sufficiently large (> 2 is already enough). Note that the coefficient of T is bounded from above and below by fixed constants, as $E > 0$ and $aE \dots 1$. If $\sup(|jS_j|; |j_j|) < 3N^{1=100}E^{1=2}$, then, for $|jN_j| > 100$, \mathcal{Q}_N will not be stationary in E provided that $|jT_j| \dots (N \dots 3N^{1=100})E^{1=2}$ and non-stationary phase in E provides, again, decay to sum in N and an $O(\dots)$ contribution. With the lower bound $E \dots^{-2=3}$, the cardinal $|JN|$ of the set of N 's that contribute is bounded by $|jT_j|^{-1=3}$. As $T = t=a^{1=2}$, $\dots = a^{3=2}=h$ and $a \dots^{-2=3}$, $|JN| \dots^{-1=3}=a \dots^{-1=3}$. Moreover, any $O(\dots)$ is also an $O(h^1)$.

3.3. Choosing the initial data \dots . — We pick $v_0(z; a; =h)$, which is now $V_0(Z; \dots)$, to be

$$(19) \quad V_0(Z; \dots) = \int_Z^{\dots} e^{i((Z-1)s + s^3 - 3 + is^2 = (2M))} ds;$$

While we do not have $V_0|_{Z=0} = 0$, this will turn to be irrelevant for our purposes: the spectral cut-off \dots insures that the datum $v_{\dots}(0; x)$ is such that $v_{\dots}(0; 0) = 0$ as a finite sum of Airy functions $Ai(\dots)$. Here M is large and will be chosen later in this section, depending on $a; h$, while \dots through the (\dots) cut-off and therefore harmless. Defined in this way, V_0 is (microlocally) concentrated around $fZ = 1g$ and the corresponding Fourier direction $f = 0g$: we may explicitly compute V_0 as follows, with $e = \dots$ and $\dots = e^{1=3}s$:

$$\begin{aligned} \int_Z^{\dots} e^{i((Z-1)s + s^3 - 3 + is^2 = (2M))} ds &= (1 = e^{1=3}) \int_Z^{\dots} e^{i(\dots = 3 + e^{2=3} (Z-1) + (i=2M) e^{1=3} \dots)} d \\ &= (1 = e^{1=3}) \int_Z^{\dots} e^{i(1=3)(\dots + (i=2M) e^{1=3})^3 + e^{2=3} (Z-1 + i=4M^2) + i e^{24M^3}} d \\ &= (1 = e^{1=3}) e^{(e^{2M})(Z-1 + i=6M^2)} 2 Ai(e^{2=3}(Z-1 + i=4M^2)); \end{aligned}$$

We select $1 \dots M \dots$: this will be our first condition on M . For $Z-1 > 1=10$, the exponential decay of $|j Ai(z)j \exp(-Cz^{3=2})$ for large z offsets the growth of the exponential factor in front of it, while for $Z-1 < 1=10$, we get exponential decay in term of e^{-M} from the front factor while Ai is bounded. In particular, for $Z = 0$,

we get

$$\int_{Z_0}^Z e^{i((Z-1)s + s^3 - 3 + is^2 = (2M))} ds = \frac{1}{e^{1-3}} e^{(e-2M)(1-1=(6M^2))} 2 \operatorname{Ai}(e^{2-3}(1+1=4M^2));$$

which is $O(e^{-1})$ as $1-1=(6M^2) > 0$ and $e-2M > e^{-\epsilon}$ for a suitable (small) $\epsilon > 0$, provided that $1-M$. Moreover, with such a choice of M , we even have

$$(20) \quad V_{0;Z_0} = \int_{Z_0}^Z e^{i((Z-1)s + s^3 - 3 + is^2 = (2M))} ds = O(e^{-1});$$

We can then compute explicitly the Fourier transform of V_0 , with $1-M$:

$$\begin{aligned} \mathcal{V}_0(e; e) &= \int_{Z_0}^Z e^{ieZ} V_0(Z; e) dZ \\ (21) \quad &= \int_{Z_0}^Z \int_{Z_0}^Z e^{ie(s-Z)} e^{i(s^3-3+is^2=(2M))} dZ ds \\ &= \frac{1}{e} e^{ie(3-3+is^2=(2M))}. \end{aligned}$$

3.4. L^2 norm of the initial data. — De ne

$$u_0(x; y) = \frac{1}{h} \int_{Z_0}^Z e^{i(=h)y} v_0(x; a; =h) () d;$$

our initial data $u(0; x; y)$ will be the projection of u_0 over a finite number of spectral modes, through (17). By Bessel inequality, $\|u(0; \cdot)\|_{L^2(\cdot)} \leq \|u_0\|_{L^2(\cdot)}$, and using (20), we have

$$(22) \quad \|u_0\|_{L^2(\mathbb{R}^2)} = \|u_0\|_{L^2(\cdot)} + O(e^{-1});$$

We therefore compute the Fourier transform of u_0 , or its rescaled version: for $x = aX$, we set $v_0(x; a; =h) = V_0(X;)$ with V_0 defined by (19), and

$$U_0(X; Y) := u(0; x; y) = \frac{1}{h} \int_{Z_0}^Z e^{iY} V_0(X;) () d;$$

The Fourier transform of U_0 is obtained by a direct computation,

$$\begin{aligned} \mathcal{U}_0(;) &= \int_{Z_0}^Z e^{iX} e^{iY} \frac{1}{h} \int_{Z_0}^Z e^{i\alpha} V_0(X; e) (e) de dX dY \\ (23) \quad &= \frac{1}{h} \int_{Z_0}^Z e^{iY} \mathcal{V}_0(; e) de \\ &= \frac{1}{h} () \mathcal{V}_0(;): \end{aligned}$$

We now estimate the L^2 norm of U_0 , using the explicit form of V_0 we already obtained:

$$\begin{aligned}
 (24) \quad kU_0k_{L^2_{X^2R;Y}}^2 &= k\Theta_0k_{L^2}^2 = \int_{\mathbb{R}} \int_{\mathbb{R}} |j\Theta_0|^2(\xi, \eta) d\xi d\eta \\
 &= \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{1}{h^{2-2s}} |\Theta_0|^2(\xi, \eta) d\xi d\eta \\
 &= \frac{1}{h^2} \int_{\mathbb{R}} \int_{\mathbb{R}} |\Theta_0|^2(\xi, \eta) d\xi d\eta \\
 &= \frac{1}{h^{2-2s}} \int_{\mathbb{R}} \int_{\mathbb{R}} e^{i(\xi^3 - 3\xi\eta + \eta^2 - 2M\xi\eta)} d\xi d\eta \\
 &= \frac{1}{h^{2-2s}} \int_{\mathbb{R}} \int_{\mathbb{R}} e^{i(\xi^3 - 3\xi\eta + \eta^2 - 2M\xi\eta)} d\xi d\eta \\
 &= h^{2-5s} M^{1-2s};
 \end{aligned}$$

where we used (23) and (21). Recalling (22), this yields $kU_0k_{L^2_{X^2R;Y}} = h^{1-5s} M^{1-2s}$.

