JEAN BOURGAIN
W. WANG

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Construction of Blowup Solutions for the Nonlinear Schrödinger Equation with Critical Nonlinearity

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1. – Introduction and statement of results

In this paper we study the behavior of the blowup solution of the nonlinear Schrödinger equation (NLS)

\[ iu_t + \Delta u + |u|^{\frac{4}{d}} u = 0 \ (x \in R^d). \tag{1.1} \]

Recall that both the \( L^2 \)-norm

\[ \| \phi \|_2 = \left( \int_{R^d} |\phi(x)|^2 dx \right)^{1/2} \tag{1.2} \]

and the Hamiltonian

\[ H(\phi) = \frac{1}{2} \int |\nabla \phi|^2 - \frac{d}{2d+4} \int |\phi|^{4+2} \tag{1.3} \]

are conserved quantities for the flow of (1.1).

The NLS (1.1) has an important soliton solution

\[ e^{i\tau} R(x) \tag{1.4} \]

where \( R \) is the ground state of the equation

\[ \Delta u - u + |u|^{\frac{4}{d}} u = 0. \tag{1.5} \]

It is known that equation (1.1) has no blowup solution in the class

\[ \{ u \in H^1(\mathbb{R}^d) | ||u||_{L^2} < ||R||_{L^2} \} \tag{1.6} \]

and, in the class

\[ \{ u \in H^1(\mathbb{R}^d) | ||u||_{L^2} = ||R||_{L^2} \} \tag{1.7} \]
(1.1) has a unique blowup solution

\[ \tilde{R}(x,t) = \frac{1}{t^{d/2}} e^{\frac{|x|^2}{4t}} R \left( \frac{x}{t} \right) \]

up to the invariances of the equation (see [G-V], [Wein], [Ml]).

In the class \( \{ u \in H^1(\mathbb{R}^d) \mid \| u \|_{L^2} > \| R \|_2 \} \), a general blowup criteria was established by Glassey [G], based on the viriel identity

\[ \frac{d^2}{dt^2} \left[ \int |x|^2 |u(x,t)|^2 dx \right] \sim H(u(t)). \]

However, a mathematically rigorous understanding of the blowup is largely open. It is known that if

\[ \lim_{t \to T} \| u(t) \|_{H^1} = \infty \]

there has to be a concentration of \( L^2 \)-mass in the following sense: there exists points \( z(t) \in \mathbb{R}^d, t < T \), such that

\[ \lim_{t \to T} \int_{B(0,\delta)} |u(x + z(t), t)|^2 dx \geq \| R \|_{L^2}^2 \]

for any \( \delta > 0 \), see [Wein 2], [MT], [N], etc.

This statement is of course far from a complete description. Among the several conjectures (based in particular on numerics), one believes that the \( L^2 \)-mass going into the blowup is quantized and the blowup solution looks like a superposition of finitely many solutions blowing up at single points and outside which it remains smooth. In the particular case of a solution satisfying (1.10) and

\[ \| u \|_2 < \| R \|_2 + \delta \]

for small \( \delta > 0 \), it is expected that \( u \) decouples as superposition

\[ u = u_0 + u_1 \]

where \( u_0 \) is a minimum norm blowup solution conformal to (1.8) and \( u_1 \) remains smooth after blowup. (Observe that these minimum norm blowup solutions are unstable). The purpose of our first result is to give at least examples of this phenomenon.
THEOREM 1. Let $d = 1$ or $d = 2$. Let $\phi$ be a smooth function on $\mathbb{R}^d$ with fast decay at infinity and such that $\phi$ vanish at $0$ of sufficiently high order. Then (1.1) has a blowup solution $u$ on $[-\delta, 0]$ of the form

$$u = \tilde{R} + u_1$$

where $\tilde{R}$ is given by (1.8) and $u_1$ extends to a smooth function on $[-\delta, \delta]$ solving the Cauchy problem

$$\begin{cases} u_1(0) = \phi \\ i\dot{u}_1 + \Delta u_1 + u_1 |u_1|^2 = 0 \end{cases}$$

on $[0, \delta]$.

Here $\delta > 0$ depends on an appropriate norm $\|\phi\|$ of $\phi$ and $\delta \to \infty$ for $\|\phi\| \to 0$. The reason of the restriction $d = 1, 2$ is the smoothness of the nonlinearity $u|u|^{4/d}$ in (1.1) (which seems insufficient in higher dimension for our purpose).

Theorem 1 may be formulated in a more precise way. Define the spaces

$$X_A = \{ \phi \in H^A(\mathbb{R}^d) \mid (1 + |x|)^A \phi \in L^2(\mathbb{R}^d) \}$$

endowed with the natural norm

$$\|\phi\|_{X_A} = \|\phi\|_{H^A} + \|(1 + |x|)^A \phi\|_{L^2}.$$ 

Denote also

$$\mathcal{P}_A = \left\{ \phi \in X_A \mid D^\alpha \phi(0) = 0 \text{ for all } |\alpha| < A - \left[ \frac{d}{2} \right] \right\}.$$ 

