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## Partial Differential Equations

# On the resolution of Pfaff systems in dimension three

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#### Abstract

We establish that the Cauchy problem associated with a Pfaff system in dimension three has a unique solution under minimal regularity assumptions on its coefficients. *To cite this article: S. Mardare, C. R. Acad. Sci. Paris, Ser. I 344 (2007).* © 2007 Académie des sciences. Published by Elsevier Masson SAS. All rights reserved.

#### Résumé

Sur la résolution des systèmes de Pfaff en dimension trois. On établit que le problème de Cauchy associé à un système de Pfaff en dimension trois a une solution unique sous des hypothèses minimales de régularité sur ses coefficients. *Pour citer cet article : S. Mardare, C. R. Acad. Sci. Paris, Ser. I 344 (2007).* 

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#### Version française abrégée

Les notations sont définies dans la version anglaise. Soit  $\Omega$  un ouvert connexe et simplement connexe de  $\mathbb{R}^3$ , soit  $x_0$  un point de  $\Omega$ , et soit  $Y^0$  une matrice de  $\mathbb{M}^{q \times \ell}$ . Il est alors bien connu (voir, e.g., Thomas [5]) que le système de Pfaff

 $\partial_i Y = Y A_i$  dans  $\Omega$ ,  $i \in \{1, 2, 3\}$ ,  $Y(x^0) = Y^0$ ,

admet une solution unique  $Y \in C^2(\Omega; \mathbb{M}^{q \times \ell})$  si les coefficients  $A_i$  appartiennent à l'espace  $C^1(\Omega; \mathbb{M}^{\ell})$  et satisfont les conditions de compatibilité

$$\partial_i A_i - \partial_i A_j = A_i A_j - A_j A_i \quad \text{dans } \Omega \text{ pour tout } i < j.$$
 (1)

L'objet de cette Note est d'établir que ce résultat reste vrai sous une hypothèse considérablement affaiblie, selon laquelle les coefficients  $A_i$  appartiennent à l'espace  $L_{loc}^p(\Omega; \mathbb{M}^\ell)$ , p > 3, la condition de compatibilité ci-dessus étant alors satisfaite au sens des distributions (voir Théorème 4.1 dans la version anglaise). La preuve repose sur deux résultats principaux : un résultat de stabilité pour les systèmes de Pfaff à coefficients dans  $L^p(\Omega)$  établi dans le

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Théorème 2.1 et un résultat d'approximation (sous les contraintes non linéaires (1)) des champs de matrices  $A_i$  établi dans le Théorème 3.1 de la version anglaise.

La démonstration complète de ces résultats, ainsi que leur généralisation à un domain  $\Omega$  de dimension quelconque, se trouve dans [4].

#### 1. Preliminaries

The notations  $\mathbb{M}^{q \times \ell}$  and  $\mathbb{M}^{\ell}$  respectively designate the set of all matrices with q rows and  $\ell$  columns and the set of all square matrices of order  $\ell$ . A generic point in  $\mathbb{R}^3$  is denoted  $x = (x_i)$  and partial derivatives are denoted  $\partial_i = \frac{\partial}{\partial x_i}$ . An open ball with radius R centered at  $x \in \mathbb{R}^3$  is denoted  $B_R(x)$ , or  $B_R$  if its center is irrelevant in the subsequent analysis. The complement of a set  $\Omega \subset \mathbb{R}^3$  is denoted by  $\Omega^c := \mathbb{R}^3 \setminus \Omega$ .

The space of distributions over an open set  $\Omega \subset \mathbb{R}^3$  is denoted  $\mathcal{D}'(\Omega)$ . The usual Sobolev spaces being denoted  $W^{m,p}(\Omega)$ , we let

$$W_{\text{loc}}^{m,p}(\Omega) := \left\{ f \in \mathcal{D}'(\Omega); f \in W^{m,p}(U) \text{ for all open set } U \Subset \Omega \right\},\$$

where the notation  $U \in \Omega$  means that the closure of U in  $\mathbb{R}^3$  is a compact subset of  $\Omega$ . If p > 3, the classes of functions in  $W^{1,p}_{\text{loc}}(\Omega)$  are identified with their continuous representatives, as in the Sobolev embedding theorem (see, e.g., Adams [1]). For matrix-valued and vector-valued function spaces, we shall use the notations  $W^{m,p}(\Omega; \mathbb{M}^{q \times \ell})$ ,  $W^{m,p}(\Omega; \mathbb{R}^{\ell})$ , etc.