3.5. Computing the parametrix U . — In the remainder of this section, we restrict ourselves to a h^{1-2s} . For a suitable chosen M , we prove Strichartz estimates (16) to hold but with a loss in the parameter $s : 6-1=2 \quad 1=10$. We start by computing the L^1 norm of U , followed by its $L^q([0; 1]; L^1)$ norm; next, we balance lower bounds on space-time norms with our upper bound on the data, proving that if (16) holds for $r = 1$, this forces $q > 5$, which is equivalent to the aforementioned loss on s . This provides our counterexample for the endpoint Strichartz estimate $(q; s+1)$. We then compute the L^r norm of U to recover other exponents, and this is ultimately useful in higher dimensions as well.

The phases θ_N in the sum defining U (in (18)) are all linear in Z : we replace V_0 given by (19) in (18) and, using Lemma 4, we restrict (up to an $O(h^1)$ term) to a finite sum over jNj . h^{-1-3s} (note that $V_0 \in L^1_{\mathbb{R}}$ from the previous pointwise bounds we obtained). In this finite sum, we may add the same integrals but with $Z < 0$: these add up to the $O(h^1)$ term, as V_0 is asymptotically small for $Z < 0$. The inner integral over $Z \in \mathbb{R}$ yields

$$\int_{\mathbb{R}} e^{iZ(s+S)} dZ = \frac{2}{s+S};$$

therefore we get

$$(25) \quad U(T; X; Y) = \frac{1}{(2^{-2s})^2 h^{1-3s}} \sum_{jNj} \int_{\mathbb{R}} \int_{\mathbb{R}} e^{i(Y+\theta_N) a(E)} (\dots) d\eta d\xi dE + O(h^1);$$

where θ_N is the (complex) phase

$$(26) \quad \theta_N = T \left(\frac{(E-1)}{1+aE} \right)^{\frac{N}{1+a}} L((\dots)^{2-3s} E) + s(E-1) + i \frac{s^2}{2M} + \frac{3}{3} + (\dots E);$$

We start by eliminating the s variable in the integral from (25) with complex phase function θ_N defined in (26). We have

$$\int_{\mathbb{R}} e^{i(s(E-1) + is^2 = (2M))} ds = \frac{r}{2} \frac{p}{M} e^{-M(E-1)^2 = 2}$$

and therefore (25) becomes

$$(27) \quad U(T; X; Y) = \frac{1=2M^{1=2}}{(2)^{3=2}h} \int_{jNj. h^{-1=3}}^X \int_{\mathbb{R}}^Z e^{i(Y + \theta_N) - a(E)} ()^{1=2} d dE d + O(h^1)$$

with phase

$$(28) \quad \theta_N = T p \frac{(E-1)}{1+aE} + p \frac{N}{1+a} L(()^{2=3}E) + i \frac{M(E-1)^2}{2} + \frac{3}{3} + (X-E):$$

Recall that $L(!) = \frac{1}{2} + \frac{4}{3}!^{3=2} B(!^{3=2})$, where $B(u) = \sum_{n=1}^{\infty} b_n u^n$, hence

$$\frac{N}{3} (L(()^{2=3}E) - 2) = \frac{N}{3} \frac{4}{3} E^{3=2} B(E^{3=2}) = \frac{4}{3} N E^{3=2} \frac{N}{3} B(E^{3=2}):$$

Remark 3.1. — For values $h^{1=2} \ll a$, the factor $\exp(iNB)$ in our phase does not oscillate anymore: indeed, the phase θ_N given in (26) is stationary in E only when $N = T = \frac{1}{a}$ and for E near 1 (which is forced by the imaginary part of the phase)

$$NB(E^{3=2}) = \frac{N}{3} \frac{t}{a} \frac{h}{a^{3=2}} \cdot \frac{h}{a^2}:$$

Therefore, when $h^{1=2} \ll a$ we can actually bring the $\exp(iNB)$ factor in the symbol rather than leave NB in the phase (in order to do explicit computations).

We have, from (28),

$$\begin{aligned} \text{Im}(\theta_N) &= \frac{M(E-1)^2}{2} \\ \theta_N &= \frac{1}{2} + X - E \\ \theta_N &= T \frac{p}{2} \frac{(E-1)}{1+aE} + p \frac{N}{1+a} L^0(()^{2=3}E) \\ &\quad + i \frac{M}{2} (E-1)^2 \end{aligned}$$

Therefore, the set $\text{Im}(\theta_N) = 0; r(\cdot; E) \theta_N = 0$ coincides with

$$E = 1; \quad \frac{1}{2} = \frac{T}{2} \frac{p}{1+a} \frac{N}{()^{1=3}} L^0(()^{2=3}); \quad X = 1 - \frac{M}{2}:$$

In the $(T; X)$ plane, this is the trajectory moving to the right from $X = 1, T = 0$. We introduce the following notations: let $\epsilon_m > 0, m \in \mathbb{Z}; 2g$ be small, $J \in \mathbb{Z}$ and set

$$\begin{aligned} I_J &= 4J \frac{p}{1+a} + (2^m \epsilon_0; 2^n \epsilon_0); \\ R_J &= f T \frac{1}{2} I_J; \quad jX = 1j \epsilon^{-1}; \quad jY = 4J = 3j \epsilon^{-2} g; \end{aligned}$$

From now on we will focus on U restricted to a set R_J on which we obtain a lower bound of its L^1 norm. We first need the following result, which states that, if for a given J we consider only points $(T; X; Y) \in R_J$, then in the sum (27) defining $U(T; X; Y)$ indexed over the number of reflections N there is only one single integral that provides a non-trivial contribution, corresponding to $N = J$.