Recall also that if $\phi \in X_A$, then the IVP

$$\begin{cases} iu_t + \Delta u + u|u|^{4/d} = 0 \\ u(0) = \phi \end{cases}$$

has a local solution $z_\phi$ in a neighborhood $[-\delta, \delta]$ of $0$, satisfying

$$z_\phi \in C([-\delta, \delta] : X_A).$$

If moreover $\|\phi\|_{L^2}$ is sufficiently small, then this local solution extends to a global one and it may be shown that (cf. [Bo])

$$\|z_\phi(t)\|_{X_A} \leq C(1 + |t|)^{C_A}.$$ 

Theorem 1 is then a consequence of the following Theorem 1'
THEOREM 1'. Given $A$, there is $A_1$ such that if \( \phi \in \mathcal{P}_{A_1} \), then (1.1) has a blowup solution $u$ on $[-\delta, 0]$ of the form

\[(1.23) \quad u = \tilde{R} + z_\phi + w \]

where

\[(1.24) \quad w \in C([-\delta, 0]; X_A) \]

and

\[(1.25) \quad \|w(t)\|_{X_A} \leq |t|^A \text{ for } |t| \to 0. \]

To obtain (1.14), define

\[(1.26) \quad u_1 = z_\phi + w \text{ for } t \in [-\delta, 0] \]

\[= z_\phi \text{ for } t \in [0, \delta]. \]

We treat Theorem 1' basically as a perturbative problem. Our first tool is the standard pseudo-conformal invariance, i.e. the formula

\[(1.27) \quad Cu(x, t) = \frac{1}{t^{d/2}} e^{\frac{|x|^2}{4t}} \mu \left( \frac{x}{t}, -\frac{1}{t} \right) \]

transforming a solution of (1.1) in another one (equation (1.1) has critical nonlinearity).

Applying this transformation in the setting of Theorem 1', we basically sends $t = 0$ to $t = \infty$ and get an equivalent problem concerning perturbations of the ground state solution (1.4).

Writing in (1.1)

\[(1.28) \quad u(x, t) = e^{it} (R(x) + v(x, t)) \]

the function $v$ has to satisfy the equation

\[(1.29) \quad iv_t + \Delta v - v + [\|R(x) + v(x, t)\|^{4/d}(R(x) + v(x, t)) - R(x)^{4/d+1}] = 0 \]

i.e.

\[(1.30) \quad iv_t + \Delta v - v + \left( \frac{2}{d} + 1 \right) R^{4/d} v + \frac{2}{d} R^{4/d} \bar{v} + 0(|v|^2) = 0 \]

One second main tool is the result [Wein 1] of M. Weinstein (for $d = 1, d = 3$ and completed in the $d = 2$ case using subsequent work [Kw]) according to which the linearized equation

\[(1.31) \quad iv_t - Lv = 0 \]
where

$$Lv = -\Delta v + v - \left(\frac{2}{d} + 1\right) R^{2/d} v - \frac{2}{d} R^{2/d} \bar{u}$$

has only algebraic instabilities (a precise statement will appear in the next section).

**REMARK.** This fact holds in subcritical and critical cases; in the supercritical case, one has exponential instability (M. Weinstein - personal communication).

This result is obviously fundamental to our perturbative analysis and permits us to go beyond certain perturbative constructions as considered for instance in [M2], where this property was not exploited. As an application, one may indeed construct blowup solutions, of (1.1) with distinct blowup times.

**THEOREM 2.** Take $d = 1, 2$ and $A$ a large number. Consider times

$$0 = t_0 > t_1 > t_2$$

where $|t_1 - t_2| < \delta (|t_0 - t_1|), |t_0 - t_1| < \delta_0$

with $\delta_0$ small enough and let $x_0, x_1 \in \mathbb{R}^d$ be such that

$$|x_0 - x_1| > 1.$$

Then (1.1) has a solution $u$ on $(t_2, t_1) \cup (t_1, t_0)$ satisfying

$$u \in C((t_2, t_1) \cup (t_1, 0); X_A)$$

$$u - \tilde{R}_0 \in C([t_1, 0]; X_A)$$

$$u - \tilde{R}_1 \in C([t_2, t_1]; X_A)$$

$$\frac{u - \tilde{R}_1)(t_1 - 0)}{u(1 + 0) .}$$

We denote here

$$\tilde{R}_0(x, t) = R(x - x_0, t - t_0) and \tilde{R}_1(x, t) = R(x - x_1, t - t_1).$$

**REMARK.**

1. A similar statement may be formulated for an arbitrary number of times.
2. In our setup in Theorem 2, we did not continue the blowup solutions $\tilde{R}_\alpha(\alpha = 0, 1)$ after the blowup time (thus there is no $L^2$-conservation) as one may do according to results of [M3].
3. A result in the spirit of Theorem 1 may be proved also in $d = 3$, but technicalities are exceedingly more significant, due to lack of smoothness of nonlinearity.
4. The results of this paper constitute a preliminary investigation in this direction.

There is no doubt that elaborating the techniques presented here and an appropriate scattering theory should also lead to general stability of solutions of (1.1) nearby $\tilde{R}$, provided we restrict data to appropriate finite codimensional spaces.


2. – Estimates on the linearized operator

In this section, we briefly recall a basic result from [Wein 1] on the linearized problem (1.31), (1.32)

\begin{equation}
\begin{cases}
  iv_t - Lv = 0 \\
  v(0) = \phi
\end{cases}
\end{equation}

where

\begin{equation}
  Lv = -\Delta v + v - \left( \frac{2}{d} + 1 \right) R^{4/d} v - \frac{2}{d} R^{4/d} \vec{v}.
\end{equation}

It is shown that one may decompose the space $H^1(\mathbb{R}^d)$ as

\begin{equation}
  H^1 = M \oplus S
\end{equation}

with both components invariant under the flow map $e^{itL}$ and where the space $S$ of “secular modes” (obtained as generalized null space of $L$) is spanned by $2d + 4$ Schwartz functions

\begin{equation}
  S = [e_1, \ldots, e_{2d+4}]
\end{equation}

satisfying

\begin{equation}
  |e_j(x)| < e^{-c|x|} \text{ for } |x| \to \infty.
\end{equation}

Moreover, for $\phi \in M$

\begin{equation}
  \|e^{itL}\phi\|_{H^1} \leq C \|\phi\|_{H^1}
\end{equation}

while, for $\phi \in S$

\begin{equation}
  \|e^{itL}\phi\| < C(1 + |t|^3) \int e^{-c|x|} |\phi(x)| dx.
\end{equation}

We will also need for later purpose the following estimates on the behaviour of $e^{itL}$ in $X_A$-norm.

