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## On Relatively Bounded Perturbations of Linear $C_0$ -Semigroups.

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In recent years we see an increasing interest and literature devoted to various system-theoretical investigations of systems of the form

$$\begin{aligned} \frac{d}{dt} x(t) &= Ax(t) + Du(t), \quad t > 0, \\ x(0) &= x_0. \end{aligned}$$

Here  $A$  is the infinitesimal generator of a linear  $C_0$ -semigroup  $T(\cdot)$  on a Banach space  $X$  and  $D$  is a continuous linear operator from the Banach-space of control parameters into  $X$ . Of particular interest are problems concerning controllability, observability, boundary control etc. If the control is implemented through a feedback relation and we deal with the realistic case of having only a finite number of controls available, we face the following problem raised for instance in [11], p. 105:

Let  $A$  be the infinitesimal generator of a  $C_0$ -semigroup  $T(\cdot)$  on  $X$  and let  $B$  be a linear operator in  $X$  satisfying

- (i) Range ( $B$ ) is finite-dimensional and
- (ii)  $B$  is  $A$ -bounded, i.e.  $D(B) \supset D(A)$  and there are nonnegative constants  $a$  and  $b$  such that  $\|Bx\| \leq a\|Ax\| + b\|x\|$  for all  $x \in D(A)$ .

Under which assumptions is  $(A + B)$  the infinitesimal generator of a  $C_0$ -semigroup on  $X$ ?

If  $X$  is reflexive, then Hess proved in [6] that (i)-(ii) imply that the  $A$ -bound of  $B$  is zero and hence we can apply a general perturbation result

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(Kato [8], p. 499) to conclude that if  $A$  generates an analytic semigroup so does  $(A + B)$ . (See also Zabczyk [12]).

A similar problem arises in the context of the semigroup approach to functional differential equations in the state space

$$X = \mathbf{R}^n \times L^p(-r, 0; \mathbf{R}^n) \quad \text{with } 0 < r < \infty \text{ and } 1 \leq p < \infty.$$

Given a linear map  $L: X \supset D(L) \rightarrow \mathbf{R}^n$  we consider the Cauchy-problem

$$(1) \quad \begin{aligned} \frac{d}{dt} x(t) &= L(x(t), x_t), \quad t > 0, \\ x(0) &= \eta, \quad x(s) = \phi(s) \quad \text{a.e. on } -r \leq s < 0. \end{aligned}$$

The « history »  $x_t$  is given by  $x_t(s) = x(s + t)$ ,  $t \geq 0$ ,  $s \in [-r, 0]$ .

If  $x(t, \eta, \phi)$  denotes the solution of (1) we define the associated solution semigroup  $T(\cdot)$  by  $T(t)(\eta, \phi) = (x(t), x_t)$ . In [7] it was shown that the infinitesimal generator  $A$  of this semigroup is given by

$$\begin{aligned} D(A) &= \{(\phi(0), \phi) \mid \phi \in W^{1,p}(-r, 0, \mathbf{R}^n)\}, \\ A(\phi(0), \phi) &= (L(\phi(0), \phi), \dot{\phi}). \end{aligned}$$

Obviously,  $A$  can be split up as  $A = A_0 + B$  where

$$A_0(\phi(0), \phi) = (0, \dot{\phi}), \quad B(\phi(0), \phi) = (L(\phi(0), \phi), 0).$$

Delfour [5] proved that this operator  $A$  is the infinitesimal generator of a  $C_0$ -semigroup iff  $L$  is a continuous map  $D(A_0) \rightarrow \mathbf{R}^n$ , i.e. (i) and (ii) hold. Thus it seems to be attractive to conjecture that (i) and (ii) imply that  $(A + B)$  is the infinitesimal generator also for non-analytic semigroups.

It is the objective of this paper to show that the above conjecture is false even if the unperturbed semigroup is ultimately compact, differentiable or a  $C_0$ -group in a Hilbert-space!

On the other hand, we verify that if  $B$  satisfies an additional continuity assumption then  $(A + B)$  is the infinitesimal generator of a  $C_0$ -semigroup on  $X$  without any restriction on the range of  $B$ .

### Some counterexamples.

To begin with, we provide some counterexamples to the above mentioned conjecture. Let  $X = l^2$ . Given a sequence  $(\lambda_n)$  of complex numbers so that  $\text{Re } \lambda_n < 0$  for all  $n$  it is clear that the linear operator  $A = \text{diag } (\lambda_n)$  is the infinitesimal generator of a  $C_0$ -semigroup  $S(\cdot)$  given by  $S(t) = \text{diag } (\exp [\lambda_n t])$ .