Detailed proofs of the results announced in this Note, together with their generalization to domains of arbitrary dimension, are given in [4].

## 2. Stability of solutions to Pfaff systems

We recall the following stability result, first established in [3], which shows that small perturbations in the  $L^p$ -norm of the coefficients of the Pfaff system and of its "initial data" induce small perturbations of its solution (in the Fréchet space  $W_{loc}^{1,p}$ ):

**Theorem 2.1.** Let  $\Omega$  be a connected open subset of  $\mathbb{R}^3$ , let p > 3, and let there be given sequences of matrix fields  $A_i^n \in L^p(\Omega; \mathbb{M}^\ell)$  and  $Y^n \in W^{1,p}_{\text{loc}}(\Omega; \mathbb{M}^{q \times \ell})$  that satisfy the Pfaff systems

$$\partial_i Y^n = Y^n A_i^n$$
 in  $\Omega$ 

in the distributional sense. Fix a point  $x^0 \in \Omega$  and assume that the sequence  $(\sum_i ||A_i^n||_{L^p(\Omega)} + ||Y^n(x^0)||)$  is bounded from above by a constant M. Then, for any open set  $K \subseteq \Omega$ , there exist a constant C > 0 (depending on M) such that, for all  $n, m \in \mathbb{N}$ ,

$$||Y^{n} - Y^{m}||_{W^{1,p}(K)} \leq C \left\{ \sum_{i} ||A_{i}^{n} - A_{i}^{m}||_{L^{p}(\Omega)} + ||Y^{n}(x^{0}) - Y^{m}(x^{0})|| \right\}.$$

An immediate consequence of Theorem 2.1 is the following uniqueness result:

**Corollary 2.2.** Let  $\Omega$  be a connected open subset of  $\mathbb{R}^3$ , let p > 3, and let there be given matrix fields  $A_i \in L^p_{loc}(\Omega; \mathbb{M}^\ell)$  and  $Y, \widetilde{Y} \in W^{1,p}_{loc}(\Omega; \mathbb{M}^{q \times \ell})$  that satisfy the relations

 $\partial_i Y = Y A_i \quad and \quad \partial_i \widetilde{Y} = \widetilde{Y} A_i \quad in \mathcal{D}'(\Omega; \mathbb{M}^{q \times \ell}).$ 

Assume that there exists a point  $x^0 \in \Omega$  such that  $Y(x^0) = \widetilde{Y}(x^0)$ . Then  $Y(x) = \widetilde{Y}(x)$  for all  $x \in \Omega$ .

#### 3. Approximation of the Pfaff system

We show in this section that a Pfaff system with  $L_{loc}^p$ -coefficients can be approximated, in a sense specified in Theorem 3.1, with Pfaff systems with smooth coefficients. The main difficulty in establishing such a result is that the coefficients of the approximating Pfaff system must preserve the compatibility conditions, which are nonlinear.

**Theorem 3.1.** Let  $\Omega$  be an open subset of  $\mathbb{R}^3$  and let  $A_i \in L^p(\Omega; \mathbb{M}^\ell)$ , p > 3, be matrix fields that satisfy the relations

$$\partial_j A_i - \partial_i A_j = A_i A_j - A_j A_i \quad for all \ i < j$$

in the space of distributions  $\mathcal{D}'(\Omega; \mathbb{M}^{\ell})$ .

Then there exists a number  $R_0 = R_0(p, \ell, ||A_i||_{L^p(\Omega)})$  with the following property: For any open cube  $\omega \in \Omega$ whose edges have lengths  $\langle R_0$ , there exist sequences of matrix fields  $(A_i^{\varepsilon})_{\varepsilon \in \mathbb{N}}$  in  $\mathcal{C}^{\infty}(\omega; \mathbb{M}^{\ell}) \cap L^p(\omega; \mathbb{M}^{\ell})$  that satisfy the relations

$$\begin{aligned} \partial_j A_i^{\varepsilon} &- \partial_i A_j^{\varepsilon} = A_i^{\varepsilon} A_j^{\varepsilon} - A_j^{\varepsilon} A_i^{\varepsilon} & \text{in } \omega \text{ for all } i < j, \\ A_i^{\varepsilon} &\to A_i & \text{in } L^p(\omega; \mathbb{M}^{\ell}) \text{ as } \varepsilon \to \infty. \end{aligned}$$

