

## ALGEBRAIC

## COMBINATORICS

Michael Joseph \& Tom Roby<br>Birational and noncommutative lifts of antichain toggling and rowmotion<br>Volume 3, issue 4 (2020), p. 955-984.<br>[http://alco.centre-mersenne.org/item/ALCO_2020__3_4_955_0](http://alco.centre-mersenne.org/item/ALCO_2020__3_4_955_0)

© The journal and the authors, 2020.
Some rights reserved.
(c) EY

This article is licensed under the
Creative Commons Attribution 4.0 International License.
http://creativecommons.org/licenses/by/4.0/

Access to articles published by the journal Algebraic Combinatorics on the website http://alco.centre-mersenne.org/ implies agreement with the Terms of Use (http://alco.centre-mersenne.org/legal/).


# Birational and noncommutative lifts of antichain toggling and rowmotion 

Michael Joseph \& Tom Roby


#### Abstract

The rowmotion action on order ideals or on antichains of a finite partially ordered set has been studied (under a variety of names) by many authors. Depending on the poset, one finds unexpectedly interesting orbit structures, instances of (small order) periodicity, cyclic sieving, and homomesy. Many of these nice features still hold when the action is extended to [ 0,1$]$-labelings of the poset or (via detropicalization) to labelings by rational functions (the birational setting).

In this work, we parallel the birational lifting already done for order-ideal rowmotion to antichain rowmotion. We give explicit equivariant bijections between the birational toggle groups and between their respective liftings. We further extend all of these notions to labellings by noncommutative rational functions, setting an unpublished periodicity conjecture of Grinberg in a broader context.


## 1. Introduction

Combinatorial rowmotion is a well-studied action on the set of order ideals $\mathcal{J}(P)$ or on the set of antichains $\mathcal{A}(P)$ of a finite poset $P$. It was first studied as a map on $\mathcal{A}(P)$ by Brouwer and Schrijver [2], and goes by several names. In recent literature, the name "rowmotion," due to Striker and Williams [27] (who summarize the history), has stuck. An updated historical survey is available in Thomas and Williams [28, § 7].

Rowmotion has proven to be of great interest in dynamical algebraic combinatorics. On several "nice" posets (e.g. positive root posets or minuscule posets, such as products of two chains), rowmotion exhibits various phenomena including periodicity (of a relatively small order), cyclic sieving (as defined by Reiner, Stanton, and White [20]), homomesy (where a natural statistic, e.g. cardinality, has the same average over every orbit) $[1,10,13,18,19,22,30,29]$, and resonance (see [4, 5]). Rowmotion is related to Auslander-Reiten translation on certain quivers [32].

Quite surprisingly, some of these features extend to the piecewise-linear (order polytope) level and can be lifted further to the birational level [6]. One sometimes gets periodicity of the same order as the combinatorial map, and often homomesy extends as well $[8,9,16]$. Just as one example, the file-cardinality homomesy for order-ideal rowmowtion on rectangular posets [19, Thm. 19ff] lifts to a birational homomesy [16, Thm. 2.16]; Rush and Wang's extension of this result to all minuscule posets [22, Thm. 1.2] has recently been lifted to the birational realm by S. Okada [17].

[^0]It is a continuing mystery why certain properties of combinatorial rowmotion on many families of posets lift to the birational realm. This question is still far from answered, but Hopkins has shown some properties must lift to the birational realm on posets which satisfy the tCDE property and have a grid-like structure [11]. Birational rowmotion is related to $Y$-systems of type $A_{m} \times A_{n}$ described in Zamolodchikov periodicity [21, § 4.4].

The lifting of order-ideal rowmotion (herein denoted $\rho_{\mathcal{J}}$ ) to BOR-motion (birational order rowmotion) proceeds by first writing $\rho_{\mathcal{J}}$ as a product of involutions called toggles, each of which acts on $\mathcal{J}(P)$, the set of order ideals of a poset. These toggles are then extended to Stanley's order polytope $\mathcal{O P}(P)$, and then lifted further to toggles at the birational level [6], following the lead of Kirillov and Berenstein [15]. Letting $\mathbb{K}$ be a field of characteristic zero, we lift from a piecewise-linear map to a birational map through detropicalization of operations. Any equality of rational expressions (such as periodicity or homomesy) that does not contain subtraction or additive inverses also holds in the piecewise-linear realm (by tropicalization) and furthermore in the combinatorial realm (by restriction); see [9, Remark 10].

As part of a broader study of toggling in general, Striker defined antichain toggles that act on $\mathcal{A}(P)[26]$. The first author gave an explicit isomorphism between these two different toggle groups (on $\mathcal{J}(P)$ and on $\mathcal{A}(P)$ ) for the same poset $P$, and extended these results to the piecewise-linear level [12], where $\mathcal{A}(P)$ extends to Stanley's chain polytope $\mathcal{C}(P)$ [23]. These toggles can be used to define the antichain rowmotion of [2] and its extension to all of $\mathcal{C}(P)$.

Our goal in this work is to study the parallel lifting of this map on $\mathcal{C}(P)$ to the birational level, which we call Birational Antichain Rowmotion or BAR-motion (Definition 3.4) for short. We construct equivariant bijections between this action and the previously studied BOR-motion, allowing us to deduce properties of one from the other. We also describe a noncommutative analogue of both these maps (the first originally discovered by Darij Grinberg, unpublished), and prove that these bijections extend even to this realm.

The paper is organized as follows. In Section 2, we include the necessary background on rowmotion at the combinatorial, piecewise-linear, and birational levels, including ways to view them as compositions of transfer maps and as products of toggles. This positions us in Section 3 to define birational antichain toggling and BAR-motion and construct the explicit bijection between the two different toggle groups at the birational level.

Section 4 contains our results that pertain specifically to graded posets, which are the only ones known thus far to exhibit homomesy or periodicity in the birational realm. Since toggles within the same rank commute with each other, we can toggle them "all at once". Toggling by ranks (hence the term "rowmotion") from top to bottom gives one map, but we can also toggle first all even ranks, then all odd ones, giving a map called gyration by Striker [25]. Grinberg and the second author worked with graded rescalings of poset labelings in several proofs in [8, 9]. We discuss the analogues of these ideas under the antichain perspective.

In Section 5, we lift our birational actions further to the noncommutative realm, where we do not assume commutativity of multiplication. This setting has not appeared in the literature before, but is based on unpublished definitions and conjectures of Darij Grinberg. In this paper, we show that NOR-motion (Noncommutative Order Rowmotion) and NAR-motion (Noncommutative Antichain Rowmotion) always exhibit the same order on any given finite poset. We use "noncommutative realm" as a short term, but we really mean "not-necessarily-commutative birational realm" as fields are skew fields.

We defer the proofs of several results in Section 3 since they follow from their noncommutative analogues in Section 5. (We originally proved the results in this realm before realizing we could extend them to the noncommutative setting.) Toggles are no longer involutions, so it is surprising that many other key properties do continue to hold (with suitably modified definitions), such as the isomorphism between the order and antichain toggle groups.

To summarize, we have four realms (combinatorial, piecewise-linear, birational, and noncommutative) and two rowmotion maps (order-ideal and antichain). Our new work here involves lifting the latter map to the birational and noncommutative realms, and giving explicit equivariant isomorphisms connecting these two maps at the two highest levels. Beyond the inherent interest of showing that Stanley's transfer maps between $\mathcal{O}(P)$ and $\mathcal{C}(P)$ lift nicely to the birational and noncommutative birational settings, we hope that having different approaches to these maps will help shed light on some of their tantalizing properties. In particular, on several minuscule and root posets, BOR-motion has the same order as combinatorial order-ideal rowmowtion, and this is conjectured to extend to NOR-motion as well. Our results show that a proof for NAR-motion would automatically imply it for NOR-motion as well.

To prove refined versions of homomesy in the product of two chain posets, J. Propp and the second author used an equivariant bijection discovered (less formally) by R. Stanley and H. Thomas [19, § 7]. In a separate paper [14] we explore the lifting of this "Stanley-Thomas word" to the piecewise-linear, birational, and noncommutative realms. Although the map is no longer a bijection, so cannot be used to prove periodicity directly, it still gives enough information to prove the homomesy at the piecewise-linear and birational levels (a result previously shown by D. Grinberg, S. Hopkins, and S. Okada). Even at the noncommutative level, the Stanley-Thomas word of a poset labeling rotates cyclically with the lifting of antichain rowmotion.

## 2. Rowmotion in the combinatorial, PiECEWISE-LINEAR, AND BIRATIONAL REALMS

This section contains the necessary background for this paper. We discuss the toggle group of a poset $P$, rowmotion on order ideals and on antichains, and define their generalizations to the piecewise-linear realm. We also discuss the lifting of orderideal rowmotion to the birational realm. Our new results begin in Section 3 with the birational lifting of antichain rowmotion.
2.1. Rowmotion in the combinatorial realm. We assume familiarity with basic notions from the theory of posets, as discussed in [24, Ch. 3]. Throughout this paper $P$ will denote a finite poset.

Following the notation of Einstein-Propp [6], we can define rowmotion via the following natural bijections between the set $\mathcal{J}(P)$ of all order ideals of $P$, the set $\mathcal{F}(P)$ of all order filters of $P$, and the set $\mathcal{A}(P)$ of all antichains of $P$.

- The map $\Theta: 2^{P} \rightarrow 2^{P}$ where $\Theta(S)=P \backslash S$ is the complement of $S$ (so $\Theta$ sends order ideals to order filters and vice versa).
- The up-transfer $\Delta: \mathcal{J}(P) \rightarrow \mathcal{A}(P)$, where $\Delta(I)$ is the set of maximal elements of $I$. For an antichain $A \in \mathcal{A}(P), \Delta^{-1}(A)=\{x \in P: x \leqslant y$ for some $y \in A\}$ ("downward saturation").
- The down-transfer $\nabla: \mathcal{F}(P) \rightarrow \mathcal{A}(P)$, where $\nabla(F)$ is the set of minimal elements of $F$. For an antichain $A \in \mathcal{A}(P), \nabla^{-1}(A)=\{x \in P: x \geqslant$ $y$ for some $y \in A\}$ ("upward saturation").
Definition 2.1. Order-ideal rowmotion is the map $\rho_{\mathcal{J}}: \mathcal{J}(P) \rightarrow \mathcal{J}(P)$ given by the composition $\rho_{\mathcal{J}}=\Delta^{-1} \circ \nabla \circ \Theta$. Antichain rowmotion is the map $\rho_{\mathcal{A}}: \mathcal{A}(P) \rightarrow \mathcal{A}(P)$
given by the composition $\rho_{\mathcal{A}}=\nabla \circ \Theta \circ \Delta^{-1}$. Order-filter rowmotion is the map $\rho_{\mathcal{F}}$ : $\mathcal{F}(P) \rightarrow \mathcal{F}(P)$ given by the composition $\rho_{\mathcal{F}}=\Theta \circ \Delta^{-1} \circ \nabla$.

Example 2.2. Below we show examples of $\rho_{\mathcal{J}}$ and $\rho_{\mathcal{A}}$ on the positive root poset $\Phi^{+}\left(A_{3}\right)$. In each step, the elements of the subset of the poset are given by the filled-in circles.
$\rho_{\mathcal{J}}:$

$\rho_{\mathcal{A}}:$

2.2. The order-ideal toggle group. The map $\rho_{\mathcal{J}}$ can also be written as a composition of involutions on $\mathcal{J}(P)$ called toggles, as first shown by Cameron and Fon-Der-Flaass [3].

Definition 2.3 ([3]). For $v \in P$, the order-ideal toggle corresponding to $v$ is the map $T_{v}: \mathcal{J}(P) \rightarrow \mathcal{J}(P)$ defined by

$$
T_{v}(I)= \begin{cases}I \cup\{v\} & \text { if } v \notin I \text { and } I \cup\{v\} \in \mathcal{J}(P), \\ I \backslash\{v\} & \text { if } v \in I \text { and } I \backslash\{v\} \in \mathcal{J}(P), \\ I & \text { otherwise. }\end{cases}
$$

Let $\operatorname{Tog}_{\mathcal{J}}(P)$ denote the toggle group of $\mathcal{J}(P)$, i.e. the subgroup of $\mathfrak{S}_{\mathcal{J}(P)}$ (the symmetric group on $\mathcal{J}(P))$ generated by the toggles $\left\{T_{v}: v \in P\right\}$.

The toggle $T_{v}$ either adds or removes $v$ from the order ideal if the resulting set is still an order ideal, and otherwise does nothing.

Definition $2.4([24, \S 3.5])$. A sequence $\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ containing all of the elements of a finite poset $P$ exactly once is called a linear extension of $P$ if it is order-preserving, that is, whenever $x_{i}<x_{j}$ in $P$ then $i<j$.

Proposition 2.5 ([3]). For any linear extension $\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ of $P$, order-ideal rowmotion is given by $\rho_{\mathcal{J}}=T_{x_{1}} T_{x_{2}} \cdots T_{x_{n}}$.

Example 2.6. For the poset $P=[2] \times[3]$ of Example 2.2, as labeled below, $(a, b, c, d, e, f)$ gives a linear extension. We show the effect of applying $T_{a} T_{b} T_{c} T_{d} T_{e} T_{f}$ to the order ideal considered in Example 2.2. In each step, we indicate the element whose toggle we apply next in red. Notice that the outcome is the same order ideal we obtained by the three step process in Example 2.2, demonstrating Proposition 2.5.

2.3. The antichain toggle group. Toggling makes sense in a broader context, as formalized by Striker [26]. We can define antichain toggles on $\mathcal{A}(P)$, by replacing $\mathcal{J}(P)$ with $\mathcal{A}(P)$ in the definition. Removing any element from an antichain always yields an antichain, giving a simpler second case.