Next, define a linear operator  $B$  in  $X$  by

$$(Bx)_n = \alpha_n \sum_{j=1}^{\infty} \alpha_j \lambda_j x_j$$

with  $\alpha = (\alpha_j) \in l^2(\mathbf{R})$  is chosen so that  $B$  is  $A$ -bounded and  $\limsup_{n \rightarrow \infty} \alpha_n^2 |\lambda_n| \cdot \exp [\operatorname{Re} \lambda_n] = \infty$ . The specific choice of  $(\lambda_n)$  and  $(\alpha_n)$  is still at our disposal.

We claim that the operator  $\mathcal{A} = \begin{pmatrix} A & B \\ 0 & A \end{pmatrix}$  cannot be the infinitesimal generator of a  $C_0$ -semigroup on  $X \times X$ . Infact, if  $\mathcal{A}$  were the infinitesimal generator of a  $C_0$ -semigroup  $\mathfrak{T}(\cdot)$  on  $X \times X$  we consider the elements  $y_m = (\delta_{m,k})_{k=1, \dots} \in X$ . As  $y_m \in D(A^\infty)$  we infer that  $t \rightarrow S(t)y_m \in C^\infty(0, \infty; D(A))$  and hence  $BS(t)y_m \in C^\infty(0, \infty; X)$ .

Consequently,

$$\tilde{x}(t) = \begin{pmatrix} \int_0^t S(t-s)BS(s)y_m ds \\ S(t)y_m \end{pmatrix}$$

would be a strong solution of the Cauchy-problem  $(d/dt)\tilde{x}(t) = \mathcal{A}\tilde{x}(t)$ .

Being a  $C_0$ -semigroup there must exist a constant  $M$  so that  $\|\mathfrak{T}(t)\| \leq M$  for  $0 \leq t \leq 1$ . In particular we thus would expect that  $\left\| \mathfrak{T}(1) \begin{pmatrix} 0 \\ y_m \end{pmatrix} \right\| \leq M$ , and in particular

$$(2) \quad \left| \left( \int_0^1 S(1-s)BS(s)y_m ds \right)_m \right| \leq M.$$

The left hand side of this inequality can be rewritten as

$$\int_0^1 \exp [(1-s)\lambda_m] \alpha_m \lambda_m \alpha_m \exp [s\lambda_m] ds = \exp [\lambda_m] \alpha_m^2 \lambda_m$$

and as by assumption  $\limsup_{m \rightarrow \infty} [\operatorname{Re} \lambda_m] \alpha_m^2 |\lambda_m| = \infty$  we see that we cannot have an estimate of the form (2), i.e.  $\mathfrak{T}(\cdot)$  is not a  $C_0$ -semigroup.

We now specify the  $(\lambda_m)$  and  $(\alpha_m)$ :

1. *The case of  $C_0$ -group.*

Let  $\lambda_m = im, m = 1, 2, \dots$ . Then  $A = -A^*$  and so  $\begin{pmatrix} A & 0 \\ 0 & A \end{pmatrix}$  generate a

$C_0$ -group on  $X$ . Putting

$$\alpha_m = \begin{cases} m^{-\frac{1}{2}} & \text{if } m^{\frac{1}{2}} \text{ is an integer} \\ 0 & \text{otherwise} \end{cases}$$

we see that  $\alpha = (\alpha_m) \in l^2(\mathbb{R})$ .

Moreover,

$$\alpha_m^2 |\lambda_m| \exp[\operatorname{Re} \lambda_m] = \begin{cases} m^{\frac{1}{2}} & \text{if } m^{\frac{1}{2}} \text{ is an integer} \\ 0 & \text{otherwise} \end{cases}$$

and hence  $\limsup_{m \rightarrow \infty} \alpha_m^2 |\lambda_m| \exp[\operatorname{Re} \lambda_m] = \infty$ .

The associated operator  $B$  clearly satisfies (i), (ii) but according to the above consideration  $\mathcal{A} + B$  is not an infinitesimal generator.

