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## Homotopy negligible subsets

by

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## 1. Introduction to homotopy negligibility

We shall say that a subset A of a topological space X is homotopy negligible if the inclusion map  $X-A \to X$  is a homotopy equivalence. The main result in this note is that under certain conditions this global property of A in X can be deduced from an analogous local property. In § 2, 3 examples are given where X is an infinite dimensional manifold. For a Palais-stable separable Hilbert manifold X the homotopy negligibility of A in X implies that X and X-A are even diffeomorphic, by recent results of Kuiper, Burghelea [5] and Nicole Moulis [6]. These results are based on Bessaga [2] and Kuiper [4].

Theorem 1. Let X be an absolute neighborhood retract and A a closed subset. Assume that each point of A has a fundamental system of neighborhoods U in X for which  $U \cap A$  is homotopy negligible in U. Then A is homotopy negligible in X.

The theorem follows from the following lemma, for which we need another definition. A continuous map  $f: Y \to Z$  of topological spaces is a *q-homotopy equivalence*, if f induces an isomorphism  $f_i: \pi_i(Y) \to \pi_i(Z)$  of homotopy groups for all  $i \leq q$ . If f is a g-homotopy equivalence for all g, then g is a weak homotopy equivalence.

Weak homotopy equivalence is again implied by compact homotopy equivalence:  $X \stackrel{\circ}{\sim} Y \Leftrightarrow$  there are maps  $f: X \to Y$  and  $g: Y \to X$ , such that for any compacts  $K \subset X$  and  $L \subset Y$ , the restrictions gf|K and fg|L are homotopic to the inclusions respectively.

LEMMA. Let X be a topological space, and A a closed subset with the following property  $P_q$ : for each  $x \in A$  there is a fundamental

<sup>&</sup>lt;sup>1</sup> Much of this research was done while this author was a guest professor at the University of Amsterdam. The authors express their gratitude for some useful comments of the referee.

system of neighborhoods U of x in X for each of which the inclusion map  $U-A=U-(U\cap A)\to U$  is a q-homotopy equivalence. Then for any neighborhood V of A in X the inclusion map  $V-A\to V$  is a q-homotopy equivalence.

COROLLARY. If A satisfies  $P_q$  for all q, then the inclusion map  $X-A \to X$  is a weak homotopy equivalence.

Assuming the Lemma we see that the conditions of Theorem 1 imply that the inclusion  $X-A \to X$  is a weak homotopy equivalence. But a theorem of J. H. C. Whitehead [8] asserts that if Y and Z are absolute neighborhood retracts and f a weak homotopy equivalence, then f is a homotopy equivalence (i.e., there exists a map  $g: Z \to Y$  which is a homotopy inverse of f).

If X is an absolute neighborhood retract and A a closed subset, then X-A is also an absolute neighborhood retract. Theorem 1 now follows.

PROOF OF THE LEMMA. Under the assumptions of the lemma we first prove that  $\pi_i(V-A) \to \pi_i(V)$  is injective for  $i \leq k$ .

Let us call a neighborhood U of x with the property  $P_k$  a preferred neighborhood of x. We use the term for  $x \in A$  as well as for  $x \in V-A$ . Let  $f: (D^{i+1}, S^i) \to (V, V-A)$  be any map of the i+1-disc  $D^{i+1}$  into V carrying its boundary  $S^i$  into V-A. We want to move  $f(D^{i+1})$  away from A, leaving f fixed on  $S^i$ . Now we cover the compact set  $f(D^{i+1})$  by a finite number of preferred neighborhoods all in V. Choose a triangulation  $T_{i+1}$  of  $D^{i+1}$  so fine that every closed i+1-simplex  $\sigma \in T_{i+1}$  has an image in some element, chosen once and for all, say  $U_{i+1}(\sigma)$  of the covering, and such that simplices that meet  $S^i$  have their images in V-A.