Definition 2.7 ([26]). Let $v \in P$. Then the antichain toggle corresponding to $v$ is the map $\tau_{v}: \mathcal{A}(P) \rightarrow \mathcal{A}(P)$ defined by

$$
\tau_{v}(A)= \begin{cases}A \cup\{v\} & \text { if } v \notin A \text { and } A \cup\{v\} \in \mathcal{A}(P) \\ A \backslash\{v\} & \text { if } v \in A \\ A & \text { otherwise }\end{cases}
$$

Let $\operatorname{Tog}_{\mathcal{A}}(P)$ denote the toggle group of $\mathcal{A}(P)$, i.e. the subgroup of $\mathfrak{S}_{\mathcal{A}(P)}$ (the symmetric group on $\mathcal{A}(P))$ generated by the toggles $\left\{\tau_{v}: v \in P\right\}$.

The first author constructed an explicit isomorphism between the toggle groups $\operatorname{Tog}_{\mathcal{J}}(P)$ and $\operatorname{Tog}_{\mathcal{A}}(P)$ [12]. A consequence of this isomorphism is that antichain rowmotion is also a product of antichain toggles in an order specified by a linear extension, but starting at the bottom and moving upwards.

Proposition 2.8 ([12, Prop. 2.24]). For any linear extension $\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ of $P$, antichain rowmotion is given by $\rho_{\mathcal{A}}=\tau_{x_{n}} \cdots \tau_{x_{2}} \tau_{x_{1}}$.

Example 2.9. For the poset $P=[2] \times[3],(a, b, c, d, e, f)$ gives a linear extension. We show the effect of applying $\tau_{f} \tau_{e} \tau_{d} \tau_{c} \tau_{b} \tau_{a}$ to the order ideal considered in Example 2.2. In each step, we indicate the element whose toggle we apply next in red. Notice that the outcome is the same order ideal we obtained by the three step process in Example 2.2, demonstrating Proposition 2.8.

2.4. Piecewise-Linear dynamics. Now we generalize our actions from subsets of $P$ (i.e. $\{0,1\}$-labelings of $P$ ) to $\mathbb{R}$-labelings of the elements of $P$; let $\mathbb{R}^{P}:=\{f: P \rightarrow$ $\mathbb{R}\}$ denote the set of such labelings. The toggling perspective allows us to extend these maps from the combinatorial realm (on finite sets) to the piecewise-linear realm (polytopes whose vertices correspond to these sets), and then lift to the birational realm by detropicalizing the operations [6]. The study of piecewise-linear dynamics begins with two polytopes introduced by Stanley [23], the order polytope and the chain polytope of $P$. The vertices of these polytopes are the sets $\mathcal{F}(P)$ of order filters and $\mathcal{A}(P)$ of antichains (associating a subset of $P$ with its indicator function labeling). Einstein and Propp defined piecewise-linear toggle operations on the order polytope that match the order-ideal toggle $T_{v}$ when restricted to the vertices (though here we use order filters instead of order ideals) $[6, \S 3,4]$.

Definition $2.10([23])$. Within $\mathbb{R}^{P}$ the order polytope of $P$ is the set $\mathcal{O P}(P)$ of labelings $f: P \rightarrow[0,1]$ that are order-preserving (i.e. if $a \leqslant b$ in $P$, then $f(a) \leqslant f(b)$ ). The chain polytope of $P$ is the set $\mathcal{C}(P)$ of labelings $f: P \rightarrow[0,1]$ such that the sum of the labels across every chain is at most 1 .

By associating a subset of $P$ with its indicator functions, the sets $\mathcal{F}(P)$ and $\mathcal{A}(P)$ describe the vertices of $\mathcal{O P}(P)$ and $\mathcal{C}(P)$ respectively [23]. Similarly, we can define an order-reversing polytope $\mathcal{O} \mathcal{R}(P)$ to consist of all labelings $f: P \rightarrow[0,1]$ that are order-reversing (i.e. if $a \leqslant b$ in $P$, then $f(a) \geqslant f(b)$ ). The vertices of $\mathcal{O} \mathcal{R}(P)$ are the order ideals of $P$. To define toggles, there is no important difference in defining them over $\mathcal{O} \mathcal{R}(P)$ as opposed to $\mathcal{O} \mathcal{P}(P)$. The piecewise-linear order toggles are typically defined on $\mathcal{O P}(P)$.

Definition 2.11 ([6]). Given a finite poset $P$, let $\widehat{P}$ denote the poset $P$ with the addition of two elements, $\widehat{0}$ and $\widehat{1}$, satisfying $\widehat{0}<v$ and $\widehat{1}>v$ for all $v \in P$. Let $v \in P$ and $f \in \mathcal{O P}(P)$. The piecewise-linear order toggle $T_{v}: \mathcal{O P}(P) \rightarrow \mathcal{O P}(P)$ is

$$
\left(T_{v}(f)\right)(x)= \begin{cases}f(x) & \text { if } x \neq v \\ \max _{y \lessdot v} f(y)+\min _{y \gtrdot v} f(y)-f(v) & \text { if } x=v\end{cases}
$$

where we set $f(\widehat{0})=0$ and $f(\widehat{1})=1$. We use the notation $x \lessdot y$ to mean " $y$ covers $x$ " and $x \gtrdot y$ to mean " $x$ covers $y$ ". By using cover relations in $\widehat{P}$ we ensure that every element of $P$ covers some element of $\widehat{P}$ and is covered by an element of $\widehat{P}$. The effect of this involution at $x=v$ is to replace the label at $v$ with the value obtained by reflecting the allowable $\mathbb{R}$-interval $\left[\max _{y \lessdot v} f(y), \min _{y \gtrdot v} f(y)\right]$ through its midpoint.

The first author defined the following generalization of antichain toggles to the chain polytope $\mathcal{C}(P)[12, \S 3]$, which matches our earlier definition of $\tau_{v}$ when restricted to the vertices $\mathcal{A}(P)$.

Definition $2.12([12])$. For $v \in P$, let $\mathrm{MC}_{v}(P)$ denote the set of all maximal chains of $P$ through $v$. The piecewise-linear antichain toggle (or chain polytope toggle) $\tau_{v}$ : $\mathcal{C}(P) \rightarrow \mathcal{C}(P)$ is

$$
\left(\tau_{v}(g)\right)(x)= \begin{cases}1-\max \left\{\sum_{i=1}^{k} g\left(y_{i}\right) \mid\left(y_{1}, \ldots, y_{k}\right) \in \mathrm{MC}_{v}(P)\right\} & \text { if } x=v \\ g(x) & \text { if } x \neq v\end{cases}
$$

We have the following generalizations of complementation $\Theta$, down-transfer $\nabla$, and up-transfer $\Delta$ (and their inverses) to the piecewise-linear realm. In fact the term "down-transfer" was chosen as it is equivalent here to Stanley's transfer map, used to transfer properties (such as volume formulas) between $\mathcal{C}(P)$ and $\mathcal{O P}(P)$ [23].

Definition 2.13 ( $[6, \S 4]$ ). The maps $\Theta: \mathbb{R}^{P} \rightarrow \mathbb{R}^{P}, \nabla: \mathcal{O} \mathcal{P}(P) \rightarrow \mathcal{C}(P), \Delta:$ $\mathcal{O} \mathcal{R}(P) \rightarrow \mathcal{C}(P)$, and their inverses are given as follows.

$$
\begin{aligned}
(\Theta f)(x) & =1-f(x) \\
(\nabla f)(x) & =f(x)-\max _{y \lessdot x} f(y) \quad(\text { with } f(\widehat{0})=0) \\
(\Delta f)(x) & =f(x)-\max _{y \gtrdot x} f(y) \quad(\text { with } f(\widehat{1})=0) \\
\left(\nabla^{-1} f\right)(x) & =\max \left\{f\left(y_{1}\right)+f\left(y_{2}\right)+\cdots+f\left(y_{k}\right): \widehat{0} \lessdot y_{1} \lessdot y_{2} \lessdot \cdots \lessdot y_{k}=x\right\} \\
& =f(x)+\max _{y \lessdot x}\left(\nabla^{-1} f\right)(y) \\
\left(\Delta^{-1} f\right)(x) & =\max \left\{f\left(y_{1}\right)+f\left(y_{2}\right)+\cdots+f\left(y_{k}\right): x=y_{1} \lessdot y_{2} \lessdot \cdots \lessdot y_{k} \lessdot \widehat{1}\right\} \\
& =f(x)+\max _{y \gtrdot x}\left(\Delta^{-1} f\right)(y) .
\end{aligned}
$$

For any linear extension $\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ of $P$, Einstein and Propp showed that piecewise-linear order rowmotion defined as $T_{x_{1}} T_{x_{2}} \cdots T_{x_{n}}$ is equivalent to the composition $\Theta \circ \Delta^{-1} \circ \nabla$ (a consequence of their proof at the birational level). The first author showed that piecewise-linear antichain rowmotion can be defined either as $\tau_{x_{n}} \cdots \tau_{x_{2}} \tau_{x_{1}}$ or as $\nabla \circ \Theta \circ \Delta^{-1}$, as in the combinatorial realm. For details, see $[6, \S 4$, § 6] and [12, § 3.3, § 3.4].
2.5. Birational dynamics. We now detropicalize the piecewise-linear order toggles to birational toggles over an arbitrary field $\mathbb{K}$ of characteristic zero in the usual way: replacing the max operation with addition, addition with multiplication, subtraction with division, and the additive identity 0 with the multiplicative identity 1 . Additionally, we replace 1 with a generic fixed constant $C \in \mathbb{K}$. (The definition in [6] is slightly more general than we need here; set $\alpha=1$ and $\omega=C$ in their version to get ours. In this paper, we will be primarily interested in birational antichain rowmotion, in which the two arbitrary constants $\alpha$ and $\omega$ would always appear together as $\omega / \alpha$; thus, one constant $C$ is sufficient.)
Definition 2.14 ([6, Definition 5.1]). Let $\mathbb{K}^{P}:=\{f: P \rightarrow \mathbb{K}\}$ be the set of $\mathbb{K}$-labelings of the elements of $P$. For $v \in P$, the birational order toggle at $v$ is the birational map $T_{v}: \mathbb{K}^{P} \rightarrow \mathbb{K}^{P}$ given by

$$
\left(T_{v}(f)\right)(x)= \begin{cases}f(x) & \text { if } x \neq v \\ \sum_{\frac{y \in \mathcal{P}, y<v}{f(v)} \sum_{y \in \widehat{P}, y>v} \frac{1}{f(y)}} \quad \text { if } x=v\end{cases}
$$

where we set $f(\widehat{0})=1$ and $f(\widehat{1})=C$.
The birational order toggles $\left\{T_{v}: v \in P\right\}$ generate the birational order toggle group, a subgroup of the group of birational automorphisms of $\mathbb{K}^{P}$, which we denote BTog $_{O}(P)$. The following shows that basic properties of order-ideal toggles lift to the birational realm.
Proposition 2.15 ([6, 8]). Each toggle $T_{v}$ is an involution (i.e. $T_{v}^{2}$ is the identity). Two toggles $T_{u}, T_{v}$ commute if and only if neither $u$ nor $v$ covers the other.

Definition 2.16 ([6, Definition 5.2]). Let $\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ be any linear extension of $P$. The birational analogue of order filter rowmotion, which we will call birational order rowmotion (or BOR-motion), is $\mathrm{BOR}=T_{x_{1}} T_{x_{2}} \cdots T_{x_{n}}$. (Compare with Proposition 2.5.)

An annoying technicality here is that for some choices of labels it is possible that these maps could lead to division by zero. But for "generic" choices of labels (say with respect to the Zariski topology) iterates of this map will be well-defined. This is discussed carefully in $[9, \S 1]$ and $[8, \S 3]$. Alternatively, Einstein and Propp make the choice to consider only positive labelings, i.e. $\left(\mathbb{R}_{>0}\right)^{\widehat{P}}$.
2.6. Birational transfer maps. By detropicalizing the operations in the transfer maps of the previous subsection, we get their birational analogues. Einstein and Propp prove $[6, \S 6]$ that, under the definitions below, $\mathrm{BOR}=\Theta \circ \Delta^{-1} \circ \nabla$. These maps are composed in the order which lifts combinatorial rowmotion on order filters.
Definition $2.17([6, \S 6])$. Let $f \in \mathbb{K}^{P}$ and $x \in P$. We define the following birational maps. Again, we call $\Theta$ complement, $\nabla$ down transfer, and $\Delta$ up transfer.

$$
\begin{aligned}
& (\Theta f)(x)=\frac{C}{f(x)} \\
& (\nabla f)(x)=\frac{f(x)}{\sum_{y<x} f(y)} \quad(\text { with } f(\widehat{0})=1) \\
& (\Delta f)(x)=\frac{f(x)}{\sum_{y>x} f(y)} \quad(\text { with } f(\widehat{1})=1)
\end{aligned}
$$

$$
\begin{aligned}
& \left(\nabla^{-1} f\right)(x)=\sum_{\widehat{0}<y_{1} \lessdot y_{2} \lessdot \cdots \lessdot y_{k}=x} f\left(y_{1}\right) f\left(y_{2}\right) \cdots f\left(y_{k}\right)=f(x) \sum_{y \lessdot x}\left(\nabla^{-1} f\right)(y) \\
& \left(\Delta^{-1} f\right)(x)=\sum_{x=y_{1} \lessdot y_{2} \lessdot \cdots \lessdot y_{k} \lessdot \widehat{1}} f\left(y_{1}\right) f\left(y_{2}\right) \cdots f\left(y_{k}\right)=f(x) \sum_{y \gtrdot x}\left(\Delta^{-1} f\right)(y) .
\end{aligned}
$$

We use the same symbols in each realm (combinatorial, piecewise-linear, birational, and noncommutative), allowing context to clarify which is meant. Examples of each $\operatorname{map} \nabla, \nabla^{-1}, \Delta$, and $\Delta^{-1}$ are given in Figure 1.


Figure 1. An example of each of the birational maps $\nabla, \nabla^{-1}, \Delta$, and $\Delta^{-1}$ on the positive root poset $\Phi^{+}\left(A_{3}\right)$.

## 3. Birational antichain toggling and rowmotion

3.1. The birational antichain toggle group. Now we will combine the different generalizations of toggling and study a new birational analogue of antichain toggling and rowmotion. Again, we fix a field $\mathbb{K}$ of characteristic zero. In the combinatorial realm, we could define rowmotion on $\mathcal{J}(P)$ or $\mathcal{A}(P)$ either as a composition of the three maps $\Theta, \Delta^{-1}$, and $\nabla$ (as is commonly done) or in terms of toggles, since these approaches are proven equivalent. BOR is usually defined in terms of toggles, and we take the analogous approach to defining BAR below, lifting the definition in Proposition 2.8.