Proposition 1. — For all $n \in \mathbb{N}$, there exists C_n such that for all $0 \leq J \leq M_a$, for all $1 \leq M$ and for all $(T; X; Y) \in R_J$, the following holds

$$U(T; X; Y) \leq \frac{1=2M^{1=2}}{(2)^{3=2h}} \int_{\mathbb{R}^n} e^{j(Y + e_J) \cdot a(E)} (\cdot)^{1=2} dE \leq C_n \cdot n:$$

Proof. — Let $0 \leq J \leq M_a$ and let $(T; X; Y) \in R_J$: we can write

$$T = (4J + 2P) \frac{P}{1+a}; \quad X = 1 + \mathcal{X}; \quad \text{where } j \in \mathbb{N}_0; \quad j \in \mathbb{N}_1:$$

We also change variable $E = 1 + (1+a)\mathcal{E}$: from the Gaussian nature of e_N , E has to stay close to 1. Using Remark 3.1, we may move $\exp(iNB(\cdot))$ in the symbol and relabel the phase to remove the harmless factor $N = 2$; with new variables \mathcal{X} and \mathcal{E} , the relabeled e_N reads

$$e_N = \frac{T \mathcal{E}^P}{1 + \frac{P}{1+a} \mathcal{E}} \frac{4}{3} N (1 + (1+a)\mathcal{E})^{3=2} + \frac{3}{3} + (\mathcal{X} - (1+a)\mathcal{E}) + \frac{i}{2} M (1+a)^2 \mathcal{E}^2:$$

The derivatives with respect to \mathcal{E} ; are

$$\begin{aligned} \partial_{\mathcal{E}} e_N &= \frac{2 + \mathcal{X}}{1 + \frac{P}{1+a} \mathcal{E}} (1+a)\mathcal{E} \\ \partial_{\mathcal{E}}^2 e_N &= T \frac{P}{1+a} \frac{1}{1 + \frac{P}{1+a} \mathcal{E}} - \frac{P}{2} \frac{a\mathcal{E}}{1 + \frac{P}{1+a} \mathcal{E}} \frac{1}{(1 + \frac{P}{1+a} \mathcal{E})^2} \\ &= \frac{2N(1+a)(1+(1+a)\mathcal{E})^{1=2}}{(1+a) + iM(1+a)^2 \mathcal{E}} \end{aligned}$$

Obviously the set $\{ \text{Im}(e_N) = 0; \text{Re}(e_N) = 0 \}$ is given by

$$\mathcal{E} = 0; \quad \mathcal{X} + \frac{2}{1+a} = (1+a)\mathcal{E} = 0; \quad = \frac{T}{2(1+a)} \frac{1}{2N} ;$$

and therefore, imposing $j \in \mathbb{N}_1$ implies $j \in \mathbb{N}_1^{1=2}$ which yields

$$\frac{T}{2(1+a)} \frac{1}{2N} = j \in \mathbb{N}_1^{1=2} \leq 2N j \in \mathbb{N}_1^{1=2}:$$

From $j \in \mathbb{N}_0$, we get that for $\mathbb{N}_0 \leq 1=4$, the last inequality forces $N = J$. This proves Proposition 1 as for $N \in \mathbb{N}$, we can perform non stationary phase, gaining powers of ϵ , and the sum is finite with at most $h^{1=3}$ terms.

Using Proposition 1 and Remark 3.1 we may rewrite, for $(T; X; Y) \in R_J$, recalling that $O(h^{-1}) = O(h^1)$ as $a \ll h^{1=2}$,

$$(29) \quad U \int_{Z'} \frac{(1+a)^p \overline{M}}{(2h)^{3=2}} (i)^J e^{i(Y + e_M + JF)} \mathcal{E}_J(\mathbb{E}; \mathbb{E}) d\mathbb{E} + O(h^1);$$

where e_J was replaced by $e_M(\mathbb{E}) + JF(\mathbb{E})$: in the new variables, e_M and F are respectively

$$e_M(\mathbb{E}; \mathbb{E}) = \frac{2\mathbb{E}^p(1+a)}{1 + \frac{1}{1+a\mathbb{E}}} + i \frac{M}{2} (1+a)^2 \mathbb{E}^2 + \frac{3}{3} + (\mathcal{E} - (1+a)\mathbb{E});$$

$$F(\mathbb{E}) = \frac{4\mathbb{E}(1+a)}{1 + \frac{1}{1+a\mathbb{E}}} - \frac{4}{3} (1 + (1+a)\mathbb{E})^{3=2};$$

and the symbol is $\mathcal{E}_J(E(\mathbb{E}); \mathbb{E})$ with $E(\mathbb{E}) = 1 + (1+a)\mathbb{E}$ and

$$\mathcal{E}_J(E; \mathbb{E}) = a(E)^{1=2} (\mathbb{E}) \exp(iNB(E - \mathbb{E}^{3=2}));$$

Since $\text{Im}(e_M) = 0$ only at $\mathbb{E} = 0$, we expand F near $\mathbb{E} = 0$,

$$F(0) = \frac{4}{3}; \quad F'(0) = 0; \quad F''(0) = (1+a)(1+2a);$$

$$F(\mathbb{E}) = \frac{4}{3} + \frac{\mathbb{E}^2}{2} (1+a)(1+2a) + O(\mathbb{E}^3);$$

Our new phase function $e_M + JF$ depends on two large parameters M , to be chosen such that $1 \ll M$ and J , taking all values from 1 to $M_a = a^{-1=2}$, depending on the region R_J containing $(T; X; Y)$.

Let us take $J \ll M_a \ll M$: in the phase $(e_M + JF)$, we consider the large parameter to be M and, for $\mathbb{E} = M(1+a)$, we get

$$(e_M + JF) = \frac{3}{3} + \mathcal{E} - \frac{4}{3}J + \frac{2\mathbb{E}^p}{1 + \frac{1}{1+a\mathbb{E}}} \frac{\mathbb{E}}{M} + \frac{i}{2} (1+a)\mathbb{E}^2 - \frac{J}{2M} \mathbb{E}^2 (1+2a) + O\left(\frac{J}{M} \mathbb{E}^3\right);$$

Remark 3.2. — In the integral (29), we may localize on $j\mathbb{E}j \ll 1=2$ using the imaginary part of the phase; indeed, for larger values of \mathbb{E} the phase is exponentially decreasing; we can then localize near the critical points in \mathbb{E} , and $\mathbb{E}^2 = (1+a)\mathbb{E} - X$ hence \mathbb{E} becomes uniformly bounded and

$$\frac{1}{M} \frac{2\mathbb{E}^p}{1 + \frac{1}{1+a\mathbb{E}}} \ll O(1=M);$$

Moreover, for $J \ll M_a \ll M$, the imaginary phase factor $\exp(i(1+a)O((J=M)\mathbb{E}^3))$ does not oscillate for values $j\mathbb{E}j \ll 1=2$ (i.e., for \mathbb{E} such that the contribution of the integral is not exponentially small).