Next we consider the *i*-skeleton  $T_{i+1}^i$  of  $T_{i+1}$ . For the image point f(x) of any point  $x \in T_{i+1}^i$  there is a preferred neighborhood U(f(x)) which is contained in the intersection of all  $U_{i+1}(\sigma)$  for which  $x \in \sigma \in T_{i+1}$ . We cover the compact set  $f(T_{i+1}^i)$  by a finite number of these preferred neighborhoods. Choose a subdivision  $T_i$  of  $T_{i+1}^i$  so fine that every closed *i*-simplex  $\sigma$  of  $T_i$  has an image in some element, chosen once and for all, say  $U_i(\sigma)$  of the last mentioned covering.

Next we consider the i-1-skeleton  $T_i^{i-1}$  of  $T_i$  and we continue analogously. In this manner we obtain a sequence of skeletons  $T_j$  of dimension  $j=0,1,2,\cdots,i+1$ , and for each j-simplex  $\sigma_j$  of  $T_j$  a preferred neighborhood  $U_j(\sigma_j)$  covering  $f(\sigma_j)$ , such that moreover  $U_j(\sigma_j) \subset U_{j+1}(\sigma_{j+1})$  whenever  $\sigma_j \subset \sigma_{j+1}$ .

Now we are ready to start our homotopic changes of f leaving

its restriction to  $S^i$  invariant. We will define a homotopy  $f_t$  starting at time t = 0 with  $f_0 = f$  and ending at time t = i+2 with  $f_{i+2}$ .  $f_{i+2}$  will have the required properties:

$$f_{i+2}|S^i=f|S^i, \quad f_{i+2}(D^{i+1}) \subset V-A.$$

The homotopy will be such that

- (a)  $f_{j+1}(T_j) \subset V A$  for  $j = 0, 1, \dots, i+1$
- (b)  $f_t|T_j = f_{j+1}|T_j$  for  $t \ge j+1$
- (c)  $f_t(\sigma_j) \subset U_j(\sigma_j)$  for  $\sigma_j \in T_j$ , all j, all t
- (d)  $f_t | S^i = f | S^i$ .

Suppose  $f_t$  has been defined with these properties for  $t \leq j$  ( $\leq i+1$ ). We first describe what happens with a j-simplex  $\sigma$  of  $T_j$  in the time from t=j to t=j+1. Because  $f_j(\sigma) \subset U_j(\sigma)$  and  $f_j(\partial \sigma) \subset V-A$  and because  $j \leq i+1 \leq k+1$ , the assumption  $P_k$  implies the existence of  $g_t: \sigma \to U_j(\sigma)$   $j \leq t \leq j+1$  with the properties:

$$g_j = f_j | \sigma, \quad g_t | \partial \sigma = g_j | \partial \sigma,$$
  
 $g_{j+1}(\sigma) \subset U_j(\sigma) - A \subset V - A.$ 

(As a matter of fact only the injectivity and not the isomorphisms are used here, as well as for the surjectivity consequence.)

We have to extend  $g_t$  to all of  $D^{i+1}$ . For that we consider a subdivision of  $T_{i+1}$  which contains  $T_j$  as a subcomplex, and such that the stars of the j-simplices  $\sigma$  of  $T_j$  have mutually disjoint interiors. Star  $\sigma$  is the union of all simplices that contain  $\sigma$ . It is also the join of  $\sigma$  and the link of  $\sigma$ : St  $\sigma = \sigma * Lk \sigma$  and it can be obtained from  $\sigma \times [0, 1] \times Lk \sigma$  by identification to one point of the sets  $x \times 0 \times Lk \sigma$  and  $\sigma \times 1 \times y$  for each  $x \in \sigma$  and each  $y \in Lk \sigma$ . The second factor gives a coordinate s on star  $\sigma$ . The triples (x, s, y) are supernumary "coordinates" for St  $\sigma$ .

In these coordinates we define for  $j \le t \le j+1$ :

$$f_t(x,s,y) = egin{cases} g_{t-2s}(x) & ext{for} & j \leq t-2s \ f_j(x) & ext{for} & t-1 \leq t-2s \leq j \ f_j((x,rac{1}{2}s,y)) & ext{for} & rac{1}{2} \leq s \leq 1. \end{cases}$$

We apply this to the stars of all j-simplices of  $T_j$  which are not in  $S^i$ . For the remaining points z we take

$$f_t(z) = f_j(z).$$

We now easily check that during this inductive step the conditions

(a), (b), (c) and (d) remain valid for  $j \le t \le j+1$ . After the step j = i+1 we obtain the required map  $f_{i+2}$ .

