# An asymmetric Neumann problem with weights 

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#### Abstract

We prove the existence of a first nonprincipal eigenvalue for an asymmetric Neumann problem with weights involving the $p$-Laplacian (cf. (1.2) below). As an application we obtain a first nontrivial curve in the corresponding Fučik spectrum (cf. (1.4) below). The case where one of the weights has meanvalue zero requires some special attention in connexion with the (PS) condition and with the mountain pass geometry.


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## Résumé

Nous démontrons l'existence d'une première valeur propre non principale pour un problème de Neumann asymétrique avec poids faisant intervenir le p-laplacien (cf. (1.2) ci-dessous). Comme application nous obtenons une première courbe non triviale dans le spectre de Fučik correspondant (cf. (1.4) ci-dessous). Le cas où l'un des poids est de moyenne nulle demande une attention particulière en liaison avec la condition de Palais-Smale et avec la géométrie du col.
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## 1. Introduction

In a previous work [2], we investigated the eigenvalues of the following asymmetric Dirichlet problem with weights:

$$
\begin{equation*}
-\Delta_{p} u=\lambda\left[m(x)\left(u^{+}\right)^{p-1}-n(x)\left(u^{-}\right)^{p-1}\right] \quad \text { in } \Omega, \quad u=0 \quad \text { on } \partial \Omega, \tag{1.1}
\end{equation*}
$$

where $\Delta_{p}$ is the $p$-Laplacian, $\Omega$ is a bounded domain in $\mathbb{R}^{N}$ and $m, n$ satisfy some summability conditions together with $m^{+} \not \equiv 0, n^{+} \not \equiv 0$. We proved the existence of a first nonprincipal positive eigenvalue for (1.1). Various applications were given to the study of the Fučik spectrum and to the study of nonresonance. The construction of this

[^0]distinguished eigenvalue was obtained by applying a version of the mountain pass theorem to the functional $\int_{\Omega}|\nabla u|^{p}$ restricted to the manifold $\left\{u \in W_{0}^{1, p}(\Omega): \int_{\Omega}\left[m\left(u^{+}\right)^{p}+n\left(u^{-}\right)^{p}\right]=1\right\}$. In this process the (PS) condition was shown to hold at all levels and the geometry of the mountain pass was derived from the observation that $\varphi_{1}(m)$ and $-\varphi_{1}(n)$ were strict local minima (where $\varphi_{1}(m)$ denotes the normalized positive first eigenfunction of the Dirichlet $p$-Laplacian with weight $m$ ).

Our purpose in the present paper is to investigate the corresponding Neumann problem:

$$
\begin{equation*}
-\Delta_{p} u=\lambda\left[m(x)\left(u^{+}\right)^{p-1}-n(x)\left(u^{-}\right)^{p-1}\right] \quad \text { in } \Omega, \quad \frac{\partial u}{\partial v}=0 \quad \text { on } \partial \Omega \tag{1.2}
\end{equation*}
$$

where $v$ denotes the unit exterior normal. When trying to adapt the preceding approach to the present situation, the relevant functional is still $\int_{\Omega}|\nabla u|^{p}$ but now restricted to the manifold

$$
\begin{equation*}
M_{m, n}:=\left\{u \in W^{1, p}(\Omega): B_{m, n}(u):=\int_{\Omega}\left[m\left(u^{+}\right)^{p}+n\left(u^{-}\right)^{p}\right]=1\right\} \tag{1.3}
\end{equation*}
$$

A first difficulty arises in connexion with the (PS) condition. It turns out that the (PS) condition remains satisfied at all levels when $\int_{\Omega} m \neq 0$ and $\int_{\Omega} n \neq 0$, but it is not satisfied anymore at level 0 when $\int_{\Omega} m=0$ or $\int_{\Omega} n=0$. In this latter case, which we will call the singular case, we do not know whether the (PS) condition still holds at all positive levels (see Remark 3.4). However one can show that the Palais-Smale condition of Cerami (abbreviated into (PSC)) holds at all positive levels. Another difficulty arises when dealing with problem (1.2), which is now connected with the geometry of the functional. It turns out that in the singular case, at least one of the two natural candidates for local minimum fails to belong to the manifold $M_{m, n}$. To bypass this difficulty we will consider a minimax procedure defined from a family of paths having free endpoints (cf. (3.1)).

The existence of a first nonprincipal positive eigenvalue for (1.2) is derived in Section 3. The argument uses a version of the mountain pass theorem for a $C^{1}$ functional restricted to a $C^{1}$ manifold and which satisfies the (PSC) condition at certain levels. Section 4 is devoted to such a theorem. In Section 5 we briefly indicate some properties of the eigenvalue constructed in Section 3 as a function of the weights $m, n$ and in Section 6 we apply our results to the study of the Fučik spectrum. Recall that the latter is defined as the set $\Sigma$ of those $(\alpha, \beta) \in \mathbb{R}^{2}$ such that

$$
\begin{equation*}
-\Delta_{p} u=\alpha m(x)\left(u^{+}\right)^{p-1}-\beta n(x)\left(u^{-}\right)^{p-1} \quad \text { in } \Omega, \quad \frac{\partial u}{\partial v}=0 \quad \text { on } \partial \Omega, \tag{1.4}
\end{equation*}
$$

has a nontrivial solution. As in the Dirichlet case we obtain for (1.4) the existence in $\Sigma$ of hyperbolic-like first curves. Note however that contrary to what was happening in the Dirichlet case, the asymptotic behaviour of these first curves does not depend on the supports of the weights (at least when the weights are bounded, cf. Proposition 6.4 and Remark 6.5).

In the preliminary Section 2 we collect some results relative to the usual eigenvalue problem

$$
\begin{equation*}
-\Delta_{p} u=\lambda m(x)|u|^{p-2} u \quad \text { in } \Omega, \quad \frac{\partial u}{\partial v}=0 \quad \text { on } \partial \Omega \tag{1.5}
\end{equation*}
$$

We also recall there some general definitions relative to (PS) and (PSC) conditions.

## 2. Preliminaries

Throughout this paper $\Omega$ will be a bounded domain in $\mathbb{R}^{N}$ with Lipschitz boundary and the weights $m, n$ will be assumed to belong to $L^{r}(\Omega)$ with $r>\frac{N}{p}$ if $p \leqslant N$ and $r=1$ if $p>N$. We also assume unless otherwise stated

$$
\begin{equation*}
m^{+} \text {and } n^{+} \not \equiv 0 \quad \text { in } \Omega \tag{2.1}
\end{equation*}
$$

Solutions of (1.2) or of related equations are always understood in the weak sense, i.e. $u \in W^{1, p}(\Omega)$ with

$$
\int_{\Omega}|\nabla u|^{p-2} \nabla u \nabla \varphi=\lambda \int_{\Omega}\left[m\left(u^{+}\right)^{p-1}-n\left(u^{-}\right)^{p-1}\right] \varphi, \quad \forall \varphi \in W^{1, p}(\Omega)
$$

Regularity results from [13] on general quasilinear equations imply that such a solution $u$ is locally Hölder continuous in $\Omega$; moreover the derivation of the $L^{\infty}$ estimates in [1] can be adapted to the present situation to show that $u \in$
$L^{\infty}(\Omega)$. Note that if in addition $m, n \in L^{\infty}(\Omega)$ and $\Omega$ is of class $C^{1,1}$, then $u \in C^{1, \alpha}(\bar{\Omega})$ for some $0<\alpha<1$ (cf. [12]).

Our main purpose in this preliminary section is to collect some results relative to the eigenvalue problem (1.5).
Clearly 0 is a principal eigenvalue of (1.5), with the constants as eigenfunctions. The search for another principal eigenvalue involves the following quantity:

$$
\begin{equation*}
\lambda^{*}(m)=\inf \left\{\int_{\Omega}|\nabla u|^{p}: u \in W^{1, p}(\Omega) \text { and } \int_{\Omega} m|u|^{p}=1\right\} . \tag{2.2}
\end{equation*}
$$

By (2.1), $\lambda^{*}(m)<\infty$.

## Proposition 2.1.

(i) Suppose $\int_{\Omega} m<0$. Then $\lambda^{*}(m)>0$ and $\lambda^{*}(m)$ is the unique nonzero principal eigenvalue; this eigenvalue is simple and admits an eigenfunction which can be chosen $>0$ in $\Omega$; moreover the interval $] 0, \lambda^{*}(m)[$ does not contain any other eigenvalue.
(ii) Suppose $\int_{\Omega} m>0$. Then $\lambda^{*}(m)=0$ and 0 is the unique nonnegative principal eigenvalue.
(iii) Suppose $\int_{\Omega} m=0$. Then $\lambda^{*}(m)=0$ and 0 is the unique principal eigenvalue.