Definition 3.1. For $v \in P$ and $g \in \mathbb{K}^{P}$, set

$$
\Upsilon_{v} g=\sum_{\left(y_{1}, \ldots, y_{k}\right) \in \mathrm{MC}_{v}(P)} g\left(y_{1}\right) \cdots g\left(y_{k}\right)
$$

where we recall $\mathrm{MC}_{v}(P)$ is the set of all maximal chains of $P$ through $v$.
Definition 3.2. Let $v \in P$. The birational antichain toggle is the birational map $\tau_{v}: \mathbb{K}^{P} \longrightarrow \mathbb{K}^{P}$ defined as follows:

$$
\left(\tau_{v}(g)\right)(x)= \begin{cases}\frac{C}{\sum_{\left(y_{1}, \ldots, y_{k}\right) \in \mathrm{MC}_{v}(P)} g\left(y_{1}\right) \cdots g\left(y_{k}\right)}=\frac{C}{\Upsilon_{v} g} & \text { if } x=v \\ g(x) & \text { if } x \neq v\end{cases}
$$

This definition is what is obtained from Definition 2.12 through detropicalization of operations. As with antichain toggles in the combinatorial and piecewise-linear realms [26, 12], birational antichain toggles do not commute as frequently as order toggles.

Proposition 3.3. Let $u, v \in P$.
(a) Each toggle $\tau_{v}$ is an involution, i.e. $\tau_{v}^{2}$ is the identity.
(b) If $u \| v$ (i.e. $u$ and $v$ are incomparable), then $\tau_{u} \tau_{v}=\tau_{v} \tau_{u}$.

Proof. (a) Let $g \in \mathbb{K}^{P}$ be a generic labeling. To show $\tau_{v}$ is an involution, we wish to show $\tau_{v}^{2}(g)=g$. Since $\tau_{v}$ can only change the label at $v$, we need only show $\left(\tau_{v}^{2}(g)\right)(v)=g(v)$. Every chain in $\mathrm{MC}_{v}(P)$ can be split into segments: below $v, v$ itself, and above $v$. As we can take the sums of products on each segment,

$$
\begin{equation*}
\left(\tau_{v}(g)\right)(v)=\frac{C}{\left(\sum_{u \lessdot v}\left(\nabla^{-1} g\right)(v)\right) g(v)\left(\sum_{u \gtrdot v}\left(\Delta^{-1} g\right)(v)\right)} \tag{1}
\end{equation*}
$$

for any $g \in \mathbb{K}^{P}$. In Eq. (1), we regard $\sum_{u \lessdot v}\left(\nabla^{-1} g\right)(v)=1$ if $v$ is minimal in $P$ and likewise $\sum_{u \gtrdot v}\left(\Delta^{-1} g\right)(v)=1$ if $v$ is maximal in $P$ (since the sums are nonempty when working in $\widehat{P}$ ).

Using Eq. (1),

$$
\begin{aligned}
\left(\tau_{v}^{2}(g)\right)(v) & =\frac{C}{\left(\sum_{u \lessdot v}\left(\nabla^{-1} \tau_{v}(g)\right)(v)\right)\left(\tau_{v}(g)\right)(v)\left(\sum_{u \gtrdot v}\left(\Delta^{-1} \tau_{v}(g)\right)(v)\right)} \\
& =\frac{C}{\left(\sum_{u \lessdot v}\left(\nabla^{-1} g\right)(v)\right) \frac{C}{\left(\sum_{u \lessdot v}\left(\nabla^{-1} g\right)(v)\right) g(v)\left(\sum_{u \gtrdot v}\left(\Delta^{-1} g\right)(v)\right)}\left(\sum_{u \gtrdot v}\left(\Delta^{-1} g\right)(v)\right)} \\
& =g(v)
\end{aligned}
$$

(b) Suppose $u \| v$. Only the label of $u$ can be changed by $\tau_{u}$ and only the label of $v$ can be changed by $\tau_{v}$. No chain contains both $u$ and $v$, so the label of $u$ has no effect on what $\tau_{v}$ does and the label of $v$ has no effect on what $\tau_{u}$ does. So $\tau_{u} \tau_{v}=\tau_{v} \tau_{u}$.

Proposition 3.3 shows that the following definition is well-defined, since any two linear extensions of a poset differ by a sequence of transpositions of incomparable elements [7].

Definition 3.4. Let $\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ be any linear extension of a finite poset $P$. Then the birational map $\mathrm{BAR}=\tau_{x_{n}} \cdots \tau_{x_{2}} \tau_{x_{1}}$, i.e. toggling once at each element of $P$ from bottom to top, is called birational antichain rowmotion (BAR-motion).

Example 3.5. Consider the poset $P=[2] \times[3]$ below, with the generic labeling $g \in \mathbb{K}^{P}$ by $u, v, w, x, y, z \in \mathbb{K}$.



To compute BAR along the linear extension $(1,1),(2,1),(1,2),(2,2),(1,3),(2,3)$, we first toggle at $(1,1)$. There are three maximal chains through this bottom element:

- $(1,1) \lessdot(2,1) \lessdot(2,2) \lessdot(2,3)$ with product of labels $u v x z$;
- $(1,1) \lessdot(1,2) \lessdot(2,2) \lessdot(2,3)$ with product of labels $u w x z$;
- $(1,1) \lessdot(1,2) \lessdot(1,3) \lessdot(2,3)$ with product of labels uwyz.

For $\Upsilon_{(1,1)} g$, we add up the products of the labels on these three maximal chains, and get $u v x z+u w x z+u w y z=u(v x+w x+w y) z$. Then to apply the toggle $\tau_{(1,1)}$, we change the label of $(1,1)$ from $u$ to $\frac{C}{u(v x+w x+w y) z}$.


Now we apply $\tau_{(2,1)}$ to $\tau_{(1,1)} g$ (our above result). There is only one maximal chain through $(2,1)$. The product of labels along that maximal chain is $\Upsilon_{(2,1)}\left(\tau_{(1,1)} g\right)=$ $\frac{C}{u(v x+w x+w y) z} v x z$. Thus we change the label of $(2,1)$ from $v$ to $\frac{{ }_{C}}{\overline{u(v x+w x+w y) z} v x z}=$ $\frac{u(v x+w x+w y)}{v x}$.


Next there are two maximal chains through $(1,2)$, one of which goes through the element labeled $x$ and the other through the element labeled $y$. Dividing $C$ by the sum of the products of the labels for both chains gives

$$
\frac{C}{\frac{C}{u(v x+w x+w y) z} w(x+y) z}=\frac{u(v x+w x+w y)}{w(x+y)}
$$



Similarly, the remaining 3 toggles give


Note this composition of the six toggles is one iteration of BAR-motion on $g$.
Theorem 3.6. On a finite poset $P$, $\mathrm{BAR}=\nabla \circ \Theta \circ \Delta^{-1}$, and the diagram below commutes.


Compare the example in Figure 2 to Example 3.5. We will not prove Theorem 3.6 now as it follows immediately from the more general noncommutative version: Theorem 5.26.

Example 3.7. Since BOR $=\nabla^{-1} \circ \mathrm{BAR} \circ \nabla$, BAR has the same order as BOR on any given finite poset $P$. On a general poset $P$, these birational rowmotion maps usually have infinite order, but on several nice families of posets described in [8, 9, 11], the order is finite (and the same as the order in the combinatorial realm). For example,



Figure 2. One iteration of BAR-motion on $[2] \times[3]$ as the composition of the three maps.
on a rectangle $[a] \times[b]$, birational rowmotion has order $a+b$. Figure 3 illustrates this with a generic orbit of BAR on $P=[2] \times[3]$, observing that the order is 5 .
3.2. Isomorphism between the two birational toggle groups. The first author constructed an explicit isomorphism between the combinatorial toggle groups of order ideals and of antichains, and then lifted it to the piecewise-linear realm [12]. Here we further lift it to the birational realm. It turns out that this isomorphism can be lifted even further to the noncommutative realm, with modified definitions because toggles are no longer involutions there. We do this in Section 5. All the proofs over skew fields imply the commutative birational counterparts by restriction. So in this subsection we merely state these (new) results.

Definition 3.8. For $v \in P$, let $T_{v}^{*}=\tau_{v_{1}} \tau_{v_{2}} \cdots \tau_{v_{k}} \tau_{v} \tau_{v_{k}} \cdots \tau_{v_{2}} \tau_{v_{1}}$ where $v_{1}, \ldots, v_{k}$ are the elements of $P$ covered by $v$. (In the case that $v$ is a minimal element of $P, k=0$ and $T_{v}^{*}=\tau_{v}$.) So $T_{v}^{*}$ is the conjugation of $\tau_{v}$ by $\prod_{w \lessdot v} \tau_{w}$, which within $\mathrm{BTog}_{A}(P)$ mimics the effect of the order toggle $T_{v}$.
Theorem 3.9 (Analogue of [12, Thm. 2.15], generalized in Thm. 5.20). Let $v \in P$. Then the following diagram commutes on the domains in which the maps are defined.


Example 3.10. Again we consider the poset $P=[2] \times[3]$ with elements named as in Example 3.5. Then $(2,2)$ covers $(2,1)$ and $(1,2)$, so $T_{(2,2)}^{*}=\tau_{(2,1)} \tau_{(1,2)} \tau_{(2,2)} \tau_{(1,2)} \tau_{(2,1)}$. Since $(2,1) \|(1,2)$, the toggles $\tau_{(2,1)}$ and $\tau_{(1,2)}$ commute by Proposition 3.3, so we can apply them "simultaneously". We verify Theorem 3.9 holds for this example in Figure 4.

Birational and noncommutative antichain rowmotion

$g$

$\operatorname{BAR}(g)$


$$
\operatorname{BAR}^{2}(g)
$$


$\operatorname{BAR}^{4}(g)$

$\operatorname{BAR}^{5}(g)$

Figure 3. An orbit of BAR starting with a generic labeling $g \in \mathbb{K}^{P}$, for $P=[2] \times[3]$. We observe that $\operatorname{BAR}^{5}(g)=g$, so the order of BAR is $5=2+3$ on this poset.

Michael Joseph \& Tom Roby


Figure 4. An illustration of Theorem 3.9. See Example 3.10.
Definition 3.11. Let $v \in P$ and let $\left(x_{1}, \ldots, x_{k}\right)$ be a linear extension of the subposet $\{x \in P \mid x<v\}$ of $P$. Define $\eta_{v}=T_{x_{1}} T_{x_{2}} \cdots T_{x_{k}}$ and $\tau_{v}^{*}=\eta_{v} T_{v} \eta_{v}^{-1}$. (Note that $\eta_{v}$ is well-defined since toggles corresponding to incomparable elements commute.)

As the next theorem formalizes, $\tau_{v}^{*}$ mimics the antichain toggle $\tau_{v}$ in terms of order toggles.

Theorem 3.12 (Analogue of [12, Thm. 2.19], generalized in Thm. 5.23). Let $v \in P$. Then the following diagram commutes on the domains in which the maps are defined.


Theorems 3.9 and 3.12 yield the following corollary.
Corollary 3.13. There is an isomorphism from $\mathrm{BTog}_{A}(P)$ to $\mathrm{BTog}_{O}(P)$ given by $\tau_{v} \mapsto \tau_{v}^{*}$ with inverse given by $T_{v} \mapsto T_{v}^{*}$.

## 4. Birational antichain toggles on graded posets

4.1. Toggling by ranks. Although rowmotion can be defined on any finite poset, only graded posets are currently known to have nice behavior (periodicity, homomesy, cyclic sieving, resonance). In fact, the name "rowmotion" references the natural factorization of this map as a product of rank ("row") toggles in the graded case [27].

Definition 4.1 ([24]). A poset $P$ is graded if it has a well-defined rank function rk: $P \rightarrow \mathbb{Z}_{\geqslant 0}$ satisfying

- $\operatorname{rk}(x)=0$ for any minimal element $x$,
- $\operatorname{rk}(y)=\operatorname{rk}(x)+1$ if $y \gtrdot x$,
- every maximal element $x$ of $P$ has $\operatorname{rk}(x)=r$, where $r$ is the $\operatorname{rank}$ of $P$.

For $x \in P$, we call $\operatorname{rk}(x)$ the rank of $x$.
In this section, $P$ will always refer to a finite graded poset of rank $r$.
Definition 4.2. Define birational antichain rank toggles as follows:

$$
\boldsymbol{T}_{\mathrm{rk}=i}:=\prod_{\operatorname{rk}(x)=i} T_{x}, \quad \boldsymbol{\tau}_{\mathrm{rk}=i}:=\prod_{\operatorname{rk}(x)=i} \tau_{x}, \quad \boldsymbol{T}_{\mathrm{rk}=i}^{*}:=\prod_{\operatorname{rk}(x)=i} T_{x}^{*}, \quad \boldsymbol{\tau}_{\mathrm{rk}=i}^{*}:=\prod_{\operatorname{rk}(x)=i} \tau_{x}^{*}
$$

Since poset elements of the same rank are pairwise incomparable, each product is of commuting toggles. Thus, the products above are all well-defined involutions.

Note
BAR $=\boldsymbol{\tau}_{\text {rk }=r} \boldsymbol{\tau}_{\mathrm{rk}=r-1} \cdots \boldsymbol{\tau}_{\mathrm{rk}=1} \boldsymbol{\tau}_{\mathrm{rk}=0} \quad$ and $\quad \mathrm{BOR}=\boldsymbol{T}_{\mathrm{rk}=0} \boldsymbol{T}_{\mathrm{rk}=1} \cdots \boldsymbol{T}_{\mathrm{rk}=r-1} \boldsymbol{T}_{\mathrm{rk}=r}$.
Under the isomorphism between $\mathrm{BTog}_{A}(P)$ and $\mathrm{BTog}_{O}(P)$, the rank toggles get sent to products of rank toggles, as the following proposition shows. The proof in the piecewise-linear realm [12, Propositions 2.30, 2.31] goes through unchanged, so we omit it here.