**Proposition 2.8.** Denote $P_M$ (respectively $P_S$) the orthogonal projection on $M$ (respectively $S$), then

\begin{equation}
  \|e^{itL}(P_M\phi)\|_{H^s} \leq C \|\phi\|_{H^s}
\end{equation}

\begin{equation}
  \|e^{itL}(P_S\phi)\|_{H^s} \leq C(1 + |t|^3) \int |\phi| e^{-c|x|} dx
\end{equation}

\begin{equation}
  \|x^\alpha e^{itL}(P_M\phi)\|_{L^2} \leq C \|x^\alpha \phi\|_{L^2} + C(1 + |t|^3) \|\phi\|_{H^s}
\end{equation}

\begin{equation}
  \|x^\alpha e^{itL}(P_S\phi)\|_{L^2} \leq C(1 + |t|^3) \int |\phi| e^{-c|x|} dx.
\end{equation}
PROOF. The statements (2.10), (2.12) are obvious from (2.7) and the fact that $S$ is contained in the Schwartz space, satisfying (2.5).

To verify (2.9), consider first $\|e^{itL}\phi\|_{H^{2s+1}}$, $\phi \in M$, where $s > 0$ is an integer. From the definition (2.2) of $L$, it is clear that

$$\|e^{itL}\phi\|_{H^{2s+1}} \leq \|L^s e^{itL}\phi\|_{H^1} + c\|e^{itL}\phi\|_{H^{2s-1}}. \tag{2.13}$$

Since $L$ maps $M$ into itself, one gets from (2.6)

$$\|L^s e^{itL}\phi\|_{H^1} = \|e^{itL}L^s\phi\|_{H^1} \leq C\|L^s\phi\|_{H^1} \leq C\|\phi\|_{H^{2s-1}}. \tag{2.14}$$

Hence, from (2.13), (2.14)

$$\|e^{itL}\phi\|_{H^{2s+1}} \leq C\|\phi\|_{H^{2s+1}} + C\|e^{itL}\phi\|_{H^{2s-1}}. \tag{2.15}$$

By induction, (2.6), (2.15), we get (2.9) for $s$ of the form $2s + 1$, $s \in \mathbb{Z}_+$. The result in general follows then by interpolation.

Next, we verify (2.11). Take $\phi \in M$ and denote $v = e^{itL}\phi$. Then the equation

$$iv_t - Lv = 0$$

yields

$$\frac{d}{dt} \left[ \int |x|^{2\alpha} |v(x, t)|^2 dx \right] = 2\text{Re} \langle |x|^{2\alpha} v, v \rangle \tag{2.16}$$

Substituting $L$ from (2.2) in (2.16), one obtains easily

$$2\text{Im} \langle |x|^{2\alpha} v, \Delta v \rangle + 0 \left( \int |v|^2 e^{-\epsilon|v|} \right)$$

bounded by

$$\int |x|^{2\alpha-1} |v| |\nabla v| dx + \|v\|_2^2. \tag{2.17}$$

Interpolating between $H^\alpha$ and $L^2(|x|^\alpha, dx)$, estimate by Hölder’s inequality

$$\int |x|^{2\alpha-1} |v| |\nabla v| \leq \| |x|^{\alpha} |v| \|_2 \| |x|^{\alpha-1} |\nabla v| \|_2 \leq \| |x|^\alpha |v| \|_2^{2-\frac{1}{\alpha}} \|v\|_{H^\alpha}^{\frac{1}{\alpha}}. \tag{2.18}$$

Invoking (2.9), we conclude that

$$\frac{d}{dt} \left[ \| |x|^\alpha |v(t)| \|_2^2 \right] \leq C\| |x|^\alpha |v| \|_2^{2-\frac{1}{\alpha}} \|v\|_{H^\alpha}^{\frac{1}{\alpha}} + \|v\|_2^2 \tag{2.19}$$

from where (2.11) is deduced.

COROLLARY 2.20. For all $\phi$ and $A \geq 3$

$$\|e^{itL}\phi\|_{X_A} \leq (1 + |t|)^A \|\phi\|_{X_A}.$$
3. – Proof of Theorem 1’

Recall first the conformal transformation

\begin{equation}
\tilde{u}(x, t) = Cu(x, t) = \frac{1}{t^{d/2}} e^{\frac{|x|^2}{4it}} u \left( \frac{x}{t}, -\frac{1}{t} \right).
\end{equation}

Thus

\begin{equation}
\| (Cu)(t) \|_{H^s} \leq C \max_{r+|\beta| \leq s} \left\| \frac{|y|^r}{|t|^{s-r}} |(D^\beta u)\left( -\frac{1}{t} \right) \right\|_2 
\end{equation}

\begin{equation}
\leq C \left( 1 + \frac{1}{|t|^s} \right) \left\| u \left( -\frac{1}{t} \right) \right\|_{X_A}
\end{equation}

and

\begin{equation}
\| |x|^a (Cu)(t) \|_2 \leq |t|^a \left\| |y|^a u \left( -\frac{1}{t} \right) \right\|_2.
\end{equation}