Remark 3.3. — Writing, for small ϵ ,

$$\frac{p^{2\mathcal{P}}}{1 + a\epsilon} = \mathcal{P}(1 - (a-4)\epsilon + O(a^2\epsilon^2));$$

we obtain the first few terms of the Taylor expansion in ϵ of the phase with large parameter a as follows

$$(\mathcal{P}) \frac{\epsilon}{M} + \frac{i}{2} a\epsilon^2 + O\left(\frac{J}{M}\epsilon^3\right); \quad a = 1 + a + i \frac{J}{M}(1 + 2a) + \frac{a\mathcal{P}}{2M} :$$

Remark 3.4. — We are still carrying a symbol $e_{j;}$; we may safely discard its $a(E)$ component as E is now localized near $E = 1$, and therefore the contributions coming from $(1 - a\epsilon)$ and $(1 - O(\epsilon^2))$ are harmless by non stationary phase, and the remaining $e_{j;}(E; \epsilon) = \exp(iJB(\epsilon^{-3/2}))$ is elliptic, close to 1 near $E = 1$ and $J = 1$.

We rewrite the integral in ϵ ; in (29) as

$$\begin{aligned} Z & \int e^{i(\epsilon_M + JF)}_{j;} d\epsilon d \\ & = \int e^{i(\epsilon^{-3/2} + \dots - 4J=3)} e^{i((\mathcal{P}) \epsilon = M + i a\epsilon^2 = 2 + O((J=M)\epsilon^3))} e_{j;} d\epsilon d + O(h^1) \end{aligned}$$

and apply stationary phase in ϵ with complex phase

$$(\mathcal{P}) \frac{\epsilon}{M} + \frac{i}{2} a\epsilon^2 + O\left(\frac{J}{M}\epsilon^3\right)$$

and large parameter a . The second derivative's absolute value equals

$$1 + i \frac{J}{M} + O(a) + O\left(\frac{J}{M}\epsilon\right) \quad \sqrt{1 + \frac{J^2}{M^2} + O\left(\frac{J}{M}\epsilon\right)} \quad \sim 1 \quad \text{for } J \gg M_a \cdot M;$$

and stationary phase yields

$$(30) \quad \int e^{i(\epsilon_M + JF)}_{j;} d\epsilon d = \int e^{i(\epsilon^{-3/2} + \dots - 4J=3)} \frac{2}{a} e^{i(a=2)(\epsilon_c^2 + O(\epsilon_c^3))} e_{j;} d + O(h^1);$$

where the critical point is $\epsilon_c = \epsilon_c(\epsilon) = i(\mathcal{P}) = (M - a)(1 + O(j\mathcal{P} - j=M))$ and $e_{j;}(\epsilon; \epsilon)$ is an elliptic symbol with an asymptotic expansion over ϵ^{-1} , with leading order contribution $e_{j;}(E(\epsilon_c(\epsilon)))$.

Remark 3.5. — Using Remark 3.2, if $j\epsilon_c(\epsilon) > (1 - \epsilon)^{-2}$ for some $\epsilon > 0$, then the integral in the right hand side term in (30) is exponentially small. On the other hand, for $j\epsilon_c < 1$, $E(\epsilon_c) = 1 + (1 + a)\epsilon_c$ stays close to 1 hence $a(E(\epsilon_c))$ vanishes together with all its derivatives. Therefore, for all ϵ such that $j\mathcal{P} - j=M_j - a_j - 1$ we have

$$(31) \quad e_{j;}(\epsilon; \epsilon) = e^{iJB(E(\epsilon_c(\epsilon))^{-3/2})} (1 + O((J = \dots)))$$

In particular, (31) holds for $j \in \mathbb{Z}$. $(1 + a)^{-2}$, i.e., where the integral in the RHS term of (30) is not exponentially decreasing.

Since $\tau = M(1 + a)$, we have, at $T = (4J + 2P)^P \sqrt{1 + a}$, $X = 1 + \mathcal{X}$,

$$(32) \quad |jU(T; X; Y)| \leq \frac{1}{h} \int_{\mathbb{Z}} e^{i(Y - 4J - 3 + iM(1 + a) - aP^2(1 + O(P)) = 2 + 3 - 3 + \mathcal{X})} c_{j; \cdot}(\cdot) d \cdot$$

with $P = (\mathcal{P}) = (M - a)$. We are now left with the integration:

$$(33) \quad I(\mathcal{P}; \mathcal{X}; \cdot) = \int_{\mathbb{Z}} e^{iG(\cdot; \mathcal{P}; \mathcal{X})} c_{j; \cdot}(\cdot) d \cdot;$$

where $c_{j; \cdot}$ is elliptic,

$$c_{j; \cdot}(\cdot) = e^{iJB(E - (E_c)^{3=2})} (1 + O(J^{-1})) (\cdot) \quad \text{for } |jP| = \frac{j\mathcal{P}}{M - a} \approx 1$$

and

$$(34) \quad G(\cdot; \mathcal{P}; \mathcal{X}) = \frac{i(1 + a)}{2M - a} (\mathcal{P})^2 + 1 + O((\mathcal{P})^{-1}) = M - a + \frac{3}{3} + \mathcal{X}.$$

We first discard the $O(P)$ term, as it may be seen later as a harmless perturbation, and forget about the symbol for now: consider

$$(35) \quad I_0(\mathcal{P}; \mathcal{X}; \cdot) = \int_{\mathbb{Z}} e^{iG_0(\cdot; \mathcal{P}; \mathcal{X})} d \cdot;$$

with phase

$$(36) \quad G_0(\cdot; \mathcal{P}; \mathcal{X}) = \frac{i(1 + a)}{2M - a} (\mathcal{P})^2 + \frac{3}{3} + \mathcal{X} = (\mathcal{P})^2 + \frac{3}{3} + \mathcal{X};$$

where we have set $\tau := i(1 + a) = 2M - a$, i.e.,

$$= \frac{i}{2(M + iJ + ia(J + \mathcal{P} = 2) = (1 + a))}.$$

We are after lower bounds for the L^1 norm of U , hence we seek values of \mathcal{P} where I_0 reaches its maximum. Write

$$G_0(\cdot; \mathcal{P}; \mathcal{X}) = (\mathcal{P}^2 + 2\mathcal{P}\mathcal{X}) + \mathcal{P}^2 - 3 = 3 + (\mathcal{P} + \mathcal{X})^3 = 3(\mathcal{P} + \mathcal{X})(\mathcal{P}^2 + 2\mathcal{P}\mathcal{X}):$$