Proposition 4.3. Let $v \in P$ with $\operatorname{rk}(v)=i$. We have the following identities involving rank toggles (where the empty product $\boldsymbol{\tau}_{\mathrm{rk}=-1}$ is the identity).

- $T_{v}^{*}=\boldsymbol{\tau}_{\mathrm{rk}=i-1} \tau_{v} \boldsymbol{\tau}_{\mathrm{rk}=i-1}$,
- $\boldsymbol{T}_{\mathrm{rk}=i}^{*}=\boldsymbol{\tau}_{\mathrm{rk}=i-1} \boldsymbol{\tau}_{\mathrm{rk}=i} \boldsymbol{\tau}_{\mathrm{rk}=i-1}$,
- $\tau_{v}^{*}=\boldsymbol{T}_{\mathrm{rk}=0} \boldsymbol{T}_{\mathrm{rk}=1} \cdots \boldsymbol{T}_{\mathrm{rk}=i-1} T_{v} \boldsymbol{T}_{\mathrm{rk}=i-1} \cdots \boldsymbol{T}_{\mathrm{rk}=1} \boldsymbol{T}_{\mathrm{rk}=0}$,
- $\boldsymbol{\tau}_{\mathrm{rk}=i}^{*}=\boldsymbol{T}_{\mathrm{rk}=0} \boldsymbol{T}_{\mathrm{rk}=1} \cdots \boldsymbol{T}_{\mathrm{rk}=i-1} \boldsymbol{T}_{\mathrm{rk}=i} \boldsymbol{T}_{\mathrm{rk}=i-1} \cdots \boldsymbol{T}_{\mathrm{rk}=1} \boldsymbol{T}_{\mathrm{rk}=0}$.
4.2. Graded rescaling. Grinberg and the second author analyzed the effect of BOR (and also birational order rank toggles) on graded rescalings of poset labelings, which highlighted the advantages of working with graded posets [9]. In this section, we give analogous results for the antichain analogues, describing how BAR and birational antichain rank toggles $\boldsymbol{\tau}_{\mathrm{rk}=i}$ act on graded rescalings.

Definition $4.4([9, \S 6])$. Let $\left(a_{0}, \ldots, a_{r}\right) \in\left(\mathbb{K}^{\times}\right)^{r+1}$ (where $\mathbb{K}^{\times}$denotes the nonzero elements of $\mathbb{K}$ ) and $g \in \mathbb{K}^{P}$. Then $\left(a_{0}, \ldots, a_{r}\right) b g$ is the $\mathbb{K}$-labeling of $P$ formed by taking $g$ and multiplying the labels of all elements of rank $i$ by $a_{i}$. This is called a graded rescaling of $g$ by $\left(a_{0}, \ldots, a_{r}\right)$.

Example 4.5. In the positive root poset $\Phi^{+}\left(A_{3}\right)$
$(2,4,9) b$


Proposition 4.6. Let $g \in \mathbb{K}^{P}$ and $\left(a_{0}, \ldots, a_{r}\right) \in\left(\mathbb{K}^{\times}\right)^{r+1}$. Then

$$
\boldsymbol{\tau}_{\mathrm{rk}=i}\left(\left(a_{0}, \ldots, a_{r}\right) b g\right)=\left(a_{0}, \ldots, a_{i-1}, \frac{1}{a_{0} \cdots a_{r}}, a_{i+1}, \ldots, a_{r}\right) b \boldsymbol{\tau}_{\mathrm{rk}=i} g
$$

The analogous result for birational order toggles [9, Prop. 39] has $\frac{a_{i-1} a_{i+1}}{a_{i}}$ in the $i$ th position.

Proof. Let $h=\left(a_{0}, \ldots, a_{r}\right) b g$. Let $v \in P$ have $\operatorname{rk}(v)=i$. Then every maximal chain $\left(y_{0}, \ldots, y_{r}\right)$ in $P$ contains one element from each rank level. Therefore,

$$
\begin{aligned}
\Upsilon_{v} h & =\sum_{\left(y_{0}, \ldots, y_{r}\right) \in \mathrm{MC}_{v}(P)} h\left(y_{0}\right) h\left(y_{1}\right) \cdots h\left(y_{r-1}\right) h\left(y_{r}\right) \\
& =\sum_{\left(y_{0}, \ldots, y_{r}\right) \in \mathrm{MC}_{v}(P)} a_{0} g\left(y_{0}\right) a_{1} g\left(y_{1}\right) \cdots a_{r-1} g\left(y_{r-1}\right) a_{r} g\left(y_{r}\right) \\
& =a_{0} a_{1} \cdots a_{r} \sum_{\left(y_{0}, \ldots, y_{r}\right) \in \mathrm{MC}_{v}(P)} g\left(y_{0}\right) g\left(y_{1}\right) \cdots g\left(y_{r-1}\right) g\left(y_{r}\right) \\
& =a_{0} a_{1} \cdots a_{r} \Upsilon_{v} g .
\end{aligned}
$$

Then for every $v$ of rank $i$,

$$
\left(\boldsymbol{\tau}_{\mathrm{rk}=i} h\right)(v)=\frac{C}{\Upsilon_{v} h}=\frac{C}{a_{0} a_{1} \cdots a_{r} \Upsilon_{v} g}=\frac{1}{a_{0} a_{1} \cdots a_{r}}\left(\boldsymbol{\tau}_{\mathrm{rk}=i} g\right)(v),
$$

while for any $x$ of rank $j \neq i,\left(\boldsymbol{\tau}_{\mathrm{rk}=i} h\right)(x)=h(x)=a_{j} g(x)=a_{j}\left(\boldsymbol{\tau}_{\mathrm{rk}=i} g\right)(x)$. Thus,

$$
\boldsymbol{\tau}_{\mathrm{rk}=i} h=\left(a_{0}, \ldots, a_{i-1}, \frac{1}{a_{0} \cdots a_{r}}, a_{i+1}, \ldots, a_{r}\right) b \boldsymbol{\tau}_{\mathrm{rk}=i} g .
$$

A straightforward induction argument shows the following analogue of [9, Prop. 40].
Proposition 4.7. Let $g \in \mathbb{K}^{P}$ and $\left(a_{0}, \ldots, a_{r}\right) \in\left(\mathbb{K}^{\times}\right)^{r+1}$. Then

$$
\operatorname{BAR}\left(\left(a_{0}, a_{1}, \ldots, a_{r}\right) b g\right)=\left(\frac{1}{a_{0} a_{1} \cdots a_{r}}, a_{0}, a_{1}, \ldots, a_{r-2}, a_{r-1}\right) b \operatorname{BAR}(g)
$$

The key idea is that, like BOR, applying BAR to a graded rescaling of $g$ yields a graded rescaling of $\operatorname{BAR}(g)$.
4.3. Gyration. For a finite graded poset $P$, Striker defined an element of $\operatorname{Tog}_{\mathcal{J}}(P)$ called gyration, which is conjugate to order-ideal rowmotion $\rho_{\mathcal{J}}[25, \S 6]$. The name $g y$ ration comes from Wieland's action of the same name on alternating sign matrices [31]. Here we give a birational lifting of gyration using the same definition, which remains conjugate to BOR in $\operatorname{Tog}_{O}(P)$ because the key algebraic properties of the order-ideal toggle group lift to the birational realm. In fact this idea goes back to Cameron and Fon-Der-Flaass, who considered (slightly more general) "rank-permuted rowmotions", and showed that they were all conjugate in the order-ideal toggle group [3, Lemma 2].

Definition 4.8. Birational order gyration is the birational map BOG: $\mathbb{K}^{P} \rightarrow \mathbb{K}^{P}$ that applies the birational order toggles for elements in even ranks first, then the odd ranks.

For example, if $P$ has rank 7,

$$
\text { BOG }=\boldsymbol{T}_{\mathrm{rk}=7} \boldsymbol{T}_{\mathrm{rk}=5} \boldsymbol{T}_{\mathrm{rk}=3} \boldsymbol{T}_{\mathrm{rk}=1} \boldsymbol{T}_{\mathrm{rk}=6} \boldsymbol{T}_{\mathrm{rk}=4} \boldsymbol{T}_{\mathrm{rk}=2} \boldsymbol{T}_{\mathrm{rk}=0}
$$

This is well-defined, since it does not matter in which order the elements of even rank are toggled, and similarly for odd rank. This is because rank toggles $\boldsymbol{T}_{\mathrm{rk}=i}, \boldsymbol{T}_{\mathrm{rk}=j}$ commute when $|i-j| \neq 1$, where there are no cover relations between an element of rank $i$ and an element of rank $j$. Since BOR and BOG are conjugate in $\operatorname{Tog}_{O}(P)$, they have the same order on any graded poset, and sometimes other properties can be transferred between the two maps.

On the other hand, birational antichain rank toggles never commute, so we need to specify a toggle order in the following definition. This definition of BAG is the image of BOG under our explicit isomorphism between $\mathrm{BTog}_{O}(P)$ and $\mathrm{BTog}_{A}(P)$.

Definition 4.9. Birational antichain gyration is the birational map BAG: $\mathbb{K}^{P} \rightarrow$ $\mathbb{K}^{P}$ that first applies the antichain toggles for odd ranks starting from the bottom of the poset up to the top, and then toggles the even ranks from the top of the poset down to the bottom.

For example, if $P$ has rank $7, \mathrm{BAG}=\boldsymbol{\tau}_{\mathrm{rk}=0} \boldsymbol{\tau}_{\mathrm{rk}=2} \boldsymbol{\tau}_{\mathrm{rk}=4} \boldsymbol{\tau}_{\mathrm{rk}=6} \boldsymbol{\tau}_{\mathrm{rk}=7} \boldsymbol{\tau}_{\mathrm{rk}=5} \boldsymbol{\tau}_{\mathrm{rk}=3} \boldsymbol{\tau}_{\mathrm{rk}=1}$. We omit the proof of the following theorem here, which is completely analogous to [12, Theorem 2.34] but now lifted to the birational realm.

Theorem 4.10. The following diagram commutes.


## 5. Noncommutative (SKEW Field) Dynamics

5.1. Introduction to skew field dynamics. Darij Grinberg has conjectured that the periodicity of BOR-motion on certain nice posets continues to hold even when extended to labelings of $P$ by elements that do not necessarily commute. Here we study the lifting to this setting of the antichain perspective and relate it to the order perspective. We first recall Grinberg's original toggling definition of this map, which we call NOR-motion, and show that it is also given as a composition of three transfer maps as in the commutative case.

Next we define the antichain analogues of toggling and NAR-motion, which can also be given in terms of the transfer maps. Along the way we give an explicit isomorphism between the group of order toggles and the group of antichain toggles in the noncommutative case.

Let $\mathbb{S}$ denote a skew field that contains an infinite field $\mathbb{F}$ as a subfield. Any such skew field $\mathbb{S}$ of characteristic zero satisfies this condition, as it contains an isomorphic copy of $\mathbb{Q}$. We will now work with $\mathbb{S}$-labelings in $\mathbb{S}^{P}:=\{f: P \rightarrow \mathbb{S}\}$. We always require the generic constant $C \in \mathbb{S}$ to be in the center of $\mathbb{S}$ (i.e. $C$ commutes with every element of $\mathbb{S})$. The proofs in this section specialize to show the results of $\S 3.2$.
Notation 5.1. For $x \in \mathbb{S}$, write $\bar{x}$ for $x^{-1}$.
Notation 5.2. The (commutative and associative) operation parallel sum is defined by $x H y=\overline{\bar{x}}+\bar{y}$. We use $\sum^{\#}$ as the analogue of $\sum$ with + replaced with $H$.

The following reciprocity relation, analogous to one in $[6, \S 5]$, is easy to show.
Proposition 5.3. For $x_{1}, \ldots, x_{n} \in \mathbb{S}$,

$$
\left(\sum_{i=1}^{n}{ }^{H} x_{i}\right)\left(\sum_{i=1}^{n} \overline{x_{i}}\right)=\left(\sum_{i=1}^{n} \overline{x_{i}}\right)\left(\sum_{i=1}^{n}{ }^{H} x_{i}\right)=1
$$

REmark 5.4. It can be quite tricky to simplify expressions in a skew field until one gains some experience. For example $x H y=\overline{\bar{x}}+\bar{y}$ can equivalently be written as

- $y \overline{(x+y)} x$ by multiplying on the left by $y \bar{y}$ and the right by $\bar{x} x$ and using the property $\overline{A B}=\bar{B} \cdot \bar{A}$,
- or as $x \overline{(x+y)} y$ by multiplying on the left by $x \bar{x}$ and the right by $\bar{y} y$,
but is not equivalent to $y x \overline{(x+y)}, \overline{(x+y)} x y, x y \overline{(x+y)}$, or $\overline{(x+y)} y x$. We can simplify $\bar{y} x \overline{(x+y)} y$ as

$$
\bar{y} x \overline{x+y)} y=\bar{y} y \overline{(x+y)} x=\overline{(x+y)} x
$$

Many other expressions are more challenging to rewrite in equivalent forms. For example,

$$
\overline{\bar{v} \cdot \bar{x}+\bar{w} \cdot \overline{(x+y)}}=(x+y) \overline{w(x v+x w+y w)} x v=x v \overline{(x v+x w+y w)}(x+y) w
$$

and

$$
\overline{\overline{(v+w)} \cdot \bar{x}+\bar{w} \cdot \bar{y}}=y w \overline{(x v+x w+y w)} x(v+w)=x(v+w) \overline{(x v+x w+y w)} y w
$$

are expressions that have arisen naturally in this study.
REmark 5.5. When we move to the noncommutative setting, we no longer have the notions from algebraic geometry and commutative algebra of Zariski topology and birational maps, so we call the analogous maps partial maps. These maps will not be defined when expressions in the denominator (i.e. expression we take the inverse of) become zero, so the domains need to be restricted somehow. We do not try to address this issue formally, which would take us too far afield. In particular, all the maps we consider are noncommutative analogues of our earlier birational maps. At a minimum, any equalities stated will hold as birational identities whenever we restrict the variables to lie in the infinite subfield $\mathbb{F}$. Practically speaking, they will hold in much greater generality.

