# SPECTRAL INEQUALITY AND OPTIMAL COST OF CONTROLLABILITY FOR THE STOKES SYSTEM* 

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#### Abstract

In this paper we present a new proof of the null controllability property for the Stokes system. The proof is based on a new spectral inequality for the eigenfunctions of the Stokes operator. As a consequence, we obtain the cost of the null controllability for the Stokes system of order $\mathrm{e}^{C / T}$, when $T$ is small, i.e., the same order in time as for the heat equation.


Mathematics Subject Classification. 35K40, 35Q30, 49J20.
Received June 6, 2016. Accepted June 7, 2016.

## 1. Introduction

Let $\Omega \subset \mathbb{R}^{N}(N \geq 2)$ be a bounded connected open set, whose boundary $\partial \Omega$ is smooth. Let $T>0$ and let $\omega$ be a nonempty subset of $\Omega$ which will usually be referred to as a control domain. We will use the notation $Q:=\Omega \times(0, T)$ and $\Sigma:=\partial \Omega \times(0, T)$ and we will denote by $\nu(x)$ the outward unit normal to $\Omega$ at the point $x \in \partial \Omega$.

We introduce the following usual spaces in the context of fluid mechanics

$$
\begin{gathered}
\mathbf{V}=\left\{u \in H_{0}^{1}(\Omega)^{N} ; \operatorname{div} u=0\right\} \\
\mathbf{H}=\left\{u \in L^{2}(\Omega)^{N} ; \operatorname{div} u=0, u \cdot \nu=0 \text { on } \partial \Omega\right\}
\end{gathered}
$$

and consider the controlled Stokes system

$$
\left\lvert\, \begin{array}{ll}
y_{t}-\Delta y+\nabla p=f 1_{\omega} & \text { in } Q, \\
\text { div } y=0 & \text { in } Q, \\
y=0 & \text { on } \Sigma,  \tag{1.1}\\
y(0)=y_{0} & \text { in } \Omega .
\end{array}\right.
$$

The goal of this paper is to present a proof of the following result.
Theorem 1.1. Let $\omega$ be a nonempty subset of $\Omega$. There exist constants $C_{1}>0, C_{2}>0$ depending only on $\Omega, \omega$, such that the following holds true.

[^0]For every $T>0$ and every $y_{0} \in \mathbf{H}$, there exists a control $f \in L^{2}(\omega \times(0, T))$ such that the associated solution of the Stokes system (1.1) satisfies

$$
\begin{equation*}
y(T)=0 \tag{1.2}
\end{equation*}
$$

and one has the following estimate on the cost of the control

$$
\begin{equation*}
\|f\|_{L^{2}(\omega \times(0, T))} \leq C_{1} \mathrm{e}^{C_{2} / T}\left\|y_{0}\right\|_{\mathbf{H}} \tag{1.3}
\end{equation*}
$$

The problem of finding a control function $f$ such that the solution of (1.1) satisfies (1.2) is known as the null controllability problem for the Stokes system, and has been proved by several authors in the past few years. Therefore what is new in our result is the bound (1.3) on the cost of the control.

Let us recall that in [8], a proof of null controllability is obtained by means of global Carleman inequalities for parabolic equations with homogeneous Dirichlet boundary conditions applied to the adjoint system of (1.1) (see also $[2,9,11]$ ). More recently, in $[12,13]$, a slightly different proof is obtained by means of a global Carleman inequality for parabolic equations with non-homogeneous Dirichlet boundary conditions applied to the dual problem of the system satisfied by $w=\operatorname{curl} y$.

The smallest positive constant $C_{S}$ for which one has

$$
\|f\|_{L^{2}(\omega \times(0, T))} \leq C_{S}\left\|y_{0}\right\|_{\mathbf{H}}
$$

is called the cost of the null controllability for the Stokes system at time $T$. Estimate (1.3) means that the cost of the null controllability for the Stokes system is at most of order $\mathrm{e}^{C / T}$ as $T \longrightarrow 0$, like the cost of null controllability for the heat equation (see, for instance, $[7,22,24]$ and references therein). It is also important to mention that, although (1.3) gives a natural bound for the cost of the null controllability of the Stokes system, until now it was not known if, for any given control domain, estimate (1.3) was true or not. In fact, in all the previous results on the null controllability for the Stokes system by means of global Carleman estimates, the best upper bound one can obtain for $C_{S}$ is of the form $\mathrm{e}^{C / T^{4}}$. As far as we know, the only known attempt of optimizing the cost of the controllability for the Stokes system was performed by the first author in [1] where, using the Control Transmutation Method, it is shown that estimate (1.3) holds if the control domain $\omega$ satisfies some geometrical conditions.

Our proof of Theorem 1.1 follows the strategy introduced in [15] for the null controllability of the heat equation. As it is well-known, one of the key ingredients in [15] is the obtainment of an interpolation inequality for an appropriate elliptic equation. However, it is not possible to prove an interpolation inequality for our equivalent associated elliptic system because the system does not have local Carleman estimates (see Rem. 2.1). Therefore, instead of proving an interpolation inequality for any solution of the associated elliptic system, we consider only those given in terms of low modes of the Stokes operator and prove an "almost" interpolation inequality for its curl instead of for the solution itself (see Thm. 2.2 in Sect. 2 for the precise statement). This idea of proving an inequality for the curl can be seen as the spectral equivalent to the one developed in $[12,13]$ and here the main difficulty is also to deal with the boundary terms, which are no longer zero. In Section 3, we deduce from Theorem 2.2 the spectral inequality given in Theorem 3.1. From this spectral inequality we then deduce in Section 4 a proof of the main Theorem 1.1; for this proof, we use an argument due to Seidman in [24] and revisited by Miller in [22]. The idea is to use the spectral inequality for low modes and the decay properties of the Stokes system to prove directly an observability inequality for the adjoint system. This strategy can be seen as dual analogous of the method developed in [15]. Finally, in Appendix A we give a proof of the Carleman inequality (2.14) following closely [15], and in Appendix B a proof of Lemma B.1, which gives a fundamental result on the spectral localization at the boundary; for the convenience of the reader, we recall also in Appendix C the proof of the interpolation estimate of Proposition 2.4.

Remark 1.2. Our proof of Theorem 1.1 applies as well in the more general case where $\Omega$ is a relatively compact connected open set in a Riemannian manifold $M$.

In all the paper, we will use semi-classical analysis in the formulation of Carleman estimates, as it is done in $[14,15,17]$. We refer to $[3,18]$ for an introduction to semi-classical analysis.

## 2. Interpolation inequality

Let $\left\{e_{j}\right\}_{j=1}^{\infty}$ be an orthonormal basis of $\mathbf{H}$, given by the eigenvectors of the Stokes equation

$$
\left\lvert\, \begin{array}{ll}
-\Delta e_{j}+\nabla p_{j}=\mu_{j} e_{j} & \text { in } \Omega  \tag{2.1}\\
\operatorname{div} e_{j}=0 & \text { in } \Omega \\
e_{j}=0 & \text { on } \partial \Omega
\end{array}\right.
$$

with the sequence of eigenvalues $\left\{\mu_{j}\right\}_{j=1}^{\infty}$ satisfying $0<\mu_{1} \leq \mu_{2} \leq \ldots$ and $\lim _{j \rightarrow \infty} \mu_{j}=\infty$. Then $\left\{e_{j}\right\}_{j=1}^{\infty}$ is also an orthogonal basis of $\mathbf{V}$ and one has

$$
\begin{equation*}
\left\|\operatorname{curl}\left(e_{j}\right)\right\|_{L^{2}}^{2}=\mu_{j} . \tag{2.2}
\end{equation*}
$$

We introduce the sets

$$
Z=(0,1) \times \Omega \text { and } W=(1 / 4,3 / 4) \times \Omega
$$

and as in [15], for $\Lambda \geq 1$, we introduce special solutions of the Stokes system of the form

$$
\begin{equation*}
(u, p)=\sum_{\mu_{j} \leq \Lambda} a_{j} \frac{\sinh \left(s \sqrt{\mu_{j}}\right)}{\sqrt{\mu_{j}}}\left(e_{j}(x), p_{j}(x)\right) \tag{2.3}
\end{equation*}
$$

where $\left(a_{j}\right)_{j}$ is a given sequence of complex numbers.
Remark 2.1. The pair $(u, p)$ given by (2.3) is a solution of the elliptic system

$$
\left\lvert\, \begin{array}{ll}
-\partial_{s s}^{2} u-\Delta_{x} u+\nabla_{x} p=0 & \text { in } Z,  \tag{2.4}\\
\operatorname{div}_{x} u=0 & \text { in } Z
\end{array}\right.
$$

with boundary conditions

$$
\left\lvert\, \begin{array}{ll}
u(s, x)=0 & \text { on }(0,1) \times \partial \Omega  \tag{2.5}\\
u(0, x)=0 & \text { in } \Omega \\
\partial_{s} u(0, x)=\sum_{\mu_{j} \leq \Lambda} a_{j} e_{j}(x) & \text { in } \Omega
\end{array}\right.
$$

The system (2.4) does not have local unique continuation property. Indeed, consider a function $q=q(s, x)$ such that $\Delta_{x} q=0$, then the pair

$$
(u, p)=\left(\nabla_{x} q, \partial_{s s}^{2} q\right)
$$

is a solution of (2.4). Taking $q(s, x)=a(s) p(x)$ with $a \in C_{0}^{\infty}(\mathbb{R})$ and $\triangle p=0$, we see that the local zeros of $q$ do not propagate through the surfaces $s=s_{0}$. Therefore, we cannot obtain a local Carleman estimate for system (2.4).

Therefore, we will work with the 2 -vector field $v=\operatorname{curl}(u)$, given by

$$
\begin{equation*}
v(s, x)=\sum_{\mu_{j} \leq \Lambda} a_{j} \frac{\sinh \left(s \sqrt{\mu_{j}}\right)}{\sqrt{\mu_{j}}} \operatorname{curl}\left(e_{j}\right)(x) \tag{2.6}
\end{equation*}
$$

which satisfies

$$
\left\lvert\, \begin{array}{ll}
-\partial_{s s}^{2} v-\Delta_{x} v=0 & \text { in } Z  \tag{2.7}\\
v(0, x)=0 & \text { in } \Omega \\
\partial_{s} v(0, x)=\sum_{\mu_{j} \leq \Lambda} a_{j} \operatorname{curl}\left(e_{j}\right)(x) & \text { in } \Omega
\end{array}\right.
$$

Recall that in $\mathbb{R}^{N}$, the 2 -vector field $v=\operatorname{curl}(u)$ is given in coordinates by the 2 -antisymetric tensor $v_{i, j}=$ $\frac{\partial u_{j}}{\partial x_{i}}-\frac{\partial u_{i}}{\partial x_{j}}$. In the Riemannian setting, if the vector field $u$ is identified with a 1-form, then $v=\operatorname{curl}(u)$ is identified
with the 2 -form $\mathrm{d} u$, where d denotes the exterior derivative. Observe that when $u$ satisfies $\left.u\right|_{\partial \Omega}=0$, the only non zero components of $\left.\operatorname{curl}(u)\right|_{\partial \Omega}$ are the tangential ones. Therefore, in that case, $\left.\operatorname{curl}(u)\right|_{\partial \Omega}$ is a vector field tangent to the boundary, which is identified with the 1-form on the boundary $\mathrm{d} u\lrcorner \nu$, where $\lrcorner$ denotes the interior product of a differential form with a vector.

To overcome the lack of boundary condition for $v$ on $(0,1) \times \partial \Omega$, we introduce a small parameter $h$ related to $\Lambda$ by

$$
\begin{equation*}
h=\frac{\delta}{\sqrt{\Lambda}} \quad \text { with } \quad \delta>0 \quad \text { small. } \tag{2.8}
\end{equation*}
$$

Informally, $x \mapsto v(s, x)$ is concentrated at frequencies $\leq \sqrt{\Lambda}$. Thus, for the semiclassical analysis with semiclassical parameter $h$, the spectrum of $v$ will be concentrated in the set

$$
|\xi| \leq h \sqrt{\Lambda}=\delta
$$

Therefore by taking $\delta>0$ small, we will force localization near $\xi=0$. The aim of this section is to prove the following result.

Theorem 2.2. There exists $\Lambda_{0}>0, \mu>0, c>0, \alpha \in(0,1)$, and for $\delta>0$ small enough $C_{\delta}>0$, such that for all $\Lambda \geq \Lambda_{0}$, all sequence of complex numbers $\left(a_{j}\right)_{j}$, the 2 -vector field $v$ defined in (2.6) satisfies with $h=\delta \Lambda^{-1 / 2}$

$$
\begin{equation*}
\|v\|_{H^{1}(W)} \leq C_{\delta}\left(\mathrm{e}^{-\mu / h}\|v\|_{H^{1}(Z)}+\mathrm{e}^{c / h}\|v\|_{H^{1}(Z)}^{1-\alpha}\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\omega)}^{\alpha}\right) \tag{2.9}
\end{equation*}
$$

Remark 2.3. If one want to minimize the right hand side of (2.9) with respect to $h$, we get that the minimum is achieved at $h_{*}$ given by

$$
\frac{c+\mu}{h_{*}}=\log \left(\frac{\mu}{c}\right)+\alpha \log \left(\frac{\|v\|_{H^{1}(Z)^{N}}}{\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\omega)^{N}}}\right)
$$

Therefore, in the case $\delta \Lambda^{-1 / 2}<h_{*}$, the minimum of the right hand side of (2.9) in the interval $\left.h \in\right] 0, \delta \Lambda^{-1 / 2}$ ] will be achieved at $h=\delta \Lambda^{-1 / 2}$. That is why we do not replace (2.9) by a pure interpolation inequality for solutions of the system (2.7).

The proof of the inequality (2.9) is based on the use of elliptic Carleman inequalities, and an analytic deformation argument with respect to the $s$ variable.

Proof of Theorem 2.2. In the proof, $v$ will allways denote the 2 -vector field defined in (2.6). We fix the notation $z=(s, x)$. Let $A:=-\triangle_{z}=-\partial_{s s}^{2}-\Delta_{x}$. For $r>0$ small, let $W_{r}$ be the open set

$$
\begin{equation*}
\left.W_{r}=\right] 1 / 9,9 / 10[\times\{x \in \Omega, \operatorname{dist}(x, \partial \Omega)>r / 2\} \tag{2.10}
\end{equation*}
$$

While not stated explicitly in [14], the following proposition is contained in the proof of the interpolation estimates in paragraph 5.1 of [14], and also implicitly in [15]. For completeness, we recall its proof in Appendix C.

Proposition 2.4. For all $r>0$, there exists $D>0$ and $\nu \in] 0,1\left[\right.$ such that for all $f \in H^{2}(Z)$ such that $\left.f\right|_{s=0}=0$, one has

$$
\begin{equation*}
\|f\|_{H^{1}\left(W_{r}\right)} \leq D\|f\|_{H^{1}(Z)}^{1-\nu}\left(\|A(f)\|_{L^{2}(Z)}+\left\|\partial_{s} f(0, x)\right\|_{L^{2}(\omega)}\right)^{\nu} \tag{2.11}
\end{equation*}
$$

For $r>0$, let $K_{r}$ be the compact set

$$
K_{r}=\{x \in \bar{\Omega}, \operatorname{dist}(x, \partial \Omega) \leq r\}
$$

In the sequel, we choose $r_{0}$ small enough, such that the map from $K_{r_{0}}$ into $\left[0, r_{0}\right] \times \partial \Omega$ defined by $x \mapsto(r, y)$, where $r=\operatorname{dist}(x, \partial \Omega)$ and $y \in \partial \Omega$ satisfies $\operatorname{dist}(x, \partial \Omega)=|x-y|$, is a $C^{\infty}$ diffeomorphism. Let $s_{0} \in[1 / 4,3 / 4]$.