## 2. The case of an ultimately compact and differentiable semigroup.

Let  $\lambda_m = -m + i \exp[4m]$  and set  $\alpha_m = \exp[-m]$ . Then we obtain  $\alpha_m^2 |\lambda_m| \exp[\operatorname{Re} \lambda_m] \geq \exp[m] \rightarrow \infty$  as  $m \rightarrow \infty$  and so again the associated operator  $\begin{pmatrix} A & B \\ 0 & A \end{pmatrix}$  cannot be an infinitesimal generator. In order to show that  $S(\cdot)$  is differentiable for  $t \geq 4$  it is sufficient to verify that  $\lambda_m \exp[\lambda_m t]$  is bounded for  $t \geq 4$ . This follows from

$$|\lambda_m \exp[\lambda_m t]| = |-m + i \exp[4m]| \exp[-mt] \leq m \exp[-mt] + \exp[m(4-t)].$$

It is also obvious that  $S(\cdot)$  is compact for  $t \geq 4$ .

## Some generation results.

As already pointed out in the introduction, we present a general generation result that seems to be very useful in applications. Throughout this section, we assume that  $(X, \|\cdot\|)$  is a Banach-space. If  $A$  is a closed linear operator in  $X$  we let  $X_A$  stand for the Banach space  $(D(A), |\cdot|_A)$ , with  $|x|_A = \|x\| + \|Ax\|$ .

**THEOREM.** Let  $A$  be the infinitesimal generator of a  $C_0$ -semigroup  $T(\cdot)$  on  $X$ . Let  $(Z, |\cdot|_Z)$  be a Banach space such that

(Z1)  $Z$  is continuously embedded in  $X$ ,

(Z2) there is a  $t_0 > 0$  so that for all continuous functions

$$\phi: [0, t_0] \rightarrow Z \quad \text{we have } \int_0^t T(t-s)\phi(s)ds \in D(A) \quad \text{for all } t \in [0, t_0]$$

(Z3) there is an increasing continuous function  $\gamma: [0, t_0] \rightarrow [0, \infty)$  satisfying  $\gamma(0) = 0$  and

$$\left| \int_0^t T(t-s)\phi(s)ds \right|_A \leq \gamma(t) \sup_{0 \leq s \leq t} |\phi(s)|_Z.$$

Then for any continuous linear operator  $B: X_A \rightarrow Z$ ,  $(A + B)$  is the infinitesimal generator of a  $C_0$ -semigroup on  $X$ .

PROOF. To begin with, we verify that under the above assumptions the map  $t \rightarrow \int_0^t T(t-s)\phi(s)ds$  is continuous from  $[0, t_0]$  into  $X_A$ : In fact, given any continuous  $\phi: [0, t_0] \rightarrow Z$  and  $t \in [0, t_0]$ , we define for all  $0 \leq h \leq t$

$$\phi_h(s) = \begin{cases} \phi(s-h) & \text{for } h \leq s \leq t+h \\ 0 & \text{otherwise.} \end{cases}$$

Then we obtain for all  $t \in [0, t_0 - h]$

$$\begin{aligned} & \left| \int_0^{t+h} T(t+h-s)\phi(s)ds - \int_0^t T(t-s)\phi(s)ds \right|_A \\ &= \left| \int_0^{t+h} T(t+h-s)(\phi(s) - \phi_h(s))ds \right|_A \\ &\leq \left| \int_h^{t+h} T(t+h-s)(\phi(s) - \phi_h(s))ds \right|_A + \left| \int_0^h T(t+h-s)(\phi(s) - \phi_h(s))ds \right|_A \\ &\leq \gamma(t) \sup |\phi(s+h) - \phi(s)|_Z + |T(t)|_A \gamma(h) \sup |\phi(s) - \phi_h(s)|_A. \end{aligned}$$

As the right side converges to 0 for  $h \rightarrow 0$ , the claim follows.

In the next step we verify that  $(A + B)$  is a closed linear operator. To this end, we first estimate  $(\lambda I - A)^{-1}B$  as an operator from  $X_A$  into  $X_A$ . Let  $N$  and  $\omega$  be constants such that

$$\|T(t)\| \leq N \exp[\omega t] \quad \text{for all } t \geq 0.$$

Then we obtain for all sufficiently large  $\lambda$  and all  $x \in D(A)$

$$\begin{aligned} & |(\lambda I - A)^{-1} Bx|_A \\ &= \left| \int_0^t \exp[-\lambda s] T(s) Bx ds + \exp[-\lambda t] T(t) \int_0^\infty \exp[-\lambda s] T(s) Bx ds \right|_A \\ &\leq \exp[-\lambda t] \left| \int_0^t T(t-s) (\exp[\lambda s] Bx) ds \right|_A + N \exp[(\omega - \lambda)t] |(\lambda I - A)^{-1} Bx|_A \\ &\leq \gamma(t) \sup |\exp[\lambda s] Bx|_Z + N \exp[(\omega - \lambda)t] |(\lambda I - A)^{-1} Bx|_A. \end{aligned}$$