Hence, from (3.2), (3.3)

\begin{equation}
\| (Cu)(t) \|_{X_A} \leq C \left( |t|^A + \frac{1}{|t|^A} \right) \left\| u \left( -\frac{1}{t} \right) \right\|_{X_A}.
\end{equation}

Transforming (1.23) by \( C \) and applying (3.4), it will clearly suffice to get a solution of (1.1) on \([\frac{1}{\delta}, \infty[\) of the form

\begin{equation}
u = \text{Re}^{it} + C^{-1}(z_\phi) + we^{it}
\end{equation}

where

\begin{equation}w \in \mathcal{C} \left( \left[ \frac{1}{\delta}, \infty[; X_A \right)
\end{equation}

satisfies

\begin{equation}\| w(t) \|_{X_A} \leq \frac{1}{t^{2A}}.
\end{equation}

Recall that \( z_\phi \) solves (1.1)

\begin{equation}i\dot{z}_\phi + \Delta z_\phi + |z_\phi|^{4/d} z_\phi = 0
\end{equation}

with \( \phi \in \mathcal{P}_{A_1} \).

Denote

\begin{equation}v_0 = C^{-1}(z_\phi)e^{-it}
\end{equation}
and substitute
\[ v = v_0 + w \]
in the difference equation (1.29). Since \( v_0 \) satisfies
\[ (3.10) \quad i \dot{v}_0 - v_0 + \Delta v_0 + |v_0|^{4/d} v_0 = 0 \]
we get
\[ (3.11) \quad i w_t + \Delta w - w + [|R + v_0 + w|^{4/d} (R + v_0 + w) - R^{4/d+1} - |v_0|^{4/d} v_0] = 0. \]

Define
\[ (3.12) \quad f_0 = |R + v_0|^{4/d} (R + v_0) - R^{4/d+1} - |v_0|^{4/d} v_0 \]
\[ (3.13) \quad a = \left(\frac{2}{d} + 1\right)(|R + v_0|^{4/d} - R^{4/d}) \]
\[ (3.14) \quad b = \frac{2}{d}((R + v_0)^{2/d+1} (R + \bar{v}_0)^{2/d-1} - R^{4/d}) \]
\[ (3.15) \quad G(w) = |R + v_0 + w|^{4/d} (R + v_0 + w) - (R + v_0)^{4/d} (R + v_0) - aw - b \bar{w} \]

and rewrite (3.11) as
\[ (3.16) \quad i w_t - L w + aw + b \bar{w} + G(w) + f_0 = 0. \]

Here \( G(w) \) is at least quadratic in \( w \).

In order to produce a solution of (3.16) on \( [\frac{1}{2}, \infty[ \), we solve the equivalent integral equation
\[ (3.17) \quad w(t) = -i \int_t^\infty e^{i(\tau-t) L} [f_0 + a w + b \bar{w} + G(w)](\tau) d\tau. \]

This procedure is reminiscent of the wave map construction in scattering theory, except that here the reference equation is the nonlinear equation (1.1).

Our aim is to derive the bound (3.7) from (3.17).

We first establish some bounds on \( v_0 \). From (3.1), (3.9)
\[ (3.18) \quad v_0(x, t) = \frac{1}{t^{d/2}} e^{\frac{|x|^2}{4it}} e^{-i t} z_\phi \left( \frac{x}{t}, \frac{1}{t} \right). \]

Since \( \phi \in P_{A_1} \subset X_{A_1} \), we have by (1.21)
\[ (3.19) \quad \|z_\phi(t)\|_{X_{A_1}} < C \quad \text{for} \quad |t| < \delta. \]

We assume here \( A_1 \) sufficiently large with respect to \( A \).
From the equation (3.8), it follows from definition of $\mathcal{P}_{A_1}$, cf. (1.19), that

\begin{equation}
\left. \frac{\partial^\alpha_x \partial_t^\ell z_\phi \right|_{x=0} = 0 \text{ for } |\alpha| + 2\ell < A_1 - \left[ \frac{d}{2} \right]. \tag{3.20}
\end{equation}

Thus, by Taylor’s theorem

\begin{equation}
|z_\phi(x, t)| < C(|x| + |t|)^{A'} \text{ for } A' \leq \frac{A_1}{2} - 1 \text{ and } |t| < \delta. \tag{3.21}
\end{equation}

From (3.18)

\begin{equation}
D^\alpha v_0(x, t) = \frac{1}{t^{d/2}} e^{i |x|^2 / 4t - i t} \left\{ 0 \left( \left[ \frac{|x|}{t} \right]^{|\alpha|} z_\phi \left( \frac{x}{t}, -\frac{1}{t} \right) \right) \right. 
+ 0 \left( \frac{1}{t^{|\alpha|}} D^\alpha z_\phi \left( \frac{x}{t}, -\frac{1}{t} \right) \right) + \text{others} \right\} \tag{3.22}
\end{equation}

and thus

\begin{equation}
|D^\alpha v_0(x, t)| \leq \frac{C}{t^{d/2}} \max_{r + |\beta| \leq |\alpha|} \left\{ \left| \left| \frac{x}{t} \right|^{r'} D^\beta z_\phi \left( \frac{x}{t}, -\frac{1}{t} \right) \right| \right\}. \tag{3.23}
\end{equation}