We introduce the function $\psi(s, r)=r-\left(s-s_{0}\right)^{2}$ and consider $\varphi=\mathrm{e}^{D \psi}$. It is well known that, for $D>0$ large enough, $\varphi$ satisfies Hormander's sub-ellipticity condition for the operator $A$ in the variables $(s, r, y)$ and one has

$$
\begin{equation*}
\partial_{r} \varphi(s, x)>0 \quad \text { in } \quad[0,1]_{s} \times K_{r_{0}} \tag{2.12}
\end{equation*}
$$

We also consider a cut-off function $\chi(s, r)=\chi_{0}(s) \chi_{1}(r)$, with $\chi_{0} \in C_{0}^{\infty}(] s_{0}-2 s_{*}, s_{0}+2 s_{*}[), 0 \leq \chi_{0} \leq 1$, $\chi_{0}(s)=1$ for $\left|s-s_{0}\right| \leq 3 s_{*} / 2$, with $s_{*}>0$ small, and $\chi_{1} \in C_{0}^{\infty}\left(\left[0, r_{0}[), 0 \leq \chi_{1} \leq 1\right.\right.$, with $\chi_{1} \equiv 1$ on $\left[0, r_{0} / 2\right]$. Decreasing $r_{0}$, we will assume $r_{0}<s_{*}^{2}$. In particular, we will use the following fact:

$$
\begin{equation*}
\text { There exists } \mu_{0}>0 \text { such that }\left\{\left|s-s_{0}\right| \geq s_{*} \text { and } r \leq r_{0}\right\} \Rightarrow\left\{\varphi(s, r) \leq \varphi\left(s_{0}, 0\right)-\mu_{0}\right\} \tag{2.13}
\end{equation*}
$$

Applying the Carleman inequality given in Theorem A. 5 in Appendix A to $\chi v$, there exist $C$ and $h_{1}>0$ such that

$$
\begin{align*}
h\left\|\mathrm{e}^{\varphi / h} \chi v\right\|_{L^{2}(Z)}^{2} & +h^{3}\left\|\mathrm{e}^{\varphi / h} \nabla_{s, x}(\chi v)\right\|_{L^{2}(Z)}^{2} \\
& \leq C\left(h\left\|\mathrm{e}^{\varphi / h} \chi v\right\|_{L^{2}(r=0)}^{2}+h^{3}\left\|\mathrm{e}^{\varphi / h} \nabla_{s, y}(\chi v)\right\|_{L^{2}(r=0)}^{2}+h^{4}\left\|\mathrm{e}^{\varphi / h} A(\chi v)\right\|_{L^{2}(Z)}^{2}\right) \tag{2.14}
\end{align*}
$$

for every $h \in\left(0, h_{1}\right]$. We now analyze each one of the terms on the right-hand side of (2.14). First, let us rewrite (2.14) in a more convenient way. We define the 2 -vector field $G$ by

$$
\begin{equation*}
G(s, r, y)=\chi_{0}(s) \chi_{1}(r) \mathrm{e}^{\varphi(s, r) / h} v(s, r, y)=\chi_{0}(s) \chi_{1}(r) \mathrm{e}^{\varphi(s, r) / h} \sum_{\mu_{j} \leq \Lambda} a_{j}(s) \operatorname{curl}\left(e_{j}\right)(r, y) \tag{2.15}
\end{equation*}
$$

and we denote by $G_{0}$ the trace of $G$ on the boundary, which is the vector field tangent to the boundary

$$
G_{0}(s, y)=\chi_{0}(s) \mathrm{e}^{\varphi_{0}(s) / h} v_{0}(s, y)=\left.\chi_{0}(s) \mathrm{e}^{\varphi_{0}(s) / h} \sum_{\mu_{j} \leq \Lambda} a_{j}(s) \operatorname{curl}\left(e_{j}\right)\right|_{\partial \Omega}(y)
$$

where $a_{j}(s)=a_{j} \sinh \left(s \sqrt{\mu_{j}}\right) / \sqrt{\mu_{j}}, \quad v_{0}=\left.v\right|_{\partial \Omega}$ and $\varphi_{0}(s)=\varphi(s, 0)$. Inequality (2.14) then reads (with an other constant $C$ ):

$$
\begin{equation*}
\|G\|_{1, s c}^{2} \leq C\left(\left\|G_{0}\right\|_{1, s c}^{2}+h^{3}\left\|\mathrm{e}^{\varphi / h} A(\chi v)\right\|_{L^{2}(Z)}^{2}\right) \tag{2.16}
\end{equation*}
$$

where we use the notations, with $X=] 0,1[\times \partial \Omega$,

$$
\|G\|_{1, s c}^{2}:=\|G\|_{L^{2}(Z)}^{2}+\left\|h \nabla_{s, x} G\right\|_{L^{2}(Z)}^{2}, \quad\left\|G_{0}\right\|_{1, s c}^{2}:=\left\|G_{0}\right\|_{L^{2}(X)}^{2}+\left\|h \nabla_{s, y} G_{0}\right\|_{L^{2}(X)}^{2}
$$

## - Estimate of the boundary terms:

We consider a cut-off function $\theta \in C_{0}^{\infty}(]-2,2[)$ satisfying $0 \leq \theta \leq 1$, and $\theta \equiv 1$ in a neighborhood of $[-\sqrt{3}, \sqrt{3}]$. Let $\triangle_{\partial \Omega}$ be the Laplace operator on the boundary $\partial \Omega$ acting on vector fields. Let $\varepsilon_{j}$ be an orthonormal basis of eigenfunctions of $\triangle_{\partial \Omega}$ with $-\triangle_{\partial \Omega} \varepsilon_{j}=\tau_{j}^{2} \varepsilon_{j}$. Let $\Theta=\theta\left(\sqrt{1-\Lambda^{-1} \Delta_{\partial \Omega}}\right)$ be the bounded operator acting on $L^{2}$ sections of the tangent bundle $T \partial \Omega$

$$
\Theta\left(\sum_{j} f_{j} \varepsilon_{j}\right)=\sum_{j} \theta\left(\sqrt{1+\Lambda^{-1} \tau_{j}^{2}}\right) f_{j} \varepsilon_{j}
$$

We know (see [3]) that $\Theta$ is a semi-classical pseudo-differential operator of degree 0 (with small parameter $\Lambda^{-1 / 2}$ ), with a scalar semi-classical principal symbol equal to

$$
\sigma(\Theta)=\theta\left(\sqrt{1+|\eta|_{y}^{2}}\right) I d
$$

where $|\eta|_{y}^{2}$ denotes the square of Riemannian length of the covector $\eta \in T_{y}^{*} \partial \Omega$. From the properties of $\theta$, we get that the essential support of $\Theta$ is contained in the set $|\eta|_{y} \leq \sqrt{3}$, and $\Theta$ is microlocally equal to $I d$ on the set $|\eta|_{y} \leq \sqrt{2}$. We write

$$
G_{0}(s, y)=G_{1}(s, y)+G_{2}(s, y)
$$

with

$$
G_{1}=\Theta\left(G_{0}\right), \quad G_{2}=(1-\Theta)\left(G_{0}\right)
$$

Remark 2.5. Notice that the operator $\Theta$ acts only on the $y \in \partial \Omega$ variable, and that $G_{1}$ and $G_{2}$ are respectively the low and the high frequencies of $G_{0}$. More precisely, $G_{1}$ is concentrated in the set $\left|\partial_{y}\right| \leq \sqrt{3} \sqrt{\Lambda}$, and $G_{2}$ is concentrated in the set $\left|\partial_{y}\right| \geq \sqrt{2} \sqrt{\Lambda}$.

From (2.16), we get

$$
\begin{equation*}
\|G\|_{H_{s c}^{1}}^{2} \leq C\left(h^{3}\left\|\mathrm{e}^{\varphi / h} A(\chi v)\right\|_{L^{2}(Z)}^{2}+2\left\|G_{1}\right\|_{1, s c}^{2}+2\left\|G_{2}\right\|_{1, s c}^{2}\right) \tag{2.17}
\end{equation*}
$$

To estimate the contribution of $G_{2}$ to the right hand side of (2.17), we first observe that Lemma B. 1 in Appendix B implies that, for every $N \in \mathbb{N}$, there exists $C_{N}$ such that for all $s \in[0,1]$ one has

$$
\begin{equation*}
\int_{\partial \Omega}\left|G_{2}(s, .)\right|^{2}+\left|h \nabla_{y} G_{2}(s, .)\right|^{2} \mathrm{~d} \sigma(y) \leq C_{N} \Lambda^{-N} K(s) \tag{2.18}
\end{equation*}
$$

where $K(s)=\sum_{\mu_{j} \leq \Lambda} \chi_{0}^{2}(s) \mathrm{e}^{2 \varphi_{0}(s) / h}\left|a_{j}\right|^{2} \frac{\sinh ^{2}\left(s \sqrt{\mu_{j}}\right)}{\mu_{j}}$. Next, we notice that

$$
\begin{equation*}
\int_{\Omega}|G|^{2} \mathrm{~d} x \geq \int_{r \leq r_{0} / 2}|G|^{2} \mathrm{~d} x \geq \mathrm{e}^{2 \varphi_{0}(s) / h} \chi_{0}^{2}(s) \sum_{\mu_{j} \leq \Lambda}\left|a_{j}\right|^{2} \sinh ^{2}\left(s \sqrt{\mu_{j}}\right)-\int_{r \geq r_{0} / 2} \chi_{0}^{2}(s) \mathrm{e}^{2 \varphi(s, r) / h}|v(s, .)|^{2} \mathrm{~d} x \tag{2.19}
\end{equation*}
$$

The proof of (2.19) is achieved taking into account that $\varphi(s, r) \geq \varphi_{0}(s)$ for every $r \in\left[0, r_{0}\right), \chi_{1}(r)=1$ for $r \in\left[0, r_{0} / 2\right]$, curl $e_{j} \perp$ curl $e_{i}$ in $L^{2}(\Omega)$ if $i \neq j$ and $\left\|\operatorname{curl} e_{j}\right\|_{L^{2}(\Omega)}^{2}=\mu_{j}$ for all $j$. From $\mu_{1}>0$, we thus get from (2.19) that there exists $C>0$ such that

$$
K(s) \leq C\left(\int_{\Omega}|G|^{2} \mathrm{~d} x+\int_{r \geq r_{0} / 2} \chi_{0}^{2}(s) \mathrm{e}^{2 \varphi(s, r) / h}|v(s, .)|^{2} \mathrm{~d} x\right)
$$

Integrating this last inequality with respect to $s$, using Proposition 2.4 and $A(v)=0$, and also $\left.\operatorname{support}(K(s)) \subset \operatorname{support}\left(\chi_{0}(s)\right) \subset\right] 1 / 9,9 / 10\left[\right.$, we get that there exists $\nu \in(0,1)$ and $C_{0}$ such that for all $\left.h \in] 0, h_{1}\right]$ the following inequality holds true

$$
\begin{equation*}
\int_{0}^{1} K(s) \mathrm{d} s \leq C\left(\|G\|_{L^{2}(Z)}^{2}+\mathrm{e}^{C_{0} / h}\|v\|_{H^{1}(Z)}^{2(1-\nu)}\left(\int_{\omega}\left|\partial_{s} v(0, x)\right|^{2} \mathrm{~d} x\right)^{2 \nu}\right) \tag{2.20}
\end{equation*}
$$

Therefore, estimate (2.18) implies

$$
\begin{equation*}
\int_{0}^{1} \int_{\partial \Omega}\left|G_{2}\right|^{2}+\left|h \nabla_{y} G_{2}\right|^{2} \mathrm{~d} \sigma(y) \mathrm{d} s \leq C_{N} \Lambda^{-N}\left(\|G\|_{L^{2}(Z)}^{2}+\mathrm{e}^{C_{0} / h}\|v\|_{H^{1}(Z)}^{2(1-\nu)}\left(\int_{\omega}\left|\partial_{s} v(0, x)\right|^{2} \mathrm{~d} x\right)^{2 \nu}\right) \tag{2.21}
\end{equation*}
$$

By Lemma B.1, we also have

$$
\begin{equation*}
\int_{\partial \Omega}\left|h \partial_{s} G_{2}(s, .)\right|^{2} \mathrm{~d} \sigma(y) \leq C_{N} \Lambda^{-N} \sum_{\mu_{j} \leq \Lambda}\left|h \partial_{s}\left(\chi_{0}(s) \mathrm{e}^{\varphi_{0}(s) / h} a_{j}(s)\right)\right|^{2} \tag{2.22}
\end{equation*}
$$

Let $\tilde{\chi}_{0} \in C_{0}^{\infty}(] s_{0}-2 s_{*}, s_{0}+2 s_{*}[), 0 \leq \tilde{\chi}_{0} \leq 1$ and $\tilde{\chi}_{0}=1$ on the support of $\chi_{0}$. Let

$$
\tilde{K}(s)=\sum_{\mu_{j} \leq \Lambda} \tilde{\chi}_{0}^{2}(s) \mathrm{e}^{2 \varphi_{0}(s) / h}\left|a_{j}\right|^{2} \frac{\sinh ^{2}\left(s \sqrt{\mu_{j}}\right)}{\mu_{j}}
$$

For $s \geq 1 / 9$ and $\mu_{j} \leq \Lambda$, one has $h \cosh \left(s \sqrt{\mu_{j}}\right) \leq c_{0} h \sqrt{\Lambda} \frac{\sinh \left(s \sqrt{\mu_{j}}\right)}{\sqrt{\mu}_{j}}$ with $c_{0}=\sup _{x \geq \sqrt{\mu_{1}} / 9} \frac{\cosh (x)}{\sinh (x)}$. Thus, we get from $h \sqrt{\Lambda}=\delta \leq 1$, that there exists $C$ such that

$$
\begin{gathered}
\left|h \partial_{s}\left(\chi_{0}(s) \mathrm{e}^{\varphi_{0}(s) / h} a_{j}(s)\right)\right|^{2} \leq \\
3\left|a_{j}\right|^{2} \mathrm{e}^{2 \varphi_{0}(s) / h}\left(\left|h \partial_{s} \chi_{0} \frac{\sinh \left(s \sqrt{\mu_{j}}\right)}{\sqrt{\mu}_{j}}\right|^{2}+\left|\chi_{0} \frac{\sinh \left(s \sqrt{\mu_{j}}\right)}{\sqrt{\mu}_{j}} \partial_{s} \varphi_{0}\right|^{2}+\left|h \cosh \left(s \sqrt{\mu_{j}}\right) \chi_{0}\right|^{2}\right) \\
\leq C \tilde{\chi}_{0}^{2}(s) \mathrm{e}^{2 \varphi_{0}(s) / h}\left|a_{j}\right|^{2} \frac{\sinh ^{2}\left(s \sqrt{\mu_{j}}\right)}{\mu_{j}}
\end{gathered}
$$

Therefore, arguing as above and using (2.22), we get

$$
\begin{equation*}
\int_{0}^{1} \int_{\partial \Omega}\left|h \partial_{s} G_{2}\right|^{2} \mathrm{~d} \sigma(y) \mathrm{d} s \leq C_{N} \Lambda^{-N}\left(\|\tilde{G}\|_{L^{2}(Z)}^{2}+\mathrm{e}^{C_{0} / h}\|v\|_{H^{1}(Z)^{N}}^{2(1-\nu)}\left(\int_{\omega}\left|\partial_{s} v(0, x)\right|^{2} \mathrm{~d} x\right)^{2 \nu}\right) \tag{2.23}
\end{equation*}
$$

where $\tilde{G}$ is defined as $G$ in $(2.15)$ with $\tilde{\chi}_{0}(s)$ instead of $\chi_{0}(s)$.
One has by construction $\tilde{\chi}_{0} \leq \chi_{0}+\mathbf{1}_{\left\{s_{*} \leq\left|s-s_{0}\right| \leq 2 s_{*}\right\}}$. This and (2.13)implies

$$
|\tilde{G}| \leq|G|+\mathrm{e}^{\left(\varphi\left(s_{0}, 0\right)-\mu_{0}\right) / h}|v|
$$

Summing up, we get that the contribution of $G_{2}$ to the right hand side of (2.17) is estimate by

$$
\begin{equation*}
\left\|G_{2}\right\|_{H_{s c}^{1}}^{2} \leq C_{N} \Lambda^{-N}\left(\|G\|_{L^{2}(Z)}^{2}+\mathrm{e}^{2\left(\varphi\left(s_{0}, 0\right)-\mu_{0}\right) / h}\|v\|_{L^{2}(Z)}^{2}+\mathrm{e}^{C_{0} / h}\|v\|_{H^{1}(Z)}^{2(1-\nu)}\left(\int_{\omega}\left|\partial_{s} v(0, x)\right|^{2} \mathrm{~d} x\right)^{2 \nu}\right) \tag{2.24}
\end{equation*}
$$

We now estimate the contribution of $G_{1}$. Let $B$ be the h-pseudodifferential operator acting on the $s$ variable defined by

$$
\begin{equation*}
B(f)(s)=\frac{1}{2 \pi h} \int \mathrm{e}^{i\left(s-s^{\prime}\right) \sigma / h} b_{1}(\sigma) b_{0}\left(s^{\prime}-s_{0}\right) f\left(s^{\prime}\right) \mathrm{d} s^{\prime} \mathrm{d} \sigma \tag{2.25}
\end{equation*}
$$

with $b_{j} \in C_{0}^{\infty}(]-\alpha_{j}, \alpha_{j}[)$ equal to 1 in $\left[-\alpha_{j} / 2, \alpha_{j} / 2\right]$, and $\alpha_{j}>0$ small.
We have with $X=] 0,1[\times \Omega$

$$
\begin{equation*}
\left\|G_{1}\right\|_{H_{s c}^{1}(X)}^{2} \leq 2\left\|B G_{1}\right\|_{H_{s c}^{1}(X)}^{2}+2\left\|(1-B) G_{1}\right\|_{H_{s c}^{1}(X)}^{2} \tag{2.26}
\end{equation*}
$$

For the first term on the right-hand side of (2.26), we prove the following.
Claim 1. There exist $\alpha_{j}>0$ and $\delta_{1}>0$ such that for all $\left.\left.\delta \in\right] 0, \delta_{1}\right], B G_{1}$ satisfies

$$
\begin{equation*}
\forall N, \exists C_{N} \text { such that }\left\|B G_{1}\right\|_{H_{s c}^{1}(X)}^{2} \leq C_{N} h^{N}\|G\|_{L^{2}(Z)}^{2} \tag{2.27}
\end{equation*}
$$

Proof of Claim 1. One has

$$
\begin{equation*}
B G_{1}=\left.B \Theta(G)\right|_{\partial \Omega} \tag{2.28}
\end{equation*}
$$

The operator $B \Theta$ is a h-pseudodifferential tangential operator with essential support contained in the set

$$
K=\left\{(s, y ; \sigma, \eta), \quad\left|s-s_{0}\right| \leq \alpha_{0}, y \in \partial \Omega,|\sigma| \leq \alpha_{1},\|\eta\| \leq \sqrt{3} \delta\right\}
$$

By construction, one has with $A_{\varphi}=h^{2} \mathrm{e}^{\varphi / h} A \mathrm{e}^{-\varphi / h}$

$$
\begin{equation*}
\left.A_{\varphi} G=h^{2} e^{\varphi / h} A\left(\chi_{0}(s) \chi_{1}(r) v\right)=0 \quad \text { on the open set } \quad\left|s-s_{0}\right|<3 s_{*} / 2, r \in\right] 0, r_{0} / 2[ \tag{2.29}
\end{equation*}
$$

The principal symbol of $A_{\varphi}$ is given by

$$
\left(\sigma+i \partial_{s} \varphi\right)^{2}+\left(\xi+i \nabla_{x} \varphi\right)^{2}
$$

where $\xi=(\tau, \eta)$ is the dual variable of $x=(r, y)$. Since $\varphi$ is radial, the principal symbol of $A_{\varphi}$ is given by

$$
\left(\sigma+i \partial_{s} \varphi\right)^{2}+\left(\tau+i \partial_{r} \varphi\right)^{2}+\eta^{2}
$$

The roots of the principal symbol with respect to $\tau$ are given by

$$
\tau_{ \pm}(r, s, y ; \sigma, \eta)=-i \partial_{r} \varphi \pm i \sqrt{\eta^{2}+\left(\sigma+i \partial_{s} \varphi\right)^{2}}
$$

From $\varphi=\mathrm{e}^{D \psi}$ and $\psi(s, r)=r-\left(s-s_{0}\right)^{2}$, we get that there exists a constant $C$ such that for all $(r, s, y ; \sigma, \eta) \in$ $\left[0, r_{0} / 2\right] \times K$ one has

$$
\operatorname{Im} \tau_{ \pm}(r, s, y ; \sigma, \eta) \leq-e^{D \psi}\left(1-C \alpha_{0}\right)+C\left(\delta+\alpha_{1}\right)
$$

Therefore, for $\delta$ and the $\alpha_{j}$ 's small enough, we get that there exists $c_{0}>0$ such that

$$
\begin{equation*}
\forall(r, s, y ; \sigma, \eta) \in\left[0, r_{0} / 2\right] \times K, \quad \operatorname{Im} \tau_{ \pm}(r, s, y ; \sigma, \eta) \leq-c_{0}<0 \tag{2.30}
\end{equation*}
$$

Then Claim 1 follows from (2.29), (2.28), and classical elliptic boundary estimates applied to the differential operator $A_{\varphi}$.