Proposition 2.1 is proved in [10] (see also [6,11]) when $m \in L^{\infty}(\Omega)$, but the arguments can easily be adapted to the present situation. We observe in this respect that in the case of an unbounded weight, Harnack's inequality as given in [13,9] should be used instead of Vazquez maximum principle [14] to derive in case (i) that the eigenfunction can be chosen $>0$ in $\Omega$. See [4] for similar considerations in the Dirichlet case. In case (i) or (ii) of Proposition 2.1, the positive eigenfunction associated to $\lambda^{*}(m)$ and normalized so as to satisfy the constraint in (2.2) will be denoted by $\varphi_{m}$. The infimum (2.2) is then achieved at $\varphi_{m}$. In case (iii) the fact that $\lambda^{*}(m)=0$ is easily verified by considering the sequence

$$
\begin{equation*}
v_{k}=\frac{(1+\psi / k)^{1 / p}}{\left[\int_{\Omega} m(1+\psi / k)\right]^{1 / p}}, \tag{2.3}
\end{equation*}
$$

where $\psi$ is any fixed smooth function with $\psi \geqslant 0$ and $\int_{\Omega} m \psi>0$. Note that in that case (iii), the infimum (2.2) is not achieved (since no constant satisfies the constraint in that case).

Let us conclude this section with some general definitions relative to the (PS) condition. Let $E$ be a real Banach space and let $M:=\{u \in E: g(u)=1\}$ where $g \in C^{1}(E, \mathbb{R})$ and 1 is a regular value of $g$. Let $f \in C^{1}(E, \mathbb{R})$ and consider the restriction $\tilde{f}$ of $f$ to $M$. The differential $\tilde{f}^{\prime}$ at $u \in M$, has a norm which will be denoted by $\left\|\tilde{f}^{\prime}(u)\right\|_{*}$ and which is given by the norm of the restriction of $f^{\prime}(u) \in E^{*}$ to the tangent space of $M$ at $u$

$$
T_{u}(M):=\left\{v \in E:\left\langle g^{\prime}(u), v\right\rangle=0\right\},
$$

where $\langle$,$\rangle denotes the pairing between E^{*}$ and $E$. A critical point of $\tilde{f}$ is a point $u \in M$ such that $\left\|\tilde{f}^{\prime}(u)\right\|_{*}=0 ; \tilde{f}(u)$ is then called a critical value of $\tilde{f}$.

We recall that $\tilde{f}$ is said to satisfy the $(\mathrm{PS})_{c}$ condition (resp. (PSC) ${ }_{c}$ condition) at level $c \in \mathbb{R}$ if for any sequence $u_{k} \in M$ such that $\tilde{f}\left(u_{k}\right) \rightarrow c$ and $\left\|\tilde{f}^{\prime}\left(u_{k}\right)\right\|_{*} \rightarrow 0$ (resp. $\tilde{f}\left(u_{k}\right) \rightarrow c$ and $\left(1+\left\|u_{k}\right\|_{E}\right)\left\|\tilde{f}^{\prime}\left(u_{k}\right)\right\|_{*} \rightarrow 0$ ), one has that $u_{k}$ admits a convergent subsequence. We will also say that $\tilde{f}$ satisfies the (PS) $c_{c}$ condition along bounded sequences if for any bounded sequence $u_{k} \in M$ such that $\tilde{f}\left(u_{k}\right) \rightarrow c$ and $\left\|\tilde{f}^{\prime}\left(u_{k}\right)\right\|_{*} \rightarrow 0$, one has that $u_{k}$ admits a convergent subsequence. Condition (PSC) $)_{c}$ was introduced in [3] as a weakening of the classical (PS) $c_{c}$ condition.

Going back to case (iii) of Proposition 2.1, one can see that the functional $\int_{\Omega}|\nabla u|^{p}$ restricted to the manifold $M_{m, n}$ (cf. (1.3)) does not satisfy the (PS) $)_{0}$ condition. Indeed the sequence $v_{k}$ from (2.3) provides an unbounded (PS) $)_{0}$ sequence. That the (PSC) $)_{0}$ condition does not hold neither will follow from Proposition 4.3.

## 3. A first nontrivial eigenvalue

The assumptions on $m, n$ in this section are those indicated at the beginning of Section 2. We look for nonnegative eigenvalues $\lambda$ of (1.2).

Clearly the only nonnegative principal eigenvalue of (1.2) are $0, \lambda^{*}(m)$ and $\lambda^{*}(n)$. Moreover multiplying by $u^{+}$ or $u^{-}$, one easily sees that if $(1.2)$ with $\lambda \geqslant 0$ has a solution which changes sign, then $\lambda>\max \left\{\lambda^{*}(m), \lambda^{*}(n)\right\}$. Proving the existence of such a solution which changes sign, and which in addition corresponds to a minimum value of $\lambda$, is our purpose in this section.

As indicated in the introduction we will use a variational approach and consider the functional $A(u):=\int_{\Omega}|\nabla u|^{p}$ on $W^{1, p}(\Omega)$, the manifold $M_{m, n}$ defined in (1.3) and the restriction $\tilde{A}$ of $A$ to $M_{m, n}$. In this context one easily verifies that $\lambda>0$ is an eigenvalue of (1.2) if and only if $\lambda$ is a critical value of $\tilde{A}$. The case of the eigenvalue $\lambda=0$ is particular: it is a critical value of $\tilde{A}$ iff $M_{m, n}$ contains a constant function, i.e. iff $\int_{\Omega} m>0$ or $\int_{\Omega} n>0$. It follows in particular from these considerations that if $\int_{\Omega} m \neq 0$, then $\lambda^{*}(m)$ is a critical value of $\tilde{A}$ corresponding to the critical point $\varphi_{m}$, and similarly for $\lambda^{*}(n)$ and $-\varphi_{n}$ if $\int_{\Omega} n \neq 0$.

To state our main result let us introduce the following family of paths in $M_{m, n}$ :

$$
\begin{equation*}
\Gamma:=\left\{\gamma \in C\left([0,1], M_{m, n}\right): \gamma(0) \leqslant 0 \text { and } \gamma(1) \geqslant 0\right\} . \tag{3.1}
\end{equation*}
$$

Lemma 3.1. $\Gamma$ is nonempty.
Proof. Choose $u \in W^{1, p}(\Omega)$ such that $\int_{\Omega} m\left(u^{+}\right)^{p}>0$ and $\int_{\Omega} n\left(u^{-}\right)^{p}>0$, which is possible by (2.1), and define $\gamma_{1}(t):=t^{1 / p} u^{+}-(1-t)^{1 / p} u^{-}$for $t \in[0,1]$. Using the fact that $u^{+}$and $u^{-}$have disjoint supports, one obtains

$$
B_{m, n}\left(\gamma_{1}(t)\right)=t \int_{\Omega} m\left(u^{+}\right)^{p}+(1-t) \int_{\Omega} n\left(u^{-}\right)^{p} \geqslant \min \left\{\int_{\Omega} m\left(u^{+}\right)^{p}, \int_{\Omega} n\left(u^{-}\right)^{p}\right\}>0
$$

The path $\gamma_{2}(t):=\gamma_{1}(t) /\left(B_{m, n}\left(\gamma_{1}(t)\right)\right)^{1 / p}$ is thus well defined and clearly belongs to $\Gamma$.
Define now the minimax value

$$
\begin{equation*}
c(m, n):=\inf _{\gamma \in \Gamma} \max _{u \in \gamma[0,1]} \tilde{A}(u), \tag{3.2}
\end{equation*}
$$

which is finite by Lemma 3.1.
Theorem 3.2. $c(m, n)$ is an eigenvalue of (1.2) which satisfies

$$
\begin{equation*}
\max \left\{\lambda^{*}(m), \lambda^{*}(n)\right\}<c(m, n) \tag{3.3}
\end{equation*}
$$

Moreover there is no eigenvalue of (1.2) between $\max \left\{\lambda^{*}(m), \lambda^{*}(n)\right\}$ and $c(m, n)$.
The rest of this section is devoted to the proof of Theorem 3.2. As indicated in the introduction, some difficulty arises in connexion with the (PS) condition.

## Proposition 3.3.

(i) $\tilde{A}$ satisfies $(\mathrm{PS})_{c}$ along bounded sequences for all $c \geqslant 0$.
(ii) $\tilde{A}$ satisfies $(\mathrm{PSC})_{c}$ for all $c>0$.
(iii) If $\int_{\Omega} m \neq 0$ and $\int_{\Omega} n \neq 0$, then $\tilde{A}$ satisfies $(\mathrm{PS})_{c}$ for all $c \geqslant 0$.