Hence

\begin{equation}
\|D^\alpha v_0(t)\|_\infty < \frac{C}{t^{d/2}} \max_{r + |\beta| \leq |\alpha|} \left\{ \left| \left| y \right|^{r'} D^\beta z_\phi \left( y, -\frac{1}{t} \right) \right| \right\} \tag{3.24}\end{equation}

and thus, by (3.19)

\begin{equation}
\|D^\alpha v_0(t)\|_\infty \leq \frac{C}{t^{d/2}} \left| z_\phi \left( -\frac{1}{t} \right) \right|_{x_{A_1}} < \frac{C}{t^{d/2}} \text{ for } t > \frac{1}{\delta} \text{ and } |\alpha| \leq A_1 - 2. \tag{3.25}\end{equation}

Also, by (3.21), (3.23)

\begin{equation}
|e^{-c|x|} D^\alpha v_0(x, t)| < \frac{C}{t^{A_1/2}} \text{ for } t > \frac{1}{\delta} \text{ and } |\alpha| \leq \frac{A_1}{2}. \tag{3.26}\end{equation}

We still make repeated use of estimation (3.25), (3.26) in what follows.

From (3.26), it follows that for $s < \frac{A_1}{2}$

\begin{equation}
\|(R v_0)(t)\|_{H^s} < \frac{C}{t^{A_1/2}} \tag{3.27}
\end{equation}

and hence, by (3.12)

\begin{equation}
\|f_0(t)\|_{x_A} < \frac{C}{t^{A_1/2}} \tag{3.28}
\end{equation}
from (3.13)

\begin{equation}
|a| = 0(R|v_0| + |v_0|^d)
\end{equation}

and hence, by (3.25), (3.26), for $|a| \leq \frac{A_1}{2}$

\begin{equation}
|D^a a(x, t)| < \frac{C}{t^{A_1/2}} + \frac{C}{t^2} < \frac{C}{t^2}.
\end{equation}

and

\begin{equation}
|e^{-s|x|} D^a b(x, t)| < \frac{C}{t^{A_1/2}}.
\end{equation}

Similarly, by (3.14)

\begin{equation}
|D^a b(x, t)| < \frac{C}{t^2}
\end{equation}

and

\begin{equation}
|e^{-s|x|} D^a b(x, t)| < \frac{C}{t^{A_1/2}}.
\end{equation}

Coming back to (3.17), rewrite the right side as

\begin{align}
- i \int_{t}^{\infty} e^{i(t-\tau)L} P_S[ f_0 + aw + b\bar{w} + G(w)](\tau) d\tau \\
+ i \int_{t}^{\infty} e^{i(t-\tau)L} P_M[ f_0 + aw + b\bar{w} + G(w)](\tau) d\tau.
\end{align}

We first verify the estimate

\begin{equation}
\|w(t)\|_{H^s} < \frac{1}{t^{A_1/4}} \quad \text{for} \quad s \leq A, \quad t \geq \frac{1}{\delta}
\end{equation}

deriving this inequality from (3.17), (3.35), (3.36).

It follows from (2.10) that

\begin{align}
\| (3.34) \|_{H^s} \\
\leq \int_{t}^{\infty} [1 + (\tau - t)^3] \left\{ \int [f_0 + aw + b\bar{w} + G(w)](x, \tau) |e^{-s|x|} dx \right\} d\tau \\
(3.37) \leq \int_{t}^{\infty} [1 + (\tau - t)^3] \left\{ \frac{C}{\tau^{A_1/2}} + \frac{C}{\tau^{A_1/2}} \|w(\tau)\|_{H^s} + C \|w(\tau)\|_{H^s}^2 \right\} d\tau
\end{align}
by (3.28), (3.31), (3.33). Reintroducing (3.36) in (3.37) gives the bound

\begin{equation}
\| (3.34) \|_{H^s} \leq \int_t^\infty \left[1 + (\tau - t)^3 \right] \frac{C}{\tau^{A_1/2}} + \frac{C}{\tau^{A_1/2}} \right] d\tau < \frac{C}{t^{A_1/2-4}} < \frac{\delta}{t^{A_1/4}}.
\end{equation}

Next, consider (3.35) and estimate from (2.9)

\begin{align*}
\| (3.35) \|_{H^s} &\leq \int_t^\infty \left[ f_0 + a w + b \bar{w} + G(w) \right] d\tau \\
&\leq \int_t^\infty \left\{ \frac{C}{\tau^{A_1/2}} + \frac{C}{\tau^2} \| w(\tau) \|_{H^s} + C \| w(\tau) \|_{H^s}^2 \right\} d\tau \\
&\leq \int_t^\infty \left\{ \frac{C}{\tau^{A_1/2}} + \frac{C}{\tau^{A_1+2}} + \frac{C}{\tau^{A_1/2}} \right\} d\tau \\
&\leq \frac{C}{t^{A_1/4+1}} < \frac{C\delta}{t^{A_1/4}}.
\end{align*}

Using (3.28), (3.30), (3.32), (3.36).

From (3.38), (3.39), the apriori bound (3.36) follows taking \( \delta \) small enough (or, alternatively, for \( \| \phi \|_{X_{A_1}} \) sufficiently small).