For the second term on the right-hand side of (2.26), we prove:
Claim 2. There exist $C>0, \delta_{0}>0, c_{0}>0$ such that

$$
\begin{equation*}
\left.\forall \delta \in] 0, \delta_{0}\right], \quad\left\|(1-B) G_{1}\right\|_{H_{s c}^{1}(X)}^{2} \leq C \mathrm{e}^{2\left(\varphi\left(s_{0}, 0\right)-c_{0}\right) / h}\|v\|_{H^{1}(Z)}^{2} \tag{2.31}
\end{equation*}
$$

Proof of Claim 2:. We begin noticing that

$$
G_{0}(s, y)=\sum_{\mu_{j} \leq \Lambda} a_{j} \chi_{0}(s) \mathrm{e}^{\varphi_{0}(s) / h}\left(\left(\mathrm{e}^{s \sqrt{\mu_{j}}}-\mathrm{e}^{-s \sqrt{\mu_{j}}}\right) / 2\right)\left(\frac{\left.\operatorname{curl} e_{j}\right|_{r=0}}{\sqrt{\mu_{j}}}\right) .
$$

Set $\nu_{j}=h^{2} \mu_{j}$. We have $\sqrt{\nu_{j}} \leq h \sqrt{\Lambda}=\delta$ and

$$
h^{-1} \varphi_{0}(s) \pm s \sqrt{\mu_{j}}=h^{-1}\left(\varphi_{0}(s) \pm s \sqrt{\nu_{j}}\right) .
$$

We also have

$$
\varphi_{0}(s)=\varphi_{0}\left(s_{0}\right)-D\left(s-s_{0}\right)^{2}+O\left(\left(s-s_{0}\right)^{4}\right)
$$

Let us now make the change of variable $s \mapsto s_{0}+t$. Set $\chi_{0}\left(s_{0}+t\right) b_{0}(t)=\tilde{\chi}(t)$ and $\theta(t)=\varphi_{0}\left(s_{0}\right)-\varphi_{0}\left(s_{0}+t\right)=$ $D t^{2}+O\left(t^{4}\right)$. The function $\tilde{\chi} \in C_{0}^{\infty}$ is equal to 1 in a neighborhood of $t=0$, and the function $\theta(t)$ is real analytic. Let $\phi_{j}(t, \sigma)$ be the phase function

$$
\phi_{j}(t, \sigma)=-t \sigma+i\left(\theta(t) \pm\left(t+s_{0}\right) \sqrt{\nu_{j}}\right) .
$$

and let $g_{j}$ be the vectors fields on the boundary $\partial \Omega$

$$
g_{j}(y)=\frac{\Theta\left(\left.\operatorname{curl} e_{j}\right|_{r=0}\right)(y)}{\sqrt{\mu_{j}}}
$$

Then one has

$$
\begin{equation*}
(1-B) G_{1}(t, y)=\frac{\mathrm{e}^{\varphi\left(s_{0}, 0\right) / h}}{2 \pi h} \sum_{\mu_{j} \leq \Lambda} a_{j} g_{j}(y) \int \mathrm{e}^{i \sigma t / h}\left(1-b_{1}(\sigma)\right)\left(\int \mathrm{e}^{i \phi_{j}\left(t^{\prime}, \sigma\right) / h} \tilde{\chi}\left(t^{\prime}\right) \mathrm{d} t^{\prime}\right) \mathrm{d} \sigma \tag{2.32}
\end{equation*}
$$

By classical trace theorem, there exists $C^{\prime}, m^{\prime}$ such that $\left\|g_{j}\right\|_{H^{1}(\partial \Omega)} \leq C^{\prime} \Lambda^{m^{\prime}}$ for all $j$ such that $0<\mu_{1} \leq \mu_{j} \leq \Lambda$, and by (2.2), one gets easily that there exists $C$ such that $\sum_{\mu_{j} \leq \Lambda}\left|a_{j}\right|^{2} \leq C\|v\|_{L^{2}(\Omega)}^{2} \leq C\|v\|_{H^{1}(\Omega)}^{2}$. Since $b_{1}(\sigma)=1$ for $|\sigma| \leq \alpha_{1} / 2$, we get from (2.32), using Cauchy-Schwartz inequality and Weyl formula to estimate $\sum_{\mu_{j} \leq \Lambda}\left|a_{j}\right|\left\|g_{j}\right\|_{H^{1}(\partial \Omega)}$, that there exists $C, m$ such that, with $\langle\sigma\rangle=\left(1+\sigma^{2}\right)^{1 / 2}$

$$
\begin{equation*}
\left\|(1-B) G_{1}\right\|_{H_{s c}^{1}(X)} \mathrm{e}^{-\varphi\left(s_{0}, 0\right) / h} \leq C \Lambda^{m} h^{-1} \sup _{j, \mu_{j} \leq \sqrt{\Lambda}} \int_{|\sigma| \geq \alpha_{1} / 2}\langle\sigma\rangle\left|\left(\int \mathrm{e}^{i \phi_{j}\left(t^{\prime}, \sigma\right) / h} \tilde{\chi}\left(t^{\prime}\right) \mathrm{d} t^{\prime}\right) \mathrm{d} \sigma\right| \tag{2.33}
\end{equation*}
$$

Therefore, Claim 2 is a consequence of (2.33), $h \sqrt{\Lambda}=\delta \leq 1$, and the following lemma.
Lemma 2.6. There exist $c_{0}>0$ and $\delta_{0}>0$ such that for $0<\delta \leq \delta_{0}$, and uniformly in $|\sigma| \geq \alpha_{1} / 2$ and $\sqrt{\nu}_{j} \leq \delta$, the following estimate holds true

$$
\begin{equation*}
\forall N, \exists C_{N}, \quad\left|\int \mathrm{e}^{i \phi_{j}(t, \sigma) / h} \tilde{\chi}(t) \mathrm{d} t\right| \leq C_{N}\langle\sigma\rangle^{-N} \mathrm{e}^{-c_{0} / h} . \tag{2.34}
\end{equation*}
$$

Proof. To estimate (2.34), we consider a deformation of the real axis $t \mapsto g(t)=t-i \frac{\sigma}{\langle\sigma\rangle} \kappa(t)$. Here $\kappa$ is a $C_{0}^{\infty}$ function whose support is contained in the interior of the set $\{t ; \tilde{\chi}(t) \equiv 1\}, 0 \leq \kappa \leq k_{0}, k_{0}>0$ small, and $\kappa \equiv k_{0}$ in some interval $\left[-\epsilon_{0}, \epsilon_{0}\right]$. On this curve, we have, with $\tilde{\phi}_{j}(t, \sigma)=\phi_{j}(g(t), \sigma)$

$$
\begin{align*}
\operatorname{Im} \tilde{\phi}_{j} & =-\operatorname{Im} \sigma\left(t-i \frac{\sigma}{\langle\sigma\rangle} \kappa(t)\right)+\operatorname{Re} \theta\left(t-i \frac{\sigma}{\langle\sigma\rangle} \kappa(t)\right) \pm \operatorname{Re}\left(\left(t-i \frac{\sigma}{\langle\sigma\rangle} \kappa(t)\right) \sqrt{\nu_{j}}\right) \pm s_{3} \sqrt{\nu_{j}} \\
& =\frac{\sigma^{2}}{\langle\sigma\rangle} \kappa(t)+\operatorname{Re} \theta\left(t-i \frac{\sigma}{\langle\sigma\rangle} \kappa(t)\right) \pm\left(t+s_{3}\right) \sqrt{\nu_{j}} \\
& \left.=\frac{\sigma^{2}}{\langle\sigma\rangle} \kappa(t)+\theta(t)-\frac{\sigma^{2}}{\langle\sigma\rangle^{2}} \kappa^{2}(t) \theta^{\prime \prime}(t) / 2+O\left(\left(\frac{\sigma}{\langle\sigma\rangle}\right)^{4} \kappa^{4}(t)\right) \pm\left(t+s_{3}\right) \sqrt{\nu_{j}}\right), \tag{2.35}
\end{align*}
$$

since $\theta(t+i \gamma)=\theta(t)+i \gamma \theta^{\prime}(t)-\gamma^{2} \theta^{\prime \prime}(t) / 2-i \gamma^{3} \theta^{\prime \prime \prime}(t) / 6+O\left(\gamma^{4}\right)$. Hence

$$
\begin{equation*}
\left.\operatorname{Im} \tilde{\phi}_{j}(t, \sigma)=\frac{\sigma^{2}}{\langle\sigma\rangle} \kappa(t)\left(1-\frac{\kappa}{\langle\sigma\rangle} \theta^{\prime \prime}(t) / 2+O\left(\frac{\sigma^{2}}{\langle\sigma\rangle^{3}} \kappa^{3}(t)\right)\right)+\theta(t) \pm\left(t+s_{3}\right) \sqrt{\nu_{j}}\right) . \tag{2.36}
\end{equation*}
$$

Let $\Gamma$ be the integration contour in the complex plane $\Gamma=\left\{t-i \frac{\sigma}{\langle\sigma\rangle} \kappa(t), t \in \mathbb{R}\right\}$. Since $\phi(t)$ is a holomorphic function and support $(\kappa) \subset\{t ; \tilde{\chi}(t)=1\}$, one has

$$
\begin{equation*}
\int_{\mathbb{R}} \mathrm{e}^{i \phi_{j}(t, \sigma) / h} \tilde{\chi}(t) \mathrm{d} t=\int_{\Gamma} \mathrm{e}^{i \phi_{j}(z, \sigma) / h} \tilde{\chi}(z) \mathrm{d} z=\int_{\mathbb{R}} \mathrm{e}^{i \tilde{\phi}_{j}(t, \sigma) / h} \tilde{\chi}(t) g^{\prime}(t) \mathrm{d} t . \tag{2.37}
\end{equation*}
$$

There exists $C_{1}>0$ such that for every $t \in \overline{\operatorname{supp}(\tilde{\chi})}$, one has $\left|t+s_{0}\right| \leq C_{1},|t| \leq \sup \left(2 s_{*}, \alpha_{0}\right)$, and there exists $C_{2}>0$ such that for $|\sigma| \geq \alpha_{1} / 2$ one has $\frac{\sigma^{2}}{\langle\sigma\rangle} \geq C_{2}\langle\sigma\rangle$. Thus we get from (2.36), decreasing $s_{*}$ and $\alpha_{0}$ if necessary, for all $\left.\delta \in] 0, \delta_{0}\right], t \in \overline{\operatorname{supp}(\tilde{\chi})},|\sigma| \geq \alpha_{1} / 2$

$$
\operatorname{Im} \tilde{\phi}_{j}(t, \sigma) \geq C_{2}\langle\sigma\rangle \kappa(t) / 4+D t^{2}+O\left(t^{4}\right)-C_{1} \delta \geq C_{2}\langle\sigma\rangle \kappa(t) / 4+D t^{2} / 2-C_{1} \delta_{0}
$$

Thus one has for all $\left.\delta \in] 0, \delta_{0}\right], t \in \overline{\operatorname{supp}(\tilde{\chi})},|\sigma| \geq \alpha_{1} / 2$

$$
\begin{align*}
& \operatorname{Im} \tilde{\phi}_{j}(t, \sigma) \geq C_{2} \alpha_{1} k_{0} / 8-C_{1} \delta_{0} \quad \text { for } \quad|t| \leq \epsilon_{0}  \tag{2.38}\\
& \operatorname{Im} \tilde{\phi}_{j}(t, \sigma) \geq D \epsilon_{0}^{2} / 2-C_{1} \delta_{0} \quad \text { for } \quad|t| \geq \epsilon_{0} \tag{2.39}
\end{align*}
$$

For $\delta_{0} \delta_{0}$ small enough, we get that there exists $c_{0}>0$ such that for all $\left.\left.\delta \in\right] 0, \delta_{0}\right], t \in \overline{\operatorname{supp}(\tilde{\chi})},|\sigma| \geq \alpha_{1} / 2$, one has $\operatorname{Im} \tilde{\phi}_{j}(t, \sigma) \geq c_{0}$, and from (2.37), we get

$$
\begin{equation*}
\left|\int_{\mathbb{R}} \mathrm{e}^{i \phi_{j}(t, \sigma) / h} \tilde{\chi}(t) \mathrm{d} t\right| \leq C \mathrm{e}^{-c_{0} / h} \tag{2.40}
\end{equation*}
$$

Therefore, (2.35) is true for $N=0$. The general case is proved by integration by parts in $t$.
From Lemma 2.6 we conclude that Claim 2 holds true.

From (2.17), $(2.24),(2.27)$ and $(2.31)$, we conclude that there exists $\Lambda_{0}, C_{0}, \mu>0$ and $\left.\nu \in\right] 0,1[$, such that for $\left.\left.\Lambda \geq \Lambda_{0}, \delta \in\right] 0, \delta_{0}\right]$ and $h=\delta \Lambda^{-1 / 2}$, the following inequality holds true

$$
\begin{equation*}
\|G\|_{H_{s c}^{1}}^{2} \leq C\left(h^{3}\left\|\mathrm{e}^{\varphi / h} A(\chi v)\right\|_{L^{2}}^{2}+\mathrm{e}^{2\left(\varphi\left(s_{0}, 0\right)-\mu\right) / h}\|v\|_{H^{1}(Z)}^{2}+\mathrm{e}^{2 C_{0} / h}\|v\|_{H^{1}(Z)}^{2(1-\nu)}\left(\int_{\omega}\left|\partial_{s} v(0, x)\right|^{2} \mathrm{~d} x\right)^{\nu}\right) \tag{2.41}
\end{equation*}
$$

- Estimate of the term $\left\|\mathrm{e}^{\varphi / h} A(\chi v)\right\|_{L^{2}}^{2}$ :

We begin noticing that, since $A v=0, A(\chi v)=\chi_{0}\left[A, \chi_{1}\right] v+\left[A, \chi_{0}\right] \chi_{1} v$ and that $\left[A, \chi_{0}\right]$ and $\left[A, \chi_{1}\right]$ are first order operators whose support are contained in the set

$$
V_{1} \cup V_{2}:=\left(\left(\left[s_{0}-2 s_{*}, s_{0}-3 s_{*} / 2\right] \cup\left[s_{0}+3 s_{*} / 2, s_{0}+2 s_{*}\right]\right) \times\left[0, r_{0}\right]\right) \cup\left(\left[s_{0}-2 s_{*}, s_{0}+2 s_{*}\right] \times\left[r_{0} / 2, r_{0}\right]\right)
$$

One has from (2.13) $\varphi \leq \varphi\left(s_{0}, 0\right)-\mu_{0}$ on $V_{1}$ and for some $C_{1}>0, \varphi \leq C_{1}$ on $V_{2}$. Therefore, from (2.41), decreasing $\mu>0$ if necessary, we get

$$
\begin{equation*}
\|G\|_{H_{s c}^{1}}^{2} \leq C\left(e^{2 C_{1} / h}\|v\|_{H^{1}\left(V_{2}\right)}^{2}+e^{2\left(\varphi\left(s_{0}, 0\right)-\mu\right) / h}\|v\|_{H^{1}(Z)}^{2}+e^{2 C_{0} / h}\|v\|_{H^{1}(Z)}^{2(1-\nu)}\left(\int_{\omega}\left|\partial_{s} v(0, x)\right|^{2} d x\right)^{\nu}\right) \tag{2.42}
\end{equation*}
$$

Let $U$ be the open subset of $Z$ defined by $U=\left\{\varphi(s, r)>\varphi\left(s_{0}, 0\right)-\mu / 2,\left|s-s_{0}\right|<s_{*}, r<r_{0} / 2\right\}$. From Proposition 2.4, one has for some $\left.\nu_{1} \in\right] 0,1[$

$$
\|v\|_{H^{1}\left(V_{2}\right)} \leq C\|v\|_{H^{1}(Z)^{N}}^{1-\nu_{1}}\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\omega)}^{\nu_{1}}
$$

Decreasing eventually $\nu$ and increasing $C_{0}$ we conclude from (2.42) that there exists $\Lambda_{0}, C_{0}, \mu>0$ and $\left.\nu \in\right] 0,1[$, such that for $\left.\left.\Lambda \geq \Lambda_{0}, \delta \in\right] 0, \delta_{0}\right]$ and $h=\delta \Lambda^{-1 / 2}$, the following inequality holds true:

$$
\begin{equation*}
\|v\|_{H_{s c}^{1}(U)} \leq C\left(\mathrm{e}^{\left.-\frac{\mu}{2 h}\|v\|_{H^{1}(Z)}+\mathrm{e}^{C_{0} / h}\|v\|_{H^{1}(Z)}^{1-\nu}\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\omega)}^{\nu}\right), ~ \text {, }}\right. \text {, } \tag{2.43}
\end{equation*}
$$

Since the open set $U$ is a neighborhood of $[1 / 4,3 / 4] \times \partial \Omega$, we conclude from $(2.43),\|v\|_{H^{1}(U)} \leq h^{-1}\|v\|_{H_{s c}^{1}(U)}$, and Proposition 2.4 that Theorem 2.2 holds true.