The last two terms (the only ones depending on \mathcal{X}) may be seen as an Airy phase function, and therefore we have

$$(37) \quad \begin{aligned} I_0(\mathcal{P}; \mathcal{X}; \cdot) &= \int_{\mathbb{Z}} e^{i(\mathcal{P}^2 + 2\mathcal{P}\mathcal{X}) + \mathcal{P}^2 - 3} e^{i((\mathcal{P} + \mathcal{X})^3 = 3(\mathcal{P} + \mathcal{X})(\mathcal{P}^2 + 2\mathcal{P}\mathcal{X}))} d \cdot \\ &= \int_{\mathbb{Z}} e^{-1=3} e^{i(\mathcal{P}^2 + 2\mathcal{P}\mathcal{X}) + \mathcal{P}^2 - 3} \text{Ai}(e^{2=3}(\mathcal{P}^2 + 2\mathcal{P}\mathcal{X})) d \cdot \end{aligned}$$

Recall $Ai(0) = 1 = (3^{2=3} (2 =3)) > 3=10$; moreover there exists a small constant $c_2(0; 1)$ such that $|Ai(z)| > 1=10$ for all $z \in \mathbb{C}$ with $|z| \leq c$. We can therefore bound from below the modulus of the Airy function in (37) as follows:

$$(38) \quad Ai(e^{2=3}(\rho^2 + 2\theta - \kappa)) > \frac{1}{10}$$

for all (θ, κ) such that $|e^{2=3}(\rho^2 + 2\theta - \kappa)| \leq c$. Here θ, κ are real, while ρ takes complex values and satisfies

$$|\rho| = \frac{i}{2(M + iJ + O(a))} = \frac{1}{M} \quad \text{for } J \leq M_a, \quad M:$$

Taking $M > 4^{-1=3}c$ it follows that (38) holds true for all $\theta \leq 1=^{-1=3}$ and all $|\kappa| \leq c=2^{-2=3}$. We now study the behavior of the exponential factor in (37). For θ, κ such that (38) holds we have

$$|e^{2=3}(\rho^2 + 2\theta - \kappa)| \leq c^{-1=3}; \quad |\rho| \leq 1=4:$$

For $|\rho| \leq 1=M \leq c=4^{-1=3}$ and $\theta \leq 1=^{-1=3}$, the remaining term in the exponential factor of the Airy integral in (37) can be bounded as follows

$$(39) \quad |e^{2=3}(\rho^2 + 2\theta - \kappa)| \leq c^{-1=3}; \quad |\rho| \leq 1=4:$$

Remark 3.6. — The condition $|\rho| \leq 1=4$ must hold in order for (38) to hold and the term $e^{2=3}|\rho|$ in the exponential factor to stay bounded. For such M , to get $|\rho| \leq 1=4$ we require $|\rho| \leq \frac{M=2=3}{M}$ and $|\kappa| \leq \frac{2=3}{M}$. On the other hand, the condition $|\rho| \leq 1=4$ gives $|\rho| \leq \frac{1}{M}$; as $M=2=3 > \frac{2=3}{M}$ for all $M > 1=3$, in order to have $|Ai(\theta, \kappa)| \geq 1=3$ we must ask

$$(40) \quad |\rho| \leq \frac{1}{M}; \quad |\rho| \leq \frac{1}{M}; \quad |\kappa| \leq \frac{2=3}{M}$$

In particular, taking $M = 1=3$ yields $|\rho| \leq 1=3$.

Let us assume for a moment that the part of phase function depending on ρ in (32) is G_0 (instead of G) and there is no symbol:

$$|jU((4J + 2\theta) \frac{\rho}{1+a}; 1 + \kappa; Y)| = \frac{1}{h} \int e^{i(Y - 4J=3 + G_0(\theta, \kappa))} d\rho$$

Then, using (37), we would immediately get

$$(41) \quad |jU((4J + 2\theta) \frac{\rho}{1+a}; 1 + \kappa; Y)| = \frac{1}{h^{1=3}} \int e^{i(Y - 4J=3 + \rho^2 - \kappa)} e^{i(\rho^2 + 2\theta - \kappa) Ai(\rho^2 + 2\theta - \kappa)} d\rho$$

and from the discussion above, for θ, κ and M like in (40), the factor from the second line in (41), $e^{i(\rho^2 + 2\theta - \kappa) Ai(\rho^2 + 2\theta - \kappa)}$, may be seen as part of the symbol (it does not oscillate). With (39) holding, we move $e^{i(\rho^2 - \kappa)}$ into the symbol as well. The (remaining) phase in (41) is $(Y - 4J=3)$ and therefore Y takes values in a ball of center $4J=3$ and radius 1 .

We now fix the heuristic assuming that G could be replaced by G_0 and there is no symbol; note that we obtained an additional condition on M , that is $M \geq 1 = 3$. In the next lemma we prove the difference between $I(\mathbb{P}; \mathcal{X}; \cdot)$ in (33) and $e^{jB(\cdot)} I_0(\mathbb{P}; \mathcal{X}; \cdot)$ with $I_0(\mathbb{P}; \mathcal{X}; \cdot)$ given in (35) to be lower order:

Lemma 5. — The following holds

$$I(\mathbb{P}; \mathcal{X}; \cdot) = e^{jB(\cdot)} I_0(\mathbb{P}; \mathcal{X}; \cdot) + O(M^{-2\epsilon} = (1 - 2\epsilon));$$

Remark 3.7. — In the next section we will take $M \geq 1 = 3$, and later $M \geq 1 = 6$, both of which produce a lower order remainder for all $0 < \epsilon < 1 = 6$.