Definition 5.6 (Darij Grinberg). Let $v \in P$. The noncommutative order toggle is the partial map $T_{v}: \mathbb{S}^{P} \rightarrow \mathbb{S}^{P}$ defined as follows. For this definition, we extend any
$f \in \mathbb{S}^{P}$ to a $\widehat{P}$-labeling by setting $f(\widehat{0})=1$ and $f(\widehat{1})=C$, recalling $C$ is in the center of $\mathbb{S}$. Then

$$
\left(T_{v}(f)\right)(w)= \begin{cases}\left(\sum_{u \in \widehat{P}, u \lessdot v} f(u)\right) \overline{f(v)}\left(\sum_{u \in \widehat{P}, u \gtrdot v}^{\#} f(u)\right) & \text { if } w=v \\ f(w) & \text { if } w \neq v\end{cases}
$$

Toggles in the noncommutative realm are not involutions, so it is surprising they have any nice features at all. Initially, the term "toggle" was chosen to be an involution, but we continue to use it here to keep terminology consistent with other realms. We will call the inverse of a toggle an elggot.

Definition 5.7. Let $v \in P$. The noncommutative order elggot is the partial map $E_{v}: \mathbb{S}^{P} \rightarrow \mathbb{S}^{P}$ defined as follows. Then

$$
\left(E_{v}(f)\right)(w)= \begin{cases}\left(\sum_{u \in \widehat{P}, u \gtrdot v}^{+} f(u)\right) \overline{f(v)}\left(\sum_{u \in \widehat{P}, u \lessdot v} f(u)\right) & \text { if } w=v \\ f(w) & \text { if } w \neq v\end{cases}
$$

A straightforward computation shows that $T_{v}$ and $E_{v}$ are inverse partial maps. Order toggles and elggots commute with each other in the skew-field setting exactly when they do in the (commutative) birational realm. We omit the elementary proof.
Proposition 5.8. Let $u, v \in P$. If neither $u$ nor $v$ covers the other, then $T_{u} T_{v}=T_{v} T_{u}$, $E_{u} E_{v}=E_{v} E_{u}, T_{u} E_{v}=E_{v} T_{u}$, and $E_{u} T_{v}=T_{v} E_{u}$.
Definition 5.9 (Darij Grinberg). Let $\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ be any linear extension of a finite poset $P$. Then the partial map NOR $=T_{x_{1}} T_{x_{2}} \cdots T_{x_{n}}$ is called noncommutative order rowmotion (NOR-motion).
Conjecture 5.10 (Darij Grinberg). On $[a] \times[b]$, NOR has order $a+b$.

### 5.2. Transfer maps in the noncommutative realm.

Definition 5.11. Let $f \in \mathbb{S}^{P}$. We define complement $\Theta$, down transfer $\nabla$, up transfer $\Delta$, inverse down transfer $\nabla^{-1}$, and inverse up transfer $\Delta^{-1}$ as follows. These specialize to Definition 2.17 when $\mathbb{S}$ is actually a field.

$$
\begin{aligned}
(\Theta f)(x) & =C \cdot \overline{f(x)} \\
(\nabla f)(x) & =f(x) \cdot \overline{\sum_{y \lessdot x} f(y)} \quad(\text { with } f(\widehat{0})=1) \\
(\Delta f)(x) & =\overline{\sum_{y \gtrdot x} f(y)} \cdot f(x) \quad(\text { with } f(\widehat{1})=1) \\
\left(\nabla^{-1} f\right)(x) & =\sum_{\widehat{0} \lessdot y_{1} \lessdot y_{2} \lessdot \cdots \lessdot y_{k}=x} f\left(y_{k}\right) \cdots f\left(y_{2}\right) f\left(y_{1}\right)=f(x) \cdot \sum_{y \lessdot x}\left(\nabla^{-1} f\right)(y) \\
\left(\Delta^{-1} f\right)(x) & =\sum_{x=y_{1} \lessdot y_{2} \lessdot \cdots \lessdot y_{k} \lessdot \widehat{1}} f\left(y_{k}\right) \cdots f\left(y_{2}\right) f\left(y_{1}\right)=\sum_{y \gtrdot x}\left(\Delta^{-1} f\right)(y) \cdot f(x) .
\end{aligned}
$$

Theorem 5.12 (Analogue of [6, Thm. 6.2]). For any finite poset $P$,

$$
\mathrm{NOR}=\Theta \circ \Delta^{-1} \circ \nabla
$$

Proof. We will prove $\left(\Theta \Delta^{-1} \nabla f\right)(x)=($ NOR $f)(x)$ for all $x \in P$ for which either side is defined (recall these are partial maps). We induct on $P$ from top to bottom. Let $x \in P$ and assume every $y>x$ satisfies the induction hypothesis.

Then

$$
(\nabla f)(x)=f(x) \overline{\sum_{y \lessdot x} f(y)}
$$

Now we apply $\Delta^{-1}$ to both sides. Using the recursive description for $\Delta^{-1}$, we obtain

$$
\begin{aligned}
\left(\Delta^{-1} \nabla f\right)(x) & =\sum_{y \gtrdot x}\left(\Delta^{-1} \nabla f\right)(y) \cdot(\nabla f)(x) \\
& =\sum_{y \gtrdot x}\left(\Delta^{-1} \nabla f\right)(y) \cdot f(x) \cdot \overline{\sum_{y \lessdot x} f(y)} \\
& =C \overline{\sum_{y \gtrdot x}^{\#}}\left(\Theta \Delta^{-1} \nabla f\right)(y) \cdot f(x) \cdot \overline{\sum_{y \lessdot x} f(y)}
\end{aligned}
$$

Next we apply $\Theta$ to both sides, which yields

$$
\begin{aligned}
\left(\Theta \Delta^{-1} \nabla f\right)(x) & =C \cdot \overline{C \cdot \overline{\sum_{y \gtrdot x}^{\#}}\left(\Theta \Delta^{-1} \nabla f\right)(y)} \cdot f(x) \cdot \overline{\sum_{y \lessdot x} f(y)} \\
& =\left(\sum_{y \lessdot x} f(y)\right) \cdot \overline{f(x)} \cdot\left(\sum_{y \gtrdot x}^{\#}\left(\Theta \Delta^{-1} \nabla f\right)(y)\right) \\
& =\left(\sum_{y \lessdot x} f(y)\right) \cdot \overline{f(x)} \cdot\left(\sum_{y \gtrdot x}^{H}(\operatorname{NOR} f)(y)\right)
\end{aligned}
$$

by the induction hypothesis. Note that the last expression equals (NOR $f)(x)$ because it is exactly what we obtain at $x$ just before we toggle at $x$ (where we have already toggled elements $y \gtrdot x$ but not elements $y \lessdot x)$.

### 5.3. Noncommutative Antichain Toggling and Rowmotion.

Definition 5.13. Let $v \in P$. The noncommutative antichain toggle is the partial map $\tau_{v}: \mathbb{S}^{P} \rightarrow \mathbb{S}^{P}$ defined so that $\left(\tau_{v}(g)\right)(x)$ equals
$C \cdot \overline{\sum\{\underbrace{g\left(y_{c-1}\right) \cdots g\left(y_{1}\right)}_{\text {(indices decrease by 1) }} \underbrace{g\left(y_{k}\right) \cdots g\left(y_{c}\right)}_{\text {indices decrease by 1) }}: \widehat{0} \lessdot y_{1} \lessdot y_{2} \lessdot \cdots \lessdot y_{k} \lessdot \widehat{1}, y_{c}=v\}}$ if $x=v$, and $\left(\tau_{v}(g)\right)(x)=g(x)$ if $x \neq v$.

The noncommutative antichain elggot is the partial map $\varepsilon_{v}: \mathbb{S}^{P} \rightarrow \mathbb{S}^{P}$ defined so that as $\left(\varepsilon_{v}(g)\right)(x)$ equals

$$
C \cdot \sum\{\underbrace{g\left(y_{c}\right) \cdots g\left(y_{1}\right)}_{\text {(indices decrease by 1) }} \underbrace{g\left(y_{k}\right) \cdots g\left(y_{c+1}\right)}_{\text {indices decrease by 1) }}: \widehat{0} \lessdot y_{1} \lessdot y_{2} \lessdot \cdots \lessdot y_{k} \lessdot \widehat{1}, y_{c}=v\}
$$

if $x=v$, and $\left(\varepsilon_{v}(g)\right)(x)=g(x)$ if $x \neq v$.
Let $\operatorname{NTog}_{A}(P)$ be the group generated by all noncommutative antichain toggles $\tau_{v}$ for $v \in P$, and let $\operatorname{NTog}_{O}(P)$ be the group generated by all noncommutative order toggles $T_{v}$.

Commutativity of toggles and elggots is the same as in the (commutative) birational realm.
Proposition 5.14. Let $u, v \in P$. If $u \| v$, then $\tau_{u} \tau_{v}=\tau_{v} \tau_{u}, \varepsilon_{u} \varepsilon_{v}=\varepsilon_{v} \varepsilon_{u}, \tau_{u} \varepsilon_{v}=\varepsilon_{v} \tau_{u}$. Proof. Analogous to the proof of Proposition 3.3(b).

Example 5.15 . Consider the poset $P=[2] \times[3]$ below, with the generic labeling $g \in \mathbb{K}^{P}$ by $u, v, w, x, y, z \in \mathbb{S}$.
$(2,1)$



- If we apply the toggle $\tau_{(1,1)}$, we would change the label at $(1,1)$ to

$$
C \cdot \overline{z x v u+z x w u+z y w u}=C \cdot \bar{u} \cdot \overline{(x v+x w+y w)} \cdot \bar{z} .
$$

- If instead we apply the toggle $\tau_{(2,1)}$, we would change the label at $(2,1)$ to

$$
C \cdot \overline{u z x v}=C \cdot \bar{v} \cdot \bar{x} \cdot \bar{z} \cdot \bar{u} .
$$

- If instead we apply the toggle $\tau_{(1,2)}$, we would change the label at $(1,2)$ to

$$
C \cdot \overline{u z x w+u z y w}=C \cdot \bar{w} \cdot \overline{(x+y)} \cdot \bar{z} \cdot \bar{u}
$$

- If instead we apply the toggle $\tau_{(2,2)}$, we would change the label at $(2,2)$ to

$$
C \cdot \overline{v u z x+w u z x}=C \cdot \bar{x} \cdot \bar{z} \cdot \bar{u} \cdot \overline{(v+w)}
$$

Definition 5.16. Let $\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ be any linear extension of a finite poset $P$. Then the partial map $\mathrm{NAR}=\tau_{x_{n}} \cdots \tau_{x_{2}} \tau_{x_{1}}$, i.e. toggling at each element of $P$ from bottom to top, is called noncommutative antichain rowmotion (NAR-motion).

Example 5.17 . On the poset $P=[2] \times[3]$, NAR has order 5 . In Figure 5, we show an orbit beginning with a generic labeling.

We now define specific elements of $\mathrm{NTog}_{A}(P)$ that mimic the action of order toggles.

Definition 5.18. For $v \in P$, let $T_{v}^{*}=\varepsilon_{v_{1}} \varepsilon_{v_{2}} \cdots \varepsilon_{v_{k}} \tau_{v} \tau_{v_{k}} \cdots \tau_{v_{2}} \tau_{v_{1}} \in \operatorname{NTog}_{A}(P)$ where $v_{1}, \ldots, v_{k}$ are the elements of $P$ covered by $v$. (In the case that $v$ is a minimal element of $P, k=0$ and $T_{v}^{*}=\tau_{v}$.) Let $E_{v}^{*}=\left(T_{v}^{*}\right)^{-1}=\varepsilon_{v_{1}} \varepsilon_{v_{2}} \cdots \varepsilon_{v_{k}} \varepsilon_{v} \tau_{v_{k}} \cdots \tau_{v_{2}} \tau_{v_{1}}$.

The following lemma (whose proof is straightforward from the definitions) will be used in the proof of Theorem 5.20.

Lemma 5.19. Let $g \in \mathbb{S}^{P}$ and $v \in P$. Then

$$
\begin{aligned}
\left(\tau_{v} g\right)(v) & =C \cdot \overline{\left(\nabla^{-1} g\right)(v) \cdot\left(\Delta^{-1} g\right)(v)} \cdot g(v) \\
& =C \cdot \overline{\left(\Delta^{-1} g\right)(v)} \cdot \overline{\left(\nabla^{-1} g\right)(v)} \cdot g(v), \\
\left(\varepsilon_{v} g\right)(v) & =C \cdot g(v) \cdot \overline{\left(\nabla^{-1} g\right)(v) \cdot\left(\Delta^{-1} g\right)(v)} \\
& =C \cdot g(v) \cdot \overline{\left(\Delta^{-1} g\right)(v)} \cdot \overline{\left(\nabla^{-1} g\right)(v)}
\end{aligned}
$$

The following result uses the transfer maps to explicitly mimic the action of order toggles using the products of antichain toggles defined above and similarly for elggots.

## Michael Joseph \& Tom Roby

$g=\operatorname{NAR}^{5}(g)=$
$v$





Figure 5. An orbit of NAR starting on a generic labeling $g \in \mathbb{S}^{P}$, for $P=[2] \times[3]$. We observe that the order of NAR, like BAR, is 5 on this poset.

Theorem 5.20 (Analogue of Theorem 3.9). Let $v \in P$. Then the following diagrams commute on the domains in which the maps are defined.


Proof. The right commutative diagram clearly follows from the left, so we will only prove the left one.