## 3. Spectral inequality

In this section, using the interpolating inequality (2.9), we show a spectral inequality for the low modes of the Stokes operator. This result will be used in the next section to prove Theorem 1.1.

Theorem 3.1. Let $\omega \subset \Omega$ be a nonempty open set. There exist constants $M>0, K>0$ such that, for every sequence of complex numbers $z_{j}$ and every real $\Lambda>0$, we have

$$
\begin{equation*}
\sum_{\mu_{j} \leq \Lambda}\left|z_{j}\right|^{2}=\int_{\Omega}\left|\sum_{\mu_{j} \leq \Lambda} z_{j} e_{j}(x)\right|^{2} \mathrm{~d} x \leq M e^{K \sqrt{\Lambda}} \int_{\omega}\left|\sum_{\mu_{j} \leq \Lambda} z_{j} e_{j}(x)\right|^{2} \mathrm{~d} x \tag{3.1}
\end{equation*}
$$

Proof. Let $\tilde{\omega}$ be a nonempty set such that $\tilde{\omega} \subset \subset \omega$ and consider $u(s, x)=\sum_{\mu_{j} \leq \Lambda} z_{j} \frac{\sinh \left(s \sqrt{\mu_{j}}\right)}{\sqrt{\mu_{j}}} e_{j}(x)$ and $v=$ curl $u$. Using (2.2), the norm $\|v\|_{H^{1}(W)}$ can be estimated from below as follows

$$
\begin{equation*}
\|v\|_{H^{1}(W)}^{2} \geq\|v\|_{L^{2}(W)}^{2}=\sum_{\mu_{j} \leq \Lambda} \int_{1 / 4}^{3 / 4}\left|z_{j}\right|^{2} \sinh ^{2}\left(s \sqrt{\mu_{j}}\right) \mathrm{d} s \geq \sum_{\mu_{j} \leq \Lambda} \mu_{j}\left|z_{j}\right|^{2} \int_{1 / 4}^{3 / 4} s^{2} \mathrm{~d} s \tag{3.2}
\end{equation*}
$$

Next, from the fact that $\left.\|v\|_{H^{1}(Z)}^{2}=\left\|\frac{\partial v}{\partial s}\right\|_{L^{2}(Z)}^{2}+\left\|\Delta_{x} u\right\|_{L^{2}(Z)}^{2}\right)+\|v\|_{L^{2}(Z)}^{2}$, we get

$$
\begin{equation*}
\|v\|_{H^{1}(Z)}^{2} \leq \sum_{\mu_{j} \leq \Lambda}\left(2 \mu_{j}+1\right)\left|z_{j}\right|^{2} \int_{0}^{1} \mathrm{e}^{2 s \sqrt{\mu_{j}}} \mathrm{~d} s \leq \sum_{\mu_{j} \leq \Lambda}\left(2 \mu_{j}+1\right)\left|z_{j}\right|^{2} \mathrm{e}^{2 \sqrt{\Lambda}} \tag{3.3}
\end{equation*}
$$

Since $\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\tilde{\omega})}^{2}=\int_{\tilde{\omega}}\left|\sum_{\mu_{j} \leq \Lambda} z_{j} \operatorname{curl}\left(e_{j}\right)\right|^{2} \mathrm{~d} x$, from Theorem 2.2, estimates (3.2) and (3.3), there exists $\alpha \in(0,1), C_{0}, \delta_{0}>0, \mu>0, \Lambda_{0}$, such that for all $\left.\left.\delta \in\right] 0, \delta_{0}\right]$ and all $\Lambda \geq \Lambda_{0}$, one has

$$
\begin{equation*}
\sum_{\mu_{j} \leq \Lambda}\left|z_{j}\right|^{2} \leq C_{\delta}\left(\mathrm{e}^{2 C_{0} \Lambda^{1 / 2} / \delta}\left(\sum_{\mu_{j} \leq \Lambda} \Lambda\left|z_{j}\right|^{2} \mathrm{e}^{2 \sqrt{\Lambda}}\right)^{1-\alpha}\left(\int_{\tilde{\omega}}\left|\sum_{\mu_{j} \leq \Lambda} z_{j} \operatorname{curl}\left(e_{j}\right)\right|^{2} \mathrm{~d} x\right)^{\alpha}+\mathrm{e}^{-2 \mu \sqrt{\Lambda} / \delta} \sum_{\mu_{j} \leq \Lambda} \Lambda\left|z_{j}\right|^{2} \mathrm{e}^{2 \sqrt{\Lambda}}\right) \tag{3.4}
\end{equation*}
$$

Take $\left.\left.\delta_{1} \in\right] 0, \delta_{0}\right]$ such that $2 \mu / \delta_{1}-2>1$ and $\Lambda_{1}$ such that one has $C_{\delta_{1}} \Lambda \mathrm{e}^{-\sqrt{\Lambda}} \leq 1 / 2$ for all $\Lambda \geq \Lambda_{1}$. From (3.4), we get for all $\Lambda \geq \Lambda_{1}$ with $C=C_{\delta_{1}}$,

$$
\sum_{\mu_{j} \leq \Lambda}\left|z_{j}\right|^{2} \leq 2 C\left(\mathrm{e}^{2 C_{0} \Lambda^{1 / 2} / \delta_{1}}\left(\sum_{\mu_{j} \leq \Lambda} \Lambda\left|z_{j}\right|^{2} \mathrm{e}^{2 \sqrt{\Lambda}}\right)^{1-\alpha}\left(\int_{\tilde{\omega}}\left|\sum_{\mu_{j} \leq \Lambda} z_{j} \operatorname{curl}\left(e_{j}\right)\right|^{2} \mathrm{~d} x\right)^{\alpha}\right)
$$

which gives for some $\tilde{M}$ and $\tilde{K}$ positive

$$
\begin{equation*}
\sum_{\mu_{j} \leq \Lambda}\left|z_{j}\right|^{2} \leq \tilde{M} \mathrm{e}^{\tilde{K} \sqrt{\Lambda}} \int_{\tilde{\omega}}\left|\sum_{\mu_{j} \leq \Lambda} z_{j} \operatorname{curl}\left(e_{j}\right)\right|^{2} \mathrm{~d} x \tag{3.5}
\end{equation*}
$$

To finish the proof, we consider a function $\theta \in C_{0}^{\infty}(\omega)$ such that $\theta \geq 0$ and $\theta \equiv 1$ in $\tilde{\omega}$ and estimate the local integral in the right-hand side of (3.5) as follows

$$
\begin{align*}
\int_{\tilde{\omega}}\left|\sum_{\mu_{j} \leq \Lambda} z_{j} \operatorname{curl}\left(e_{j}\right)\right|^{2} \mathrm{~d} x & \leq \int_{\omega} \theta\left|\sum_{\mu_{j} \leq \Lambda} z_{j} \operatorname{curl}\left(e_{j}\right)\right|^{2} \mathrm{~d} x \\
& =\int_{\omega} \theta\left(\sum_{\mu_{j} \leq \Lambda} z_{j} \operatorname{curl}\left(e_{j}\right)\right)\left(\sum_{\mu_{k} \leq \Lambda} \bar{z}_{k} \operatorname{curl}\left(e_{k}\right)\right) \mathrm{d} x \\
& =\int_{\omega}\left(\sum_{\mu_{j} \leq \Lambda} z_{j} e_{j}\right) P\left(\theta \sum_{\mu_{k} \leq \Lambda} \bar{z}_{k} \operatorname{curl}\left(e_{k}\right)\right) \mathrm{d} x \tag{3.6}
\end{align*}
$$

where $P$ is a first order differential operator. Thus we get by Cauchy-Schwarz inequality

$$
\begin{align*}
\int_{\tilde{\omega}}\left|\sum_{\mu_{j} \leq \Lambda} z_{j} \operatorname{curl}\left(e_{j}\right)\right|^{2} \mathrm{~d} x & \leq\left(\int_{\omega}\left|\sum_{\mu_{j} \leq \Lambda} z_{j} e_{j}\right|^{2} \mathrm{~d} x\right)^{1 / 2}\left(\int_{\Omega}\left|P\left(\theta \sum_{\mu_{k} \leq \Lambda} z_{k} \operatorname{curl}\left(e_{k}\right)\right)\right|^{2} \mathrm{~d} x\right)^{1 / 2} \\
& \leq C \Lambda\left(\int_{\omega}\left|\sum_{\mu_{j} \leq \Lambda} z_{j} e_{j}\right|^{2} \mathrm{~d} x\right)^{1 / 2}\left(\sum_{\mu_{j} \leq \Lambda}\left|z_{j}\right|^{2}\right)^{1 / 2} \tag{3.7}
\end{align*}
$$

Finally, from (3.5) and (3.7), we get that Theorem 3.1 holds true.

## 4. Cost of the null controllability for the Stokes system

In this section we prove Theorem 1.1. This proof follows closely the ideas in [22, 24]. First, we introduce the adjoint system (with the change of orientation $t \mapsto T-t$ ) of the Stokes system (1.1):

$$
\left\lvert\, \begin{array}{ll}
z_{t}-\Delta z+\nabla q=0 & \text { in } Q  \tag{4.1}\\
\operatorname{div} z=0 & \text { in } Q \\
z=0 & \text { on } \Sigma \\
z(0)=z_{0} & \text { in } \Omega
\end{array}\right.
$$

It is well-know that the Stokes system 1.1 is null controllable at time $T$ if and only if

$$
\begin{equation*}
\|z(T)\|_{\mathbf{H}}^{2} \leq C_{S}^{2} \int_{0}^{T} \int_{\omega}|z|^{2} \mathrm{~d} x \mathrm{~d} t, \forall z_{0} \in \mathbf{H} \tag{4.2}
\end{equation*}
$$

Moreover, we have that (4.2) holds if and only if (1.3) holds with $C_{S}=C_{1} \mathrm{e}^{C_{2} / T}$.
To prove Theorem 1.1, we need the following two results:
Lemma 4.1. Let $T^{\prime}>0$ and $m \in(0,1)$. If the approximate observability estimate

$$
\begin{equation*}
f(t)\|z(t)\|^{2}-f(m t)\left\|z_{0}\right\|^{2} \leq \int_{0}^{t} \int_{\omega}|z|^{2} \mathrm{~d} x \mathrm{~d} t, \forall z_{0} \in H^{2}(\Omega)^{N} \cap \mathbf{V}, t \in\left(0, T^{\prime}\right] \tag{4.3}
\end{equation*}
$$

holds with $f(t) \longrightarrow 0$ as $t \longrightarrow 0^{+}$, then $C_{S}^{2} \leq 1 / f((1-m) T)$ for $T \in\left(0, T^{\prime}\right]$, i.e., the cost does not grow more than the inverse of $\sqrt{f}$.

Proof. Let $T<T^{\prime}, \tau_{k}=m^{k}(1-m) T$ and consider a disjoint partition $\cup\left(T_{k+1}, T_{k}\right]$ of $(0, T]$, with $T_{k+1}=T_{k}-\tau_{k}$, $T_{0}=T, k \in \mathbb{N}$. We apply (4.3) to $z_{0}=z\left(T_{k+1}\right)$ and $t=\tau_{k}$, we obtain

$$
f\left(\tau_{k}\right)\left\|z\left(T_{k}\right)\right\|^{2}-f\left(\tau_{k+1}\right)\left\|z\left(T_{k+1}\right)\right\|^{2} \leq \int_{T_{k+1}}^{T_{k}} \int_{\omega}|z|^{2} \mathrm{~d} x \mathrm{~d} t, k \in \mathbb{N} .
$$

We add these inequalities to get

$$
f\left(\tau_{0}\right)\|z(T)\|^{2}-f\left(\tau_{k}\right)\left\|z\left(T_{k}\right)\right\|^{2} \leq \int_{T_{k}}^{T} \int_{\omega}|z|^{2} \mathrm{~d} x \mathrm{~d} t, k \in \mathbb{N}
$$

and taking the limit $k \longrightarrow \infty$ completes the proof since $f(t) \longrightarrow 0$ and the function $t \mapsto\|z(t)\|$ is bounded in $[0, T]$.

We use Lemma 4.1 to prove:
Lemma 4.2. Let $T_{0}>0$ and $\beta>0$. If the approximate observability estimate

$$
\begin{equation*}
f(T)\|z(T)\|^{2}-g(T)\left\|z_{0}\right\|^{2} \leq \int_{0}^{T} \int_{\omega}|z|^{2} \mathrm{~d} x \mathrm{~d} t, \forall z_{0} \in H^{2}(\Omega)^{N} \cap \mathbf{V}, t \in\left(0, T_{0}\right] \tag{4.4}
\end{equation*}
$$

holds with $f(T)=f_{0} \mathrm{e}^{-2 /\left(d_{2} T\right)^{\beta}}$ and $g(T)=g_{0} \mathrm{e}^{-2 /\left(d_{1} T\right)^{\beta}}$, where $f_{0}, g_{0}, d_{1}<d_{2}$ are positive, then for all $d \in\left(0, d_{2}-d_{1}\right)$ there exists $T^{\prime} \in\left(0, T_{0}\right]$ such that $C_{S}^{2} \leq f_{0}^{-1} \mathrm{e}^{2 /(d T)^{\beta}}$ for $T \in\left(0, T^{\prime}\right]$. Moreover, if $g_{0} \leq f_{0}$ then we may take $d=d_{1}-d_{2}$ and $T^{\prime}=T_{0}$.
Proof. First, we compute the least $m$ such that $g(T) \leq f(m T)$ for all $T \in\left(0, T^{\prime}\right]$. We find $m=\frac{d_{1}}{d_{2}} h\left(T^{\prime}\right)$, with $h\left(T^{\prime}\right)=\left(1+\inf _{t \in\left(0, T^{\prime}\right)} t^{\beta} d_{1}^{\beta} \ln \left(f_{0} / g_{0}\right) / 2\right)^{-1 / \beta}$, where the parenthesis is 1 when $g_{0} \leq f_{0}$ and positive for $T^{\prime}$ is small enough. Now $C_{S}^{2} \leq 1 /(f((1-m) T))=\frac{1}{f_{0}} \mathrm{e}^{2 /\left(d_{3} T\right)^{\beta}}$, with $d_{3}=d_{2}-d_{1} h\left(T^{\prime}\right) \longrightarrow d_{2}-d_{1}$ as $T^{\prime} \longrightarrow 0$.
Proof of Theorem 1.1. Let $T_{0}>0, T \in\left(0, T_{0}\right)$ and $z_{0} \in \mathbf{H}$. Set $H_{\Lambda}=\operatorname{span}\left\{e_{j} ; \mu_{j} \leq \Lambda\right\}$. For any $\Lambda$, the solution $z$ of (4.1) can be split into $z=u+v$, where $u$ and $v$ are (together with some pressure) the solutions of (4.1) associated to $u_{0} \in H_{\Lambda}$ and $v_{0} \in H_{\Lambda}^{\perp}, z_{0}=u_{0}+v_{0}$, respectively. Moreover,

$$
\begin{equation*}
u(t) \in H_{\Lambda} \text { and }\|v(t)\|_{\mathbf{H}} \leq \mathrm{e}^{-\Lambda t}\left\|v_{0}\right\|_{\mathbf{H}} \tag{4.5}
\end{equation*}
$$

for every $t>0$. For every $M_{1}>0$, we have

$$
\begin{equation*}
\|z(T)\|_{\mathbf{H}}^{2} \leq \frac{1}{T} \int_{0}^{T} \int_{\Omega}|z(t)|^{2} \mathrm{~d} x \mathrm{~d} t \leq \frac{1}{M_{1}} \mathrm{e}^{\frac{M_{1}}{T}} \int_{0}^{T} \int_{\Omega}|z(t)|^{2} \mathrm{~d} x \mathrm{~d} t, \forall T \in\left(0, T_{0}\right) \tag{4.6}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{0}^{T} \int_{\omega}|z(t)|^{2} \mathrm{~d} x \mathrm{~d} t \leq T\left\|z_{0}\right\|_{\mathbf{H}}^{2} \tag{4.7}
\end{equation*}
$$

From (4.6) and Theorem 3.1, we get

$$
\begin{equation*}
\|u(\tau)\|_{\mathbf{H}}^{2} \leq \frac{M}{M_{1}} \mathrm{e}^{\frac{M_{1}}{\tau}+K \sqrt{\Lambda}} \int_{0}^{\tau} \int_{\omega}|u(t)|^{2} \mathrm{~d} x \mathrm{~d} t, \forall \tau \in\left(0, T_{0}\right) . \tag{4.8}
\end{equation*}
$$