Proof. — Let us define $C(\cdot) = j^{\mathbb{P}} \int_{\mathbb{R}^d} |j - a_j|^{-6} (1 - \epsilon)^{-2}$, with small $\epsilon > 0$. From (33) and Remark 3.5,

$$I(\mathbb{P}; \mathcal{X}; \cdot) = \int_{C(\cdot)} e^{jG(\cdot; \mathbb{P}; \mathcal{X})} \zeta_j(\cdot) d + O(1^{-1});$$

Replacing ζ_j in the last integral by (31) yields

$$I(\mathbb{P}; \mathcal{X}; \cdot) = \int_{C(\cdot)} e^{jG(\cdot; \mathbb{P}; \mathcal{X})} e^{jB(E(\mathbb{E}_c(\cdot))^{3=2})} 1 + O(J = \cdot) d + O(1^{-1});$$

The last integral can be re-arranged as follows

$$\begin{aligned} (42) \quad & \int_{C(\cdot)} e^{jB(\cdot)} e^{jG_0(\cdot; \mathbb{P}; \mathcal{X})} e^{j(G - G_0)(\cdot; \mathbb{P}; \mathcal{X})} \\ & e^{j(B(E(\mathbb{E}_c(\cdot))^{3=2}) - B(\cdot))} 1 + O(J = \cdot) d \\ = & \int_{C(\cdot)} e^{jG_0(\cdot; \mathbb{P}; \mathcal{X})} \\ & e^{j(G - G_0)(\cdot; \mathbb{P}; \mathcal{X})} e^{j(B(E(\mathbb{E}_c(\cdot))^{3=2}) - B(\cdot))} 1 + O(J = \cdot) d \\ & + \int_{C(\cdot)} e^{jB(\cdot)} e^{jG_0(\cdot; \mathbb{P}; \mathcal{X})} d ; \end{aligned}$$

As

$$I_0(\mathbb{P}; \mathcal{X}; \cdot) = \int_{C(\cdot)} e^{jG_0(\cdot; \mathbb{P}; \mathcal{X})} d + O(1^{-1});$$

the third line of (42) is nothing but $e^{jB(\cdot)} I_0(\mathbb{P}; \mathcal{X}; \cdot) + O(1^{-1})$. It remains to evaluate the integral in the second line of (42). Using (34) and (36), we have, as $|j - a_j|^{-1} = M^{-1}$,

$$jG - G_0(\cdot; \mathbb{P}; \mathcal{X}) = \frac{(1 + a)}{2} \frac{(\mathbb{P} - \cdot)^2}{M |j - a_j|} O \frac{j^{\mathbb{P}} - j}{M |j - a_j|} \frac{j^{\mathbb{P}} - j^3}{M};$$

For $j^{\mathbb{P}} - j = M |j - a_j|^{-6} (1 - \epsilon)^{-2}$ we therefore have

$$e^{j(G - G_0)(\cdot; \mathbb{P}; \mathcal{X})} = 1 + \frac{j^{\mathbb{P}} - j^3}{M} (1 - 3\epsilon)^{-2};$$

As

$$J B(E(\mathbb{E}_c(\cdot))^{3=2}) - B(\cdot) = \frac{J}{j} \mathbb{E}_c j - \frac{J j^{\mathbb{P}} - j}{M};$$

Figure 1. Wave packet scales in space-time

we get

$$e^{iJ(B(E(\mathbb{P}_c(\cdot)))^{3=2})B(\cdot)} \cdot \frac{J}{(1-\cdot)^2}.$$

Therefore, with $\mathbb{P} := (1-\cdot)^2(\mathbb{P}) = (M_a)$, the integral in the second line of (42) is bounded with

$$M \int_{j\mathbb{P} \leq 1}^Z (\mathbb{P}^{(1-\cdot)^2})^3 + \frac{J}{(\mathbb{P}^{(1-\cdot)^2})} + \frac{J}{d\mathbb{P}} \cdot \frac{M}{1-\cdot} (\cdot + J) = \frac{M}{1-2\cdot};$$

as $J \leq M$, $\cdot = M$. We conclude as $M = 1-2\cdot = M^2 = 1-2\cdot$.

3.6. Choice of M and Strichartz norms for U . — Let $M > 4^{1=3}=c$ and $j\mathbb{P} \leq 6$, as well as $j\mathbb{X} \leq 6^{2=3}$, $j\mathbb{Y} := jY - 4J=3j \cdot 1$; from (41) we get

$$hjU((4J + 2\mathbb{P})^{1+a}; 1 + \mathbb{X}; 4J=3 + \mathbb{Y})j \cdot 1=3:$$

Recall that in the sum over N defining U there are at most M_a terms: summing over M_a intervals I_k of size \overline{M} gives

$$khUK_{L^q(0;M_a;L^1_{X,Y})} \cdot (M_a \overline{M})^{1=q} \cdot 1=3:$$

Asking moreover $M_a \overline{M} > 1$ gives $M_a^2 > M$, $M > M_a$. Recalling (16) and (24), we get a condition on :

$$(M_a \overline{M})^{1=q} \cdot 1=3 \cdot 1-1=q M_a^{(1=2-2=q)} \cdot 5=4 M^{1=4}$$

and it turns out that the best choice of parameters in order to maximize q is a $h^{1=3}$, $M = M_a^{1=3}$ which yields, for large \cdot , $q > 5$, e.g. $6-2=5$ and a loss $> 1=10$ at the endpoint $(5; 1)$.

We now compute the $L^r_{X;Y}$ norms for $r < +1$ while retaining the chosen values of a and M : for $j \in \mathbb{P}_j$, $1=3$, $T = 4J + \mathbb{P}$, we get that

$$\begin{aligned} \int_{X;Y} |jhU(T; X; Y)|^r dX dY &> \int_{X;Y} |jhU(T; X; Y)|^r dX dY \\ &\& \int_{X;Y} |jhU(T; X; Y)|^r dX dY \\ &\& \int_{X;Y} |jhU(T; X; Y)|^r dX dY \end{aligned}$$

Then, we have

$$\int_{I_J} \int_{X;Y} |jhU(T; X; Y)|^r dX dY \int_{\mathbb{P}_j} |jhU(T; X; Y)|^r dT > \int_{I_J} \int_{X;Y} |jhU(T; X; Y)|^r dX dY \int_{\mathbb{P}_j} |jhU(T; X; Y)|^r dT$$

and

$$\begin{aligned} \int_{J} \int_{I_J} \int_{X;Y} |jhU(T; X; Y)|^r dX dY \int_{\mathbb{P}_j} |jhU(T; X; Y)|^r dT &\& M_a \\ \int_{Z} \int_{M_a} \int_{X;Y} |jhU(T; X; Y)|^r dX dY \int_{\mathbb{P}_j} |jhU(T; X; Y)|^r dT &\& \end{aligned}$$

Recalling (16), we get

$$5=(3r) \ 1=3 \ . \ 1 \ 1=q \ 2=r \ (1=2 \ 1=r \ 2=q)=3 \ 5=4 \ 1=12$$

which translates into

$$\frac{5}{q} + \frac{2}{r} \geq 16 \ 0;$$

which is our statement (5). This proves Theorem 1.