Remark 3.4. One can show that if $p=2$, then $\tilde{A}$ satisfies (PS) $)_{\mathrm{c}}$ for all $c>0$, but the case $p \neq 2$ remains undecided. On the other hand, if $\int_{\Omega} m=0$ or $\int_{\Omega} n=0$, then $\tilde{A}$ does not satisfy (PSC) $)_{0}$. This latter fact can be seen as in Section 2: assuming $\int_{\Omega} m=0$, one first observes that $v_{k}$ from (2.3) provides an unbounded (PS) $)_{0}$ sequence for $\tilde{A}$, and then one applies Proposition 4.3 below; similar argument when $\int_{\Omega} n=0$.

Proof of Proposition 3.3. (i) Let $u_{k} \in M_{m, n}$ be a bounded (PS) $c_{c}$ sequence for $\tilde{A}$. So $\int_{\Omega}\left|\nabla u_{k}\right|^{p} \rightarrow c$ and

$$
\begin{equation*}
\left.\left|\int_{\Omega}\right| \nabla u_{k}\right|^{p-2} \nabla u_{k} \nabla \xi \mid \leqslant \varepsilon_{k}\|\xi\| \quad \forall \xi \in T_{u_{k}} M_{m, n} \tag{3.4}
\end{equation*}
$$

where $\varepsilon_{k} \rightarrow 0$ and $\|\cdot\|$ denotes the $W^{1, p}(\Omega)$ norm. For a subsequence and some $u_{0} \in W^{1, p}(\Omega)$, one has that $u_{k} \rightharpoonup u_{0}$ in $W^{1, p}(\Omega)$. Let us write for $w \in W^{1, p}(\Omega)$

$$
a_{k}(w):=w-\left[\int_{\Omega}\left(m\left(u_{k}^{+}\right)^{p-1}-n\left(u_{k}^{-}\right)^{p-1}\right) w\right] u_{k} \in T_{u_{k}} M_{m, n}
$$

Taking $\xi=a_{k}(w)$ in (3.4), one deduces

$$
\left.\left|\int_{\Omega}\right| \nabla u_{k}\right|^{p-2} \nabla u_{k} \nabla w-\left[\int_{\Omega}\left(m\left(u_{k}^{+}\right)^{p-1}-n\left(u_{k}^{-}\right)^{p-1}\right) w\right] \int_{\Omega}\left|\nabla u_{k}\right|^{p} \mid \leqslant \varepsilon_{k}\left\|a_{k}(w)\right\| \leqslant D \varepsilon_{k}\left(\left\|u_{k}\right\|^{p}+1\right)\|w\|
$$

for some constant $D$; taking now $w=u_{k}-u_{0}$ in the above, one obtains

$$
\int_{\Omega}\left|\nabla u_{k}\right|^{p-2} \nabla u_{k} \nabla\left(u_{k}-u_{0}\right) \rightarrow 0 .
$$

It then follows from the $\left(S^{+}\right)$property that $u_{k} \rightarrow u_{0}$ in $W^{1, p}(\Omega)$, which yields the conclusion of part (i).
(ii) Let now $u_{k} \in M_{m, n}$ be a (PSC) sequence for $\tilde{A}$, with $c>0$. So $\int_{\Omega}\left|\nabla u_{k}\right|^{p} \rightarrow c$ and (3.4) is replaced by

$$
\begin{equation*}
\left.\left|\int_{\Omega}\right| \nabla u_{k}\right|^{p-2} \nabla u_{k} \nabla \xi \left\lvert\, \leqslant \frac{\varepsilon_{k}}{1+\left\|u_{k}\right\|}\|\xi\| \quad \forall \xi \in T_{u_{k}} M_{m, n}\right. \tag{3.5}
\end{equation*}
$$

where $\varepsilon_{k} \rightarrow 0$. We will show that $u_{k}$ remains bounded so that part (i) applies and yields the conclusion of part (ii). Let us assume by contradiction that, for a subsequence, $\left\|u_{k}\right\| \rightarrow \infty$. Write $v_{k}=u_{k} /\left\|u_{k}\right\|$. For a further subsequence and some $v_{0} \in W^{1, p}(\Omega)$, one has that $v_{k} \rightharpoonup v_{0}$ in $W^{1, p}(\Omega)$. Since $\int_{\Omega}\left|\nabla u_{k}\right|^{p}$ remains bounded, one has $\int_{\Omega}\left|\nabla v_{k}\right|^{p} \rightarrow 0$ and it follows easily that $v_{0} \equiv c s t \neq 0$ and that $v_{k} \rightarrow v_{0}$ in $W^{1, p}(\Omega)$. On the other hand, taking $\xi=a_{k}(w)$ in (3.5) and dividing by $\left\|u_{k}\right\|^{p-1}$, one gets

$$
\begin{aligned}
& \left.\left|\int_{\Omega}\right| \nabla v_{k}\right|^{p-2} \nabla v_{k} \nabla w-\left[\int_{\Omega}\left(m\left(v_{k}^{+}\right)^{p-1}-n\left(v_{k}^{-}\right)^{p-1}\right) w\right] \int_{\Omega}\left|\nabla u_{k}\right|^{p} \mid \\
& \quad \leqslant \varepsilon_{k} \frac{\left\|u_{k}\right\|}{1+\left\|u_{k}\right\|}\left\|\frac{w}{\left\|u_{k}\right\|^{p}}-\left[\int_{\Omega}\left(m\left(v_{k}^{+}\right)^{p-1}-n\left(v_{k}^{-}\right)^{p-1}\right) w\right] v_{k}\right\| .
\end{aligned}
$$

This implies that $v_{0}$ is a solution of

$$
\begin{equation*}
-\Delta_{p} v_{0}=c\left[m\left(v_{0}^{+}\right)^{p-1}-n\left(v_{0}^{-}\right)^{p-1}\right] \quad \text { in } \Omega, \quad \frac{\partial v_{0}}{\partial v}=0 \quad \text { on } \partial \Omega, \tag{3.6}
\end{equation*}
$$

where $c$ is the level appearing in the $(\operatorname{PSC})_{c}$ sequence. Since $v_{0} \equiv c s t$, the right-hand side of (3.6) is $\equiv 0$, and since $c>0$, one gets $m\left(v_{0}^{+}\right)^{p-1}-n\left(v_{0}^{-}\right)^{p-1} \equiv 0$. This relation with a nonzero constant $v_{0}$ implies $m \equiv 0$ or $n \equiv 0$, which contradicts (2.1).
(iii) Let us finally consider the case where $\int_{\Omega} m \neq 0, \int_{\Omega} n \neq 0$, and let $u_{k} \in M_{m, n}$ be a (PS) $)_{c}$ sequence for $\tilde{A}$ with $c \geqslant 0$. We will show that $u_{k}$ remains bounded so that part (i) applies and yields the conclusion. Assume that for a subsequence $\left\|u_{k}\right\| \rightarrow+\infty$. For a further subsequence one obtains as above that $v_{k} \rightarrow v_{0}$ in $W^{1, p}(\Omega)$ with $v_{0}$ a nonzero constant. But $B_{m, n}\left(u_{k}\right)=1$ and so, dividing by $\left\|u_{k}\right\|^{p}$ and going to the limit, one obtains

$$
\int_{\Omega}\left[m\left(v_{0}^{+}\right)^{p}+n\left(v_{0}^{-}\right)^{p}\right]=0 .
$$

This is a contradiction since $v_{0}$ is a nonzero constant and $\int_{\Omega} m \neq 0, \int_{\Omega} n \neq 0$.
We now turn to the geometry of $\tilde{A}$. The situation here is again simpler in the nonsingular case where the following proposition applies.

Proposition 3.5. If $\int_{\Omega} m \neq 0$, then $\varphi_{m} \in M_{m, n}$ is a strict local minimum of $\tilde{A}$, with in addition for some $\varepsilon_{0}>0$ and all $0<\varepsilon<\varepsilon_{0}$,

$$
\begin{equation*}
\tilde{A}\left(\varphi_{m}\right)=\lambda^{*}(m)<\inf \left\{\tilde{A}(u): u \in M_{m, n} \cap \partial B\left(\varphi_{m}, \varepsilon\right)\right\}, \tag{3.7}
\end{equation*}
$$

where $B\left(\varphi_{m}, \varepsilon\right)$ denotes the ball in $W^{1, p}(\Omega)$ of center $\varphi_{m}$ and radius $\varepsilon$. Similar conclusion for $-\varphi_{n}$ if $\int_{\Omega} n \neq 0$.
Proof. We only sketch it since it is adapted from [2]. One first shows that for some $\varepsilon_{0}>0$,

$$
\begin{equation*}
\tilde{A}\left(\varphi_{m}\right)<\tilde{A}(u) \quad \forall u \in M_{m, n} \cap B\left(\varphi_{m}, \varepsilon_{0}\right), u \neq \varphi_{m} . \tag{3.8}
\end{equation*}
$$