Let us now consider an observation time $\tau=\epsilon T$, with $\epsilon \in(0,1)$ small enough and take $\sqrt{\Lambda}=\frac{1}{\tau}$. From (4.8), it follows that

$$
\begin{equation*}
\|u(T)\|_{\mathbf{H}}^{2} \leq \frac{1}{f(T)} \int_{(1-\epsilon) T}^{T} \int_{\omega}|u(t)|^{2} \mathrm{~d} x \mathrm{~d} t, \quad f(T)=\frac{M_{1}}{M} \mathrm{e}^{-\frac{M_{1}+K}{\epsilon T}} . \tag{4.9}
\end{equation*}
$$

Using (4.9), the definition of $z$ and (4.7), we get

$$
\begin{equation*}
f(T)\|u(T)\|_{\mathbf{H}}^{2} \leq \int_{(1-\epsilon) T}^{T} \int_{\omega}|u(t)|^{2} \mathrm{~d} x \mathrm{~d} t \leq 2 \int_{(1-\epsilon) T}^{T} \int_{\omega}|z(t)|^{2} \mathrm{~d} x \mathrm{~d} t+2 \epsilon T\|v((1-\epsilon) T)\|_{\mathbf{H}}^{2} \tag{4.10}
\end{equation*}
$$

Hence,

$$
\begin{equation*}
f(T)\|z(T)\|_{\mathbf{H}}^{2} \leq \int_{(1-\epsilon) T}^{T} \int_{\omega}|z(t)|^{2} \mathrm{~d} x \mathrm{~d} t+\epsilon T\|v((1-\epsilon) T)\|_{\mathbf{H}}^{2}+2 f(T)\|v(T)\|_{\mathbf{H}}^{2} \tag{4.11}
\end{equation*}
$$

Using (4.5) in (4.11), we obtain

$$
\begin{equation*}
f(T)\|z(T)\|_{\mathbf{H}}^{2}-\left(\epsilon T \mathrm{e}^{-2 \Lambda(1-\epsilon) T}+2 f(T) \mathrm{e}^{-2 \Lambda T}\right)\left\|v_{0}\right\|_{\mathbf{H}}^{2} \leq \int_{(1-\epsilon) T}^{T} \int_{\omega}|z(t)|^{2} \mathrm{~d} x \mathrm{~d} t \tag{4.12}
\end{equation*}
$$

Since $\left\|v_{0}\right\|_{\mathbf{H}}^{2} \leq\left\|z_{0}\right\|_{\mathbf{H}}^{2}$ and $f(T) \leq f\left(T_{0}\right)$, we obtain

$$
\begin{equation*}
f(T)\|z(T)\|_{\mathbf{H}}^{2}-\left(T_{0}+2 f\left(T_{0}\right)\right) \mathrm{e}^{-2 \Lambda(1-\epsilon) T}\left\|z_{0}\right\|_{\mathbf{H}}^{2} \leq \int_{(1-\epsilon) T}^{T} \int_{\omega}|z(t)|^{2} \mathrm{~d} x \mathrm{~d} t \tag{4.13}
\end{equation*}
$$

Therefore, since $\Lambda T=1 /\left(\epsilon^{2} T\right)$, Lemma 4.2 holds with $\beta=1$ and

$$
f_{0}=\frac{M_{1}}{M}, g_{0}=T_{0}+2 f\left(T_{0}\right), d_{2}=2 \epsilon /\left(M_{1}+K\right), d_{1}=\epsilon^{2} /(1-\epsilon)
$$

One has $g\left(T_{0}\right) \longrightarrow 0$ if $T_{0} \longrightarrow 0$, and for $\epsilon$ small enough, one has $d_{1}<d_{2}$. Thus we can apply Lemma 4.2 with $g_{0} \leq f_{0}$ and $T_{0}$ small and conclude that there exists $C_{S}$ for which (4.2) is true for all solutions of (4.1). Moreover, there exists $T^{\prime}>0$ and $C_{1}, C_{2}>0$ such that

$$
C_{S} \leq C_{1} \mathrm{e}^{C_{2} / T}, \forall T \in\left(0, T^{\prime}\right]
$$

Remark 4.3. Arguing as in Theorem 2.2 of [22], it is possible to get some estimate on the size of $C_{2}$. Nevertheless, the obtainment of the optimal constant $C_{2}$ for which inequality (1.3) holds has an interest on its own and, as far as we know, it is open problem.

## Appendix A. Carleman inequality for The Laplace operator

In this section we prove the Carleman inequality (2.14) that we have used in the proof of the Theorem 2.2. The proof follows closely the one given in [15], but we have to take care of the non zero Dirichlet data at the boundary. Since the notational distinction between the variables $s$ and $x$ plays here no role, we may replace the triple $\left((s, x),\left(0, s_{0}\right) \times \Omega, A\right)$ by the triple $(x, \Omega,-\triangle)$.

Remark A.1. Observe that since we work on $\mathbb{R}^{N}$, it is equivalent to prove the Carleman inequality (2.14) for vector fields or for functions. If one replace $\mathbb{R}^{N}$ by a Riemannian manifold $(M, g)$, since the Laplace operator acting on vector fields has a scalar principal symbol equal to the principal symbol of the Laplace operator acting on functions, and since the Carleman inequality (2.14) is insensitive to lower order terms, it is still equivalent to prove the Carleman inequality (2.14) for vector fields or for functions.

Given $x_{0} \in \partial \Omega$, we choose the normal geodesic coordinate system $x=\left(x^{\prime}, x_{N}\right), x^{\prime} \in \mathbb{R}^{N-1}$, where $x^{\prime}$ is a local coordinate system for $\partial \Omega$ so that $x_{0}=0$. In this new coordinate system, $\Omega$ is locally define by $x_{N}>0$, the metric $g$ is of the form $\mathrm{d} x_{N}^{2}+\sum_{i, j \leq N-1} g_{i, j} \mathrm{~d} x_{i} \mathrm{~d} x_{j}$, and one has

$$
\begin{equation*}
\operatorname{dist}\left(\left(x^{\prime}, x_{N}\right), \partial \Omega\right)=x_{N} \tag{A.1}
\end{equation*}
$$

where in (A.1), dist is the distance given by the Riemannian metric $g$. In this coordinate system, the Laplace operator is equal to

$$
\begin{equation*}
\Delta_{g}=\frac{1}{\sqrt{\operatorname{det} g}} \partial_{x_{N}}\left[\sqrt{\operatorname{det} g} \partial_{x_{N}}\right]+\sum_{i, j \leq N-1} \frac{1}{\sqrt{\operatorname{det} g}} \partial_{x_{i}^{\prime}}\left[\sqrt{\operatorname{det} g} g^{i, j} \partial_{x_{j}^{\prime}}\right] \tag{A.2}
\end{equation*}
$$

where $\left(g^{i, j}\right)$ is the inverse matrix of $g=\left(g_{i, j}\right)$. Therefore, one has

$$
\begin{equation*}
-\Delta_{g}=-\partial_{x_{N}}^{2}-R\left(x^{\prime}, x_{N}, \partial_{x^{\prime}}\right)+A_{1}\left(x, \partial_{x}\right) \tag{A.3}
\end{equation*}
$$

where $A_{1}$ is a first order operator and

$$
R\left(x^{\prime}, x_{N}, \partial_{x^{\prime}}\right)=\sum_{i, j \leq N-1} g^{i, j}\left(x^{\prime}, x_{N}\right) \partial_{x_{i}} \partial_{x_{j}}
$$

Since $A_{1}$ is a first order operator, and first order terms do not affect the validity of the Carleman inequality of Theorem A.5, for the rest of this section, we will work with the operator

$$
\begin{equation*}
P=-\partial_{x_{N}}^{2}-R\left(x^{\prime}, x_{N}, \partial_{x^{\prime}}\right) \tag{A.4}
\end{equation*}
$$

In the sequel, we will use the notations of [15] for the class of tangential symbols $S^{j}$, and tangential operators $\mathcal{E}^{j}$ (see [15], Sect. 3, formulas (9) and (10)). We recall the following definition:

Definition A.2. Let $V$ be an open set of $\mathbb{R}^{N}$ and $\varphi \in C^{\infty}\left(\mathbb{R}^{N} ; \mathbb{R}\right)$. We say that $\varphi$ satisfies Hormander's subellipticity condition on $\bar{V}$ for the operator $P$ if, for every $x \in \bar{V}, \nabla \varphi(x) \neq 0$, and there exists $C>0$ such that

$$
\forall(x, \xi) \in \bar{V} \times \mathbb{R}^{N}, p_{\varphi}(x, \xi)=0 \Longrightarrow\left\{\tilde{q}_{1}, \tilde{q}_{2}\right\}(x, \xi) \geq C
$$

where $p_{\varphi}$ is the principal symbol of the conjugated operator

$$
\begin{equation*}
P_{\varphi}=h^{2} \mathrm{e}^{\varphi(x) / h} P \mathrm{e}^{-\varphi(x) / h}, \tag{A.5}
\end{equation*}
$$

i.e.,

$$
p_{\varphi}=\tilde{q}_{2}+i \tilde{q}_{1}
$$

with

$$
\tilde{q}_{2}=\left|\xi_{N}\right|^{2}-\left|\partial_{x_{N}} \varphi\right|^{2}+\sum_{i, j \leq N-1} g_{i, j}(x)\left(\xi_{i} \xi_{j}-\partial_{x_{i}} \varphi \partial_{x_{j}} \varphi\right)
$$

and

$$
\tilde{q}_{1}=2\left(\partial_{x_{N}} \varphi \xi_{N}+\sum_{i, j \leq N-1} g_{i, j}(x) \partial_{x_{i}} \varphi \xi_{j}\right)
$$

Remark A.3. The set

$$
\begin{equation*}
Z=\left\{(x, \xi) \in \bar{V} \times \mathbb{R}^{N} ; p_{\varphi}(x, \xi)=0\right\} \tag{A.6}
\end{equation*}
$$

is compact.
The following well known Lemma will be useful to construct functions satisfying Hormander's sub-ellipticity on a set $\bar{V}$ for the Lapace operator.

Lemma A.4. Let $\psi \in C^{\infty}\left(\mathbb{R}^{N} ; \mathbb{R}\right)$ be such that $\nabla \psi(x) \neq 0$ for every $x \in \bar{V}$. Let $G \in C^{\infty}(\mathbb{R} ; \mathbb{R})$ be such that $G^{\prime}>0$ and $G^{\prime \prime}>0$. There exists a constant $A>0$ such that if $G^{\prime \prime} \geq A G^{\prime}$, then $\varphi(x)=G(\psi(x))$ satisfies Hormander's sub-ellipticity condition on $\bar{V}$ for the Laplace operator operator $-\Delta$.

Let $V=V^{\prime} \times(-r, r)$ be a neighborhood of $x_{0}$ in $\mathbb{R}^{N}$ and $\varphi\left(x^{\prime}, x_{N}\right)$ a weight function satisfying Hormander's sub-ellipticity condition on $\bar{V}$ for $P$ and such that

$$
\frac{\partial \varphi}{\partial x_{N}}\left(x^{\prime}, x_{N}\right) \neq 0, \forall\left(x^{\prime}, x_{N}\right) \in \bar{V}
$$

We prove the following result.
Theorem A. 5 (Carleman inequality). Let $K$ be a compact set of $V^{\prime}$ and $r^{\prime}<r$. There exist $h_{1}>0$ and $C>0$ such that for every $h \in\left(0, h_{1}\right]$, and every $u\left(x^{\prime}, x_{N}\right) \in C^{\infty}\left(V^{\prime} \times[0, r)\right)$ satisfying $u\left(x^{\prime}, 0\right)=g\left(x^{\prime}\right)$ and supported in $K \times\left[0, r^{\prime}\right]$, the following inequality holds true

$$
\begin{align*}
h\left\|\mathrm{e}^{\varphi / h} u\right\|_{L^{2}}^{2}+h^{3}\left\|\mathrm{e}^{\varphi / h} \nabla u\right\|_{L^{2}}^{2} \leq & C\left(h^{4}\left\|\mathrm{e}^{\varphi / h} P u\right\|_{L^{2}}^{2}+h \int \mathrm{e}^{2 \varphi\left(x^{\prime}, 0\right) / h}\left|g\left(x^{\prime}\right)\right|^{2} \mathrm{~d} x^{\prime}+h^{3} \int \mathrm{e}^{2 \varphi\left(x^{\prime}, 0\right) / h}\left|\nabla_{x^{\prime}} g\left(x^{\prime}\right)\right|^{2} \mathrm{~d} x^{\prime}\right. \\
& \left.+h^{3} \int \mathrm{e}^{2 \varphi\left(x^{\prime}, 0\right) / h}\left|\partial_{x_{N}} u\left(x^{\prime}, 0\right)\right|^{2} \mathrm{~d} x^{\prime}\right) \tag{A.7}
\end{align*}
$$

Moreover, if $\partial_{x_{N}} \varphi>0$ for every $\left(x^{\prime}, x_{N}\right) \in \bar{V}$, we have
$h\left\|\mathrm{e}^{\varphi / h} u\right\|_{L^{2}}^{2}+h^{3}\left\|\mathrm{e}^{\varphi / h} \nabla u\right\|_{L^{2}}^{2} \leq C\left(h^{4}\left\|\mathrm{e}^{\varphi / h} P u\right\|_{L^{2}}^{2}+h \int \mathrm{e}^{2 \varphi\left(x^{\prime}, 0\right) / h}\left|g\left(x^{\prime}\right)\right|^{2} \mathrm{~d} x^{\prime}+h^{3} \int \mathrm{e}^{2 \varphi\left(x^{\prime}, 0\right) / h}\left|\nabla_{x^{\prime}} g\left(x^{\prime}\right)\right|^{2} \mathrm{~d} x^{\prime}\right)$.

Remark A.6. Since $-\Delta_{g}=P+A_{1}$, with $A_{1}$ being a first order operator, by taking $h_{1}$ smaller, inequalities (A.7) and (A.8) are still true if we replace $P$ by $-\Delta_{g}$.
Proof. Taking $v=\mathrm{e}^{\varphi / h} u$, we see that $v$ solves

$$
\left\lvert\, \begin{align*}
& P_{\varphi} v=\tilde{f} \quad \text { in } V^{\prime} \times(0, r),  \tag{A.9}\\
& v\left(x^{\prime}, 0\right)=\tilde{g}\left(x^{\prime}\right),
\end{align*}\right.
$$

where, $P_{\varphi}$ is given by (A.5), $\tilde{f}=h^{2} \mathrm{e}^{\varphi / h} f$ and $\tilde{g}=\mathrm{e}^{\varphi\left(x^{\prime}, 0\right) / h} g$.
Noticing that $h \partial_{x_{N}} v=\mathrm{e}^{\varphi / h}\left(h \partial_{x_{N}} u+\varphi_{x_{N}} u\right)$ and using the fact that $u\left(x^{\prime}, 0\right)=g\left(x^{\prime}\right)$, we see that (A.7) is equivalent to (see [15] for the definition of the semi-classical tangential norms $\|\cdot\|_{t, s}$ )

$$
\begin{equation*}
h\left(\|v\|_{t, 1}^{2}+\left\|h \partial_{x_{N}} v\right\|_{t, 0}^{2}\right) \leq C\left(\|\tilde{f}\|_{t, 0}^{2}+h \int\left|\tilde{g}\left(x^{\prime}\right)\right|^{2} \mathrm{~d} x^{\prime}+h^{3} \int\left|\nabla_{x^{\prime}} \tilde{g}\left(x^{\prime}\right)\right|^{2} \mathrm{~d} x^{\prime}+h \int\left|h \partial_{x_{N}} v\left(x^{\prime}, 0\right)\right|^{2} \mathrm{~d} x^{\prime}\right) \tag{A.10}
\end{equation*}
$$

and (A.8) is equivalent to

$$
\begin{equation*}
h\left(\|v\|_{t, 1}^{2}+\left\|h \partial_{x_{N}} v\right\|_{t, 0}^{2}\right) \leq C\left(\|\tilde{f}\|_{t, 0}^{2}+h \int\left|\tilde{g}\left(x^{\prime}\right)\right|^{2} \mathrm{~d} x^{\prime}+h^{3} \int\left|\nabla_{x^{\prime}} \tilde{g}\left(x^{\prime}\right)\right|^{2} \mathrm{~d} x^{\prime}\right) \tag{A.11}
\end{equation*}
$$

Next, we write $P_{\varphi}=\tilde{Q}_{2}+i \tilde{Q}_{1}$, with $\tilde{Q}_{2}=\operatorname{Re}\left(P_{\varphi}\right)=\frac{1}{2}\left(P_{\varphi}+P_{\varphi}^{*}\right)$ and $\tilde{Q}_{1}=\operatorname{Im}\left(P_{\varphi}\right)=\frac{1}{2 i}\left(P_{\varphi}-P_{\varphi}^{*}\right)$. Moreover, we separate the operators $\tilde{Q}_{i}, i=1,2$, in the derivatives in the normal variable $x_{N}$ and the tangential ones. Indeed, we write

$$
\begin{gathered}
\tilde{Q}_{2}=\left(\frac{h}{i} \partial_{x_{N}}\right)^{2}+Q_{2}, \quad Q_{2} \in \mathcal{E}^{2} \\
\sigma_{2}\left(Q_{2}\right)=q_{2}=R\left(x^{\prime}, x_{N}, \xi^{\prime}\right)-R\left(x^{\prime}, x_{N}, \varphi_{x^{\prime}}\right)-\left(\varphi_{x_{N}}\right)^{2} \\
\tilde{Q}_{1}=\frac{2 h}{i} \varphi_{x_{N}} \partial_{x_{N}}+2 Q_{1}, \quad Q_{1} \in \mathcal{E}^{1} \\
\sigma_{1}\left(Q_{1}\right)=q_{1}=\hat{R}\left(x^{\prime}, x_{N} ; \xi^{\prime}, \varphi_{x^{\prime}}\right)
\end{gathered}
$$

where $\hat{R}\left(x^{\prime}, x_{N} ; a, b\right)=\sum_{j, k \leq N-1} g_{j, k}\left(x^{\prime}, x_{N}\right) a_{j} b_{k}$.