**Proof.** The idea is to decompose the coefficients  $A := (A_i) : \omega \to (\mathbb{M}^{\ell})^3$  into two parts,

 $A = \operatorname{Curl} X + \nabla \phi,$ 

where  $\phi: \omega \to \mathbb{M}^{\ell}$  is a vector field not subjected to any constraints, while  $X = (X_i): \omega \to (\mathbb{M}^{\ell})^3$  is uniquely determined by  $\phi$  and the compatibility conditions satisfied by the coefficients  $A_i$ . Hereinafter, the gradient operator, the Curl operator, and the exterior product  $\wedge$  are defined by

$$\nabla \phi := (\partial_1 \phi, \partial_2 \phi, \partial_3 \phi),$$
  

$$\operatorname{Curl} X := (\partial_2 X_3 - \partial_3 X_2, \partial_3 X_1 - \partial_1 X_3, \partial_1 X_2 - \partial_2 X_1),$$
  

$$A \wedge B := (A_2 B_3 - A_3 B_2, A_3 B_1 - A_1 B_3, A_1 B_2 - A_2 B_1).$$

Then the approximation of A will be defined by mollifying  $\phi$  with a convolution kernel, then by defining the approximation of X as the solution of a nonlinear problem that is related to the compatibility conditions that must be satisfied by the approximating coefficients. The proof is broken into several steps:

(i) *Decomposition of the coefficients*. Let there be given a cube  $\omega$  satisfying the assumptions of the theorem and let  $\phi$  and  $X := (X_i)$  be defined such that

 $A = \operatorname{Curl} X + \nabla \phi$ 

and such that

div X = 0 in  $\omega$ ,  $X_{\tau} = \partial_{\nu} X_{\nu} = 0$  on  $\partial \omega$ ,

where  $\nu$  is the outward-pointing unit normal to  $\partial \omega$ , and where  $X_{\nu}$  and  $X_{\tau}$  are respectively the normal and tangent components of X defined by

 $X_{\nu} := (X \cdot \nu)\nu = (\nu_i(\nu_1 X_1 + \nu_2 X_2 + \nu_3 X_3))$  and  $X_{\tau} := X - X_{\nu}$ .

Since  $\omega$  is a cube, say  $\omega := (a_1, b_1) \times (a_2, b_2) \times (a_3, b_3)$ , these components are in fact the vector fields

 $X_{\nu} = (0, 0, X_3)$  and  $X_{\tau} = (X_1, X_2, 0)$  on  $(a_1, b_1) \times (a_2, b_2) \times \{a_3, b_3\},\$ 

and the boundary conditions on  $(a_1, b_1) \times (a_2, b_2) \times \{a_3, b_3\}$  for instance read

$$X_1 = X_2 = \partial_3 X_3 = 0.$$

Note that the above equalities imply that  $\partial_1 X_1 = \partial_2 X_2 = \partial_3 X_3 = 0$  on  $(a_1, b_1) \times (a_2, b_2) \times \{a_3, b_3\}$ . Therefore div X = 0 on  $\partial \Omega$ .

That such a decomposition exists is proved as follows: First, the problem

$$\Delta X = A \wedge A,$$

$$X_{\tau} = \partial_{\nu} X_{\nu} = 0 \quad \text{on } \partial \omega,$$

has a unique solution in  $H^1(\omega, (\mathbb{M}^{\ell})^3)$  (note that since p > 3,  $A \wedge A \in L^{p/2}(\omega, (\mathbb{M}^{\ell})^3) \subset H^{-1}(\omega, (\mathbb{M}^{\ell})^3)$ ) since it is a Laplace problem with mixed boundary conditions (the unknown  $X_1$  satisfies Dirichlet boundary conditions on  $[(a_1, b_1) \times (a_2, b_2) \times \{a_3, b_3\}] \cup [(a_1, b_1) \times \{a_2, b_2\} \times (a_3, b_3)]$  and Neumann boundary conditions on  $\{a_1, b_1\} \times (a_2, b_2) \times (a_3, b_3)$ , the unknowns  $X_2$  and  $X_3$  satisfy similar conditions on  $\partial \omega$ ). Note that  $X_i \in W^{2, p/2}(\omega; \mathbb{M}^{\ell}) \subset$   $W^{1,p}(\omega; \mathbb{M}^{\ell})$  by the regularizing effect of the Laplace equation and by the Sobolev embeddings (we use here the assumption p > 3). Since div X satisfies the system