We now consider a different choice of parameters: assume $h^{1=2}$ and retain $M \ M_a = h^{1=4} \ h^{=2}$. Then $M \ h^2$, we still have $j \in \mathbb{P}_j$, $2=3$ and $j \in \mathbb{P}_j$, 1 , but now $j \in \mathbb{P}_j$, h . Therefore we now get a condition on h that reads

$$1=q \ h^{=q} \ 5=(3r) \ 1=3 \ . \ 1 \ 1=q \ 2=r \ 1=2 \ 1=r \ 2=q \ 5=4 \ 1=4 \ h^{2" (3=4 \ 1=r \ 3=q)};$$

this turns out to match exactly the requirements from [3] (see Remark 1.7): for $(q; r)$ such that $r > 4$, we necessarily have, with a positive $C(\cdot)$ in the meaningful range,

$$\frac{3}{q} + \frac{1}{r} \geq 6 \ \frac{15}{24} \ "C(\cdot; q; r):$$

One may take $"$ to zero and rewrite this condition on $(q; r)$ to highlight its distance to the free space requirement:

$$\frac{1}{q} \geq 6 \ \frac{1}{2} \ \frac{1}{12} \ \frac{4=r}{24=r} \ \frac{1}{2} \ \frac{1}{r}$$

making clear the restriction $r > 4$ to be relevant as well as the loss $1=12$ for the $(q; 1)$ pair, e.g. $q > 24=5 > 4$.)

3.7. Higher dimensions. — In this section we prove Theorem 3 by taking advantage of the 2D example we just constructed: consider for simplicity, for $d > 3$, the isotropic model convex domain $\Omega = \{(x, y) \in \mathbb{R}^{1+d}; x > 0; y \in \mathbb{R}^d\}$ and $\mathcal{F} = \Delta_x + (1+x)\Delta_y$ with Dirichlet boundary condition (one may without loss of generality replace Δ_x by $xQ(y)$, where Q is a constant coefficient second order elliptic operator). Denote by $u(t; x; y_1)$ the solution to the 2D equation we previously constructed (in unscaled variables), and let ϕ be a smooth function from \mathbb{R}^{d-2} to \mathbb{R} such that ϕ is positive, has compact support in a ball of size one and $\phi = 1$ near the origin. We may moreover select such a bump function so that, for $y^0 \in \mathbb{R}^{d-2}$, $\phi(y^0) > 1/10$. Set $e_h(y^0) = h^{-(d-2)/4} \phi(y^0/h)$, which is L^2 normalized.

We seek a solution to the d -dimensional wave equation of the form

$$v(t; x; y_1; y^0) = u(t; x; y_1) e_h(y^0) + w(t; x; y);$$

with $w(0; x; y) = 0$. Plugging our ansatz into the wave equation, we get

$$(\Delta_x - \mathcal{F})w + h(y^0)(\Delta_x - (\Delta_x + (1+x)\Delta_y))u - u(t; x; y_1)(1+x)e_h(y^0) = 0;$$

The middle term vanishes: u is a solution to the 2D wave equation, and $e_h(y^0) = e_h(y^0) = e_h$, where e_h is again L^2 normalized. Therefore,

$$(\Delta_x - \mathcal{F})w = \frac{1}{h} u(t; x; y_1)(1+x)e_h(y^0);$$

If we denote by F the source term, w is the solution given by the Duhamel formula: if the wave equation satisfies a homogeneous Strichartz estimate with exponents $(q; r)$, then

$$\|h^{-1} \int_0^T (hD_t)w\|_{L^q([0;T];L^r)} \leq h \int_0^T \|kF\|_{L^2_{x,y}};$$

and therefore we have

$$\|h^{-1} \int_0^T (hD_t)w\|_{L^q([0;T];L^r)} \leq T \sup_t \|ku(t; x; y_1)(1+x)e_h(y^0)\|_{L^2_{x,y}} + T \|ku(0; x; y_1)\|_{L^2_{x,y_1}};$$

We are left with computing the $L^r_{y^0}$ norm of e_h : from its construction, we have $\|e_h\|_{L^r} = 1$ and by rescaling,

$$\|e_h\|_{L^r} = h^{-(d-2)/4} h^{(d-2)/2r} = h^{(1-r)(d-2)/2};$$

From

$$\|ku\|_{L^q_t L^r_{x,y_1}} \leq \|e_h\|_{L^r_{y^0}} \|k\|_{L^q_t L^r_{x,y}} \leq \|k\|_{L^q_t L^r_{x,y}}$$

and our computation from the 2D case in the case where $h^{1=2}$, together with $h^{1=4} \Rightarrow 3=2$, we eventually get the limiting condition

$$2(d-2) \frac{1}{2} \frac{1}{r} \frac{4}{q} \frac{4}{3r} + \frac{5}{6} \leq 0$$

in other words

$$\frac{1}{q} \leq \frac{d-1}{2} \frac{1}{12} \frac{4=r}{24=r} \frac{1}{2} \frac{1}{r};$$

which is the desired condition.

Remark 3.8. — The general philosophy is that of the usual Knapp counterexample: the main propagation is in the direction y_1 , and our wave packet has no time to decorrelate in transverse directions. A similar argument was used in [4] to extend the previous counterexamples from the 2D model to the general case of any strictly convex domain in higher dimensions.

Remark 3.9. — If one plugs the other case, $a = h^{1/3}$ and $M = h^{1/3}$ in the higher dimensional setting, it does not provide any interesting condition. The main difference appears to be that in that later case, the 2D counterexample is reaching its peak on very small subintervals (size $h^{1/3}$) whereas in the limiting sense, for $a = h^{1/2}$ and $M = h^{1/2}$, the constructed example maintains its peak on the whole time interval, like the usual Knapp counterexample.

Appendix. Complements on Airy and related functions

Well-known properties of Airy functions, including A_+ may be found on classical textbooks on special functions. The recent reference [16] provides an extensive review of such functions.