To prove that  $\pi_i(V-A) \to \pi_i(V)$  is surjective  $(i \le k)$  it suffices to show that any map  $f: S^i \to V$  can be deformed in V to a map into V-A; the same argument yields that (even for  $i \le k+1$ , but we do not need that). The lemma is proved, and so is Theorem 1.

## 2. Applications

Example 1. Submanifolds.

Let E be a metrizable locally convex topological vector space. Suppose that X is a manifold modeled on E; more precisely, X is a paracompact Hausdorff space such that with every point  $x \in X$  we can associate a chart  $(\kappa, U)$  i.e., a neighborhood U and a homeomorphism  $\kappa$  mapping U onto an open subset of E. Every such manifold X is an absolute neighborhood retract [3, 7].

Let A be a closed submanifold of X; thus A is a closed subset of X with the following property: There is a closed linear subspace F of E and for each  $x \in A$  a chart  $(\kappa, U)$  containing x such that  $\kappa(U \cap A) = \kappa(U) \cap F$ . We will call dim E/F the codimension codim (X, A) of A in X. Since  $E-F \to E$  is a weak k-homotopy equivalence for all  $k \leq \operatorname{codim}(E, F) - 2$ , we conclude that A satisfies  $P_k$  for all  $k \leq \operatorname{codim}(X, A) - 2$ . Thus we obtain for  $k = \infty$ :

Theorem 2. Any infinite codimensional closed submanifold A in X is homotopy negligible.

Example 2. Fibre bundles and zero sections.

Let  $\xi: X \to B$  be a vector bundle over the base space B with total space the ANR X, whose fibres are infinite dimensional metrizable locally convex topological vector spaces. If A denotes the image of the zero section, then  $X-A \to X$  is a homotopy equivalence; since  $\xi$  is also a homotopy equivalence, we see that X-A and A have the same homotopy type.

Example 3. A mapping space.

Let M be a separable smooth (i.e.,  $C^{\infty}$ ) manifold modeled on a Hilbert space (possibly finite dimensional!), and S a compact topological space. Then the mapping space C(S, M) of all continuous maps  $S \to M$  with the topology of uniform convergence

is a smooth manifold modeled on a Banach space (infinite dimensional except in trivial cases, which we exclude). The identification of each point  $m \in M$  with the point mapping  $S \to m$  defines an imbedding of M into C(S,M) of infinite codimension. The theorem implies that  $C(S,M)-M\to C(S,M)$  is a homotopy equivalence.

#### 3. Approximately infinite codimension

The next lemma prepares the way to a more general class of homotopy negligible subsets. Let  $\rho$  be a metric for the model E.

LEMMA. Let A be a closed subset of the open subset U of E. Suppose that for every  $\varepsilon > 0$  there is a closed linear subspace  $F_{A,\varepsilon}$  of E with codim  $(E, F_{A,\varepsilon}) = \infty$  and such that  $\rho(x, F_{A,\varepsilon}) < \varepsilon$  for all  $x \in A$ . Let D be a compact subset of U, and S a closed subset of D disjoint from A. Then there is a homotopy  $f_I: (D, S) \to (U, U-A)$  such that  $f_0 = identity$ ,  $f_t(x) = x$  for all  $x \in S$ ,  $t \in I$ , and  $f_1(D) \subset U-A$ .

We will say that such subsets A are approximately infinite codimensional in E. For example, any compact set in E has this property.