$$\Delta(\operatorname{div} X) = \operatorname{div}(A \land A) = \operatorname{div}(-\operatorname{Curl} A) = 0 \quad \text{in } \omega,$$
  
 
$$\operatorname{div} X = 0 \quad \text{on } \partial \omega,$$

we must have div X = 0 in  $\omega$ . It turn, this implies that Curl Curl  $X = -A \wedge A$ , since the formula Curl Curl  $Y = -\Delta Y + \nabla(\operatorname{div} Y)$  holds for all matrix field  $Y = (Y_i)$ . Hence

 $\operatorname{Curl}(\operatorname{Curl} X - A) = \operatorname{Curl} \operatorname{Curl} X + A \wedge A = 0,$ 

which in turn implies that there exists a field  $\phi \in W^{1,p}(\omega; \mathbb{M}^{\ell})$  such that  $\operatorname{Curl} X - A = \nabla \phi$ . This shows that the desired decomposition of A can indeed be achieved.

(ii) Approximation of  $\phi$  and X. It suffices to mollify  $\phi$  by convolution, i.e.,  $\phi^{\varepsilon} = \phi * \rho_{\varepsilon}$  with  $(\rho_{\varepsilon})$  a sequence of mollifiers, then to define  $X^{\varepsilon} \in W^{2, p/2}(\omega; \mathbb{M}^{\ell})$  as the solution, given by the inverse function theorem (the assumptions of this theorem are indeed satisfied), to the nonlinear system

$$\Delta X^{\varepsilon} = (\operatorname{Curl} X^{\varepsilon} + \nabla \phi^{\varepsilon}) \wedge (\operatorname{Curl} X^{\varepsilon} + \nabla \phi^{\varepsilon}) \quad \text{in } \mathcal{D}'(\omega; (\mathbb{M}^{\ell})^{3}), \\ X^{\varepsilon}_{\tau} = \partial_{\nu} X^{\varepsilon}_{\nu} = 0 \quad \text{on } \partial \omega.$$

Assume for a moment that we have proved that the solution to this system satisfies div  $X^{\varepsilon} = 0$  in  $\omega$ . This implies that Curl Curl  $X^{\varepsilon} = -\Delta X^{\varepsilon}$ , so that the previous system shows that

$$\operatorname{Curl}\operatorname{Curl} X^{\varepsilon} = - \left(\operatorname{Curl} X^{\varepsilon} + \nabla \phi^{\varepsilon}\right) \wedge \left(\operatorname{Curl} X^{\varepsilon} + \nabla \phi^{\varepsilon}\right) \quad \text{in } \omega,$$

which in turn implies that

$$\operatorname{Curl}(\operatorname{Curl} X^{\varepsilon} + \nabla \phi^{\varepsilon}) = -(\operatorname{Curl} X^{\varepsilon} + \nabla \phi^{\varepsilon}) \wedge (\operatorname{Curl} X^{\varepsilon} + \nabla \phi^{\varepsilon}) \quad \text{in } \omega.$$

We now prove that div  $X^{\varepsilon} = 0$  in  $\omega$ . First, the boundary conditions satisfied by  $X^{\varepsilon}$  imply that div  $X^{\varepsilon} = 0$  on the boundary  $\partial \omega$ . Second, div  $X^{\varepsilon}$  satisfies the equation

$$\Delta(\operatorname{div} X^{\varepsilon}) = \operatorname{div}((\operatorname{Curl} X^{\varepsilon} + \nabla \phi^{\varepsilon}) \wedge (\operatorname{Curl} X^{\varepsilon} + \nabla \phi^{\varepsilon})) \quad \text{in } \omega.$$

The key formula here is

$$\operatorname{div}(Y \wedge Z) = (\operatorname{Curl} Y) \cdot Z - Y \cdot (\operatorname{Curl} Z)$$

for all fields  $Y = (Y_i)$  and  $Z = (Z_i)$  in  $H^1(\omega; (\mathbb{M}^{\ell})^3)$  (here  $P \cdot Q := \sum_i P_i Q_i$  for  $P, Q : \Omega \to (\mathbb{M}^{\ell})^3$ ). With the notation  $A^{\varepsilon} := \operatorname{Curl} X^{\varepsilon} + \nabla \phi^{\varepsilon}$ , it implies that

$$div((Curl X^{\varepsilon} + \nabla\phi^{\varepsilon}) \wedge (Curl X^{\varepsilon} + \nabla\phi^{\varepsilon}))$$
  