Let $g \in \mathbb{S}^{P}$. We must show that $\Theta \Delta^{-1}\left(T_{v}^{*} g\right)=T_{v}\left(\Theta \Delta^{-1} g\right)$.
Suppose $v$ is a minimal element of $P$. Then $T_{v}^{*}=\tau_{v}$. Note from the definitions that

$$
\left(\Theta \Delta^{-1} g\right)(x)=C \cdot \overline{\sum\left\{g\left(y_{k}\right) \cdots g\left(y_{2}\right) g\left(y_{1}\right): x=y_{1} \lessdot y_{2} \lessdot \cdots \lessdot y_{k} \lessdot \widehat{1}\right\}} .
$$

Thus, $\left(\Theta \Delta^{-1} g\right)(x)$ only depends on the labels $g(y)$ for any $y \geqslant x$. Let $x \neq v$. Since $\tau_{v}$ only affects the label at $v$, and $x \nless v$ (by minimality of $v$ ), it follows that

$$
\left(\Theta \Delta^{-1}\left(\tau_{v} g\right)\right)(x)=\left(\Theta \Delta^{-1} g\right)(x)=\left(T_{v}\left(\Theta \Delta^{-1} g\right)\right)(x)
$$

Now we must confirm that $\left(\Theta \Delta^{-1}\left(\tau_{v} g\right)\right)(v)=\left(T_{v}\left(\Theta \Delta^{-1} g\right)\right)(v)$. We have

$$
\begin{aligned}
& \left(\Theta \Delta^{-1}\left(\tau_{v} g\right)\right)(v) \\
= & C \cdot \overline{\left(\Delta^{-1}\left(\tau_{v} g\right)\right)(v)} \\
= & C \cdot \overline{\sum_{y \gtrdot v}\left(\Delta^{-1}\left(\tau_{v} g\right)\right)(y) \cdot\left(\tau_{v} g\right)(v)} \\
= & C \cdot \overline{\sum_{y \gtrdot v}\left(\Delta^{-1} g\right)(y) \cdot\left(\tau_{v} g\right)(v)} \\
= & \left.C \cdot \overline{\sum_{y \gtrdot v}\left(\Delta^{-1} g\right)(y) \cdot C \cdot \overline{\left(\Delta^{-1} g\right)(v)}} \quad \text { (definitions of } \tau_{v} \text { and } \Delta^{-1} \text { for minimal } v\right) \\
= & C \cdot \overline{\left(\Delta^{-1} g\right)(v)}\left(\overline{C \cdot \sum_{y \gtrdot v}\left(\Delta^{-1} g\right)(y)}\right) \\
= & \left(\Theta \Delta^{-1} g\right)(v)\left(\sum_{y \gtrdot v}^{\#}\left(\Theta \Delta^{-1} g\right)(y)\right) \quad(v \text { is minimal so there is no } y \lessdot v \text { in } P) . \\
= & \left(T_{v}\left(\Theta \Delta^{-1} g\right)\right)(v) \quad
\end{aligned}
$$

Now assume $v$ is not minimal in $P$. Let $v_{1}, \ldots, v_{k}$ be the elements $v$ covers. Let

$$
\begin{array}{lll}
g^{\prime}=\tau_{v} \tau_{v_{k}} \cdots \tau_{v_{1}} g, & g^{\prime \prime}=\varepsilon_{v_{1}} \cdots \varepsilon_{v_{k}} g^{\prime}=T_{v}^{*} g \\
f=\Theta \Delta^{-1} g, & f^{\prime}=\Theta \Delta^{-1} g^{\prime}, & f^{\prime \prime}=\Theta \Delta^{-1} g^{\prime \prime}
\end{array}
$$

The goal is to show that $f^{\prime \prime}=T_{v} f$. Note that $g, g^{\prime}$, and $g^{\prime \prime}$ can only possibly differ in the labels of $v, v_{1}, v_{2}, \cdots, v_{k}$. From the definitions of $\Theta$ and $\Delta^{-1}$, we note that $T_{v} f$ and $f^{\prime \prime}$ can only possibly differ in the labels of elements $\leqslant v$.

We begin by proving $f^{\prime \prime}(v)=\left(T_{v} f\right)(v)$. Since $v_{1}, \cdots, v_{k}$ are pairwise incomparable (so each chain can only contain at most one of them), for $1 \leqslant j \leqslant k$,

$$
\begin{aligned}
\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\left(v_{j}\right) & =C \cdot \overline{\left(\nabla^{-1} g\right)\left(v_{j}\right) \cdot\left(\Delta^{-1} g\right)\left(v_{j}\right)} \cdot g\left(v_{j}\right) \\
& =C \cdot \overline{\overline{g\left(v_{j}\right)} \cdot\left(\nabla^{-1} g\right)\left(v_{j}\right) \cdot\left(\Delta^{-1} g\right)\left(v_{j}\right)} \\
& =C \cdot \overline{\sum_{y \lessdot v_{j}}\left(\nabla^{-1} g\right)\left(v_{j}\right) \cdot\left(\Delta^{-1} g\right)\left(v_{j}\right)} \\
& =C \cdot \overline{\left(\Delta^{-1} g\right)\left(v_{j}\right)} \cdot \overline{\sum_{y \lessdot v_{j}}\left(\nabla^{-1} g\right)\left(v_{j}\right)} \\
& =f\left(v_{j}\right) \cdot \overline{\sum_{y<v_{j}}\left(\nabla^{-1} g\right)\left(v_{j}\right)}
\end{aligned}
$$

We restate the above fact

$$
\begin{equation*}
\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\left(v_{j}\right)=f\left(v_{j}\right) \cdot \overline{\sum_{y<v_{j}}\left(\nabla^{-1} g\right)\left(v_{j}\right)} \tag{2}
\end{equation*}
$$

as an equation we will reference later.
Then to get $g^{\prime}(v)$, we apply $\tau_{v}$ to $\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)(v)$. Lemma 5.19 gives

$$
\begin{aligned}
& g^{\prime \prime}(v)=g^{\prime}(v)=C \cdot \overline{\left(\nabla^{-1}\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\right)(v) \cdot\left(\Delta^{-1}\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\right)(v)} \cdot\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)(v) \\
&=C \cdot \overline{\overline{\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)(v)} \cdot\left(\nabla^{-1}\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\right)(v) \cdot\left(\Delta^{-1}\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\right)(v)} \\
&=C \cdot \overline{\left(\sum_{v_{j} \lessdot v}\left(\nabla^{-1}\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\right)(v)\right) \cdot\left(\Delta^{-1} g\right)(v)} \\
&=C \cdot \overline{\left(\Delta^{-1} g\right)(v)} \cdot \overline{\sum_{v_{j} \lessdot v}\left(\nabla^{-1}\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\right)(v)} \\
&=f(v) \cdot \overline{\sum_{v_{j} \lessdot v}\left(\nabla^{-1}\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\right)(v)} \\
&=f(v) \cdot \sum_{v_{j} \lessdot v}\left(\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\left(v_{j}\right) \sum_{y \leqslant v_{j}}\left(\nabla^{-1}\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\right)(y)\right) \\
&=f(v) \cdot \sum_{v_{j} \lessdot v}\left(\left(\tau_{v_{1}} \cdots \tau_{v_{k}} g\right)\left(v_{j}\right) \sum_{y \leqslant v_{j}}\left(\nabla^{-1} g\right)(y)\right) \\
& \underbrace{f\left(v_{j}\right)}_{v_{j} \lessdot v}
\end{aligned} .
$$

Then using the recursive descripion of $\Delta^{-1}$,

$$
\begin{aligned}
f^{\prime \prime}(v) & =C \cdot \overline{\left(\Delta^{-1} g^{\prime \prime}\right)(v)}=C \cdot \overline{\sum_{y>v}\left(\Delta^{-1} g^{\prime \prime}\right)(v) \cdot g^{\prime \prime}(v)}=C \cdot \overline{\sum_{y>v}\left(\Delta^{-1} g\right)(y) \cdot g^{\prime \prime}(v)} \\
& =\overline{g^{\prime \prime}(v)} \cdot C \cdot \overline{\sum_{y \gtrdot v}\left(\Delta^{-1} g\right)(y)}=\overline{g^{\prime \prime}(v)} \cdot \sum_{y>v}^{\#}\left(\Theta \Delta^{-1} g\right)(y) \\
& =\overline{f(v) \cdot \overline{\sum_{v_{j}<v} f\left(v_{j}\right)}} \cdot \sum_{y>v}^{H} f(y)=\sum_{v_{j}<v} f\left(v_{j}\right) \cdot \overline{f(v)} \cdot \sum_{y>v}^{H} f(y)=\left(T_{v} f\right)(v) .
\end{aligned}
$$

We noted earlier in the proof that $\left(T_{v} f\right)(x)=f^{\prime \prime}(x)=f(x)$ for all $x>v$. Now we have proven $\left(T_{v} f\right)(v)=f^{\prime \prime}(v)$. What remains to be shown is that $\left(T_{v} f\right)(x)=f^{\prime \prime}(x)=$ $f(x)$ for all $x<v$, which we will now prove using downward induction on $x$. We begin with the base case $x \lessdot v$. For $1 \leqslant j \leqslant k$,

$$
\begin{aligned}
g^{\prime \prime}\left(v_{j}\right) & =\left(\varepsilon_{v_{j}} g^{\prime}\right)\left(v_{j}\right) \\
& =C \cdot g^{\prime}\left(v_{j}\right) \cdot \overline{\left(\nabla^{-1} g^{\prime}\right)\left(v_{j}\right) \cdot\left(\Delta^{-1} g^{\prime}\right)\left(v_{j}\right)} \\
& =C \cdot \overline{\left(\nabla^{-1} g^{\prime}\right)\left(v_{j}\right) \cdot\left(\Delta^{-1} g^{\prime}\right)\left(v_{j}\right) \cdot \overline{g^{\prime}\left(v_{j}\right)}} \quad \quad \quad \text { (from Lemma 5.19) } \\
& =C \cdot \overline{\left(g^{\prime}\left(v_{j}\right) \sum_{y \lessdot v_{j}}\left(\nabla^{-1} g^{\prime}\right)(y)\right) \cdot\left(\sum_{y \gtrdot v_{j}}\left(\Delta^{-1} g^{\prime}\right)(y) \cdot g^{\prime}\left(v_{j}\right)\right) \cdot \overline{g^{\prime}\left(v_{j}\right)}} \\
= & C \cdot \overline{g^{\prime}\left(v_{j}\right) \cdot \sum_{y \lessdot v_{j}}\left(\nabla^{-1} g^{\prime}\right)(y) \cdot \sum_{y \gtrdot v_{j}}\left(\Delta^{-1} g^{\prime}\right)(y)} \\
= & \overline{f\left(v_{j}\right) \cdot \overline{\sum_{y \lessdot v_{j}}\left(\nabla^{-1} g\right)\left(v_{j}\right)} \cdot \sum_{y \lessdot v_{j}}\left(\nabla^{-1} g^{\prime}\right)(y) \cdot \sum_{y \gtrdot v_{j}}\left(\Delta^{-1} g^{\prime}\right)(y)} \quad \quad \text { (from Eq. (2)) } \\
= & \overline{f\left(v_{j}\right) \sum_{y \gtrdot v_{j}}\left(\Delta^{-1} g^{\prime}\right)(y)} \\
= & \overline{f\left(v_{j}\right) \sum_{y \gtrdot v_{j}}\left(\Delta^{-1} g^{\prime \prime}\right)(y)}
\end{aligned}
$$

where the last equality is because $\Delta^{-1} g^{\prime}, \Delta^{-1} g^{\prime \prime}$ are the same for $y>v_{j}$. Using the above fact in the fourth equality below,

$$
\begin{aligned}
f^{\prime \prime}\left(v_{j}\right) & =C \cdot \overline{\left(\Delta^{-1} g^{\prime \prime}\right)\left(v_{j}\right)}=\overline{\sum_{y \gtrdot v_{j}}\left(\Delta^{-1} g^{\prime \prime}\right)(y) \cdot g^{\prime \prime}\left(v_{j}\right)}=C \cdot \overline{g^{\prime \prime}\left(v_{j}\right)} \cdot \overline{\sum_{y \gtrdot v_{j}}\left(\Delta^{-1} g^{\prime \prime}\right)(y)} \\
& =f\left(v_{j}\right) \sum_{y \gtrdot v_{j}}\left(\Delta^{-1} g^{\prime \prime}\right)(y) \cdot \overline{\sum_{y \gtrdot v_{j}}\left(\Delta^{-1} g^{\prime \prime}\right)(y)}=f\left(v_{j}\right)=\left(T_{v} f\right)\left(v_{j}\right)
\end{aligned}
$$

Now let $x<v$ and $x \notin\left\{v_{1}, \ldots, v_{k}\right\}$. Assume that $\left(T_{v} f\right)(y)=f(y)=f^{\prime \prime}(y)$ for every $y$ covering $x$ (which cannot include $y=v$ because $x \notin\left\{v_{1}, \ldots, v_{k}\right\}$ ). Also since $x \notin\left\{v, v_{1}, \ldots, v_{k}\right\}$, recall that $g(x)=g^{\prime \prime}(x)$. So

$$
\begin{aligned}
f^{\prime \prime}(x) & =C \cdot \overline{\left(\Delta^{-1} g^{\prime \prime}\right)(x)}=C \cdot \overline{\sum_{y \gtrdot x}\left(\Delta^{-1} g^{\prime \prime}\right)(y) \cdot g^{\prime \prime}(x)}=\overline{\sum_{y \gtrdot x}\left(\Theta f^{\prime \prime}\right)(y) \cdot g^{\prime \prime}(x)} \\
& =\overline{\sum_{y \gtrdot x}(\Theta f)(y) \cdot g(x)}=\overline{\sum_{y \gtrdot x}\left(\Delta^{-1} g\right)(y) \cdot g(x)}=\overline{\left(\Delta^{-1} g\right)(x)}=f(x)=\left(T_{v} f\right)(x)
\end{aligned}
$$

We continue the group-theoretic approach of [12] to prove NAR $=\nabla \circ \Theta \circ \Delta^{-1}$. The proofs here are similar to those in [12], but modified as toggles are no longer involutions. The next two definitions and theorem allow us to mimic antichain toggles by order toggles.

DEFINITION 5.21. For $S \subseteq P$ let $\eta_{S}:=T_{x_{1}} T_{x_{2}} \cdots T_{x_{k}}$ where $\left(x_{1}, x_{2}, \ldots, x_{k}\right)$ is a linear extension of the subposet $\{x \in P \mid x<y$ for some $y \in S\}$. (In the special case where every element of $S$ is minimal in $P, \eta_{S}$ is the identity.) For $v \in P$, we write $\eta_{v}:=\eta_{\{v\}}$.