PROOF. Choose  $\varepsilon > 0$  so that  $\rho(A, S) > 5\varepsilon$  and  $\rho(E - U, D) > 6\varepsilon$ . The compact set D can be covered by a finite number of discs of radius  $\varepsilon$ ; their centers span a finite dimensional subspace  $F_D$ , and  $\rho(x, F_D) < \varepsilon$  for all  $x \in D$ . Let F be the closed linear subspace spanned by  $F_{A,\varepsilon}$  and  $F_D$ ; then codim  $(E, F) = \infty$ , and  $\rho(x, F) < \varepsilon$  for all  $x \in A \cup D$ . Now take any point  $x_2$  with  $\rho(x_2, F) = 3\varepsilon$ , and let  $x_1 \in F$  be a point such that  $\rho(x_1, x_2) < 4\varepsilon$ . Set  $v = x_2 - x_1$ , and define the map  $f_1: D \to E$  by

$$f_1(x) = x + \varphi(\rho(x, S)/\varepsilon)v,$$

where  $\varphi: \mathbf{R} \to \mathbf{R}$  is given by

$$\varphi(t) = 0 \ (t \le 0), \ \varphi(t) = t(0 < t < 1), \ \varphi(t) = 1(t \ge 1).$$

Then  $f_t = (1-t)f_0 + tf_1$ , where  $f_0 =$  identity map, is a homotopy of the desired sort.

THEOREM 3. Let A be a closed subset of a manifold X modeled on E. Assume that every point  $x \in A$  is contained in a chart  $(\kappa, U)$  of X such that  $\kappa(U \cap A)$  is approximately infinite codimensional. Then A is homotopy negligible in X. For example, any locally compact set in X has this property.

PROOF. Since  $\kappa(U \cap A)$  is closed in the open subset  $\kappa(U)$  of the model E, it follows from the lemma that all relative homotopy groups  $\pi_i(U, U-A) = 0$   $(i \in \mathbb{Z})$ , whence that the inclusion map  $U-A \to U$  is a weak homotopy equivalence. Since for any chart  $(\kappa, U)$  containing x we know that U and U-A are absolute neighborhood retracts, it follows that  $U-A \to U$  is a homotopy equivalence. Therefore A is homotopy negligible in X.

APPLICATION. (Nicole Moulis [6]). If X is a separable Hilbert manifold and X is diffeomorphic with  $X \times H$  (H is Hilbert space; X is called Palais-stable in this case) and A is locally compact in X, then X and X-A are diffeomorphic.

PROOF. By the above theorems X and X-A are homotopy equivalent. As X is Palais-stable it is diffeomorphic with an open set in H. Then so is X-A. By Moulis [6], X-A has a non-degenerate Morse function with minimum fulfilling Condition C of Palais-Smale. By Kuiper-Burghelea [5], X-A is also Palais-stable, and X-A and X are diffeomorphic.

Example. If A is an approximately infinite codimensional closed subset of a contractible manifold X, then X-A is contractible.

As another instance, let H be an infinite dimensional Hilbert space and X = GL(H) the group of bounded linear automorphisms of H; then X is an open nonseparable subset of the Banach space of bounded endomorphisms of H, and GL(H) is a contractible Lie group [4]. Let  $GL_{\mathfrak{o}}(H)$  denote the closed subgroup of automorphisms of the form I+K where I= identity map, and K is a compact endomorphism. Then  $GL(H)-GL_{\mathfrak{o}}(H)$  is contractible.

Added in proof.

- 1) If X is a separable metrizable  $C^0$ -manifold modeled on an infinite dimensional Fréchet space, and A is a closed subset as in Theorem 1, then there is a homeomorphism of X-A onto X; see  $\lceil 1 \rceil$ .
- 2) Very general conditions to insure that X-A is homeomorphic to X (with good control on the homeomorphism) have recently been given by W. H. Cutler, Negligible subsets of non-separable Hilbert manifolds (to appear). For instance, if X is a  $C^0$ -manifold modeled on a non-separable Hilbert space and A is a countable union of locally compact subsets, then X-A is homeomorphic to X, by a homeomorphism near the inclusion map  $X-A \to X$ .

- 3) Every separable metrizable  $C^{\infty}$ -manifold modeled on infinite dimensional Hilbert space is Palais-stable. This follows from combined work of [5], [6], and J. Eells-K. D. Elworthy, On the differential topology of Hilbertian manifolds, Proc. Summer Institute, Berkeley, 1968.
- 4) The application of §3 (without the unnecessary hypothesis of Palais-stability) is also due to J. E. West, The diffeomorphic excision of closed local compacta from infinite-dimensional Hilbert manifolds (to appear). Comp. Math.

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