Next estimate the \( \| w(t) \|_{L^2(|x|^{-A} dx)} \). We verify the estimate

\begin{equation}
\| w(t) \|_{L^2(|x|^{-A} dx)} \leq \frac{C}{t^{A_1/5}} \text{ for } t > \frac{1}{\delta}.
\end{equation}

From (3.38), we also get

\begin{equation}
\| (3.34) \|_{L^2(|x|^{-A} dx)} \leq C \| (3.34) \|_2 < \frac{\delta}{t^{A_1/4}}.
\end{equation}

To estimate \( \| (3.35) \|_{L^2(|x|^{-A} dx)} \), apply (2.11). We get thus

\begin{align*}
\| (3.35) \|_{L^2(|x|^{-A} dx)} &\leq C \int_t^\infty \left[ f_0 + a w + b \bar{w} + G(w) \right] d\tau \\
&\leq C \int_t^\infty (1 + |t - \tau|^A) \| f_0 + a w + b \bar{w} + G(w) \|_{H^s} d\tau.
\end{align*}

From (3.28), (3.30), (3.32), (3.36) and (3.40), it follows

\begin{align*}
\int_t^\infty \left\{ \frac{C}{\tau^{A_1/2}} + \frac{C}{\tau^2} \| w(\tau) \|_{L^2(|x|^{-A} dx)} + C \| w(\tau) \|_{L^2(|x|^{-A} dx)} d\tau \\
&\leq \int_t^\infty \left\{ \frac{C}{\tau^{A_1/2}} + \frac{C}{\tau^{A_1/4+A_1/5}} + \frac{C}{\tau^{A_1/4+A_1/5}} \right\} d\tau < \frac{1}{t^{A_1/5}} < \frac{C\delta}{t^{A_1/5}}.
\end{align*}
For (3.43), we get from (3.36), (3.30), (3.32)

\[(3.43) \leq C \int_{t}^{\infty} \left[ 1 + (\tau - t)A \right] \left\{ \frac{C}{\tau^{A_1/2}} + C\|w(\tau)\|_{H^A} \right\} \]

\[(3.45) \leq C \int_{t}^{\infty} \tau^A \left\{ \frac{C}{\tau^{A_1/2}} + \frac{C}{\tau^{A_1/4}} \right\} d\tau < \frac{C}{t^{A_1/4 - A - 1}} < \frac{\delta}{t^{A_1/5}}
\]

taking \(A_1\) sufficiently large. Hence (3.40) holds and from (3.36), (3.40) establishing (3.7).

This completes the proof of Theorem 1' and hence Theorem 1.

Remark. The following observation will be useful in the proof to Theorem 2. Given \(\phi \in \mathcal{P}_{A_1},\ A_1\) sufficiently large depending on \(A\), the function \(w = w_\phi \in C([-\delta, 0), X_{A_1})\) in (1.23), which we constructed above, has clearly a Lipschitz dependence on \(\phi\), i.e. for \(t \in [-\delta, 0]\)

\[(3.46) \|w(t)\|_{X_{A_1}} < \frac{C}{t^{A_1/5}} < \frac{1}{t^{2A}} \quad \text{for } t > \frac{1}{\delta}
\]

establishing (3.7).

This completes the proof of Theorem 1' and hence Theorem 1.

4. – Proof of Theorem 2

We will use the following

Lemma 4.1. Let \(x_1, \ldots, x_J \in \mathbb{R}^d\) and \(t_1, \ldots, t_J \in \mathbb{R}\) be such that

\[(4.2) |x_j - x_k| \geq 1 \text{ for } 1 \leq j \neq k \leq J.
\]

Fix \(j = 1, \ldots, J\), an integer \(A\) and an index \(\alpha \in \mathbb{Z}^d, |\alpha| \leq A\). There is a Schwartz function \(\eta_{j_\alpha}\) satisfying

\[(4.3) D^\beta (e^{i\alpha x_j} \eta_{j_\alpha})(x_k) = \delta_{jk} \delta_{\alpha \beta} \text{ for } 1 \leq k \leq J, \ |\beta| \leq A.
\]

Moreover, if we restrict the system \(\{(x_j, t_j)\}\), subject to (4.2), to a bounded set, the functions \(\eta_{j_\alpha}\) are subject to uniform estimates.
PROOF. Since
\begin{equation}
  e^{it\Delta} \phi = \int e^{i(|\lambda|^2 t + \lambda x) \hat{\phi}(\lambda)} d\lambda
\end{equation}
one has
\begin{equation}
  D^\beta (e^{it\Delta} \phi)(x_k) = \int (i \lambda)^\beta e^{i(|\lambda|^2 t + \lambda x_k) \hat{\phi}(\lambda)} d\lambda.
\end{equation}
Denote by \( \psi_{k\beta}(1 \leq k \leq J, |\beta| \leq A) \) the function
\begin{equation}
  \psi_{k\beta}(\lambda) = (i \lambda)^\beta e^{i(|\lambda|^2 t_k + \lambda x_k)} \gamma(\lambda)
\end{equation}
where \( \gamma \) is a smooth, compactly supported function, such that
\begin{equation}
  \gamma(\lambda) = 1 \text{ for } |\lambda| \leq 1.
\end{equation}
The lemma will clearly follow from the fact that the system \( \{\psi_{k\beta}|1 \leq k \leq J, |\beta| \leq A\} \) consists of linearly independent functions, or equivalently
\begin{equation}
  \det((\psi_{k\beta}, \psi_{k', \beta}')) \neq 0.
\end{equation}
Assume this were not the case, then there would be coefficients \( \overline{a} = \{a_{k\beta}\} \subset \mathbb{C}, \overline{a} \neq 0 \) s.t.
\begin{equation}
  \sum a_{k\beta} \psi_{k\beta}(\lambda) = 0 \text{ for all } \lambda.
\end{equation}
Hence, by (4.7)
\begin{equation}
  \sum_k \left[ \sum_\beta a_{k\beta}(i \lambda)^\beta e^{i(|\lambda|^2 t_k + \lambda x_k)} \right] = 0 \text{ for } |\lambda| < 1.
\end{equation}
Observe that the left side of (4.10) extends to an entire function on \( \mathbb{C}^d \), which consequently vanishes identically. Using induction on the number of summands, taking (4.2) into account, and derivative considerations, one easily reaches a contradiction. The uniformity statement results from a standard compactness consideration.