Putting

$$t(\lambda) = \frac{\ln N + \ln 2}{\lambda - \omega}$$

we obtain

$$|(\lambda I - A)^{-1} Bx|_A \leq 2\gamma(t(\lambda)) \beta |x|_A,$$

where  $\beta$  denotes the norm of  $B$  regarded as an operator from  $X_A$  into  $Z$ , and as  $t(\lambda) \rightarrow 0$  as  $\lambda \rightarrow \infty$  we deduce that

$$K(\lambda) = 2\gamma(t(\lambda)) \quad \text{converges to } 0 \quad \text{as } \lambda \rightarrow \infty.$$

In order to prove that  $(A + B)$  is closed, let  $(x_n)$  be a sequence in  $X_A$  such that  $x_n \rightarrow x$  (in  $X$ ) and  $y_n := (A + B)x_n$  converges to  $y \in X$ . We have to show that  $(x_n)$  is a Cauchy sequence in  $X_A$ : Fix some  $\lambda > 0$  with  $K(\lambda) < 1$ . Then we have

$$\begin{aligned} |x_n - x_m|_A &= |\lambda(\lambda I - A)^{-1}(x_n - x_m) - (\lambda I - A)^{-1}A(x_n - x_m)|_A \\ &= |\lambda(\lambda I - A)^{-1}(x_n - x_m) - (\lambda I - A)^{-1}(y_n - y_m) + (\lambda I - A)^{-1}B(x_n - x_m)|_A \\ &\leq q\lambda \|x_n - x_m\| + q \|y_n - y_m\| + K(\lambda) |x_n - x_m|_A, \end{aligned}$$

where  $q$  denotes the norm of  $(\lambda I - A)^{-1}$  regarded as an operator from  $X$  into  $X_A$ .

Consequently, we obtain

$$|x_n - x_m|_A \leq \frac{1}{1 - K(\lambda)} (\lambda q \|x_n - x_m\| + q' \|y_n - y_m\|).$$

This implies that  $y_n = (A + B)x_n$  converges to  $(A + B)x$  so that  $(A + B)x = y$ . The proof that  $(A + B)$  is infact the infinitesimal generator of a  $C_0$ -semi-

group on  $X$  is performed by making use of Ball's Theorem ([1]). Roughly speaking, we are to show that for any  $x \in X$  the Cauchy problem

$$(3) \quad \begin{aligned} \frac{d}{dt} x(t) &= (A + B)x(t), \quad t > 0 \\ x(0) &= x, \end{aligned}$$

admits a unique weak solution  $x(t)$  on  $[0, \infty)$ , i.e. for all  $x^* \in D((A + B)^*)$  and  $t \geq 0$

$$\langle x(t), x^* \rangle = \langle x, x^* \rangle + \int_0^t \langle x(s), (A + B)^* x^* \rangle ds.$$

So, fix  $x \in X$  and  $\hat{t} > 0$ . Given any continuous function  $z: [0, \hat{t}] \rightarrow X_A$  we put

$$(\mathfrak{C}z)(t) = \int_0^t T(t-s)Bz(s)ds + \int_0^t T(t-s)xds, \quad 0 \leq t \leq \hat{t}.$$

By the above considerations  $(\mathfrak{C}z)(\cdot)$  is a continuous function  $[0, \hat{t}] \rightarrow X_A$ . If  $\beta$  denotes again the norm of  $B$  regarded as an operator  $X_A \rightarrow Z$ , we obtain for all  $0 \leq t \leq \hat{t}$ :

$$|\mathfrak{C}z_1(t) - \mathfrak{C}z_2(t)|_A \leq \beta\gamma(t) \sup |z_1(s) - z_2(s)|_A.$$