To prove (3.8) one distinguishes two cases: (i) $\lambda^{*}(m)=0$ or (ii) $\lambda^{*}(m)>0$. In case (i) one chooses $\varepsilon_{0}$ such that $M_{m, n} \cap B\left(\varphi_{m}, \varepsilon_{0}\right)$ only contains $\varphi_{m}$ as constant function. This clearly implies (3.8). In case (ii) one assumes by contradiction the existence of a sequence $u_{k} \in M_{m, n}$ with $u_{k} \neq \varphi_{m}, u_{k} \rightarrow \varphi_{m}$ in $W^{1, p}(\Omega)$ and $\tilde{A}\left(u_{k}\right) \leqslant \lambda^{*}(m)$. One then deduces, as on p .585 of [2], that $u_{k}$ changes sign for $k$ sufficiently large. One also has

$$
\lambda^{*}(m) \int_{\Omega}\left[m\left(u_{k}^{+}\right)^{p}+n\left(u_{k}^{-}\right)^{p}\right]=\lambda^{*}(m) \geqslant \tilde{A}\left(u_{k}\right) \geqslant \lambda^{*}(m) \int_{\Omega} m\left(u_{k}^{+}\right)^{p}+\int_{\Omega}\left|\nabla u_{k}^{-}\right|^{p}
$$

and consequently

$$
\lambda^{*}(m) \int_{\Omega} n^{+}\left(u_{k}^{-}\right)^{p} \geqslant \lambda^{*}(m) \int_{\Omega} n\left(u_{k}^{-}\right)^{p} \geqslant \int_{\Omega}\left|\nabla u_{k}^{-}\right|^{p} .
$$

Since $u_{k} \rightarrow \varphi_{m},\left|u_{k}^{-}>0\right| \rightarrow 0$ where $\left|u_{k}^{-}>0\right|$ denotes the measure of the set where $u_{k}^{-}$is $>0$. The desired contradiction then follows from Lemma 3.6 below. Thus (3.8) is proved.

The fact that (3.8) implies (3.7) follows from Lemma 6 in [2], after observing that it suffices in this lemma that the functional satisfies (PS) along bounded sequences, a property which holds here by Proposition 3.3. This concludes the proof of Proposition 3.5 when $\int_{\Omega} m \neq 0$. Similar arguments when $\int_{\Omega} n \neq 0$.

Lemma 3.6. Let $v_{k} \in W^{1, p}(\Omega)$ with $v_{k} \geqslant 0, v_{k} \not \equiv 0$ and $\left|v_{k}>0\right| \rightarrow 0$. Let $n_{k}$ be bounded in $L^{r}(\Omega)$. Then

$$
\int_{\Omega} n_{k} v_{k}^{p} / \int_{\Omega}\left|\nabla v_{k}\right|^{p} \rightarrow 0 .
$$

Proof. Without loss of generality, one can assume $\left\|v_{k}\right\|=1$. So for a subsequence, $v_{k} \rightharpoonup v$ in $W^{1, p}(\Omega)$ and $v_{k} \rightarrow v$ in $L^{p}(\Omega)$. The assumption on $\left|v_{k}>0\right|$ implies $v \equiv 0$ and consequently $\int_{\Omega}\left|\nabla v_{k}\right|^{p} \rightarrow 1$. The conclusion then follows since, by Hölder inequality, $\int_{\Omega} n_{k} v_{k}^{p} \rightarrow 0$.

In the singular case, one at least of the two local minima provided by Proposition 3.5 is missing. The search for suitable endpoints of paths which allow the application of a mountain pass argument will be based on the following lemmas (see in particular Lemma 3.10).

Lemma 3.7. Inequality (3.3) holds.
Proof. The inequality $\leqslant$ easily follows from the definition of $\lambda^{*}(m)$ and $\lambda^{*}(n)$. Indeed for any $\gamma \in \Gamma, \gamma(1)$ belongs to $M_{m, n}$, is $\geqslant 0$ and so satisfies the constraint in the definition (2.2) of $\lambda^{*}(m)$. Consequently $c(m, n) \geqslant \lambda^{*}(m)$, and a similar argument applies to $\lambda^{*}(n)$. To prove the strict inequality assume by contradiction that for instance $\lambda^{*}(m)=$ $c(m, n)$. So, there exists a sequence $\gamma_{k} \in \Gamma$ such that

$$
\begin{equation*}
\max _{t \in[0,1]} \tilde{A}\left(\gamma_{k}(t)\right) \rightarrow \lambda^{*}(m) . \tag{3.9}
\end{equation*}
$$

Put $u_{k}:=\gamma_{k}(1)$. Since $u_{k} \geqslant 0$, one has

$$
\begin{equation*}
\lambda^{*}(m) \leqslant \int_{\Omega}\left|\nabla u_{k}\right|^{p} \leqslant \max _{t \in[0,1]} \tilde{A}\left(\gamma_{k}(t)\right) \rightarrow \lambda^{*}(m) \tag{3.10}
\end{equation*}
$$

and consequently $\int_{\Omega}\left|\nabla u_{k}\right|^{p} \rightarrow \lambda^{*}(m)$. Let us now distinguish two cases: either (i) $\left\|u_{k}\right\|$ remains bounded or (ii) for a subsequence $\left\|u_{k}\right\| \rightarrow \infty$.

In case (i), for a subsequence and for some $u_{0} \in W^{1, p}(\Omega)$, one has that $u_{k} \rightharpoonup u_{0}$ in $W^{1, p}(\Omega)$. Since $u_{k} \geqslant 0$, one has

$$
\begin{equation*}
\int_{\Omega} m\left|u_{0}\right|^{p}=1, \tag{3.11}
\end{equation*}
$$

and so

$$
\lambda^{*}(m) \leqslant \int_{\Omega}\left|\nabla u_{0}\right|^{p} \leqslant \liminf \int_{\Omega}\left|\nabla u_{k}\right|^{p}=\lambda^{*}(m),
$$

which implies that $\int_{\Omega}\left|\nabla u_{0}\right|^{p}=\lambda^{*}(m)$. Consequently $u_{k} \rightarrow u_{0}$ in $W^{1, p}(\Omega)$. If $\int_{\Omega} m=0$, then $\lambda^{*}(m)=0$ and so $u_{0} \equiv c s t$, which leads to a contradiction with (3.11). So $\int_{\Omega} m \neq 0$ and we conclude that $u_{0}=\varphi_{m}$. Let us now choose $\varepsilon>0$ such that (3.7) holds and $B\left(\varphi_{m}, \varepsilon\right)$ does not contain any function $v$ with $v \leqslant 0$, which is clearly possible. For $k$ sufficiently large $u_{k}=\gamma_{k}(1) \in B\left(\varphi_{m}, \varepsilon\right)$, while $\gamma_{k}(0) \notin B\left(\varphi_{m}, \varepsilon\right)$ since $\gamma_{k}(0) \leqslant 0$. It follows that the path $\gamma_{k}$ intersects $\partial B\left(\varphi_{m}, \varepsilon\right)$ and consequently

$$
\max _{t \in[0,1]} \tilde{A}\left(\gamma_{k}(t)\right) \geqslant \inf \left\{\tilde{A}(u): u \in M_{m, n} \cap \partial B\left(\varphi_{m}, \varepsilon\right)\right\}>\lambda^{*}(m) .
$$

This contradicts (3.9).
In case (ii) we put $v_{k}=u_{k} /\left\|u_{k}\right\|$. For a subsequence and some $v_{0} \in W^{1, p}(\Omega), v_{k} \rightharpoonup v_{0}$ in $W^{1, p}(\Omega)$. Since $\int_{\Omega}\left|\nabla u_{k}\right|^{p}$ remains bounded, we obtain $\int_{\Omega}\left|\nabla v_{k}\right|^{p} \rightarrow 0$ and so $v_{0} \equiv c s t$; also $v_{0} \not \equiv 0$ since $\left\|v_{k}\right\|=1$ implies $\left\|v_{0}\right\|=1$. Moreover $\int_{\Omega} m\left|v_{0}\right|^{p}=0$ since $\int_{\Omega} m\left|u_{k}\right|^{p}=1$. We have reached a contradiction if $\int_{\Omega} m \neq 0$. So let us assume from now on that $\int_{\Omega} m=0$. We first observe that for any $\gamma \in \Gamma$ there exists $t_{0}=t_{0}(\gamma) \in[0,1]$ such that

$$
\begin{equation*}
\int_{\Omega} m\left(\gamma\left(t_{0}\right)^{+}\right)^{p}=\int_{\Omega} n\left(\gamma\left(t_{0}\right)^{-}\right)^{p}=\frac{1}{2} . \tag{3.12}
\end{equation*}
$$