COROLLARY 4.11. Let the system \( \{(x_j, t_j)\} \) be as in Lemma 4.1 and \( A, A_1 \) integers. Then, given complex numbers \( \overline{a} = (a_j, a) \), there is a Schwartz function \( \eta \) such that
\begin{equation}
  D^\alpha (e^{it_j \Delta} \eta)(x_j) = a_{j\alpha} \text{ for all } 1 \leq j \leq J, |\alpha| \leq A
\end{equation}
and
\begin{equation}
  \|\eta\|_{X_{A_1}} \leq C|\overline{a}|.
\end{equation}
In fact \( \eta = \eta_{\overline{a}} \) depends linearly on \( \overline{a} \).

The constant \( C = C(J, A, A_1) \) in (4.13) is again uniform if we restrict the system \( \{(x_j, t_j)\} \) to a bounded set, subject to condition (4.2).
We let $d = 1$ or $d = 2$ again.

**Lemma 4.14.** Fix $\varepsilon > 0$, a large integer $A$, $x_1 \in \mathbb{R}^d$, $|x_1| > 1$ and $0 > t_1 > -\delta$, $\delta$ small enough.

Then (1.1) has a blowup solution $u$ on $[-\delta, 0]$ of the form

\begin{equation}
(4.15) \quad u = \tilde{R} + u_1
\end{equation}

where $\tilde{R}$ is given by (1.8) and such that $u_1$ is smooth on $[-\delta, \delta]$, solving (1.1) on $[0, \delta]$

\begin{equation}
(4.16) \quad \|u_1(t)\|_{X_A} < \varepsilon
\end{equation}

and

\begin{equation}
(4.17) \quad D^\alpha u(x_1, t_1) = 0 \text{ for all } |\alpha| \leq A.
\end{equation}

Thus $u$ is a perturbation of $\tilde{R}$ such that (4.17) holds.

**Proof.** We will construct $u$ by an iterative process, based on Theorem 1’ and (3.47). Recall first (1.8)

\begin{equation}
(4.18) \quad \tilde{R}(x, t) = \frac{1}{t^{d/2}} e^{\frac{|x|^2 - 4}{4t}} R\left(\frac{x}{t}\right)
\end{equation}

implying that

\begin{equation}
(4.19) \quad |D^\alpha \tilde{R}(x_1, t_1)| < \frac{2^\frac{d}{2} \varepsilon}{2^{\frac{d}{2}} e^{\frac{c|x_1|^2}{4}}} < e^{-c\frac{1}{\delta}} \xrightarrow{\delta \to 0} 0.
\end{equation}

Fix $A_1$ sufficiently large. Using (4.11), take $\eta_1 \in \mathcal{S}$ satisfying

\begin{align}
(4.20) \quad D^\alpha \eta_1(0, 0) &= 0 \text{ for } |\alpha| \leq A_1 \\
(4.21) \quad D^\alpha (e^{\frac{\varepsilon t}{2}} \eta_1)(x_1) &= -D^\alpha \tilde{R}(x_1, t_1) \text{ for } |\alpha| \leq A \\
(4.22) \quad \|\eta_1\|_{X_{A_1}} &= \kappa_1 < C(A_1) e^{-c/\delta}
\end{align}

where (4.22) follows from (4.13), (4.19).

Applying Theorem 1’, cf. (3.47), with $\eta_1 \in \mathcal{P}_{A_1}$, we get $w_{\eta_1} \in C([-\delta, 0]; X_A)$ such that

\begin{equation}
(4.23) \quad U_1 = \tilde{R} + z_{\eta_1} + w_{\eta_1}
\end{equation}

solves (1.1) on $[-\delta, 0]$ and

\begin{equation}
(4.24) \quad \|w_{\eta_1}(t)\|_{X_{A+2}} < C|t|^A \|\eta_1\|_{X_{A_1}}
\end{equation}
From (4.22), we estimate for $|\alpha| \leq A$

$$|\text{(4.25)}| < \left\| \int_0^1 e^{i(t_1-t)d}(z_{\eta_1}|z_{\eta_1}|^{4/d})\eta d\tau \right\|_{H^{|\alpha|+2}} < C|t_1|\|z_{\eta_1}\|^{4/d+1}_{H^{|\alpha|+2}}$$

(4.27) 

$$< C\delta\|\eta_1\|^{4/d+1}_{X_{A+2}} < C\delta\kappa_1^{4/d+1}$$

and from (4.22), (4.24)

$$|\text{(4.26)}| < \|w_{\eta_1}(t_1)\|_{H^{|\alpha|+2}} < \|w_{\eta_1}(t_1)\|_{X_{A+2}} < C\delta^A\kappa_1.$$  

(4.28)

Replacing $U_0 = \tilde{R}$ by $U_1$, (4.27), (4.28) give thus

$$|D^\alpha U_1(x_1, t_1)| < \delta\kappa_1$$ for $|\alpha| \leq A.$

(4.29)

Choose next $\eta_2 \in S$ such that

$$D^\alpha\eta_2(0, 0) = 0 \text{ for } |\alpha| \leq A_1$$

(4.30)

$$D^\alpha(e^{it\Delta}\eta_2)(x_1) = -D^\alpha U_1(x_1, t_1) \text{ for } |\alpha| \leq A$$