Choosing  $\hat{t}$  sufficiently small we conclude that there exists a unique fixed point of  $\mathfrak{C}$ . As  $\beta\gamma(t)$  does not depend on  $x$ , we may continue this procedure and obtain a continuous function  $y: [0, \infty) \rightarrow X_A$  satisfying

$$y(t) = \int_0^t T(t-s)By(s)da + \int_0^t T(t-s)xds.$$

Putting  $x(t) = (A + B)y(t) + x$ , it is clear that  $x(0) = x$  and  $x$  is continuous  $[0, \infty) \rightarrow X$ . Moreover, we have for all  $h > 0$

$$\begin{aligned} \frac{1}{h} (y(t+h) - y(t)) &= \frac{1}{h} \left( \int_0^{t+h} T(t+h-s)(x + By(s)) ds - \int_0^t T(t-s)(x + By(s)) ds \right) \\ &= \frac{1}{h} (T(h) - I) \int_0^t T(t-s)(x + By(s)) ds + \frac{1}{h} \int_t^{t+h} T(t+h-s)(x + By(s)) ds. \end{aligned}$$



and as  $y(t) \in D(A)$ , the right hand side converges to  $Ay(t) + x + By(t)$  as  $h \rightarrow 0^+$ . Therefore, we have

$$\frac{d^+}{dt} y(t) = (A + B)y(t) + x = x(t).$$

For any  $x^* \in D((A + B)^*)$  we obtain

$$\langle x(t), x^* \rangle = \langle x, x^* \rangle + \langle y(t), (A + B)^* x^* \rangle$$

and hence  $x(t)$  is a weak solution of (3).

In order to verify uniqueness of this weak solution, let  $x(\cdot)$  be any weak solution of (3) with  $x(0) = 0$ . Putting

$$y(t) = \int_0^t x(s) ds,$$

we get for all  $x^* \in D((A + B)^*)$

$$\langle x(t), x^* \rangle = \int_0^t \langle x(s), (A + B)^* x^* \rangle ds = \langle y(t), (A + B)^* x^* \rangle.$$

As  $(A + B)$  is closed, this implies that  $y(\cdot) \in D(A)$  and hence

$$x(t) = \frac{d}{dt} y(t) = (A + B)y(t).$$

From the variation of constants formula for  $T(\cdot)$  we get

$$y(t) = \int_0^t T(t-s)By(s)ds.$$

The unique solution of this integral equation is  $y = 0$  and hence  $x = 0$ .

Hence (3) admits a unique weak solution for all  $x \in X$  showing that  $(A + B)$  is the infinitesimal generator of a  $C_0$ -semigroup on  $X$ .

The particular choice of  $Z$  depends of course, heavily on the problem under consideration and it may vary through a large class of different spaces and is illustrated by the following examples.

1.  $Z = X_A$ .

A particular interesting case of  $Z$  is provided by putting  $Z = X_A$ . Clearly, assumptions (Z1)-(Z3) are satisfied (with  $\gamma(t) = tM \exp[\omega t]$ ), and hence we deduce that for any continuous linear operator  $B: X_A \rightarrow X_A$  the operator  $(A + B)$  is the infinitesimal generator of a  $C_0$ -semigroup on  $X$ .

2. Delay equations on product spaces.

Let  $Y$  be a real Banach space and put  $X = Y \times L^p(-r, 0; Y)$ ,  $1 \leq p < \infty$ ,  $0 < r < \infty$ . Let  $T(\cdot)$  denote the solution semigroup of the unperturbed equation given by

$$T(t)(\eta, \varphi) = (\eta, \psi)$$

$$\psi(s) = \begin{cases} \eta & \text{if } s + t \geq 0 \\ \varphi(s + t) & \text{if } s + t < 0. \end{cases}$$

As already mentioned in the introduction its infinitesimal generator  $A$  is given by

$$D(A) = \{(u(0), u) \mid u \in W^{1,p}(-r, 0; Y)\},$$

$$A(u(0), u) = (0, \dot{u}).$$

Then the assumptions of the generation theorem are satisfied with  $Z = Y \times \{0\}$ . Therefore, for any linear operator  $B$  that maps  $W^{1,p}(-r, 0; Y)$  continuously into  $Y$  the operator  $(A + B)$  is an infinitesimal generator of a  $C_0$ -semigroup on  $X$ .