A.1. Proof of Lemma 1. — From A_+ being analytic with values in \mathbb{C} and never vanishing on the real line, there exist unique analytic functions $\rho(\xi) > 0$ and $\theta(\xi) \in \mathbb{R}$ such that $A_+(\xi) = \rho(\xi)e^{i\theta(\xi)}$. Then one has $A(\xi) = \rho(\xi)e^{-i\theta(\xi)}$ and, from its definition, $L(\xi) = \rho(\xi) + 2i\theta(\xi)$ is real on the real axis. Using (7), at $\xi = 0$ we find $A(0) = e^{-i/3} \text{Ai}(0)$ which yields $A(0) = A_+(0) = e^{-2i/3} = e^{2i/3}$, hence $L(0) = \rho(0) + 2i\theta(0) = 3$. As $\text{Ai}(\xi) = \frac{1}{2} A(\xi) + \frac{1}{2} A_+(\xi) = \rho(\xi) \cos(\theta(\xi))$, [16, (2.87), (2.104), (2.106)] yields asymptotic expansions for ρ and θ as $|\xi| \rightarrow +\infty$:

$$\rho(\xi) \sim \sum_{k=0}^{\infty} \frac{1}{k!} \xi^{-3k}; \quad \theta(\xi) \sim \frac{1}{4} \sum_{k=0}^{\infty} \frac{2}{3!} \xi^{3-2k}; \quad \rho(0) = 1; \quad \theta(0) = \frac{5\pi}{32}$$

The last formula yields $L(\xi) = \rho(\xi) + 2i\theta(\xi) = \frac{4}{3} \xi^{3/2} + \dots = 2 B(\xi^{3/2})$, where we set

$$B(\xi^{3/2}) = \sum_{k>1} \frac{4}{3!} \xi^{3-2k}$$

Setting $b_{2k-1} := \frac{4}{3} k$ and $b_{2k} = 0$ yields (9) with $b_1 = 5/24 > 0$. From [16, (2.95)] we have moreover $(\rho(\xi))^2 \theta(\xi) = 1$: this yields $L(\xi) = 2\theta(\xi) = 1/2 \rho(\xi) > 0$, hence L is strictly increasing. Set $A(\xi) = \text{Ai}(\xi)$, then $A(\xi) = \rho(\xi) \cos(\theta(\xi))$. Therefore, $A(\xi) = 0$ is equivalent to $\theta(\xi) = \pi/2 + \dots$, $\pi/2 + 2\pi Z$, which is equivalent to $L(\xi) = 2(\pi/2 + \dots)$. From L being a diffeomorphism from \mathbb{R} onto $(0; +\infty)$, one has that for all integer $k > 1$, $\text{Ai}(\xi_k) = 0$ if and only if $L(\xi_k) = 2\pi k$.

Finally, using the Airy equation $A''(z) + zA(z) = 0$ and integrating by parts, we get

$$\int_0^1 \text{Ai}^2(x) dx = \int_1^Z A^2(z) dz = \frac{1}{2} A^2(Z) - \int_1^Z 2zA(z)A'(z) dz = \frac{1}{2} A^2(Z) + \int_1^Z 2A''(z)A'(z) dz = \frac{1}{2} A^2(Z) + A'(Z)A'(1)$$

From $A^{(k)} = 2^{-k} \cos(2^{-k}) + 2^{-k} \sin(2^{-k})$, as well as $A^{(k)} = 2^{-k} \cos(2^{-k}) = 0$ (therefore $\sin(2^{-k}) = 2^{-k}$), we get using $(2^{-k})^2 = 2^{-2k}$, $L^{(k)} = 2^{-k}$

$$\int_0^1 A^{(k)} dx = A^{(k)} = Ai^{(k)} = 4^{-k} A^{(k)} = \frac{L^{(k)}}{2};$$

thus the last assertion in (10) holds true. The proof of Lemma 1 is complete.

A.2. Proof of Lemma 2. — Using the Airy equation we just recalled, one easily checks that $(e_k)_k$ are the eigenfunctions of $\partial_x^2 + (1+x)^2$ with Dirichlet boundary condition at $x = 0$, associated with eigenvalues λ_k . It will be enough to prove that they form an orthogonal family on $L^2(\mathbb{R}_+)$. In order to do so, we use well-known formulas for Airy functions: in particular, it follows from [16, (3.53)] that

$$\frac{d}{dx} \frac{Ai'(x+\lambda_1) Ai(x+\lambda_2) - Ai(x+\lambda_1) Ai'(x+\lambda_2)}{(\lambda_1 - \lambda_2)^2} = Ai(x+\lambda_1) Ai(x+\lambda_2);$$

Taking $\lambda_1 = \lambda_k, \lambda_2 = \lambda_j$ with $k \neq j$, we can therefore compute explicitly $\int_0^{+\infty} Ai(x+\lambda_k) Ai(x+\lambda_j) dx$ to get vanishing traces at $x = 0$ and $x = +\infty$, hence

$$\langle e_k, e_j \rangle_{L^2(\mathbb{R}_+)} = 0;$$

and this holds for all $k \neq j$.

A.3. Proof of Lemma 3. — Consider ϕ , a smooth, compactly supported, function defined for $\lambda \in \mathbb{R}$. The function $L(\phi)$ defines a one to one map from \mathbb{R} to \mathbb{R}_+ . Now define $\psi(x)$ for $x \in \mathbb{R}_+$ with

$$\psi(L(\lambda)) = \frac{1}{L'(\lambda)} \phi(\lambda);$$

We may extend ψ to be zero for $x \in \mathbb{R}$ and still retain a smooth, compactly supported function: there exists λ^* such that $\phi(\lambda) = 0$ if $|\lambda| > \lambda^*$, and we have $\psi(x) = 0$ for $x < L(\lambda^*)$, e.g. ψ is always supported on \mathbb{R}_+ . We apply the usual Poisson summation formula to ψ , which reads

$$\sum_{k \in \mathbb{Z}} \psi(2k) = \frac{1}{2} \sum_{n \in \mathbb{Z}} \int_{\mathbb{R}} e^{inx} \psi(x) dx;$$

Since ψ vanishes on \mathbb{R} , this becomes

$$\sum_{k \in \mathbb{N}} \psi(2k) = \frac{1}{2} \sum_{n \in \mathbb{Z}} \int_{\mathbb{R}_+} e^{inx} \psi(x) dx;$$

and we can now change variables with $x = L(\lambda)$:

$$\sum_{k \in \mathbb{N}} \psi(2k) = \frac{1}{2} \sum_{n \in \mathbb{Z}} \int_{\mathbb{R}} e^{i n L(\lambda)} \phi(\lambda) L'(\lambda) d\lambda;$$

and recalling that $L(\lambda_k) = 2^{-k}$ this reads

$$\sum_{k \in \mathbb{N}} \psi(L(\lambda_k)) = \frac{1}{2} \sum_{n \in \mathbb{Z}} \int_{\mathbb{R}} e^{i n L(\lambda)} \phi(\lambda) L'(\lambda) d\lambda;$$

Finally, with $L = L^0$,

$$\frac{1}{L^{\alpha}(\cdot)_k} = \frac{1}{2} \int_{\mathbb{R}^N} \frac{X^Z}{N 2^Z} e^{iNL(\cdot)}(\cdot) d!;$$

which is the desired formula.

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