(4.31)

$$\|\eta_2\|_{X_{A_1}} = \kappa_2 < C(A_1)\delta\kappa_1 < \delta_1^{1/2} \kappa_1$$

(4.32)

applying again (4.11). Considering $\eta_1 + \eta_2 \in P_{A_1}$, we get $w_{\eta_1+\eta_2}$ s.t.

$$U_2 = \tilde{R} + z_{\eta_1+\eta_2} + w_{\eta_1+\eta_2}$$

(4.33)

solves (1.1) on $[-\delta, 0[$ and, by (3.47),

$$\|w_{\eta_1+\eta_2}(t) - w_{\eta_1}(t)\|_{X_{A+2}} < C|t|^A\|\eta_2\|_{X_{A_1}}.$$  

(4.34)

We have

$$U_2 = U_1 + z_{\eta_1+\eta_2} - z_{\eta_1} + w_{\eta_1+\eta_2} - w_{\eta_1}$$

$$= U_1 + e^{it\Delta}\eta_2 + i\int_{t_1}^0 e^{i(t_1-\tau)\Delta}(z_{\eta_1+\eta_2}|z_{\eta_1+\eta_2}|^{4/d} - z_{\eta_1}|z_{\eta_1}|^{4/d})(\tau)d\tau$$

$$+ w_{\eta_1+\eta_2} - w_{\eta_1}.$$  

(4.35)
Thus (4.35) gives for $|x| \leq A$, by (4.31), (4.34), (4.32)

$$|D^\alpha U_2(x_1, t_1)| \leq \int_{t_1}^0 \| (z_{\eta_1+\eta_2} |z_{\eta_1+\eta_2}|^{4/d} - z_{\eta_1} |z_{\eta_1}|^{4/d}) (\tau) \|_{H^{2d+2}} + C |t_1|^A \kappa_2$$

$$< C \delta \kappa_1^{4/d} \|z_{\eta_2} - z_{\eta_2}\|_{H^{2d+2}} + C \delta^A \kappa_2$$

$$< \delta \kappa_2$$

(4.36)

The continuation of the process is clear. In general

$$U_{\eta} = \tilde{R} + z_{\eta \eta_1 + \cdots + \eta_2} + w_{\eta_1 + \cdots + \eta_2}$$

solves (1.1) on $[-\delta, 0]$, where

$$\eta = \lim_{s \to \infty} (\eta_1 + \cdots + \eta_s) \text{ in } X_{A_1}$$

$$z_{\eta} = \lim_{s \to \infty} z_{\eta_1 + \cdots + \eta_s} \text{ in } C([-\delta, \delta] : X_{A_1})$$

solves (1.1) on $[0, \delta]$ and

$$w_{\eta} = \lim_{s \to \infty} w_{\eta_1 + \cdots + \eta_s} \text{ in } C([-\delta, 0]; X_{A+2})$$

satisfies

$$\|w_{\eta}(t)\|_{X_{A+2}} \leq C \kappa_1 |t|^A.$$  

(4.41)

Thus, by construction

$$u = \lim_{\eta \to 0} U_{\eta} = \tilde{R} + z_{\eta} + w_{\eta} = \tilde{R} + u_1$$

satisfies (4.17) and

$$\|u_1(t)\|_{X_{A}} \leq \|\eta\|_{X_{A_1}} + \|w_{\eta}(t)\|_{X_{A+2}} < \kappa_1 \to 0 \text{ for } \delta \to 0$$

(4.43)

so that the conditions of Lemma 4.14 hold.

**Proof of Theorem 2.** We let $(x_0, t_0) = (0, 0)$, $0 < |t_1| < \delta$ and apply Lemma 4.14 to get a blowup solution $U$ on $[-2\delta, 0]$ of the form

$$U = \tilde{R} + U_1$$

(4.44)

such that $U_1$ is smooth on $[-2\delta, 2\delta]$, solving (1.1) on $[0, 2\delta]$ and

$$\|U_1(t)\|_{X_{A_1}} \leq 1, \quad |t| < 2\delta$$

(4.45)
(4.46) \[ D^\alpha U(x_1, t_1) = 0 \text{ for all } |\alpha| \leq A_1. \]

Thus, by (4.45), (4.46)

(4.47) \[ \phi = U(\cdot - x_1, t_1) = \tilde{R}(\cdot - x_1, t_1) + U_1(\cdot - x_1, t_1) \]

is in \( \mathcal{P}_{A_1} \); the bounds on \( \|\phi\|_{A_1} \) depending obviously on \( |t_1| \). Application of Theorem 1' yields for

(4.48) \[ t_1 > t_2, \ t_1 - t_2 < \delta(|t_1|) < \delta \]

a blowup solution \( U' \) on \([t_2, t_1[\) of the form

(4.49) \[ U' = \tilde{R}_1 + U + w \]

where

(4.50) \[ w \in C([t_2, t_1]; X_A), \ \|w(t)\|_{X_A} \leq |t - t_1|^A. \]

Extend \( w \) to \([t_2, \infty[\) by letting \( w(t) = 0 \) for \( t > t_1 \), cf. (4.50). Define

(4.51) \[ u(t) = \begin{cases} U(t) & \text{for } t \in ]t_1, 0[ \\ U'(t) & \text{for } t \in ]t_2, t_1[ \end{cases} \]

clearly satisfying the conditions of Theorem 2.

REFERENCES


Institute for Advanced study
Princeton, New Jersey
bourgain@math.ias.edu
and
University of Illinois at Urbana-Champaign

University of Southern California
wensheng@math.usc.edu
and
Institute for Advanced Study
Princeton, New Jersey
wwang@math.ias.edu