Consider now $w_{k}:=\gamma_{k}\left(t_{0}\left(\gamma_{k}\right)\right)$. We have now instead of (3.10)

$$
\begin{equation*}
0 \leqslant \int_{\Omega}\left|\nabla w_{k}\right|^{p} \leqslant \max _{t \in[0,1]} \tilde{A}\left(\gamma_{k}(t)\right) \rightarrow \lambda^{*}(m)=0 . \tag{3.13}
\end{equation*}
$$

We again distinguish two cases: either $\left\|w_{k}\right\|$ remains bounded, or for a subsequence $\left\|w_{k}\right\| \rightarrow \infty$. In the first case, for a subsequence and some $w_{0} \in W^{1, p}(\Omega), w_{k} \rightharpoonup w_{0}$ in $W^{1, p}(\Omega)$. It follows from (3.13) that $w_{0} \equiv c s t$ and that $w_{k} \rightarrow w_{0}$ in $W^{1, p}(\Omega)$. A contradiction then follows from

$$
\int_{\Omega} m\left(w_{0}^{+}\right)^{p}=\int_{\Omega} n\left(w_{0}^{-}\right)^{p}=\frac{1}{2} .
$$

In the second case we put $z_{k}:=w_{k} /\left\|w_{k}\right\|$. For a subsequence and some $z_{0} \in W^{1, p}(\Omega), z_{k} \rightharpoonup z_{0}$ in $W^{1, p}(\Omega)$. It follows from (3.13) that $z_{0} \equiv$ cst and that $z_{k} \rightarrow z_{0}$ in $W^{1, p}(\Omega)$; consequently $\left\|z_{0}\right\|=1$. If $z_{0}>0$ then $\left|w_{k}<0\right|=$ $\left|z_{k}<0\right| \rightarrow 0$; moreover $w_{k}$ changes sign and by (3.12)

$$
\frac{\int_{\Omega} n^{+}\left|w_{k}^{-}\right|^{p}}{\int_{\Omega}\left|\nabla w_{k}^{-}\right|^{p}} \geqslant \frac{1 / 2}{\int_{\Omega}\left|\nabla w_{k}\right|^{p}} \rightarrow+\infty .
$$

This yields a contradiction with Lemma 3.6. A similar argument applies if $z_{0}<0$.
Lemma 3.8. For any $d>0$, the set

$$
\mathcal{O}:=\left\{u \in M_{m, n}: u \geqslant 0 \text { and } \tilde{A}(u)<d\right\}
$$

is arcwise connected. Similar conclusion if $u \geqslant 0$ is replaced by $u \leqslant 0$.

Note that by the definition of $c(m, n),\left\{u \in M_{m, n}: \tilde{A}(u)<d\right\}$ is not $\operatorname{arcwise}$ connected when $\max \left\{\lambda^{*}(m), \lambda^{*}(n)\right\}<$ $d<c(m, n)$.

Proof of Lemma 3.8. Since $\mathcal{O}$ is empty if $d \leqslant \lambda^{*}(m)$, we can assume from now on $d>\lambda^{*}(m)$. We first consider the case where $\int_{\Omega} m \neq 0$. Using Lemma 3.9 below, one constructs a weight $\hat{n} \in L^{r}(\Omega)$ such that $\hat{n}^{+} \not \equiv 0, \hat{n} \leqslant m, \int_{\Omega} \hat{n}<0$ and $\lambda^{*}(\hat{n})>d$. When $m^{-} \not \equiv 0$, it suffices in this construction to take $\hat{n}=\varepsilon m^{+}-m^{-}$with $\varepsilon>0$ sufficiently small; when $m^{-}=0$ i.e. $m \geqslant 0$, it suffices to take $\hat{n}=\varepsilon m-k \chi_{B}$ with $\varepsilon$ sufficiently small and $k$ sufficiently large, where $\chi_{B}$ is the characteristic function of a ball $B \Subset \Omega$ such that $m^{+} \not \equiv 0$ on $\Omega \backslash B$. We then consider the manifold $M_{m, \hat{n}}$ and the sublevel set

$$
\widehat{\mathcal{O}}:=\left\{u \in M_{m, \hat{n}}: A(u)<d\right\} .
$$

By part (iii) of Proposition 3.3, the restriction $\hat{A}$ of $A$ to $M_{m, \hat{n}}$ satisfies (PS) $)_{c}$ for all $c \geqslant 0$. Lemma 14 from [2] then implies that any (nonempty) component of $\widehat{\mathcal{O}}$ contains a critical point of $\hat{A}$. But the first two critical levels $\lambda^{*}(m), \lambda^{*}(\hat{n})$ of $\hat{A}$ verify $\lambda^{*}(m)<d<\lambda^{*}(n)$, and consequently $\hat{A}$ admits only one critical point in $\widehat{\mathcal{O}}$. We can conclude in this way that $\widehat{\mathcal{O}}$ is arcwise connected.

Let now $u_{1}, u_{2} \in \mathcal{O}$. Since they are $\geqslant 0$, they also belong to $\widehat{\mathcal{O}}$. Let $\gamma$ be a path in $\widehat{\mathcal{O}}$ from $u_{1}$ to $u_{2}$ and consider the path

$$
\gamma_{1}(t):=\frac{|\gamma(t)|}{\left(\int_{\Omega} m|\gamma(t)|^{p}\right)^{1 / p}} .
$$

By the choice of $\hat{n}$,

$$
\begin{equation*}
\int_{\Omega} m|\gamma(t)|^{p} \geqslant \int_{\Omega}\left[m\left(\gamma(t)^{+}\right)^{p}+\hat{n}\left(\gamma(t)^{-}\right)^{p}\right]=1, \tag{3.14}
\end{equation*}
$$

and consequently $\gamma_{1}$ is a well defined path in $M_{m, n}$, which clearly goes from $u_{1}$ to $u_{2}$ and is made of nonnegative functions. Moreover, by (3.14),

$$
A\left(\gamma_{1}(t)\right)=\frac{A(\gamma(t))}{\int_{\Omega} m|\gamma(t)|^{p}} \leqslant A(\gamma(t))<d
$$

for all $t$, and we conclude that the path $\gamma_{1}$ lies in $\mathcal{O}$.
Consider now the case where $\int_{\Omega} m=0$. Let $u_{1}, u_{2} \in \mathcal{O}$. One starts by decreasing a little bit the weight $m$ into a weight $\hat{m} \in L^{r}(\Omega)$ such that $\hat{m} \leqslant m, \int_{\Omega} \hat{m}<0, \int_{\Omega} \hat{m} u_{1}^{p}>0, \int_{\Omega} \hat{m} u_{2}^{p}>0$ and

$$
\frac{\int_{\Omega}\left|\nabla u_{1}\right|^{p}}{\int_{\Omega} \hat{m} u_{1}^{p}}<d, \quad \frac{\int_{\Omega}\left|\nabla u_{2}\right|^{p}}{\int_{\Omega} \hat{m} u_{2}^{p}}<d,
$$

which is clearly possible since $\lambda^{*}(m)<d$. Put

$$
v_{1}:=\frac{u_{1}}{\left(\int_{\Omega} \hat{m} u_{1}^{p}\right)^{1 / p}} \quad \text { and } \quad v_{2}:=\frac{u_{2}}{\left(\int_{\Omega} \hat{m} u_{2}^{p}\right)^{1 / p}} .
$$

By the first part of this proof, there exists a path $\gamma$ in $M_{\hat{m}, \hat{m}}$ which goes from $v_{1}$ to $v_{2}$, is made of nonnegative functions and is such that $A(\gamma(t))<d$ for all $t$. Consider now the path

$$
\gamma_{1}(t):=\frac{\gamma(t)}{\left(\int_{\Omega} m|\gamma(t)|^{p}\right)^{1 / p}} .
$$

By the choice of $\hat{m}$,

$$
\begin{equation*}
\int_{\Omega} m|\gamma(t)|^{p} \geqslant \int_{\Omega} \hat{m}|\gamma(t)|^{p}=1 \tag{3.15}
\end{equation*}
$$

and consequently $\gamma_{1}$ is a well defined path in $M_{m, n}$, which clearly goes from $u_{1}$ to $u_{2}$ and is made of nonnegative functions. Moreover, by (3.15),

$$
A\left(\gamma_{1}(t)\right)=\frac{A(\gamma(t))}{\int_{\Omega} m|\gamma(t)|^{p}} \leqslant A(\gamma(t))<d
$$

for all $t$. This concludes the proof of Lemma 3.8 for $\mathcal{O}$ with $u \geqslant 0$. Similar argument in the case $u \leqslant 0$.
Lemma 3.9. Let $m_{k} \in L^{r}(\Omega)$ with $m_{k}^{+} \not \equiv 0$ and $m_{k} \rightarrow m$ in $L^{r}(\Omega)$ where $m \leqslant 0, m \not \equiv 0$. Then $\lambda^{*}\left(m_{k}\right) \rightarrow+\infty$.
Proof. Suppose by contradiction that for a subsequence, $\lambda^{*}\left(m_{k}\right) \rightarrow \lambda<+\infty$. Let $\varphi_{k}$ be the positive eigenfunction associated to $\lambda^{*}\left(m_{k}\right)$ and normalized by $\left\|\varphi_{k}\right\|_{p r^{\prime}}=1$, where $\|\cdot\|_{q}$ denotes the $L^{q}(\Omega)$ norm. One has

$$
\int_{\Omega}\left|\nabla \varphi_{k}\right|^{p}=\lambda^{*}\left(m_{k}\right) \int_{\Omega} m_{k} \varphi_{k}^{p} \leqslant \lambda^{*}\left(m_{k}\right)\left\|m_{k}^{+}\right\|_{r}
$$