Definition 5.22. For $v \in P$, define $\tau_{v}^{*} \in \operatorname{NTog}_{O}(P)$ as $\tau_{v}^{*}:=\eta_{v} T_{v} \eta_{v}^{-1}$. Let $\varepsilon_{v}^{*}=$ $\left(\tau_{v}^{*}\right)^{-1}=\eta_{v} E_{v} \eta_{v}^{-1}$.

Theorem 5.23 (Analogue of 3.12 and [12, Thm. 2.19]). Let $v \in P$. Then the following diagrams commute on the domains in which the maps are defined.


To prove Theorem 5.23, we first need a lemma.

Lemma 5.24 (Analogue of [12, Lemma 2.21]). Let $v_{1}, \ldots, v_{k}$ be pairwise incomparable elements of $P$. Then for $1 \leqslant i \leqslant k$,

$$
\tau_{v_{1}}^{*} \tau_{v_{2}}^{*} \ldots \tau_{v_{i}}^{*}=\eta_{\left\{v_{1}, \ldots, v_{i}\right\}} T_{v_{1}} T_{v_{2}} \ldots T_{v_{i}} \eta_{\left\{v_{1}, \ldots, v_{i}\right\}}^{-1}
$$

Proof. This proof is similar to that of [12, Lemma 2.21].
This claim is true by definition for $i=1$ and we proceed inductively. Suppose it is true for some given $i \leqslant k-1$. Let

- $x_{1}, \ldots, x_{a}$ be the elements that are both less than $v_{i+1}$ and less than at least one of $v_{1}, \ldots, v_{i}$,
- $y_{1}, \ldots, y_{b}$ be the elements that are less than at least one of $v_{1}, \ldots, v_{i}$ but not less than $v_{i+1}$,
- $z_{1}, \ldots, z_{c}$ be the elements that are less than $v_{i+1}$ but not less than any of $v_{1}, \ldots, v_{i}$.

Clearly, it is possible for one or more of the sets $\left\{x_{1}, \ldots, x_{a}\right\},\left\{y_{1}, \ldots, y_{b}\right\}$, and $\left\{z_{1}, \ldots, z_{c}\right\}$ to be empty. For example, if $b=0$, then the product $T_{y_{1}} \cdots T_{y_{b}}$ is just the identity.

Note than none of $y_{1}, \ldots, y_{b}$ are less than any of $x_{1}, \ldots, x_{a}$ because any element less than some $x_{j}$ is automatically less than $v_{i+1}$. By similar reasoning, none of $z_{1}, \ldots, z_{c}$ are less than any of $x_{1}, \ldots, x_{a}$ either. Also any pair $y_{m}, z_{n}$ are incomparable, because $y_{m} \leqslant z_{n}$ would imply $y_{m}<v_{i+1}$, while $z_{n} \leqslant y_{m}$ would imply $z_{n}$ is less than some $v_{j}$. By transitivity and the pairwise incomparability of $v_{1}, \ldots, v_{i+1}$, each $y_{m}$ is incomparable with $v_{i+1}$, and each $z_{m}$ is incomparable with any of $v_{1}, \ldots, v_{i}$.

We will pick the indices so that $\left(x_{1}, \ldots, x_{a}\right),\left(y_{1}, \ldots, y_{b}\right)$, and $\left(z_{1}, \ldots, z_{c}\right)$ are linear extensions of the subposets $\left\{x_{1}, \ldots, x_{a}\right\},\left\{y_{1}, \ldots, y_{b}\right\}$, and $\left\{z_{1}, \ldots, z_{c}\right\}$, respectively. Then we have the following

- $\left(x_{1}, \ldots, x_{a}, y_{1}, \ldots, y_{b}\right)$ is a linear extension of $\{p \in P \mid p<q, q \in$ $\left.\left\{v_{1}, \ldots, v_{i}\right\}\right\}$.
- This yields $\eta_{\left\{v_{1}, \ldots, v_{i}\right\}}=T_{x_{1}} \cdots T_{x_{a}} T_{y_{1}} \cdots T_{y_{b}}$.
- $\left(x_{1}, \ldots, x_{a}, z_{1}, \ldots, z_{c}\right)$ is a linear extension of $\left\{p \in P \mid p<v_{i+1}\right\}$.
- This yields $\eta_{v_{i+1}}=T_{x_{1}} \cdots T_{x_{a}} T_{z_{1}} \cdots T_{z_{c}}$.
- $\left(x_{1}, \ldots, x_{a}, y_{1}, \ldots, y_{b}, z_{1}, \ldots, z_{c}\right)$ and $\left(x_{1}, \ldots, x_{a}, z_{1}, \ldots, z_{c}, y_{1}, \ldots, y_{b}\right)$ are both linear extensions of $\left\{p \in P \mid p<q, q \in\left\{v_{1}, \ldots, v_{i+1}\right\}\right\}$.
- This yields $\eta_{\left\{v_{1}, \ldots, v_{i+1}\right\}}=T_{x_{1}} \cdots T_{x_{a}} T_{y_{1}} \cdots T_{y_{b}} T_{z_{1}} \cdots T_{z_{c}}$.

Using the induction hypothesis,

$$
\begin{aligned}
& \tau_{v_{1}}^{*} \cdots \tau_{v_{i}}^{*} \tau_{v_{i+1}}^{*} \\
& =\eta_{\left\{v_{1}, \ldots, v_{i}\right\}} T_{v_{1}} \cdots T_{v_{i}} \eta_{\left\{v_{1}, \ldots, v_{i}\right\}}^{-1} \eta_{v_{i+1}} T_{v_{i+1}} \eta_{v_{i+1}}^{-1} \\
& = \\
& =T_{x_{1}} \cdots T_{x_{a}} T_{y_{1}} \cdots T_{y_{b}} T_{v_{1}} \cdots T_{v_{i}} E_{y_{b}} \cdots E_{y_{1}} E_{x_{a}} \cdots E_{x_{1}} \\
& \\
& \quad T_{x_{1}} \cdots T_{x_{a}} T_{z_{1}} \cdots T_{z_{c}} T_{v_{i+1}} E_{z_{c}} \cdots E_{z_{1}} E_{x_{a}} \cdots E_{x_{1}} \\
& = \\
& =T_{x_{1}} \cdots T_{x_{a}} T_{y_{1}} \cdots T_{y_{b}} T_{v_{1}} \cdots T_{v_{i}} E_{y_{b}} \cdots E_{y_{1}} T_{z_{1}} \cdots T_{z_{c}} T_{v_{i+1}} E_{z_{c}} \cdots E_{z_{1}} E_{x_{a}} \cdots E_{x_{1}} \\
& = \\
& T_{x_{1}} \cdots T_{x_{a}} T_{y_{1}} \cdots T_{y_{b}} T_{v_{1}} \cdots T_{v_{i}} T_{z_{1}} \cdots T_{z_{c}} T_{v_{i+1}} E_{z_{c}} \cdots E_{z_{1}} E_{y_{b}} \cdots E_{y_{1}} E_{x_{a}} \cdots E_{x_{1}} \\
& = \\
& =T_{x_{1}} \cdots T_{x_{a}} T_{y_{1}} \cdots T_{y_{b}} T_{z_{1}} \cdots T_{z_{c}} T_{v_{1}} \cdots T_{v_{i}} T_{v_{i+1}} E_{z_{c}} \cdots E_{z_{1}} E_{y_{b}} \cdots E_{y_{1}} E_{x_{a}} \cdots E_{x_{1}} \\
& =
\end{aligned} \eta_{\left\{v_{1}, \ldots, v_{i+1}\right\}} T_{v_{1}} \cdots T_{v_{i}} T_{v_{i+1}} \eta_{\left\{v_{1}, \ldots, v_{i+1}\right\}}^{-1} .
$$

where each commutation above is between toggles/elggots for pairwise incomparable elements.

We are now ready to prove Theorem 5.23.
Proof of Theorem 5.23. The right commutative diagram clearly follows from the left, so we will simply prove the left.

We use induction on $v$. If $v$ is a minimal element of $P$, then $\tau_{v}^{*}=T_{v}$ and $T_{v}^{*}=\tau_{v}$, so the diagram commutes by Theorem 5.20.

Now suppose $v$ is not minimal. Let $v_{1}, \ldots, v_{k}$ be the elements of $P$ covered by $v$, and suppose that the theorem is true for every $v_{i}$. That is, for every $A \in \mathbb{S}^{P}$ with $I=\Theta \Delta^{-1} A$, we have $\Theta \Delta^{-1}\left(\tau_{v_{i}}(A)\right)=\tau_{v_{i}}^{*}(I)$.

Then

$$
\Theta \Delta^{-1}\left(\tau_{v_{1}} \tau_{v_{2}} \ldots \tau_{v_{k}}(A)\right)=\tau_{v_{1}}^{*} \tau_{v_{2}}^{*} \ldots \tau_{v_{k}}^{*}(I)=\eta_{\left\{v_{1}, \ldots, v_{k}\right\}} T_{v_{1}} T_{v_{2}} \ldots T_{v_{k}} \eta_{\left\{v_{1}, \ldots, v_{k}\right\}}^{-1}(I)
$$

and

$$
\Theta \Delta^{-1}\left(\varepsilon_{v_{1}} \varepsilon_{v_{2}} \ldots \varepsilon_{v_{k}}(A)\right)=\varepsilon_{v_{1}}^{*} \varepsilon_{v_{2}}^{*} \ldots \varepsilon_{v_{k}}^{*}(I)=\eta_{\left\{v_{1}, \ldots, v_{k}\right\}} E_{v_{1}} E_{v_{2}} \ldots E_{v_{k}} \eta_{\left\{v_{1}, \ldots, v_{k}\right\}}^{-1}(I)
$$

by Lemma 5.24.
Throughout this proof, we let $A \in \mathbb{S}^{P}$ and $I=\Theta \Delta^{-1} A \in \mathbb{S}^{P}$. Think $A$ for "antichain" and $I$ as referring to "the order ideal generated by $A$ " if we were in the combinatorial realm.

From the definition of $T_{v}^{*}$, it follows that $\tau_{v_{1}} \tau_{v_{2}} \cdots \tau_{v_{k}} T_{v}^{*} \varepsilon_{v_{k}} \cdots \varepsilon_{v_{2}} \varepsilon_{v_{1}}=\tau_{v}$. Then

$$
\begin{aligned}
\Theta \Delta^{-1} & \left(\tau_{v}(A)\right) \\
& =\Theta \Delta^{-1}\left(\tau_{v_{1}} \tau_{v_{2}} \cdots \tau_{v_{k}} T_{v}^{*} \varepsilon_{v_{k}} \cdots \varepsilon_{v_{2}} \varepsilon_{v_{1}}(A)\right) \\
& =\eta_{\left\{v_{1}, \ldots, v_{k}\right\}} T_{v_{1}} T_{v_{2}} \cdots T_{v_{k}} \eta_{\left\{v_{1}, \ldots, v_{k}\right\}}^{-1} T_{v} \eta_{\left\{v_{1}, \ldots, v_{k}\right\}} E_{v_{k}} \cdots E_{v_{2}} E_{v_{1}} \eta_{\left\{v_{1}, \ldots, v_{k}\right\}}^{-1}(I)
\end{aligned}
$$

by Theorem 5.20 (for $T_{v}^{*}$ ) and the induction hypothesis (for $\tau_{v_{1}} \tau_{v_{2}} \cdots \tau_{v_{k}}$ and $\left.\varepsilon_{v_{k}} \cdots \varepsilon_{v_{2}} \varepsilon_{v_{1}}\right)$. Thus, it suffices to show that
(3) $\quad \eta_{\left\{v_{1}, \ldots, v_{k}\right\}} T_{v_{1}} T_{v_{2}} \cdots T_{v_{k}} \eta_{\left\{v_{1}, \ldots, v_{k}\right\}}^{-1} T_{v} \eta_{\left\{v_{1}, \ldots, v_{k}\right\}} E_{v_{k}} \cdots E_{v_{2}} E_{v_{1}} \eta_{\left\{v_{1}, \ldots, v_{k}\right\}}^{-1}=\tau_{v}^{*}$.

The toggles in the product $\eta_{\left\{v_{1}, \ldots, v_{k}\right\}}$ correspond to elements strictly less than $v_{1}, \ldots, v_{k}$; none of these cover nor are covered by $v$. Thus we can commute $T_{v}$ with $\eta_{\left\{v_{1}, \ldots, v_{k}\right\}}$ on the left side of (3) and then cancel $\eta_{\left\{v_{1}, \ldots, v_{k}\right\}}^{-1} \eta_{\left\{v_{1}, \ldots, v_{k}\right\}}$. Thus the left side of (3) is

$$
\eta_{\left\{v_{1}, \ldots, v_{k}\right\}} T_{v_{1}} T_{v_{2}} \cdots T_{v_{k}} T_{v} E_{v_{k}} \cdots E_{v_{2}} E_{v_{1}} \eta_{\left\{v_{1}, \ldots, v_{k}\right\}}^{-1} .
$$

Note that

$$
\{x \in P \mid x<v\}=\left\{x \in P \mid x<y \text { for some } y \in\left\{v_{1}, \ldots, v_{k}\right\}\right\} \cup\left\{v_{1}, \ldots, v_{k}\right\}
$$

where the union is disjoint and that $v_{1}, \ldots, v_{k}$ are maximal elements of this set. Thus for any linear extension $\left(x_{1}, \ldots, x_{n}\right)$ of $\{x \in P \mid x<y$ for some $y \in$ $\left.\left\{v_{1}, \ldots, v_{k}\right\}\right\}$, a linear extension of $\{x \in P \mid x<v\}$ is $\left(x_{1}, \ldots, x_{n}, v_{1}, \ldots, v_{k}\right)$. So $\eta_{\left\{v_{1}, \ldots, v_{k}\right\}} T_{v_{1}} T_{v_{2}} \cdots T_{v_{k}}=\eta_{v}$ and $E_{v_{k}} \cdots E_{v_{2}} E_{v_{1}} \eta_{\left\{v_{1}, \ldots, v_{k}\right\}}^{-1}=\eta_{v}^{-1}$ which means the left side of (3) is $\eta_{v} T_{v} \eta_{v}^{-1}=\tau_{v}^{*}$, the same as the right side.