PROOF. For any  $t > 0$  let  $\varphi$  be a continuous function  $[0, t] \rightarrow Y$ . Define  $\psi$  by

$$\psi(s)(\theta) = \begin{cases} \varphi(s) & \text{if } \theta \geq s - t, \\ 0 & \text{otherwise.} \end{cases}$$

Then for all  $\theta \in [-r, 0]$  we have

$$\int_0^t \psi(s)(\theta) ds = \int_0^{t+\theta} \varphi(s) ds,$$

$$\left( \int_0^t \psi(s) ds, \int_0^t \varphi(s) ds \right) = \int_0^t T(t-s)(\psi(s), \varphi(s)) ds \in D(A)$$

and since

$$\left( \int_{-r}^0 |\tilde{\varphi}(s+t)|^p ds \right)^{1/p} \leq t^{1/p} \sup |\varphi(\tau)|$$

where

$$\tilde{\varphi}(s) = \begin{cases} \varphi(s) & \text{for } s \geq 0, \\ 0 & \text{otherwise,} \end{cases}$$

also (Z3) is satisfied.

Thus it is not the finite-dimensional range property of the perturbation that ensures the generation of a  $C_0$ -semigroup. Of course, the above condition is too restrictive for partial-differential equations involving delay terms, although they are not far away from being necessary ([9]).

We next turn to partial differential equations: To begin with we provide

### 3. The Favard-class of $T(\cdot)$ .

Let  $A$  be the infinitesimal generator of a  $C_0$ -semigroup  $T(\cdot)$  on  $X$ . Then the assumptions of the theorem are satisfied for  $Z$  being the Favard class of  $T(\cdot)$ , i.e.

$$Z = \left\{ x \in X \mid \limsup_{t \rightarrow 0^+} \frac{1}{t} \|T(t)x - x\| \text{ is finite} \right\},$$

$$|x|_Z = \|x\| + \limsup_{t \rightarrow 0^+} \frac{1}{t} \|T(t)x - x\|.$$

PROOF. Let  $\varphi$  be a continuous function  $[0, t] \rightarrow Z$ . Then there is a sequence  $(\varphi_n)$  of continuously differentiable functions such that  $\varphi_n \rightarrow \varphi$  as  $n \rightarrow \infty$ . Clearly,  $\int_0^t T(t-s)\varphi_n(s)ds \in D(A)$ , and

$$\left\| A \int_0^t T(t-s)\varphi_n(s)ds \right\| \leq \limsup_{h \rightarrow 0^+} \int_0^t \frac{1}{h} \|(T(h) - I)T(t-s)\varphi_n(s)ds\|$$

$$\leq M \exp[\omega t] \int_0^t |\varphi_n(s)|_Z ds \leq tM \exp[\omega t] \sup |\varphi_n|_Z.$$

(Here  $M$  and  $\omega$  are constants such that  $\|T(t)\| \leq M \exp[\omega t]$  for all  $t \geq 0$ ). A closedness argument now shows that the same estimate is also valid for  $\varphi$ .

An interesting application of this result is

### 4. Integrodifferential equations.

Let  $Y$  be a Banach space and consider the Cauchy problem

$$(4) \quad \frac{d}{dt} u(t) = Lu(t) + \int_0^t C(t-s)u(s)ds + f(t), \quad t \geq 0,$$

$$u(0) = u_0.$$

Here  $L$  is the infinitesimal generator of a  $C_0$ -semigroup  $S(\cdot)$  on  $Y$  and  $\{C(t); t \geq 0\}$  is a family of continuous linear operators  $X_L \rightarrow Y$  such that for each  $x \in X_L$  the map  $Cx$  given by  $(Cx)(t) = C(t)x$  belongs to  $L^1(0, \infty; Y)$ .

Following the notation used in [3], we say that (4) is uniformly well posed if for each  $u_0 \in D(L)$  and each  $f \in W^{1,1}(0, \infty; Y)$  then exists a unique strong solution  $u(t, u_0; f)$  of (4) which depends continuously on  $u_0$  (with respect to the  $Y$ -norm) and  $f$  (with respect to the  $L^1$ -norm), uniformly for  $t$  in compact intervals.

There is a large number of papers in which uniform well-posedness of (4) is proven under various additional smoothness assumptions on  $C(\cdot)$ . Our approach allows the following very general result:

**THEOREM.** (4) is uniformly well-posed if  $Cx$  is of bounded variation for each  $x \in D(L)$ .

The underlying basic idea that was introduced in [10] and carried out in a more general framework in [3] is to associate to (4) a differential equation in a larger Banach space.

To this end, let  $T(\cdot)$  denote the shift semigroup on  $L^1(0, \infty; Y)$  defined by  $(T(t)\phi)(s) = \phi(s + t)$ ,  $s \geq 0, t \geq 0$ . Moreover, let  $D_s$  denote its infinitesimal generator and let  $\delta$  be the operator  $W^{1,1}(0, \infty; Y) \rightarrow Y$  given by  $(\delta\phi = \phi(0))$ .