It follows that for a subsequence, $\varphi_{k} \rightharpoonup \varphi$ in $W^{1, p}(\Omega)$, with $\|\varphi\|_{p r^{\prime}}=1$. Moreover, by the above inequality, $\int_{\Omega}\left|\nabla \varphi_{k}\right|^{p} \rightarrow 0$, which implies $\varphi \equiv c s t \neq 0$ (call it $A$ ) and $\varphi_{k} \rightarrow \varphi$ in $W^{1, p}(\Omega)$. Consequently, for $k$ sufficiently large so that $\int_{\Omega} m_{k}<0$, one has

$$
0<\frac{1}{\lambda^{*}(m)} \int_{\Omega}\left|\nabla \varphi_{k}\right|^{p}=\int_{\Omega} m_{k} \varphi_{k}^{p} \rightarrow A^{p} \int_{\Omega} m<0
$$

a contradiction.
Lemma 3.10. There exists $u_{1} \geqslant 0$ and $u_{2} \leqslant 0$ in $M_{m, n}$ such that $\tilde{A}\left(u_{1}\right)<c(m, n)$ and $\tilde{A}\left(u_{2}\right)<c(m, n)$. Moreover, for any such choice of $u_{1}, u_{2}$, one has

$$
\begin{equation*}
c(m, n)=\inf _{\gamma \in \bar{\Gamma}} \max _{u \in \gamma[0,1]} \tilde{A}(u) \tag{3.16}
\end{equation*}
$$

where

$$
\bar{\Gamma}:=\left\{\gamma \in C\left([0,1], M_{m, n}\right): \gamma(0)=u_{2} \text { and } \gamma(1)=u_{1}\right\}
$$

Proof. If $\int_{\Omega} m \neq 0$, one takes $u_{1}=\varphi_{m}$ and the inequality $\tilde{A}\left(u_{1}\right)<c(m, n)$ follows from Lemma 3.7. Similarly with $u_{2}=-\varphi_{n}$ in case $\int_{\Omega} n \neq 0$. If now $\int_{\Omega} m=0$, one takes $u_{1}=v_{k}$ for $k$ sufficiently large, where $v_{k}$ is defined in (2.3). Indeed $\tilde{A}\left(v_{k}\right) \rightarrow 0$ and by Lemma $3.7,0<c(m, n)$, so that $\tilde{A}\left(v_{k}\right)<c(m, n)$ for $k$ sufficiently large. Similar argument for the choice of $u_{2}$ in case $\int_{\Omega} n=0$.

It remains to prove (3.16). Call $\bar{c}$ the right-hand side of (3.16). One clearly has $c(m, n) \leqslant \bar{c}$. To prove the converse inequality, let $\varepsilon>0$ and take $\gamma_{\varepsilon} \in \Gamma$ such that

$$
\max _{u \in \gamma_{\varepsilon}[0,1]} \tilde{A}(u)<c(m, n)+\varepsilon
$$

By Lemma 3.8 there exits a path $\eta_{1}$ in $M_{m, n}$ joining $\gamma_{\varepsilon}(1)$ and $u_{1}$, made of nonnegative functions, and such that

$$
\max _{u \in \eta_{1}[0,1]} \tilde{A}(u)<c(m, n)+\varepsilon
$$

Similarly there exists a path $\eta_{2}$ in $M_{m, n}$ joining $\gamma_{\varepsilon}(0)$ and $u_{2}$, made of nonpositive functions, and such that

$$
\max _{u \in \eta_{2}[0,1]} \tilde{A}(u)<c(m, n)+\varepsilon
$$

Gluing together $\eta_{2}, \gamma_{\varepsilon}$ and $\eta_{1}$, one gets a path in $M_{m, n}$ joining $u_{2}$ and $u_{1}$, and such that $\tilde{A}$ remains $<c(m, n)+\varepsilon$ along this path. This implies $\bar{c}<c(m, n)+\varepsilon$. Since $\varepsilon>0$ is arbitrary, the conclusion follows.

We are now ready to give the
Proof of Theorem 3.2. Inequality (3.3) was established in Lemma 3.7. To prove that $c(m, n)$ is an eigenvalue, we pick $u_{1}, u_{2}$ as in Lemma 3.10 and we will show that $\bar{c}$, the right-hand side of (3.16), is a critical value of $\tilde{A}$. If $\int_{\Omega} m \neq 0$ and $\int_{\Omega} n \neq 0$, then $\tilde{A}$ satisfies (PS) ${ }_{c}$ for all $c \geqslant 0$ and the classical mountain pass theorem for a $C^{1}$ functional on a $C^{1}$ manifold (cf. e.g. Proposition 4 from [2]) yields the conclusion. If either $\int_{\Omega} m=0$ or $\int_{\Omega} n=0$, then we only know that $\tilde{A}$ satisfies $(\mathrm{PSC})_{c}$ for all $c>0$. It is then Theorem 4.1 from the following section which yields the conclusion.

It remains to show that there is no eigenvalue between $\max \left\{\lambda^{*}(m), \lambda^{*}(n)\right\}$ and $c(m, n)$. Assume by contradiction the existence of such an eigenvalue $\lambda$ and let $u$ be the corresponding nontrivial solution of (1.2). We know that $u$ changes sign (since $\left.\lambda>\max \left\{\lambda^{*}(m), \lambda^{*}(n)\right\}\right)$; moreover

$$
0<\int_{\Omega}\left|\nabla u^{+}\right|^{p}=\lambda \int_{\Omega} m\left(u^{+}\right)^{p}, \quad 0<\int_{\Omega}\left|\nabla u^{-}\right|^{p}=\lambda \int_{\Omega} n\left(u^{-p}\right),
$$

and we can normalize $u$ so that $u \in M_{m, n}$. The functions

$$
u_{1}:=\frac{u^{+}}{\left(\int_{\Omega} m\left(u^{+}\right)^{p}\right)^{1 / p}}, \quad u_{2}:=\frac{-u^{-}}{\left(\int_{\Omega} n\left(u^{-}\right)^{p}\right)^{1 / p}}
$$

belongs to $M_{m, n}$, with $u_{1} \geqslant 0, u_{2} \leqslant 0$. We will construct a path $\gamma$ in $M_{m, n}$ joining $u_{1}$ and $u_{2}$, and such that $\tilde{A}$ remains equal to $\lambda$ along that path. This will give a contradiction with the definition of $c(m, n)$. To construct $\gamma$ we first go from $u_{1}$ to $u$ by the path

$$
\gamma_{1}(t):=\frac{u^{+}-t u^{-}}{\left(B_{m, n}\left(u^{+}-t u^{-}\right)\right)^{1 / p}}
$$

and then from $u$ to $u_{2}$ by the path

$$
\gamma_{2}(t):=\frac{t u^{+}-u^{-}}{\left(B_{m, n}\left(t u^{+}-u^{-}\right)\right)^{1 / p}}
$$

It is easily verified that the path constructed in this way is well defined and satisfies all the required conditions.
Remark 3.11. Reproducing the end of the above proof with $\lambda$ replaced by $c(m, n)$, we conclude that the infimum in (3.2) is achieved.

## 4. A mountain pass theorem

Our purpose in this section is to derive a mountain pass theorem for a $C^{1}$ functional on a $C^{1}$ manifold and which satisfies the (PSC) condition.

We put ourselves in the general setting of the end of Section 2: $E$ is a real Banach space, $g \in C^{1}(E, \mathbb{R}), M:=$ $\{u \in E: g(u)=1\}$ with 1 a regular value of $g, f \in C^{1}(E, \mathbb{R}), \tilde{f}$ the restriction of $f$ to $M$. The space $E$ in this section is assumed to be uniformly convex.