= Curl Curl X<sup>\varepsilon</sup> \Lambda A^\varepsilon - A^\varepsilon \Lambda Curl Curl X^\varepsilon  
= (-\Delta X^\varepsilon + \nabla(\div X^\varepsilon)) \Lambda A^\varepsilon - A^\varepsilon \Lambda (-\Delta X^\varepsilon + \nabla(\div X^\varepsilon)))  
= -(A^\varepsilon \Lambda A^\varepsilon + \nabla(\div X^\varepsilon) \Lambda A^\varepsilon + A^\varepsilon \Lambda (A^\varepsilon + \nabla(\div X^\varepsilon)))

Since  $(A^{\varepsilon} \wedge A^{\varepsilon}) \cdot A^{\varepsilon} = A^{\varepsilon} \cdot (A^{\varepsilon} \wedge A^{\varepsilon})$ , we deduce from the previous formulas that

$$\Delta(\operatorname{div} X^{\varepsilon}) = \nabla(\operatorname{div} X^{\varepsilon}) \cdot A^{\varepsilon} - A^{\varepsilon} \cdot \nabla(\operatorname{div} X^{\varepsilon}) \quad \text{in } \omega,$$
  
$$\operatorname{div} X^{\varepsilon} = 0 \quad \text{on } \partial\omega.$$

If the cube  $\omega$  is small enough, this implies that div  $X^{\varepsilon} = 0$  by using the energy estimate associated with the above system combined with the convergence  $A^{\varepsilon} \to A$  in  $L^{p}(\omega)$  (see the next step).

(iii) Approximation of A. Let  $A^{\varepsilon} = \operatorname{Curl} X^{\varepsilon} + \nabla \phi^{\varepsilon}$  in  $\omega$ . Then  $A^{\varepsilon} \to A$  in  $L^{p}(\omega)$ , since  $\phi^{\varepsilon} \to \phi$  in  $W^{1,p}(\omega)$  and  $X^{\varepsilon} \to X$  in  $W^{2,p/2}(\omega; (\mathbb{M}^{\ell})^{3})$  (by the inverse function theorem) and, a fortiori, in  $W^{1,p}(\omega; (\mathbb{M}^{\ell})^{3})$  (by the Sobolev embeddings). That  $\operatorname{Curl} X^{\varepsilon}$  belongs to  $\mathcal{C}^{\infty}(\omega; (\mathbb{M}^{\ell})^{3})$  is a consequence, by a bootstrap argument, of the interior regularity of the Laplacian.  $\Box$ 

## 4. Existence and uniqueness of solutions

The main result of this Note is the following existence and uniqueness result for the Cauchy problem associated with a Pfaff system with  $L_{loc}^{p}$ -coefficients:

**Theorem 4.1.** Let  $\Omega \subset \mathbb{R}^3$  be a connected and simply connected open set, let  $x^0 \in \Omega$ , and let  $Y^0 \in \mathbb{M}^{q \times \ell}$ . Let there be given three matrix fields  $A_i \in L^p_{loc}(\Omega; \mathbb{M}^\ell)$ , p > 3, satisfying the relations

$$\partial_j A_i - \partial_i A_j = A_i A_j - A_j A_i$$
 for all  $i < j$ ,

in the space of distributions  $\mathcal{D}'(\Omega; \mathbb{M}^{\ell})$ . Then the Cauchy problem

$$\partial_i Y = Y A_i \quad in \mathcal{D}'(\Omega; \mathbb{M}^{q \times \ell}),$$
  

$$Y(x^0) = Y^0,$$
(2)

has one and only one solution  $Y \in W^{1,p}_{loc}(\Omega; \mathbb{M}^{q \times \ell})$ .