In [3] it is shown that (4) is uniformly well-posed if and only if the following abstract Cauchy problem is uniformly well-posed in  $X = Y \times Y \times L^1(0, \infty; Y)$

$$(5) \quad \begin{aligned} \frac{d}{dt} x(t) &= \mathcal{A}x(t), \quad t \geq 0, \\ x(0) &= x_0, \end{aligned}$$

where  $\mathcal{A}$  is given by

$$\begin{aligned} D(\mathcal{A}) &= Y \times D(L) \times W^{1,1}(0, \infty; Y), \\ \mathcal{A} &= \begin{pmatrix} 0 & L & 0 \\ 0 & L & \delta \\ 0 & C & D_s \end{pmatrix}. \end{aligned}$$

So, we have to show that  $\mathcal{A}$  is the infinitesimal generator of a  $C_0$ -semigroup on  $X$ . To prove this claim, we split up  $\mathcal{A}$  as

$$\mathcal{A} = \mathcal{A}_0 = \mathcal{B}$$

where

$$\mathcal{A}_0 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & L & \delta \\ 0 & 0 & D_s \end{pmatrix} \quad \text{and} \quad \mathcal{B} = \begin{pmatrix} 0 & L & 0 \\ 0 & 0 & 0 \\ 0 & C & 0 \end{pmatrix}.$$

It is an elementary calculation to verify that  $\mathcal{A}_0$  generates a semigroup  $\mathfrak{G}(\cdot)$  given by

$$\mathfrak{G}(t) \begin{pmatrix} x \\ y \\ f \end{pmatrix} = \begin{pmatrix} x \\ S(t)y + \int_0^t S(t-s)f(s) ds \\ T(f)t \end{pmatrix}.$$

The range of  $\mathfrak{B}$  consists of all vectors  $\begin{pmatrix} x \\ 0 \\ f \end{pmatrix}$  where  $f$  is of bounded variation. If we can verify that these vectors belong to the Favard class of  $\mathfrak{G}(\cdot)$ . Example 2 implies that  $\mathcal{A}$  generates a  $C_0$ -semigroup on  $X$  and hence (4) is uniformly well-posed.

As

$$\frac{1}{t} \left( \mathfrak{G}(t) \begin{pmatrix} x \\ 0 \\ f \end{pmatrix} - \begin{pmatrix} x \\ 0 \\ f \end{pmatrix} \right) = \left( 0, \frac{1}{t} \int_0^t S(t-s)f(s) ds, \frac{1}{t} (T(t)f - f) \right)^x$$

and

$$\frac{1}{t} \left\| \int_0^t S(t-s)f(s) ds \right\| \leq \sup_{0 \leq s \leq t} \|S(t-s)\| \|f(s)\|$$

is bounded as  $f$  has bounded variation, and

$$\frac{1}{t} \|T(t)f - f\| = \frac{1}{t} \int_0^\infty \|f(s+t) - f(s)\| ds \leq \text{Var}(f, (0, \infty))$$

([2], Appendix), we conclude that

$$\limsup_{t \rightarrow 0^+} \frac{1}{t} \left\| \mathfrak{G}(t) \begin{pmatrix} x \\ 0 \\ f \end{pmatrix} - \begin{pmatrix} x \\ 0 \\ f \end{pmatrix} \right\| \text{ is finite.}$$

##### 5. Interpolation spaces.

Let  $A$  be the infinitesimal generator of an analytic semigroup  $T(\cdot)$ . Then we can take  $Z = (D(A), X)_I$ , an interpolation space between  $D(A)$  and  $X$ .

The proof follows from the general properties of interpolation spaces (see [4]).

If we are dealing with nonlinear perturbations then the situation is much more complicated as is seen by the following example. Roughly speaking, we show that even for a one-dimensional,  $C^\infty$ -nonlinear perturbation  $B$  that maps  $X_A$  into itself the operator  $(A + B)$  is not a generator of a non-linear semigroup on  $X$ .

EXAMPLE. Let  $X = \mathbf{R} \times C_{u,b}(\mathbf{R}; \mathbf{R})$ , where  $C_{u,b}(\mathbf{R}; \mathbf{R})$  denotes the usual Banach space of all uniformly continuous, bounded functions  $\mathbf{R} \rightarrow \mathbf{R}$ .