Theorem 4.1. Let $K$ be a compact metric space, $K_{0} \subset K$, and $h_{0} \in C\left(K_{0}, M\right)$. Consider the family of extensions of $h_{0}$ :

$$
\mathcal{H}:=\left\{h \in C(K, M): h_{\left.\right|_{K_{0}}}=h_{0}\right\} .
$$

Assume $\mathcal{H}$ nonempty as well as the following condition:

$$
\max _{t \in K_{0}} f\left(h_{0}(t)\right)<\max _{t \in K} f(h(t))
$$

for any $h \in \mathcal{H}$. Define

$$
\begin{equation*}
c:=\inf _{h \in H} \max _{t \in K} f(h(t)) . \tag{4.1}
\end{equation*}
$$

Assume that $\tilde{f}$ satisfies $(\mathrm{PSC})_{c}$ for $c$ given in (4.1). Then $c$ is a critical value of $\tilde{f}$.
Typically, as in the application in Section 3, $K=[0,1]$ and $K_{0}=\{0,1\}$.
Proof of Theorem 4.1. Arguing as in the proof of Theorem 2.1 in [5] but using the strong form of Ekeland variational principle (cf. [8,7]) instead of the usual one, one obtains that if $h \in \mathcal{H}$ and $\varepsilon>0$ are such that

$$
\begin{equation*}
\max _{t \in K} f(h(t))<c+\frac{\varepsilon}{2}, \tag{4.2}
\end{equation*}
$$

then, for each $\mu>0$, there exists $u_{\mu} \in M$ with

$$
\begin{aligned}
& c \leqslant f\left(u_{\mu}\right) \leqslant c+\frac{\varepsilon}{2}, \\
& \operatorname{dist}\left(u_{\mu}, h(K)\right) \leqslant \mu, \\
& \left\|\tilde{f}^{\prime}\left(u_{\mu}\right)\right\|_{*} \leqslant \frac{\varepsilon}{\mu} .
\end{aligned}
$$

We let $\varepsilon=\frac{1}{k}$ and pick $h=h_{k}$ such that (4.2) holds, which is possible by the definition (4.1) of $c$. We also take $\mu=\mu_{k}=1+\left\|h_{k}\right\|_{\infty}$, where $\|\cdot\|_{\infty}$ denotes the $C(K, E)$ norm. So there exists $u_{k} \in M$ such that

$$
\begin{align*}
& c \leqslant f\left(u_{k}\right) \leqslant c+\frac{1}{2 k} \\
& \operatorname{dist}\left(u_{k}, h_{k}(K)\right) \leqslant 1+\left\|h_{k}\right\|_{\infty}  \tag{4.3}\\
& \left\|\tilde{f}^{\prime}\left(u_{k}\right)\right\|_{*} \leqslant\left[k\left(1+\left\|h_{k}\right\|_{\infty}\right)\right]^{-1} \tag{4.4}
\end{align*}
$$

It follows from (4.3) that

$$
\left\|u_{k}\right\|_{E} \leqslant \operatorname{dist}\left(u_{k}, h_{k}(K)\right)+\left\|h_{k}\right\|_{\infty} \leqslant 1+2\left\|h_{k}\right\|_{\infty}
$$

and so $1+\left\|u_{k}\right\|_{E} \leqslant 2\left(1+\left\|h_{k}\right\|_{\infty}\right)$. Replacing in (4.4) gives

$$
\left\|\tilde{f}^{\prime}\left(u_{k}\right)\right\|_{*} \leqslant\left[2 k\left(1+\left\|u_{k}\right\|_{E}\right)\right]^{-1}
$$

Thus $u_{k}$ is a (PSC) ${ }_{c}$ sequence, and the conclusion follows.
The following additional information will be used later (cf. Proposition 2.3 in [5]).
Proposition 4.2. Let $K, K_{0}, h_{0}, \mathcal{H}$ and $c$ be as in Theorem 4.1 and let $h \in \mathcal{H}$ satisfy

$$
\max _{t \in K} f(h(t))=c .
$$

Then $h(K)$ contains a critical point of $\tilde{f}$ at level .
The strong form of Ekeland variational principle can also be used in a way rather similar to the above to derive
Proposition 4.3. Assume $\tilde{f}$ bounded from below and let $c:=\inf \{f(u): u \in M\}$. Then $\tilde{f}$ satisfies $(\operatorname{PSC})_{c}$ if and only if $\tilde{f}$ satisfies (PS) ${ }_{c}$.

Proof. It clearly suffices to prove that (PSC) ${ }_{c}$ implies (PS) ${ }_{c}$. Let $u_{k} \in M$ satisfy $c \leqslant f\left(u_{k}\right) \leqslant c+1 / k$ with $\left\|\tilde{f}^{\prime}\left(u_{k}\right)\right\|_{*} \rightarrow 0$ and $\left\|u_{k}\right\| \rightarrow \infty$ (if $\left\|u_{k}\right\|$ remains bounded then $u_{k}$ is a (PSC) ${ }_{c}$ sequence and the conclusion follows immediately). Using the strong form of Ekeland variational principle, we obtain for any $k$ and any $\mu>0$ the existence of $v_{\mu} \in M$ with

$$
\begin{aligned}
& c \leqslant f\left(v_{\mu}\right) \leqslant c+\frac{1}{2 k}, \\
& \left\|v_{\mu}-u_{k}\right\| \leqslant \mu, \\
& \left\|\tilde{f}^{\prime}\left(v_{\mu}\right)\right\|_{*} \leqslant \frac{1}{k \mu} .
\end{aligned}
$$

We take $\mu=\left\|u_{k}\right\| / 2$ and we write $v_{k}$ instead of $v_{\mu}$. We have

$$
\begin{align*}
& \frac{1}{2}\left\|u_{k}\right\| \leqslant\left\|v_{k}\right\| \leqslant \frac{3}{2}\left\|u_{k}\right\| \\
& \left(1+\left\|v_{k}\right\|\right)\left\|\tilde{f}^{\prime}\left(v_{k}\right)\right\|_{*} \leqslant \frac{1}{k} \frac{2}{\left\|u_{k}\right\|}\left(1+\frac{3}{2}\left\|u_{k}\right\|\right) \leqslant \frac{c s t}{k} \tag{4.5}
\end{align*}
$$

and so, by $(\mathrm{PSC})_{c}, v_{k}$ has a subsequence $v_{n_{k}}$ which converges. Combining with (4.5) leads to a contradiction with the fact that $\left\|u_{k}\right\| \rightarrow \infty$.

## 5. Some properties of $\boldsymbol{c}(\boldsymbol{m}, n)$

We briefly study here the dependence of $c(m, n)$ with respect to $m, n$. All the weights in this section are assume to belong to $L^{r}(\Omega)$ and to satisfy (2.1). The results and proofs below are similar to those of Section 4 in [2].

Proposition 5.1. If $\left(m_{k}, n_{k}\right) \rightarrow(m, n)$ in $L^{r}(\Omega) \times L^{r}(\Omega)$, then $c\left(m_{k}, n_{k}\right) \rightarrow c(m, n)$.
Proof. It is easily adapted from that of Proposition 22 in [2]. One successively proves upper and lower semicontinuity. In the latter part it is convenient here to normalize $u_{k}$ so that $\left\|u_{k}\right\|_{p r^{\prime}}=1$.

Proposition 5.2. If $m \leqslant \tilde{m}$ and $n \leqslant \tilde{n}$ a.e., then

$$
c(\tilde{m}, \tilde{n}) \leqslant c(m, n) .
$$

## If in addition

$$
\int_{\Omega}(\tilde{m}-m)\left(u^{+}\right)^{p}+\int_{\Omega}(\tilde{n}-n)\left(u^{-}\right)^{p}>0
$$

for at least one eigenfunction $u$ associated to $c(m, n)$, then $c(\tilde{m}, \tilde{n})<c(m, n)$.
Proof. It is easily adapted from that of Propositions 23 and 25 of [2]. Proposition 4.2 is used to derive the strict monotonicity.

Finally let us observe that $c(m, n)$ is homogeneous of degree -1 . Some sort of separate sub-homogeneity also holds, which will be used later:

Proposition 5.3. If $0<s<\hat{s}$, then

$$
c(\hat{s} m, n)<c(s m, n) \quad \text { and } \quad c(m, \hat{s} n)<c(m, s n) .
$$

Proof. It is easily adapted from that of Proposition 31 of [2]. Again Proposition 4.2 is used here.

## 6. Fučik spectrum

Let $m, n \in L^{r}(\Omega)$ with $r$ as before. Unless otherwise stated, we also assume (2.1). The Fučik spectrum $\Sigma=$ $\Sigma(m, n)$ clearly contains the lines $\{0\} \times \mathbb{R}, \mathbb{R} \times\{0\}, \mathbb{R} \times\left\{\lambda^{*}(n)\right\},\left\{\lambda^{*}(m)\right\} \times \mathbb{R}$ and also possibly the lines $\mathbb{R} \times$ $\left\{-\lambda^{*}(-n)\right\}$ and $\left\{-\lambda^{*}(-m)\right\} \times \mathbb{R}$. It will be convenient to denote by $\Sigma^{*}=\Sigma^{*}(m, n)$ the set $\Sigma(m, n)$ without these 2 , 3 or 4 lines.