The following is a corollary of Theorems 5.20 and 5.23 .
Corollary 5.25. There is an isomorphism from $\operatorname{NTog}_{A}(P)$ to $\operatorname{NTog}_{O}(P)$ given by $\tau_{v} \mapsto \tau_{v}^{*}$, with inverse given by $T_{v} \mapsto T_{v}^{*}$.

Theorem 5.26. For any finite poset $P$, NAR $=\nabla \circ \Theta \circ \Delta^{-1}$.
Proving Theorem 5.26 is equivalent to proving the following diagram commutes on the domains in which the maps are defined. This is because of Theorem 5.12 which says NOR $=\Theta \circ \Delta^{-1} \circ \nabla$.


Since NOR $=\Theta \circ \Delta^{-1} \circ \nabla$, this leads to the following simpler commutative diagram.


Proof. This proof is similar to the proof of [12, Theorem 3.21].
Let $\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ be any linear extension of a finite poset $P$. By the definitions, $\mathrm{NAR}=\tau_{x_{n}} \cdots \tau_{x_{2}} \tau_{x_{1}}$ and NOR $=T_{x_{1}} T_{x_{2}} \cdots T_{x_{n}}$.

Using the isomorphism from $\mathrm{NTog}_{A}(P)$ to $\mathrm{NTog}_{O}(P)$ given by $\tau_{v} \mapsto \tau_{v}^{*}$, it suffices to show that $\tau_{x_{n}}^{*} \cdots \tau_{x_{2}}^{*} \tau_{x_{1}}^{*}=\mathrm{NOR}=T_{x_{1}} T_{x_{2}} \cdots T_{x_{n}}$. We will use induction to prove that $\tau_{x_{k}}^{*} \cdots \tau_{x_{2}}^{*} \tau_{x_{1}}^{*}=T_{x_{1}} T_{x_{2}} \cdots T_{x_{k}}$ for $1 \leqslant k \leqslant n$.

For the base case, $\tau_{x_{1}}^{*}=T_{x_{1}}$ since $x_{1}$ is a minimal element of $P$. For the induction hypothesis, let $1 \leqslant k \leqslant n-1$ and assume that $\tau_{x_{k}}^{*} \cdots \tau_{x_{2}}^{*} \tau_{x_{1}}^{*}=T_{x_{1}} T_{x_{2}} \cdots T_{x_{k}}$. Then

$$
\begin{equation*}
\tau_{x_{k+1}}^{*} \tau_{x_{k}}^{*} \cdots \tau_{x_{2}}^{*} \tau_{x_{1}}^{*}=\eta_{x_{k+1}} T_{x_{k+1}} \eta_{x_{k+1}}^{-1} T_{x_{1}} T_{x_{2}} \cdots T_{x_{k}} . \tag{4}
\end{equation*}
$$

Let $\left(y_{1}, \ldots, y_{k^{\prime}}\right)$ be a linear extension of the subposet $\left\{y \in P \mid y<x_{k+1}\right\}$ of $P$. Then since $\left(x_{1}, \ldots, x_{n}\right)$ is a linear extension of $P$, all of $y_{1}, \ldots, y_{k^{\prime}}$ must be in $\left\{x_{1}, \ldots, x_{k}\right\}$. Furthermore, any element less than one of $y_{1}, \ldots, y_{k^{\prime}}$ must be less than $x_{k+1}$ so none of the elements of $\left\{x_{1}, \ldots, x_{k}\right\}$ outside of $\left\{y_{1}, \ldots, y_{k^{\prime}}\right\}$ are less than any of $y_{1}, \ldots, y_{k^{\prime}}$. Therefore, we can name these elements in such a way that $\left(y_{1}, \ldots, y_{k^{\prime}}, y_{k^{\prime}+1}, \ldots, y_{k}\right)$ is a linear extension of $\left\{x_{1}, \ldots, x_{k}\right\}$. Noting again that any two linear extensions of a poset differ by a sequence of swaps between adjacent incomparable elements [7], toggles of incomparable elements commute so $T_{x_{1}} T_{x_{2}} \cdots T_{x_{k}}=T_{y_{1}} \cdots T_{y_{k^{\prime}}} T_{y_{k^{\prime}+1}} \cdots T_{y_{k}}$.

From Eq. (4) and $\eta_{x_{k+1}}=T_{y_{1}} \cdots T_{y_{k^{\prime}}}$, we obtain

$$
\begin{aligned}
\tau_{x_{k+1}}^{*} \tau_{x_{k}}^{*} \cdots \tau_{x_{2}}^{*} \tau_{x_{1}}^{*} & =\eta_{x_{k+1}} T_{x_{k+1}} \eta_{x_{k+1}}^{-1} T_{x_{1}} T_{x_{2}} \cdots T_{x_{k}} \\
& =T_{y_{1}} \cdots T_{y_{k^{\prime}}} T_{x_{k+1}} E_{y_{k^{\prime}}} \cdots E_{y_{1}} T_{y_{1}} \cdots T_{y_{k^{\prime}}} T_{y_{k^{\prime}+1}} \cdots T_{y_{k}} \\
& =T_{y_{1}} \cdots T_{y_{k^{\prime}}} T_{x_{k+1}} T_{y_{k^{\prime}+1}} \cdots T_{y_{k}} \\
& =T_{y_{1}} \cdots T_{y_{k^{\prime}}} T_{y_{k^{\prime}+1}} \cdots T_{y_{k}} T_{x_{k+1}} \\
& =T_{x_{1}} T_{x_{2}} \cdots T_{x_{k}} T_{x_{k+1}} .
\end{aligned}
$$

In the fourth equality above, we could move $T_{x_{k+1}}$ to the right of $T_{y_{k^{\prime}+1}} \cdots T_{y_{k}}$ because $x_{k+1}$ is incomparable with each of $y_{k^{\prime}+1}, \ldots, y_{k}$. This is because none of these are less than $x_{k+1}$ by design nor greater than $x_{k+1}$ by position within the linear extension $\left(x_{1}, \ldots, x_{n}\right)$ of $P$.

By induction, we have $\tau_{x_{n}}^{*} \cdots \tau_{x_{2}}^{*} \tau_{x_{1}}^{*}=T_{x_{1}} T_{x_{2}} \cdots T_{x_{n}}=\mathrm{NOR}=\Theta \circ \Delta^{-1} \circ \nabla$ so

$$
\tau_{x_{n}} \cdots \tau_{x_{2}} \tau_{x_{1}}=\mathrm{NAR}=\nabla \circ \Theta \circ \Delta^{-1}
$$

From Theorem 5.26, and the ensuing commutative diagrams, the orders of NAR and NOR are equal on any poset. So Grinberg's Conjecture 5.10 is equivalent to the claim that NAR has order $a+b$ on $[a] \times[b]$. Although we do not resolve this conjecture here, we hope that giving another approach from the antichain perspective may be helpful in studying these questions.

Furthermore, it appears at every step of the process, the labels can be written in a way that is no more complicated than in the (commutative) birational realm. What we mean by that is they can be written in a way that contains every factor from the birational realm (multiplied in a certain order) and does not require extra factors that would cancel in the commutative realm. Compare Figures 3 and 5 for $P=[2] \times[3]$.

We can extend the main results on graded rescalings from § 4.2 to the noncommutative setting as long as each component of the rescaling vector $\left(a_{0}, \ldots, a_{r}\right)$ lies in the center of $\mathbb{S}$. Under this assumption Propositions 4.6 and 4.7 go through with BAR replaced by NAR. (The analogous results for NOR are true as well.) We omit the details.

Acknowledgements. The authors are grateful for useful conversations with David Einstein, Darij Grinberg, Sam Hopkins, Soichi Okada, James Propp, Richard Stanley, Jessica Striker, Corey Vorland, and Nathan Williams. We also thank an anonymous referee, who made a number of useful suggestions incorporated into this version. The second author gratefully acknowledges the hospitality of the Institut Mittag-Leffler, where a revised version of this manuscript was prepared.

## References

[1] Drew Armstrong, Christian Stump, and Hugh Thomas, A uniform bijection between nonnesting and noncrossing partitions, Trans. Amer. Math. Soc. 365 (2013), no. 8, 4121-4151.
[2] Andries E. Brouwer and Alexander Schrijver, On the period of an operator, defined on antichains, Stichting Mathematisch Centrum, 1974, Stichting Mathematisch Centrum. Zuivere Wiskunde ZW 24/74.
[3] Peter J. Cameron and Dmitriĭ G. Fon-Der-Flaass, Orbits of antichains revisited, European J. Combin. 16 (1995), no. 6, 545-554.
[4] Kevin Dilks, Oliver Pechenik, and Jessica Striker, Resonance in orbits of plane partitions and increasing tableaux, J. Combin. Theory Ser. A 148 (2017), 244-274.
[5] Kevin Dilks, Jessica Striker, and Corey Vorland, Rowmotion and increasing labeling promotion, J. Combin. Theory Ser. A 164 (2019), 72-108.
[6] David Einstein and James Propp, Combinatorial, piecewise-linear, and birational homomesy for products of two chains, Preprint, https://arxiv.org/abs/1310.5294, 2018.
[7] Gwihen Etienne, Linear extensions of finite posets and a conjecture of G. Kreweras on permutations, Discrete Math. 52 (1984), no. 1, 107-111.
[8] Darij Grinberg and Tom Roby, Iterative properties of birational rowmotion II: rectangles and triangles, Electron. J. Combin. 22 (2015), no. 3, Paper 3.40 (49 pages).
[9] , Iterative properties of birational rowmotion I: generalities and skeletal posets, Electron. J. Combin. 23 (2016), no. 1, Paper 1.33 (40 pages).
[10] Shahrzad Haddadan, Some instances of homomesy among ideals of posets, Preprint, https: //arxiv.org/abs/1410.4819, 2016.
[11] Sam Hopkins, Minuscule doppelgängers, the coincidental down-degree expectations property, and rowmotion, Preprint, https://arxiv.org/abs/1902.07301, 2019.
[12] Michael Joseph, Antichain toggling and rowmotion, Electron. J. Combin. 26 (2019), no. 1, Paper No. 1.29.
[13] Michael Joseph and Tom Roby, Toggling independent sets of a path graph, Electron. J. Combin. 25 (2018), no. 1, Paper No. 1.18 (31 pages).
[14] , A birational lifting of the Stanley-Thomas word on products of two chains, Preprint, https://arxiv.org/abs/2001.03811, 2020.
[15] Anatol N. Kirillov and Arkadiy D. Berenstein, Groups generated by involutions, Gel'fandTsetlin patterns, and combinatorics of Young tableaux, Algebra i Analiz 7 (1995), no. 1, 92-152, Translation available at http://pages.uoregon.edu/arkadiy/bk1.pdf.
[16] Gregg Musiker and Tom Roby, Paths to understanding birational rowmotion on products of two chains, Algebr. Comb. 2 (2019), no. 2, 275-304.
[17] Soichi Okada, Birational rowmotion and Coxeter-motion on minuscule posets, Preprint, https: //arxiv.org/abs/2004.05364, 2020.
[18] Dmitri I. Panyushev, On orbits of antichains of positive roots, European J. Combin. 30 (2009), no. 2, 586-594.
[19] James Propp and Tom Roby, Homomesy in products of two chains, Electron. J. Combin. 22 (2015), no. 3, Paper 3.4 (29 pages).
[20] Victor Reiner, Dennis Stanton, and Dennis White, The cyclic sieving phenomenon, J. Combin. Theory Ser. A 108 (2004), no. 1, 17-50.
[21] Tom Roby, Dynamical algebraic combinatorics and the homomesy phenomenon, in Recent trends in combinatorics, IMA Vol. Math. Appl., vol. 159, Springer, Cham, 2016, pp. 619-652.
[22] David B. Rush and Kevin Wang, On orbits of order ideals of minuscule posets II: Homomesy, Preprint, https://arxiv.org/abs/1509.08047, 2015.
[23] Richard P. Stanley, Two poset polytopes, Discrete Comput. Geom. 1 (1986), no. 1, 9-23.
[24] , Enumerative combinatorics. Volume 1, second ed., Cambridge Studies in Advanced Mathematics, vol. 49, Cambridge University Press, Cambridge, 2012.
[25] Jessica Striker, The toggle group, homomesy, and the Razumov-Stroganov correspondence, Electron. J. Combin. 22 (2015), no. 2, Paper 2.57 (17 pages).
$[26] \quad$, Rowmotion and generalized toggle groups, Discrete Math. Theor. Comput. Sci. 20 (2018), no. 1, Paper No. 17 (26 pages).
[27] Jessica Striker and Nathan Williams, Promotion and rowmotion, European J. Combin. 33 (2012), no. 8, 1919-1942.
[28] Hugh Thomas and Nathan Williams, Rowmotion in slow motion, Proc. Lond. Math. Soc. (3) 119 (2019), no. 5, 1149-1178.
[29] Corey Vorland, Homomesy in products of three chains and multidimensional recombination, Preprint, https://arxiv.org/abs/1705.02665v2, 2017.
[30] , Multidimensional toggle dynamics, Ph.D. thesis, North Dakota State University, 2018.
[31] Benjamin Wieland, A large dihedral symmetry of the set of alternating sign matrices, Electron. J. Combin. 7 (2000), Research Paper 37 (13 pages).
[32] Emine Yıldırım, The Coxeter transformation on cominuscule posets, Algebr. Represent. Theory 22 (2019), no. 3, 699-722.

Michael Joseph, Department of Technology and Mathematics, Dalton State College, 650 College Dr., Dalton, GA 30720, USA
E-mail : mjosephmath@gmail.com
Tom Roby, University of Connecticut, 341 Mansfield Road, Storrs, CT 06269-1009, USA
E-mail : tom.roby@uconn.edu


[^0]:    Manuscript received 1st October 2019, revised and accepted 20th April 2020.
    Keywords. Antichain, birational rowmotion, dynamical algebraic combinatorics, graded poset, homomesy, isomorphism, noncommutative algebra, periodicity, rowmotion, toggle group, transfer map.