Let us denote $D_{N}=\frac{h}{i} \partial_{x_{N}}$ and $<z, w>_{0}=\int z\left(x^{\prime}, 0\right) \bar{w}\left(x^{\prime}, 0\right) \mathrm{d} x^{\prime}$ the scalar product of the trace of the functions $z$, $w$ over the boundary $x_{N}=0$. We have the following identities

$$
\begin{gathered}
\left(w_{1}, \tilde{Q}_{2} w_{2}\right)=\left(\tilde{Q}_{2} w_{1}, w_{2}\right)-i h\left(\left\langle w_{1}, D_{N} w_{2}\right\rangle_{0}+\left\langle D_{N} w_{1}, w_{2}\right\rangle_{0}\right) \\
\left(w_{1}, \tilde{Q}_{1} w_{2}\right)=\left(\tilde{Q}_{1} w_{1}, w_{2}\right)-2 i h\left\langle\varphi_{x_{N}} w_{1}, w_{2}\right\rangle_{0}
\end{gathered}
$$

Then, we have

$$
\|\tilde{f}\|_{L^{2}}^{2}=\left\|\left(\tilde{Q}_{2}+i \tilde{Q}_{1}\right) v\right\|_{L^{2}}^{2}=\left\|\tilde{Q}_{2} v\right\|_{L^{2}}^{2}+\left\|\tilde{Q}_{1} v\right\|_{L^{2}}^{2}+h\left(\frac{i}{h}\left[\tilde{Q}_{2}, \tilde{Q}_{1}\right] v, v\right)+h B_{0}(v)
$$

with

$$
\begin{equation*}
B_{0}(v)=\left\langle\left(D_{N} \tilde{Q}_{1}-2 \varphi_{x_{N}} \tilde{Q}_{2}\right) v, v\right\rangle_{0}+\left\langle\tilde{Q}_{1} v, D_{N} v\right\rangle_{0} \tag{A.12}
\end{equation*}
$$

One has

$$
\begin{aligned}
D_{N} \tilde{Q}_{1}-2 \varphi_{x_{N}} \tilde{Q}_{2}=D_{N}\left(2 \varphi_{x_{N}} D_{N}+2 Q_{1}\right)-2 \varphi_{x_{N}}\left(D_{N}^{2}+Q_{2}\right) & =2 D_{N} Q_{1}-2 \varphi_{x_{N}} Q_{2}+2 \frac{h}{i}\left(\partial_{x_{N}}^{2} \varphi\right) D_{N} \\
& =A_{2}+A_{1} D_{N}
\end{aligned}
$$

with $A_{j} \in \mathcal{E}^{j}$. Therefore, we get by Cauchy-Schwarz, with the notation $D_{N} v\left(x^{\prime}, 0\right)=w$

$$
\left|\left\langle\left(D_{N} \tilde{Q}_{1}-2 \varphi_{x_{N}} \tilde{Q}_{2}\right) v, v\right\rangle_{0}\right| \leq C\left(\|\tilde{g}\|_{0}^{2}+h^{2}\left\|\nabla_{x^{\prime}} \tilde{g}\right\|_{0}^{2}+\|w\|_{0}\left(\|\tilde{g}\|_{0}+\left\|h \nabla_{x^{\prime}} \tilde{g}\right\|_{0}\right)\right)
$$

Since $\tilde{Q}_{1}=2 \varphi_{x_{N}} D_{N}+2 Q_{1}$, we get from (A.12)

$$
\begin{equation*}
\left|B_{0}(v)-2\left\langle\varphi_{x_{N}}\left(x^{\prime}, 0\right) w, w\right\rangle_{0}\right| \leq C\left(\|\tilde{g}\|_{0}^{2}+h^{2}\left\|\nabla_{x^{\prime}} \tilde{g}\right\|_{0}^{2}+\|w\|_{0}\left(\|\tilde{g}\|_{0}+\left\|h \nabla_{x^{\prime}} \tilde{g}\right\| \|_{0}\right)\right) \tag{A.13}
\end{equation*}
$$

Next, using that $\frac{i}{h}\left[\tilde{Q}_{2}, \tilde{Q}_{1}\right]$ is a differential operator of order 2 , and the definition of $\tilde{Q}_{2}$ and $\tilde{Q}_{1}$, we see that

$$
\frac{i}{h}\left[\tilde{Q}_{2}, \tilde{Q}_{1}\right]=H_{0} \tilde{Q}_{2}+H_{1} \tilde{Q}_{1}+H_{2}
$$

with $H_{k} \in \mathcal{E}^{k}, 0 \leq k \leq 2$. Writing

$$
\tilde{q}_{2}=\xi_{N}^{2}+q_{2}\left(x^{\prime}, x_{N}, \xi\right), \quad \tilde{q}_{1}=2\left(\varphi_{x_{N}} \xi_{N}+2 q_{1}\left(x^{\prime}, x_{N}, \xi\right)\right)
$$

and using the sub-ellipticity condition on $\varphi$, we have, for every $\left(x^{\prime}, x_{N}\right) \in[-r, r] \times \overline{V^{\prime}}$ and every $\xi \in \mathbb{R}^{N}$,

$$
\begin{equation*}
\tilde{q}_{2}=\tilde{q}_{1}=0 \Longrightarrow\left\{\tilde{q}_{2}, \tilde{q}_{1}\right\} \geq C \tag{A.14}
\end{equation*}
$$

To finish the proof, we use the following Lemma, which is proved in ([15], Sect. 3, Lem. 1):
Lemma A.7. There exists $\mu$ (large enough) such that

$$
\begin{equation*}
\frac{\mu}{\left\langle\xi^{\prime}\right\rangle^{2}}\left(q_{1}^{2}+\varphi_{x_{N}}^{2} q_{2}\right)+\sigma_{2}\left(H_{2}\right) \geq C\left\langle\xi^{\prime}\right\rangle^{2} \tag{A.15}
\end{equation*}
$$

To finish the proof of Theorem A.5, we consider

$$
G=\frac{\mu}{\Lambda_{t}^{2}}\left(Q_{1}^{2}+\varphi_{x_{N}}^{2} Q_{2}\right) \in \mathcal{E}^{0}
$$

and use Garding's inequality to see that there exists $h_{1}>0$ such that

$$
\begin{align*}
\|\tilde{f}\|_{L^{2}}^{2}-h B_{0}(v) & =\left\|\tilde{Q}_{2} v\right\|_{L^{2}}^{2}+\left\|\tilde{Q}_{1} v\right\|_{L^{2}}^{2}+h\left(\frac{i}{h}\left[\tilde{Q}_{2}, \tilde{Q}_{1}\right] v, v\right) \\
& \geq\left\|\tilde{Q}_{2} v\right\|_{L^{2}}^{2}+\left\|\tilde{Q}_{1} v\right\|_{L^{2}}^{2}+h \operatorname{Re}\left(H_{0} \tilde{Q}_{2} v, v\right)+h \operatorname{Re}\left(H_{1} \tilde{Q}_{1} v, v\right) \\
& -h \operatorname{Re}\left(\tilde{Q}_{1}^{2}+\varphi_{x_{N}}^{2} \tilde{Q}_{2} v, G v\right)-C_{0} h\|v\|_{t, 1}^{2}, \tag{A.16}
\end{align*}
$$

for some $C_{0}>0$ and every $h \in\left(0, h_{1}\right)$. Since $H^{k} \in \mathcal{E}^{k}$, we have

$$
\begin{gathered}
\left|h \operatorname{Re}\left(H_{0} \tilde{Q}_{2} v, v\right)\right| \leq C h^{1 / 2}\left\|\tilde{Q}_{2} v\right\|_{t, 0}^{2}+C h^{3 / 2}\|v\|_{t, 0}^{2}, \\
\left|h \operatorname{Re}\left(H_{1} \tilde{Q}_{1} v, v\right)\right| \leq C h^{1 / 2}\left\|\tilde{Q}_{1} v\right\|_{t, 0}^{2}+C h^{3 / 2}\|v\|_{t, 1}^{2}
\end{gathered}
$$

and

$$
\left\|D_{N} v\right\|_{t, 0}^{2} \leq C\left(\left\|\tilde{Q}_{1} v\right\|_{t, 0}^{2}+\|v\|_{t, 1}^{2}\right) .
$$

Taking $h_{1}$ smaller, we obtain from (A.16) that

$$
\begin{equation*}
\|\tilde{f}\|_{L^{2}}^{2}-h B_{0}(v)+h \operatorname{Re}\left(\tilde{Q}_{1}^{2}+\varphi_{x_{N}}^{2} \tilde{Q}_{2} v, G v\right) \geq \frac{1}{2}\left(\left\|\tilde{Q}_{2} v\right\|_{L^{2}}^{2}+\left\|\tilde{Q}_{1} v\right\|_{L^{2}}^{2}\right)+C h\left(\|v\|_{t, 1}^{2}+\left\|D_{N} v\right\|_{t, 0}^{2}\right) \tag{A.17}
\end{equation*}
$$

From the definition, we also have

$$
\tilde{Q}_{1}^{2}+\varphi_{x_{N}}^{2} \tilde{Q}_{2} \in \varphi_{x_{N}} \tilde{Q}_{2}-\frac{1}{2} D_{N} \circ \varphi_{x_{N}} \tilde{Q}_{1}+\mathcal{E}^{1} \tilde{Q}_{1}+h \mathcal{E}^{0} D_{N}+h \mathcal{E}^{1}
$$

and

$$
h \operatorname{Re}\left(D_{N} \circ \varphi_{x_{N}} \tilde{Q}_{1} v, G v\right)=h \operatorname{Re}\left(\varphi_{x_{N}} \tilde{Q}_{1} v, D_{N} G v\right)-h \operatorname{Re}\left\langle\frac{h}{i} \varphi_{x_{N}} \tilde{Q}_{1} v, G v\right\rangle_{0}
$$

Taking $h_{1}$ smaller if necessary, and from the fact that $D_{N} G \in G D_{N}+h \mathcal{E}^{0}$, we deduce that

$$
\begin{equation*}
C h\left(\|v\|_{t, 1}^{2}+\left\|D_{N} v\right\|_{t, 0}^{2}\right) \leq\|\tilde{f}\|_{L^{2}}^{2}-h B_{0}(v) \tag{A.18}
\end{equation*}
$$

The proof of (A.10) and (A.11) then follows from (A.13).

## Appendix B. Spectral inequality for LOW Frequencies At The boundary

This section is devoted to the proof of Lemma B.1, which gives an inequality for the traces on the boundary $\partial \Omega$ of vector fields of the form $u(x)=\sum_{\mu_{j} \leq \Lambda} a_{j} e_{j}(x)$. As in Appendix A, we choose on the open subset $\left\{x \in \Omega, \operatorname{dist}(x, \partial \Omega)<r_{0}\right\}$ of $\Omega$, with $r_{0}$ small, the normal geodesic coordinate system $x=\left(x^{\prime}, x_{N}\right), x^{\prime} \in$ $\left.\partial \Omega, x_{N}=\operatorname{dist}(x, \partial \Omega) \in\right] 0, r_{0}[$.
Let $\boldsymbol{\Delta}$ be the Laplace operator acting on vector fields. Let us first recall the expression of $\boldsymbol{\Delta}$ in this coordinate system (see [6]). For a vector field $u$, we have the following decomposition

$$
u=u_{\|}+u_{\perp} \frac{\partial}{\partial_{x_{N}}}, \quad u_{\|}=\sum_{j=1}^{N-1} u_{\|, j} \frac{\partial}{\partial_{x_{j}^{\prime}}}
$$

and we write $u=\left(u_{\|}, u_{\perp}\right)$. We also have

$$
\operatorname{div}_{g} u=\frac{1}{\sqrt{\operatorname{det} g}} \partial_{x_{N}}\left[\sqrt{\operatorname{det} g} u_{\perp}\right]+\operatorname{div}_{\|} u_{\|}
$$

with

$$
\operatorname{div}_{\|} u_{\|}=\frac{1}{\sqrt{\operatorname{det} g}} \sum_{j=1}^{N-1} \frac{\partial}{\partial_{x_{j}^{\prime}}}\left(\sqrt{\operatorname{det} g} u_{\|, j}\right)
$$

For a given function $p$, we have

$$
\nabla_{g} p=\left(\nabla_{x^{\prime}} p, \frac{\partial p}{\partial_{x_{N}}}\right)
$$

with

$$
\nabla_{x^{\prime}} p=\sum_{j=1}^{N-1} q_{j} \frac{\partial}{\partial_{x_{j}^{\prime}}}, \quad q_{j}=\sum_{k=1}^{N-1} g^{j, k} \frac{\partial p}{\partial_{x_{k}^{\prime}}}
$$

For $u=\left(u_{\|}, u_{\perp}\right)$, the Laplace operator applied to $u, \boldsymbol{\Delta} u$, is the vector field

$$
\begin{equation*}
\boldsymbol{\Delta}\binom{u_{\|}}{u_{\perp}}=\binom{\Delta_{\|} u_{\|}}{\Delta_{g} u_{\perp}}+M_{1}\binom{u_{\|}}{u_{\perp}}+M_{0}\binom{u_{\|}}{u_{\perp}} \tag{B.1}
\end{equation*}
$$

where $\Delta_{g}$ is the Laplace operator acting on functions, given by (A.2), and $\Delta_{\|}$the operator

$$
\Delta_{\|}=\frac{1}{\sqrt{\operatorname{det} g}} \partial_{x_{N}}\left[\sqrt{\operatorname{det} g} \partial_{x_{N}}\right] I d+P\left(x^{\prime}, x_{N}, \partial_{x^{\prime}}\right)
$$

Here P is a $(N-1) \times(N-1)$ matrix that contains only horizontal derivatives $\partial_{x^{\prime}}$ of order at most 2 . Moreover, the principal symbol of $\Delta_{\|}$is scalar, and one has $\sigma\left(\Delta_{\|}\right)=\sigma\left(\Delta_{g}\right) I d$. In (B.1), $M_{1}$ is a differential operator of order 1 of the form

$$
\begin{equation*}
M_{1}=\sum M_{1, j}\left(x^{\prime}, x_{N}\right) \frac{\partial}{\partial_{x_{j}^{\prime}}^{\prime}}, \quad \sum M_{1, j}=\left(\frac{* \mid *}{* \mid 0}\right) \tag{B.2}
\end{equation*}
$$

and $M_{0}$ is a $N \times N$ matrix (i.e., a differential operator of order 0 ). Observe that $M_{1}$ does not contain derivatives in $\partial_{x_{N}}$ and sends the normal vector $\nu$ into a horizontal vector.

As in Section 2, we consider a cut-off function $\theta \in C_{0}^{\infty}(]-2,2[)$ satisfying $0 \leq \theta \leq 1$, and $\theta \equiv 1$ in a neighborhood of $[-\sqrt{3}, \sqrt{3}]$, and we denote by $\triangle_{\partial \Omega}$ the Laplace operator on the boundary $\partial \Omega$ acting on vector fields. Recall that $\Theta$ is the bounded operator acting on $L^{2}$ sections of the tangent bundle $T \partial \Omega$ defined by $\Theta=\theta\left(\sqrt{1-\Lambda^{-1} \Delta_{\partial \Omega}}\right)$. The aim of this section is to prove the following lemma.

Lemma B.1. Let $Q\left(x, D_{x}\right)$ be a differential operator defined in a neighborhood of $\partial \Omega$. For all $M, N \in \mathbb{N}$ there exists constants $C_{M}$ and $D_{M, N}$ such that for all $\Lambda>0$ and $u(x)=\sum_{\mu_{j} \leq \Lambda} a_{j} e_{j}(x)$ with $a_{j} \in \mathbb{C}$, one has, with $v=\left.Q(u)\right|_{\partial \Omega}$ and $w=(I d-\Theta) v$

$$
\begin{equation*}
\left\|\Delta_{\partial \Omega}^{M} v\right\|_{L^{2}(\partial \Omega)} \leq C_{M} \Lambda^{2 M+1}\left(\sum_{\mu_{j} \leq \Lambda}\left|a_{j}\right|^{2}\right)^{1 / 2} \text { and }\left\|\Delta_{\partial \Omega}^{M} w\right\|_{L^{2}(\partial \Omega)} \leq D_{M, N} \Lambda^{-N}\left(\sum_{\mu_{j} \leq \Lambda}\left|a_{j}\right|^{2}\right)^{1 / 2} \tag{B.3}
\end{equation*}
$$

Proof. For notational simplicity, we write $\partial \Omega=Y$. The bound on $\left\|\Delta_{Y}^{M} v\right\|_{L^{2}(Y)}$ follows from classical trace theorems, thus we will just concentrated on the bound on $\left\|\Delta_{Y}^{M} w\right\|_{L^{2}(Y)}$. From

$$
\Delta_{Y}^{M} w=\sum_{\mu_{j} \leq \Lambda} a_{j} \Delta_{Y}^{M}(1-\theta)\left[\sqrt{1-\Lambda^{-1} \Delta_{Y}}\right]\left(\left.\left(Q\left(x, D_{x}\right) e_{j}\right)\right|_{Y}\right)
$$

we see that it is sufficient to show that

$$
\begin{equation*}
\sup _{\mu_{j} \leq \Lambda}\left\|\Delta_{Y}^{M}(1-\theta)\left[\sqrt{1-\Lambda^{-1} \Delta_{Y}}\right]\left(\left.\left(Q\left(x, D_{x}\right) e_{j}\right)\right|_{Y}\right)\right\|_{L^{2}(Y)} \leq D_{M, N} \Lambda^{-N} \tag{B.4}
\end{equation*}
$$

Indeed, if (B.4) holds true, by Cauchy-Schwartz, we get

$$
\left\|\Delta_{Y}^{M} w\right\|_{L^{2}(Y)} \leq \#\left\{j ; \mu_{j} \leq \Lambda\right\}^{1 / 2}\left(\sum_{\mu_{j} \leq \Lambda}\left|a_{j}\right|^{2}\right)^{1 / 2} D_{M, N} \Lambda^{-N}
$$

and the result will then follows from Weyl's formula (i.e., $\#\left\{j ; \mu_{j} \leq \Lambda\right\}^{1 / 2} \leq c \Lambda^{c}$ ). Let us now prove (B.4). We start with the following lemma.