We start by looking at the part of $\Sigma^{*}$ which lies in $\mathbb{R}^{+} \times \mathbb{R}^{+}$. From the properties of $\lambda^{*}(m), \lambda^{*}(n)$ follows that if $(\alpha, \beta) \in \Sigma^{*} \cap\left(\mathbb{R}^{+} \times \mathbb{R}^{+}\right)$, then $\alpha>\lambda^{*}(m)$ and $\beta>\lambda^{*}(n)$.

Theorem 6.1. For any $s>0$, the line $\beta=s \alpha$ in the $(\alpha, \beta)$ plane intersects $\Sigma^{*} \cap\left(\mathbb{R}^{+} \times \mathbb{R}^{+}\right)$. Moreover the first point in this intersection is given by $\alpha(s)=c(m, s n), \beta(s)=s \alpha(s)$, where $c(\cdot, \cdot)$ is defined in (3.2).

Proof. An easy consequence of Theorem 3.2.
Letting $s>0$ varying, we thus get a first curve $\mathcal{C}:=\{(\alpha(s), \beta(s)): s>0\}$ in $\Sigma^{*} \cap\left(\mathbb{R}^{+} \times \mathbb{R}^{+}\right)$.
Proposition 6.2. The functions $\alpha(s)$ and $\beta(s)$ in Theorem 6.1 are continuous. Moreover $\alpha(s)$ is strictly decreasing and $\beta(s)$ is strictly increasing. One also has that $\alpha(s) \rightarrow+\infty$ as $s \rightarrow 0$ and $\beta(s) \rightarrow+\infty$ as $s \rightarrow+\infty$.

Proof. The first two statements are direct consequences of the results of Section 5. The last one easily follows from Lemma 6.3 below.

Lemma 6.3. The lines $\mathbb{R} \times\left\{\lambda^{*}(n)\right\}$ and $\left\{\lambda^{*}(m)\right\} \times \mathbb{R}$ are isolated in $\Sigma^{*} \cap\left(\mathbb{R}^{+} \times \mathbb{R}^{+}\right)$.
Proof. Assume by contradiction the existence of a sequence $\left(\alpha_{k}, \beta_{k}\right) \in \Sigma^{*} \cap\left(\mathbb{R}^{+} \times \mathbb{R}^{+}\right)$such that $\alpha_{k} \rightarrow \alpha_{0}, \beta_{k} \rightarrow \beta_{0}$ with $\alpha_{0} \in \mathbb{R}$ and say $\beta_{0}=\lambda^{*}(n)$. Let $u_{k}$ be an eigenfunction corresponding to ( $\alpha_{k}, \beta_{k}$ ), normalized by $\left\|u_{k}\right\|_{p r^{\prime}}=1$. Note that $u_{k}$ changes sign. By standard arguments one gets that for a subsequence, $u_{k} \rightarrow u$ in $W^{1, p}(\Omega)$ with $u \neq 0$ satisfying

$$
\begin{equation*}
-\Delta_{p} u=\alpha_{0} m(x)\left(u^{+}\right)^{p-1}-\lambda^{*}(n) n(x)\left(u^{-}\right)^{p-1} \quad \text { in } \Omega, \quad \frac{\partial u}{\partial v}=0 \quad \text { on } \partial \Omega . \tag{6.1}
\end{equation*}
$$

It follows from (6.1) that

$$
\int_{\Omega}\left|\nabla u^{-}\right|^{p}=\lambda^{*}(n) \int_{\Omega} n(x)\left(u^{-}\right)^{p}
$$

and consequently either (i) $u^{-} \equiv 0$ or (ii) $u^{-}$is an eigenfunction associated to $\lambda^{*}(n)$. In case (i), $u \geqslant 0, u \not \equiv 0$ and so $u>0$ in $\Omega$, which implies $\left|u_{k}^{-}>0\right| \rightarrow 0$. It then follows from Lemma 3.6 that

$$
\begin{equation*}
\frac{\int_{\Omega} \beta_{k} n(x)\left(u_{k}^{-}\right)^{p}}{\int_{\Omega}\left|\nabla u_{k}^{-}\right|^{p}} \rightarrow 0 \tag{6.2}
\end{equation*}
$$

which is impossible since by the equation satisfied by $u_{k}$, the expression in (6.2) is equal to 1 . In case (ii), $u<0$ in $\Omega$, which implies $\left|u_{k}^{+}>0\right| \rightarrow 0$. An argument as above applied to $u_{k}^{+}$then leads to a contradiction.

We now investigate the asymptotics values $\alpha_{\infty}:=\lim _{s \rightarrow \infty} \alpha(s)$ and $\beta_{\infty}:=\lim _{s \rightarrow \infty} \beta(s)$ of the first curve $\mathcal{C}$. We will limit ourselves to the study of $\alpha_{\infty}$. Similar results on $\beta_{\infty}$ can be proved interchanging the roles of $m$ and $n$.

Proposition 6.4. If $p \leqslant N$, then $\alpha_{\infty}=\lambda^{*}(m)$. If $p>N$ and one of the following conditions holds: (i) $\int_{\Omega} m \geqslant 0$, or (ii) $m \in L^{\infty}(\Omega)$, or (iii) $\operatorname{supp}\left(n^{+}\right) \Subset \Omega$, then $\alpha_{\infty}>\lambda^{*}(m)$.

Proof. The arguments are rather similar to those in the proof of Proposition 35 in [2] and we will only indicate below the main steps as well as the differences.

One starts by introducing

$$
\begin{equation*}
\bar{\alpha}:=\inf \left\{\int_{\Omega}\left|\nabla u^{+}\right|^{p}: u \in W^{1, p}(\Omega), \int_{\Omega} m\left(u^{+}\right)^{p}=1 \text { and } \int_{\Omega} n\left(u^{-}\right)^{p}>0\right\} \tag{6.3}
\end{equation*}
$$

and shows that $\alpha_{\infty}=\bar{\alpha}$. The proof here is a direct adaption of our argument on p .599 in [2]. In fact it is simpler since the required path has just to belong to $\Gamma$ and so can be constructed directly through a normalized convex combination.

One then considers the case $p \leqslant N$. If $\int_{\Omega} m \neq 0$ then the argument on p. 600 in [2] adapts immediately to obtain $\bar{\alpha}=\lambda^{*}(m)$. If $\int_{\Omega} m=0$ one considers the sequence $v_{k}$ defined in (2.3) and applies to each $v_{k}$ the construction on p. 600 in [2].

One now considers the case $p>N$ Assume by contradiction that $\bar{\alpha}=\lambda^{*}(m)$ and let $\left(u_{k}\right)$ be a minimizing sequence for $\bar{\alpha}$. We claim that $u_{k}^{+}$remains bounded in $W^{1, p}(\Omega)$. Indeed otherwise, one easily sees that for a subsequence $v_{k}:=u_{k}^{+} /\left\|u_{k}^{+}\right\|$converges uniformly on $\bar{\Omega}$ to a positive constant, which implies $v_{k}>0$ (and so $u_{k}>0$ ) in $\bar{\Omega}$ for $k$ sufficiently large, contradicting the admissibility of $u_{k}$ in definition (6.3). So $u_{k}^{+}$remains bounded in $W^{1, p}(\Omega)$ and it follows by standard arguments that for a subsequence, $u_{k}^{+}$converges uniformly on $\bar{\Omega}$ to $\varphi_{m}$ when $\int_{\Omega} m \neq 0$, to a positive constant when $\int_{\Omega} m=0$. In case (i) $\varphi_{m}$ is also a positive constant, and we conclude as above that $u_{k}$ is not admissible in definition (6.3) for $k$ sufficiently large, a contradiction. In case (ii) $\varphi_{m} \in C^{1}(\bar{\Omega})$ by [12] and the strong maximum principle of [14] applies to guarantee that $\varphi_{m}$ is positive on $\bar{\Omega}$; a contradiction can then be derived as above. Finally in case (iii) one has $\varphi_{m} \geqslant \operatorname{some} \epsilon>0$ on $\operatorname{supp}\left(n^{+}\right)$, and one deduces again that $u_{k}$ is not admissible in definition (2.2) for $k$ sufficiently large, a contradiction.

Remark 6.5. When the weight $m$ is unbounded and $\int_{\Omega} m<0$, it is unclear whether $\varphi_{m}$ is positive on $\bar{\Omega}$. This is why we impose condition (iii) in Proposition 6.4.

We finally observe that the distribution of $\Sigma^{*}$ in the other quadrants of $\mathbb{R} \times \mathbb{R}$ could be studied here in a manner similar to that in [2].

One could also adapt to the present setting the results of [2] relative to the study of nonresonance.

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