Let  $T(\cdot)$  be the linear semigroup given by  $T(t) \begin{pmatrix} x \\ \varphi \end{pmatrix} = \begin{pmatrix} x \\ \varphi(t + \cdot) \end{pmatrix}$ .

An easy calculation shows that its infinitesimal generator  $A$  is given by

$$D(A) = \left\{ \begin{pmatrix} x \\ \varphi \end{pmatrix} \mid \varphi' \in C_{u,b}(\mathbf{R}; \mathbf{R}) \right\}$$

$$A \begin{pmatrix} \varphi \\ x \end{pmatrix} = \begin{pmatrix} 0 \\ \varphi' \end{pmatrix}.$$

Let  $\psi$  be a  $C^\infty$ -function  $\mathbf{R} \rightarrow \mathbf{R}$  such that

$$\psi(0) = 0, \quad \psi(s) \geq \inf(|s|, s^2),$$

and  $\psi$  is Lipschitzian with constant  $\leq 2$ .

We define  $B$  by  $B \begin{pmatrix} x \\ \varphi \end{pmatrix} = \begin{pmatrix} \psi(\varphi'(0)) \\ 0 \end{pmatrix}$ .

For  $\begin{pmatrix} 0 \\ \zeta \end{pmatrix} \in D(A)$ , the Cauchy problem

$$\frac{d}{dt} \begin{pmatrix} x \\ \varphi \end{pmatrix} = A \begin{pmatrix} x \\ \varphi \end{pmatrix} + B \begin{pmatrix} x \\ \varphi \end{pmatrix}, \quad \begin{pmatrix} x \\ \varphi \end{pmatrix}(0) = \begin{pmatrix} 0 \\ \zeta \end{pmatrix},$$

has a unique strong solution given by

$$\begin{pmatrix} x \\ \varphi \end{pmatrix}(t) = \left( \int_0^t \psi(\zeta'(s)) ds, \zeta(t + \cdot) \right)$$

Given  $t \in (0, 1]$  we choose a  $\zeta \in C_{u,b}(\mathbf{R}; \mathbf{R})$  such that the restriction of  $\zeta$  to  $(0, t]$  does not have a bounded variation. Let  $(\zeta_n)$  be a sequence in  $C_{u,b}(\mathbf{R}; \mathbf{R})$  so that  $\zeta_n \rightarrow \zeta$  and  $(0, \zeta_n)^T \in D(A)$ .

If the solutions  $\begin{pmatrix} x_n(\cdot) \\ \varphi_n(\cdot) \end{pmatrix}$  with initial values  $\begin{pmatrix} 0 \\ \zeta_n \end{pmatrix}$  were convergent to, say  $\begin{pmatrix} \eta(t) \\ \omega(t) \end{pmatrix}$ , then we clearly have  $\omega(t) = \zeta(t + \cdot)$ .

Let  $0 \leq s_1 \leq s_2 \leq t$ . We choose measurable sets  $E_1$  and  $E_2$  such that

$$[s_1, s_2] = E_1 \cup E_2 \quad \text{and} \quad \psi(\zeta'_n(s)) \geq |\zeta'_n(s)| \quad \text{on } E_1$$

and

$$\psi(\zeta'_n(s)) \geq (\zeta'_n(s))^2 \quad \text{on } E_2.$$

Then

$$\int_{s_1}^{s_2} \psi(\zeta'_n(s)) \, ds \geq \int_{E_1} |\zeta'_n(s)| \, ds + \int_{E_2} (\zeta'_n(s))^2 \, ds \geq \int_{E_1} |\zeta'_n(s)| \, ds + \left( \int_{E_2} |\zeta'_n(s)| \, ds \right)^2 \cdot \frac{1}{\text{meas}(E_2)}.$$

Consequently,

$$\int_{s_1}^{s_2} |\zeta'_n(s)| \, ds \leq (s_2 - s_1) + \int_{s_1}^{s_2} \psi(\zeta'_n(s)) \, ds.$$

Taking the limit  $n \rightarrow \infty$  we thus obtain

$$|\zeta(s_2) - \zeta(s_1)| \leq \gamma(s_2) - \gamma(s_1) + s_2 - s_1,$$

where  $\gamma$  is the limit of the sequence of monotone functions  $\int_0^t \psi(\zeta'_n(s)) \, ds$  and hence  $\gamma$  is itself monotone. Therefore  $\zeta$  must be of bounded variation which contradicts the assumptions. As a consequence we deduce that the solution operators cannot be continuous which is a standing hypothesis for all nonlinear semigroups.

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