Lemma B.2. We have

$$
\left.\left(Q\left(x, D_{x}\right) e_{j}\right)\right|_{Y}=\left.Q_{1}\left(\mu_{j}, x^{\prime}, \partial_{x^{\prime}}\right)\left(\partial_{x_{N}} e_{j}\right)\right|_{Y}+\left.Q_{2}\left(\mu_{j}, x^{\prime}, \partial_{x^{\prime}}\right)\left(\partial_{x_{N}} p_{j}\right)\right|_{Y}+\left.Q_{3}\left(\mu_{j}, x^{\prime}, \partial_{x^{\prime}}\right) p_{j}\right|_{Y}
$$

where the $Q_{i}\left(\mu_{j}, x^{\prime}, \partial_{x^{\prime}}\right), 1 \leq i \leq 3$, are differential operators at the boundary with polynomial dependence in $\mu$.
Proof. We write $Q\left(x, D_{x}\right)=\sum_{k, \beta} a_{\alpha, \beta}\left(x^{\prime}, x_{N}\right) \partial_{x^{\prime}}^{\beta} \partial_{x_{N}}^{k}$.
Since

$$
\begin{aligned}
& \Delta_{g}=\partial_{x_{N}}^{2}+g_{N}\left(x^{\prime}, x_{N}\right) \partial_{x_{N}}+\tilde{R}\left(x^{\prime}, x_{N}, \partial_{x^{\prime}}\right) \\
& \boldsymbol{\Delta}=\partial_{x_{N}}^{2}+M_{N}\left(x^{\prime}, x_{N}\right) \partial_{x_{N}}+\tilde{Q}\left(x^{\prime}, x_{N}, \partial_{x^{\prime}}\right)
\end{aligned}
$$

we get from $\boldsymbol{\Delta} e_{j}=\nabla_{g} p_{j}-\mu_{j} e_{j}$

$$
\partial_{x_{N}}^{2} e_{j}=-M_{N}\left(x^{\prime}, x_{N}\right) \partial_{x_{N}} e_{j}-\tilde{Q}\left(x^{\prime}, x_{N}, \partial_{x^{\prime}}\right) e_{j}-\mu_{j} e_{j}+\nabla_{g} p_{j}
$$

We also have that $\Delta_{g} p=0$, which gives

$$
\partial_{x_{N}}^{2} p_{j}=-g_{N}\left(x^{\prime}, x_{N}\right) \partial_{x_{N}} p_{j}-\tilde{R}\left(x^{\prime}, x_{N}, \partial_{x^{\prime}}\right) p_{j}
$$

We get easily from this identities by induction on $k \geq 2$,

$$
\partial_{x_{N}}^{k} e_{j}=A_{k}^{1}\left(\mu_{j}, x, \partial_{x^{\prime}}\right) e_{j}+A_{k}^{2}\left(\mu_{j}, x, \partial_{x^{\prime}}\right) \partial_{x_{N}} e_{j}+A_{k}^{3}\left(\mu_{j}, x, \partial_{x^{\prime}}\right) p_{j}+A_{k}^{4}\left(\mu_{j}, x, \partial_{x^{\prime}}\right) \partial_{x_{N}} p_{j}
$$

where the $A_{k}^{j}\left(\mu, x, \partial_{x^{\prime}}\right)$ are tangential differential operators with polynomial dependence in $\mu$. Then the result follows from $\left.e_{j}\right|_{x_{N}=0}=0$.

Let us denote by $W F_{\Lambda}$ the semi-classical wave front set of a family of functions $f\left(x^{\prime}, \hbar\right)$ on the boundary $\partial \Omega=Y$, with small semi-classical parameter $\hbar=\Lambda^{-1 / 2}$ (see [3,18]). Let us recall that the essential support of the operator $I d-\Theta$ is contained in the set $|\eta|_{y} \geq \sqrt{2}$. One has

$$
\begin{aligned}
\Delta_{Y}^{M}(1-\theta)\left[\sqrt{1-\Lambda^{-1} \Delta_{Y}}\right] \varphi\left(x^{\prime}\right) \partial_{x^{\prime}}^{\alpha} & =\Lambda^{2 M+|\alpha|}\left(\Lambda^{-2} \Delta_{Y}\right)^{M}(1-\theta)\left[\sqrt{1-\Lambda^{-1} \Delta_{Y}}\right] \varphi\left(x^{\prime}\right) \Lambda^{-|\alpha|} \partial_{x^{\prime}}^{\alpha} \\
& =\Lambda^{2 M+|\alpha|} p\left(x^{\prime}, \frac{\hbar}{i} \partial_{x^{\prime}}\right)
\end{aligned}
$$

where $p$ is an $\hbar$ pseudo-differential operator of degree $2 M+|\alpha|$ and essential support contained in the set $\{|\eta| \geq \sqrt{2}\}$. Therefore, from Lemma B.2, the proof of (B.4) will be achieved if we show the existence of a constant $C<\sqrt{2}$, such that

$$
\begin{equation*}
W F_{\Lambda}\left(\left.\partial_{x_{N}} e_{j}\right|_{Y}\right) \subset\{|\eta| \leq C\} \tag{B.5}
\end{equation*}
$$

$$
\begin{equation*}
W F_{\Lambda}\left(\left.p\right|_{Y}\right) \subset\{|\eta| \leq C\} \tag{B.6}
\end{equation*}
$$

$$
\begin{equation*}
W F_{\Lambda}\left(\left.\partial_{x_{N}} p\right|_{Y}\right) \subset\{|\eta| \leq C\} \tag{B.7}
\end{equation*}
$$

We will get in fact that (B.5), (B.6) and (B.7) hold true with $C=1$. Since $p$ is a harmonic function, we have that (B.6) implies (B.7) and hence we just need to prove (B.5) and (B.6).

Let us introduce $\tilde{e_{j}}=1_{x_{N} \geq 0} e_{j}$. Using $\left.e_{j}\right|_{x_{N}=0}=0$, we get that $\tilde{e_{j}}$ satisfies

$$
\left\lvert\, \begin{align*}
& -\boldsymbol{\Delta}_{g} \tilde{e}_{j}+1_{x_{N} \geq 0} \nabla_{g} p_{j}=\mu_{j} \tilde{e}_{j}+\left(k_{\|}, k_{\perp}\right) \delta_{0}  \tag{B.8}\\
& \operatorname{div} \tilde{e}_{j}=0
\end{align*}\right.
$$

where $\left(k_{\|}, k_{\perp}\right)=\left(k_{\|}, k_{\perp}\right)\left(x^{\prime}\right)$. Taking the divergence operator in (B.8) ${ }_{1}$, and using (B.8) $)_{2}$, we get

$$
\operatorname{div}_{g}\left(1_{x_{N} \geq 0} \nabla p_{j}\right)=\frac{1}{\sqrt{\operatorname{det} g}} \partial_{x_{N}}\left[\sqrt{\operatorname{det} g} k_{\perp} \delta_{0}\right]+\operatorname{div}_{\|}\left(k_{\|} \delta_{0}\right)
$$

Denoting by $p_{j}^{0}:=\left.p_{j}\right|_{x_{N}=0}$, and $p_{j}^{1}:=\left.\frac{\partial p_{j}}{\partial x_{N}}\right|_{x_{N}=0}$, and using $-\Delta_{g} p_{j}=0$, we obtain

$$
p_{j}^{1} \delta_{0}=k_{\perp} \delta_{0}^{\prime}+\frac{1}{\sqrt{\operatorname{det} g}} \partial_{x_{N}}[\sqrt{\operatorname{det} g}] k_{\perp} \delta_{0}+\operatorname{div}_{\|}\left(k_{\| \mid}\right) \delta_{0}
$$

Therefore, we have that $k_{\perp}=0$ and $p_{j}^{1}=\operatorname{div}_{\| \mid}\left(k_{\| \mid}\right)$. Hence, from (B.8),

$$
\left(-\mu_{j}-\Delta_{g}\right) \tilde{e}_{j}+1_{x_{N} \geq 0} \nabla_{g} p_{j}=\left(k_{\|}, 0\right) \delta_{0}
$$

Now, since $\nabla_{g} \tilde{p}_{j}:=\nabla_{g}\left(1_{x_{N} \geq 0} p_{j}\right)=1_{x_{N} \geq 0} \nabla_{g} p_{j}+\left(0, p_{j}^{0} \delta_{0}\right)$, we obtain

$$
\left(-\mu-\Delta_{g}\right) \tilde{e}_{j}+\nabla_{g} \tilde{p}_{j}=\left(k_{\|}, p_{j}^{0}\right) \delta_{0} .
$$

Noticing that

$$
-\boldsymbol{\Delta}_{g} \tilde{e}_{j}=-1_{x_{N} \geq 0} \boldsymbol{\Delta}_{g} e_{j}-\left.\left(\partial_{x_{N}} e_{j}\right)\right|_{x_{N}=0} \otimes \delta_{0}
$$

we get

$$
\begin{equation*}
\left(-\mu-\Delta_{g}\right) \tilde{e}_{j}+\nabla_{g} \tilde{p}_{j}=\left(0, p_{j}^{0}\right) \delta_{0}-\binom{\left.\partial_{x_{N}} e_{j, \|}\right|_{Y}}{\left.\partial_{x_{N}} e_{j, \perp}\right|_{Y}} \delta_{0} \tag{B.9}
\end{equation*}
$$

Moreover, we have that $\left.\partial_{x_{N}} e_{j, \perp}\right|_{Y}=0 \operatorname{because}_{\operatorname{div}}^{g}{ }_{j}=0$ and div$\|\left.\left(k_{\|}\right)\right|_{Y}=0$. Hence,

$$
\begin{equation*}
k_{\|}=-\left.\partial_{x_{N}} e_{j, \|}\right|_{Y} \tag{B.10}
\end{equation*}
$$

and we find that $\tilde{e}_{j}, \hbar \tilde{p}_{j}=\tilde{q}_{j}$ satisfy the following system:

$$
\left\lvert\, \begin{align*}
& \left(-\mu \hbar^{2}-\hbar^{2} \boldsymbol{\Delta}_{g}\right) \tilde{e}_{j}+\hbar \nabla_{g} \tilde{q}_{j}=\left(\hbar^{2} k_{\|}, \hbar q_{j}^{0}\right) \delta_{0}  \tag{B.11}\\
& \hbar \operatorname{div}_{g} \tilde{e}_{j}=0
\end{align*}\right.
$$

The proof of Lemma B. 1 will be achieved if we show that the system (B.11) is elliptic in $|\eta|>1$ under the assumption $\mu \hbar^{2} \leq 1$. In order to prove ellipticity, it is sufficient to verify that ellipticity holds true in the flat case, i.e., when the boundary is $x_{N}=0$ and $\boldsymbol{\Delta}$ is the constant coefficient Laplacian. This ellipticity property is supposed to be well known, but we will recall the proof for the convenience of the reader.

In order to prove ellipticity for the system (B.11), we will construct the parametrix (in the flat case) for the system

$$
\left\lvert\, \begin{align*}
& A(v, q):=(-\mu-\Delta) v+\nabla q=f=\left(f_{\|}, f_{\perp}\right) \otimes \delta_{0} \\
& \operatorname{div} v=0  \tag{B.12}\\
& v=0 \text { and } q=0 \text { in } x_{N}<0
\end{align*}\right.
$$

where $|\mu| \leq \Lambda$. Taking the Fourier transform in $\mathbb{R}^{N}$ in (B.12), we get

$$
\left\lvert\, \begin{align*}
& \left(|\zeta|^{2}-\mu\right) \hat{v}+i \zeta \hat{q}=\hat{f}  \tag{B.13}\\
& \zeta \cdot \hat{v}=0
\end{align*}\right.
$$

From the fact that $\Delta q=\operatorname{div} f$, we also have that

$$
\begin{equation*}
i|\zeta|^{2} \hat{q}=\zeta \cdot \hat{f} \tag{B.14}
\end{equation*}
$$

or equivalently for $\zeta \neq 0$

$$
\begin{equation*}
i \zeta \hat{q}=\frac{\zeta(\zeta \cdot \hat{f})}{|\zeta|^{2}} \tag{B.15}
\end{equation*}
$$

From (B.13) and (B.15), we see that

$$
\hat{v}=\frac{1}{|\zeta|^{2}-\mu}\left[\hat{f}-\frac{\zeta(\zeta \cdot \hat{f})}{|\zeta|^{2}}\right]
$$

for $|\zeta|>\Lambda$. Let us now consider a real valued function $\theta \in C^{\infty}$ such that $0 \leq \theta \leq 1$ and for $\varepsilon>0$ small

$$
\theta(\zeta)=0, \text { for }|\zeta| \leq(1+\varepsilon) \sqrt{\Lambda}
$$

and

$$
\theta(\zeta)=1, \text { for }|\zeta| \geq(1+2 \varepsilon) \sqrt{\Lambda}
$$

and introduce (recall that we have $|\mu| \leq \Lambda$, hence $\frac{\theta(\zeta)}{|\zeta|^{2}-\mu}$ is well defined)

$$
\widehat{E(f)}=\left\{\begin{array}{c}
\hat{v}_{\theta}=\frac{\theta(\zeta)}{|\zeta|^{2}-\mu}\left[\hat{f}-\frac{\zeta(\zeta \cdot \hat{f})}{|\zeta|^{2}}\right]  \tag{B.16}\\
\hat{q}_{\theta}=\theta(\zeta) \frac{(\zeta \cdot \hat{f})}{i|\zeta|^{2}}
\end{array}\right.
$$

It is easy to see that $\left(v_{\theta}, q_{\theta}\right)=E(f)$ is the solution of

$$
(-\mu-\Delta) v_{\theta}+\nabla q_{\theta}=\theta(D) f
$$

Applying $E$ to both sides of $(\mathrm{B} .12)_{1}$, we see that

$$
E A(v, q)=(\theta(D) v, \theta(D) q)=E(f)
$$

and then we get

$$
E(f)=(v, q)+(\theta(D)-1)(v, q)
$$

Therefore

$$
\lim _{x_{N} \rightarrow 0^{-}} E(f)=\lim _{x_{N} \rightarrow 0^{-}}(\theta(D)-1)(v, q)
$$

and hence

$$
W F_{\Lambda}\left(\lim _{x_{N} \rightarrow 0^{-}} E(f)\right)=W F_{\Lambda}\left(\lim _{x_{N} \rightarrow 0^{-}}(\theta(D)-1)(v, q)\right)
$$

Writing $\zeta=(\xi, \eta)$, the dual variable of $\left(x_{N}, y\right) \in \mathbb{R} \times \mathbb{R}^{N-1}$, we have

$$
\begin{align*}
\int \mathrm{e}^{-i y \cdot \eta}\left(\lim _{x_{N} \rightarrow 0^{-}}(\theta(D)-1)(v, q)\right) \mathrm{d} y & =\frac{1}{2 \pi} \lim _{x_{N} \rightarrow 0^{-}} \int \mathrm{e}^{i x_{N} \xi}(\theta(\xi, \eta)-1)(\hat{v}, \hat{q})(\xi, \eta) \mathrm{d} \xi, \\
& =0, \quad \text { if }|\eta| \geq(1+2 \varepsilon) \sqrt{\Lambda}, \tag{B.17}
\end{align*}
$$

which gives

$$
W F_{\Lambda}\left(\lim _{x_{N} \rightarrow 0^{-}}(1-\theta(D))(v, q)\right) \subset\{|\eta| \leq(1+2 \varepsilon) \sqrt{\Lambda},\} .
$$

Using (B.11), we see that the proof will be consequence of the ellipticity for $|\eta| \geq(1+2 \varepsilon) \Lambda$ of the map $\left(\hat{f}_{\|}(\eta), \hat{f}_{\perp}(\eta)\right) \mapsto \lim _{x_{N} \rightarrow 0^{-}} \hat{E}(f)(\eta)$. Indeeed, for fixed $|\eta| \geq(1+2 \varepsilon) \Lambda$, since $\theta(\xi, \eta)=1$ for all $\xi$, we get that $\lim _{x_{N} \rightarrow 0^{-}} \hat{E}(f)(\eta)$ is equal to

$$
\left.\begin{array}{rl} 
& \lim _{x_{N} \rightarrow 0^{-}} \frac{1}{2 \pi} \int \mathrm{e}^{i x_{N} \xi} \frac{1}{\xi^{2}+\eta^{2}-\mu}\left[\begin{array}{l}
\hat{f}_{\perp}(\eta)-\frac{\xi\left(\xi \hat{f}_{\perp}(\eta)+\eta \cdot \hat{f}_{\|}(\eta)\right)}{\xi^{2}+\eta^{2}} \\
\hat{f}_{\|}(\eta)-\frac{\eta\left(\xi\left(\xi \hat{f}_{\perp}(\eta)+\eta \cdot \hat{f}_{\|}(\eta)\right)\right.}{\xi^{2}+\eta^{2}}
\end{array}\right] \mathrm{d} \xi \\
= & \frac{1}{2 \sqrt{|\eta|^{2}-\mu}}\left[\begin{array}{c}
\hat{f}_{\perp}(\eta)+i \frac{\sqrt{|\eta|^{2}-\mu}}{\mu} \\
\quad \hat{f}_{\| \mid}(\eta)-\frac{\eta}{\mu}\left(-i \sqrt{|\eta|^{2}-\mu} \hat{f}_{\perp}(\eta)+\eta \cdot \hat{f}_{\|}(\eta)\right) \\
\\
\quad+\frac{i}{\mu}\left[\frac{-i|\eta|\left(-i|\eta| \hat{f}_{\perp}(\eta)+\eta \cdot \hat{f}_{\|}(\eta)\right)}{2 i|\eta|}\right. \\
\frac{\eta\left(-i| | \eta \mid \hat{f}_{\perp}(\eta)+\eta \cdot \hat{f}_{\| \mid}(\eta)\right)}{2 i|\eta|}
\end{array}\right]=\frac{1}{2 \sqrt{|\eta|^{2}-\mu}} M_{\eta, \mu}\left(\hat{f}_{\perp}(\eta), \hat{f}_{\|}(\eta)\right) .
\end{array}\right] .
$$