**Proof.** We first prove the following local existence result: Let  $\widetilde{\Omega} \subseteq \Omega$ . Then for each open ball  $B_r := B_r(y^0) \subseteq \widetilde{\Omega}$  whose radius satisfies  $r < \min(\frac{1}{3}\operatorname{dist}(y^0, \widetilde{\Omega}^c), \frac{R_0}{2})$ , where  $R_0 = R_0(\widetilde{\Omega})$  is the number defined in Theorem 3.1, there exists a field  $Y \in W^{1,p}(B_r; \mathbb{M}^{q \times \ell})$  that satisfies the Pfaff system

$$\partial_i Y = Y A_i \quad \text{in } \mathcal{D}'(B_r; \mathbb{M}^{q \times \ell}),$$
  

$$Y(y^0) = Z^0,$$
(3)

where  $Z^0$  is an arbitrary matrix in  $\mathbb{M}^{q \times \ell}$ . We find this solution as a limit of solutions to a sequence of Pfaff systems with smooth coefficients.

Note that the assumption on the radius of the ball  $B_r(x_0)$  implies that  $B_{3r}(y^0) \in \widetilde{\Omega}$ . It is then possible to choose R such that  $r < R < R_0/2$  and  $B_{3R}(y^0) \in \widetilde{\Omega}$ . Since the open cube  $\omega_{2R}$  centered at  $y^0$  with edges of length 2R is contained in  $B_{3R}(y^0) \in \widetilde{\Omega}$ , Theorem 3.1 shows that there exist sequences of matrix fields  $A_i^n \in \mathcal{C}^{\infty}(\omega_{2R}; \mathbb{M}^{\ell}) \cap L^p(\omega_{2R}; \mathbb{M}^{\ell})$  that satisfy

$$\begin{aligned} \partial_j A_i^n &- \partial_i A_j^n = A_i^n A_j^n - A_j^n A_i^n \quad \text{in } \omega_{2R}, \\ A_i^n &\to A_i \quad \text{in } L^p(\omega_{2R}; \mathbb{M}^\ell) \text{ as } n \to \infty. \end{aligned}$$

Since the coefficients  $A_i^n$  are smooth, the classical result on Pfaff systems (see, e.g., Thomas [5]) shows that there exists a matrix field  $Y^n \in C^{\infty}(\omega_{2R}; \mathbb{M}^{q \times \ell})$  that satisfies

$$\partial_i Y^n = Y^n A_i^n \quad \text{in } \omega_{2R},$$

$$Y^n(y^0) = Z^0.$$
(4)

By the stability result of Theorem 2.1, there exists a constant C > 0 such that

$$||Y^{n} - Y^{m}||_{W^{1,p}(B_{r})} \leq C \sum_{i} ||A_{i}^{n} - A_{i}^{m}||_{L^{p}(\omega_{2R})},$$

which means that  $(Y^n)$  is a Cauchy sequence in the space  $W^{1,p}(B_r; \mathbb{M}^{q \times \ell})$ . Since this space is complete, there exists a field  $Y \in W^{1,p}(B_r; \mathbb{M}^{q \times \ell})$  such that

$$Y^n \to Y$$
 in  $W^{1,p}(B_r; \mathbb{M}^{q \times \ell})$  as  $n \to \infty$ .

In addition, the Sobolev continuous embedding  $W^{1,p}(B_r; \mathbb{M}^{q \times \ell}) \subset \mathcal{C}^0(B_r; \mathbb{M}^{q \times \ell})$  shows that  $Y^n(y^0) \to Y(y^0)$  in  $\mathbb{M}^{q \times \ell}$  as  $n \to \infty$ . By passing to the limit  $n \to \infty$  in the equations of the system (4), we deduce that the field Y satisfies the Pfaff system (3).

Finally, we define a global solution to the Pfaff system (2) as in the proof of Theorem 3.1 of [2], by glueing together some sequences of local solutions along curves starting from the given point  $x^0$ . We prove that this definition is unambiguous thanks to the uniqueness result of Corollary 2.2 and to the simply-connectedness of the set  $\Omega$ . That this solution is unique follows from Corollary 2.2.  $\Box$ 

**Remark 1.** The minimal value of p for which the Cauchy problem (2) with coefficients  $A_i \in L^p_{loc}(\Omega; \mathbb{M}^{\ell})$  is well posed in the distributional sense is p > 3. Otherwise, the initial condition does not make sense because the value of Y at  $x^0$  cannot be defined since the solution need not be continuous. Moreover, a simple example in the scalar case (i.e., when  $A_i$  and Y are usual functions) shows that the Pfaff system alone (without the initial condition at  $x^0$ ) need not have a solution in the distributional sense if p < 3.

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