One find

$$
M_{\eta, \mu}\left(\hat{f}_{\perp}, \hat{f}_{\|}\right)=\left(\left(1+g_{1}(\eta, \mu)\right) \hat{f}_{\perp}, \hat{f}_{\|}+g_{2}(\eta, \mu) \eta\left(\eta \cdot \hat{f}_{\|}\right)\right)
$$

with

$$
g_{1}=|\eta| \sqrt{\eta^{2}-\mu} g_{2}, \quad g_{2}(\eta, \mu)=\frac{\sqrt{\eta^{2}-\mu}-|\eta|}{\mu|\eta|}=\frac{-1}{|\eta|\left(|\eta|+\sqrt{\eta^{2}-\mu}\right)} .
$$

We also have

$$
\begin{align*}
\lim _{x_{N} \rightarrow 0^{-}} \frac{1}{2 \pi} \int \mathrm{e}^{i x_{N} \xi} \frac{\left(\xi \hat{f}_{\perp}(\eta)+\eta \cdot \hat{f}_{\|}(\eta)\right)}{\xi^{2}+\eta^{2}} \mathrm{~d} \xi & =\frac{\left(-i|\eta| \hat{f}_{\perp}(\eta)+\eta \cdot \hat{f}_{\|}(\eta)\right)}{2|\eta|} \\
& =m_{\eta}\left(\hat{f}_{\perp}(\eta), \hat{f}_{\| \mid}(\eta)\right) . \tag{B.19}
\end{align*}
$$

Let $a \in \mathbb{R}, b \in \mathbb{R}^{N-1}$, and define $h \in \mathbb{R}$ and $H=\left(H_{1}, H_{2}\right) \in \mathbb{R} \times \mathbb{R}^{N-1}$ by the system

$$
\left\{\begin{array}{c}
M_{\eta, \mu}(a, b)=H  \tag{B.20}\\
m_{\eta}(a, b)=h .
\end{array}\right.
$$

It remains to prove that there exists $C$ such that for $\Lambda \geq 1,|\eta| \geq(1+2 \varepsilon) \Lambda$ and $|\mu| \leq \Lambda$ the following inequality holds true for solutions of (B.20)

$$
\begin{equation*}
|a|+|b| \leq C(|h|+|H|) . \tag{B.21}
\end{equation*}
$$

Since $m_{\eta}$ and $M_{\eta, \mu}$ are homogeneous of degree zero under the action of $\mathbb{R}_{+}^{*}(\eta, \mu) \mapsto\left(s \eta, s^{2} \mu\right)$, we may assume $|\eta|=1$ and $|\mu| \leq c$ for some $c<1$. Since the set $K=\{|\eta|=1,|\mu| \leq c\}$ is compact, it remains to show that for any $(\eta, \mu) \in K$, the system (B.20) is injective, which is easy to verify. The proof of Lemma B. 1 is complete.

## Appendix C. Proof of Proposition 2.4

In this section, we follow the arguments in [14]. It is sufficient to prove that for every $z \in \bar{W}_{r}$, there exist $D>0, \nu \in] 0,1[$ and a neighborhood $U$ of $z$ such that the following inequality holds true

$$
\begin{equation*}
\|v\|_{H^{1}(U)} \leq D\|v\|_{H^{1}(Z)}^{1-\nu}\left(\|A v\|_{L^{2}(Z)}+\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\omega)}\right)^{\nu} \tag{C.1}
\end{equation*}
$$

Let us begin explaining how we construct the weight function $\varphi$ we need in order to apply Carleman inequalities. For a domain $U \subset \mathbb{R}^{N+1}$ and $z_{0} \in U$, we will take our basic function $\psi \in C^{\infty}\left(U \backslash\left\{z_{0}\right\} ; \mathbb{R}\right)$ verifying

$$
\begin{align*}
& \lim _{z \rightarrow z_{0}} \psi(z)=+\infty \text { and } \psi^{\prime}(z) \neq 0 \forall z \in U \backslash\left\{z_{0}\right\} \\
& \exists c_{0}>0 \text { such that }\left\{z \in U, c_{0} \leq \psi(z) \leq c^{\prime}\right\} \text { is compact } \forall c^{\prime} \geq c_{0} \tag{C.2}
\end{align*}
$$

We also choose a sequence of numbers satisfying

$$
c_{0}<c_{1}<c_{1}^{\prime}<c_{2}<c_{2}^{\prime}<c_{3}<c_{3}^{\prime}<\infty
$$

and set

$$
\begin{gathered}
V=\left\{z \in U \backslash\left\{z_{0}\right\}, c_{1}<\psi(z)<c_{3}^{\prime}\right\}, V^{\prime}=\left\{z \in U \backslash\left\{z_{0}\right\}, c_{1}^{\prime}<\psi(z)<c_{3}\right\} \\
V_{j}=\left\{z \in U \backslash\left\{z_{0}\right\}, c_{j}<\psi(z)<c_{j}^{\prime}\right\} \subset V, j=1,2,3
\end{gathered}
$$

We have $V^{\prime} \subset V$ and the closure $\bar{V}$ of $V$ in $\mathbb{R}^{N+1}$ is compact and contained in $U \backslash\left\{z_{0}\right\}$. Therefore, from Lemma A.4, there exists a constant $D>0$ such that $\varphi=\mathrm{e}^{D \psi}$ satisfies Hormander's sub-ellipticity condition on $\bar{V}$ for the Laplace operator $A:=-\partial_{s s}^{2}-\Delta$.

In the sequel, we take $\rho_{j}=\mathrm{e}^{D c_{j}}, \rho_{j}^{\prime}=\mathrm{e}^{D c_{j}^{\prime}}$ and $\chi$ to be a cutt-off function in $C_{0}^{\infty}(V)$ such that $\chi \equiv 1$ in a neighborhood of $\overline{V^{\prime}}$. We have $\rho_{j} \leq \varphi \leq \rho_{j}^{\prime}$ in $\bar{V}_{j}$ for $j=1,2,3$.
Proof of case 1: $z=\left(s, x_{1}\right) \in\left(0, s_{0}\right) \times \omega$, with $s>0$ small.
Fix $z_{1}=\left(-1, x_{1}\right)$ and consider $\psi(z)=\left(z-z_{1}\right)^{-1}$, with $U=\mathbb{R}^{N+1}$. We have that $\frac{\partial \psi}{\partial s}(s, x) \neq 0$ for $s>-1$. We begin choosing $c_{0}<1$ such that

$$
\begin{equation*}
\left\{x \in \mathbb{R}^{N} ; 1+\left|x-x_{1}\right|^{2} \leq c_{0}^{-2}\right\} \subset \omega \tag{C.3}
\end{equation*}
$$

Next, we choose $1<c_{3}<c_{3}^{\prime}$ so that $\bar{V}_{3} \subset\{s<0\}$ and take $c_{2}^{\prime}=1$ and $c_{1}, c_{1}^{\prime}, c_{2}$ satisfying $c_{0}<c_{1}<c_{1}^{\prime}<c_{2}<1$.
The vector function $\chi v$ verifies $(\chi v)(0, x)=0$ and $\partial_{s}(\chi v)(0, x)=\chi(0, x) \partial_{s} v(0, x)$. From Theorem A. 5 (applied to each component), there exist $C, h_{1}>0$ such that, for every $h \in\left(0, h_{1}\right]$, we have

$$
\begin{equation*}
h\left\|\mathrm{e}^{\varphi / h} \chi v\right\|_{L^{2}}^{2}+h^{3}\left\|\mathrm{e}^{\varphi / h} \nabla_{s, x}(\chi v)\right\|_{L^{2}}^{2} \leq C\left(h^{4}\left\|\mathrm{e}^{\varphi / h} A(\chi v)\right\|_{L^{2}}^{2}+h^{3} \int \mathrm{e}^{2 \varphi(0, x) / h}\left|\chi \partial_{s} v(0, x)\right|^{2} \mathrm{~d} x\right) \tag{C.4}
\end{equation*}
$$

Noticing that $A(\chi v)=\chi(A v)+[A, \chi] v,[A, \chi]$ is a first order differential operator, $[A, \chi] v$ is supported in $V_{1} \cup V_{3}$ and that $\chi=1$ in $V_{2} \subset V^{\prime}$, from (C.3) and (C.4), we get

$$
\begin{equation*}
\mathrm{e}^{\rho_{2} / h}\|v\|_{H^{1}\left(V_{2} \cap Z\right)} \leq C^{\prime}\left(\mathrm{e}^{\rho_{1}^{\prime} / h}\|v\|_{H^{1}(Z)}+\mathrm{e}^{\rho_{3}^{\prime} / h}\left(\|A v\|_{L^{2}(Z)}+\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\omega)}\right)\right) \tag{C.5}
\end{equation*}
$$

for some $C^{\prime}>0$ and every $h \in\left(0, h_{1}\right]$. Then we use the following lemma due to Robbiano [23].
Lemma C.1. Let $C_{1}, C_{2}$ be positive and $M_{0}, M_{1}$ and $M_{2}$ be nonnegative. Assume there exists $C_{3}>0$ such that $M_{0} \leq C_{3} M_{1}$ and $\delta_{0}>0$ such that

$$
M_{0} \leq \mathrm{e}^{-C_{1} \delta} M_{1}+\mathrm{e}^{C_{2} \delta} M_{2}
$$

for every $\delta \geq \delta_{0}$. Then, there exits $C_{0}$ such that

$$
M_{0} \leq C_{0} M_{1}^{C_{2} /\left(C_{1}+C_{2}\right)} M_{2}^{C_{1} /\left(C_{1}+C_{2}\right)}
$$

Indeed, since $\rho_{1}^{\prime}<\rho_{2}<\rho_{3}^{\prime}$, defining $C_{1}=\rho_{2}-\rho_{1}^{\prime}$ and $C_{2}=\rho_{3}^{\prime}-\rho_{2}$, we obtain

$$
\begin{equation*}
\left.\|v\|_{H^{1}\left(V_{2} \cap Z\right)} \leq C^{\prime}\left(\mathrm{e}^{-C_{1} / h}\|v\|_{H^{1}(Z)}+\mathrm{e}^{C_{2} / h}\left(\|A v\|_{L^{2}(Z)}+\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\omega)}\right) \|\right)\right) \tag{C.6}
\end{equation*}
$$

for every $h \in\left(0, h_{1}\right]$. Hence,

$$
\begin{equation*}
\|v\|_{H^{1}\left(V_{2} \cap Z\right)} \leq 2 C^{\prime}\|v\|_{H^{1}(Z)}^{1-\delta}\left(\|A v\|_{L^{2}(Z)}+\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\omega)}\right)^{\delta}, \tag{C.7}
\end{equation*}
$$

with $\delta=\frac{C_{1}}{C_{1}+C_{2}} \in(0,1)$. The proof is finished noticing that, since $c_{2}<c_{2}^{\prime}=1$, the set $V_{2} \cap Z$ contains the points of the form $\left(s, x_{1}\right)$, with $s$ small.

Proof of case 2: $z_{2}=\left(s_{2}, x_{2}\right) \in\left(0, s_{0}\right) \times \Omega$.
From case 1 , there exists $z_{1}=\left(s_{1}, x_{1}\right), s_{1}$ small and $x_{1} \in \omega$ such that $z_{1}$ verifies (C.1). Since $\Omega$ is connected, $Z$ is connected as well and there exists a path $\gamma \in C^{\infty}([0,1])$ within $Z$ such that $\gamma(0)=z_{1}$ and $\gamma(1)=z$. Since $\gamma([0,1])$ is compact in $Z$, there exists an open set $U$ such that $\gamma([0,1]) \subset U \subset Z$ and a $C^{\infty}$ diffeomorphism $\Phi: U \longrightarrow \mathbb{R}^{N+1}=\left\{\left(x_{1}, x_{2}\right) \in \mathbb{R} \times \mathbb{R}^{N}\right\}$ such that $\Phi\left(\gamma\left(x_{1}\right)\right)=\left(x_{1}, 0\right)$ for every $x_{1} \in[0,1]$. Taking $a=-1+\sqrt{2}$, which gives $\frac{a}{1-a^{2}}=\frac{1}{2}$, and a $C^{\infty}$ function $F$ over $\mathbb{R}^{N+1} \backslash\{(0,0)\}$, defined by

$$
F\left(x_{1}, x_{2}\right)=\sqrt{x_{1}^{2}+x_{2}^{2}}-a x_{1}
$$

We have that $F>0$ and $\nabla F \neq 0$ in $\mathbb{R}^{N+1} \backslash\{(0,0)\}$. Moreover, for every $d>0$, the level sets of $F\left(x_{1}, x_{2}\right)=d$ are the ellipsoids with equation

$$
2 a\left(x_{1}-d / 2\right)^{2}+\left|x_{2}\right|^{2}=d^{2}(1+a / 2) .
$$

In particular, the open set $\left\{F\left(x_{1}, x_{2}\right)<1\right\} \cup\{(0,0)\}$ contains the segment $x_{1} \in[0,1], x_{2}=0$. Let us now define a $C^{\infty}$ function $\psi$ in $U \backslash\left\{z_{1}\right\}$ by

$$
\psi(z)=\frac{1}{F(\Phi(z))}
$$

The function $\psi$ verifies assumption (C.2) (with $z_{0}=z_{1}$ and any $c_{0}>0$ ). We denote by $r_{1}, C_{1}$ and $\delta_{1}$ the constants for which interpolation (C.1) holds for the point $z_{1}$ and choose $c_{2}=1, c_{2}^{\prime}$ large enough such that $z_{2} \in V_{2}$ and $c_{3}>c_{2}^{\prime}$ in such a way that $\bar{V}_{3} \subset B_{r_{1}}\left(z_{1}\right) \cap Z$.

From ([17], Thm. 3.5), there exist $C, h_{1}>0$ such that

$$
\begin{equation*}
h\left\|e^{\varphi / h} \chi v\right\|_{L^{2}}^{2}+h^{3}\left\|e^{\varphi / h} \nabla_{s, x}(\chi v)\right\|_{L^{2}}^{2} \leq C h^{4}\left\|e^{\varphi / h} A(\chi v)\right\|_{L^{2}}^{2} \tag{C.8}
\end{equation*}
$$

for every $h \in\left(0, h_{1}\right]$. Arguing as in case 1 , we conclude that there exists $C^{\prime}$ such that

$$
\begin{equation*}
\mathrm{e}^{\rho_{2} / h}\|v\|_{H^{1}\left(V_{2}\right)} \leq C^{\prime}\left(\mathrm{e}^{\rho_{1}^{\prime} / h}\|v\|_{H^{1}(Z)}+\mathrm{e}^{\rho_{3}^{\prime} / h}\|v\|_{H^{1}\left(V_{3}\right)}\right), \tag{C.9}
\end{equation*}
$$

for every $h \in\left(0, h_{1}\right]$. From (C.1), and the choice of $c_{3}$, there exist $C_{1}$ and $\delta_{1} \in(0,1)$ such that $\|v\|_{H^{1}\left(V_{3}\right)} \leq$ $C_{1}\|v\|_{H^{1}(Z)}^{1-\delta_{1}}\left(\|A v\|_{L^{2}(Z)}+\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\omega)}\right)^{\delta_{1}}$. Therefore, (C.9) implies

$$
\begin{equation*}
\mathrm{e}^{\rho_{2} / h}\|v\|_{H^{1}\left(V_{2}\right)} \leq C^{\prime}\left(\mathrm{e}^{\rho_{1}^{\prime} / h}\|v\|_{H^{1}(Z)}+C_{1} \mathrm{e}^{\rho_{3}^{\prime} / h}\|v\|_{H^{1}(Z)}^{1-\delta_{1}}\left(\|A v\|_{L^{2}(Z)}+\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\omega)}\right)^{\delta_{1}}\right), \tag{C.10}
\end{equation*}
$$

for every $h \in\left(0, h_{1}\right]$. From Lemma C.1, there exist $C_{2}>0$ and $\delta \in(0,1)$ such that

$$
\begin{equation*}
\|v\|_{H^{1}\left(V_{2}\right)} \leq C_{2}\|v\|_{H^{1}(Z)}^{1-\delta \delta_{1}}\left\|\partial_{s} v(0, x)\right\|_{L^{2}(\omega)}^{\delta \delta_{1}} . \tag{C.11}
\end{equation*}
$$

Since $V_{2}$ contains a neighborhood of $z_{2}$, (C.1) is a consequence of (C.11). This finishes the proof of case 2 , hence the proof of Proposition 2.4.

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[^0]:    Keywords and phrases. Stokes system, null controllability, Carleman estimates, spectral inequality.

    * F.W. Chaves-Silva and G. Lebeau were supported by the ERC Project No. 320845: Semi Classical Analysis of Partial Differential Equations, ERC-2012-ADG.
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