

ANNALES DE L'INSTITUT FOURIER

ROGER C. MCCANN

On absolute stability

Annales de l'institut Fourier, tome 22, n° 4 (1972), p. 265-269

http://www.numdam.org/item?id=AIF_1972__22_4_265_0

© Annales de l'institut Fourier, 1972, tous droits réservés.

L'accès aux archives de la revue « Annales de l'institut Fourier » (<http://annalif.ujf-grenoble.fr/>) implique l'accord avec les conditions générales d'utilisation (<http://www.numdam.org/legal.php>). Toute utilisation commerciale ou impression systématique est constitutive d'une infraction pénale. Toute copie ou impression de ce fichier doit contenir la présente mention de copyright.

NUMDAM

Article numérisé dans le cadre du programme
Numérisation de documents anciens mathématiques

<http://www.numdam.org/>

ON ABSOLUTE STABILITY

by Roger C. McCANN

It is well known that absolute stability of a compact subset M of a locally compact metric space can be characterized by the presence of a fundamental system of absolutely stable neighbourhoods, and also by the existence of a continuous Liapunov function V defined on some neighbourhood of $M = V^{-1}(0)$, [1]. Here we characterize the absolute stability of M in terms of the cardinality of the set of positively invariant neighbourhoods of M .

Throughout this paper \mathbb{R} and \mathbb{R}^+ will denote the reals and non-negative reals respectively. A rational number r is called dyadic if and only if there are integers n and j such that $n \geq 0$, $1 \leq j \leq 2^n$, and $r = \frac{j}{2^n}$.

A dynamical system on a topological space X is a mapping π of $X \times \mathbb{R}$ into X satisfying the following axioms (where $x\pi t = \pi(x, t)$):

- (1) $x\pi 0 = x$ for $x \in X$.
- (2) $(x\pi t)\pi s = x\pi(t + s)$ for $x \in X$ and $t, s \in \mathbb{R}$.
- (3) π is continuous in the product topology.

If $M \subset X$ and $N \subset \mathbb{R}$, then $M\pi N$ will denote the set $\{x\pi t : x \in M, t \in N\}$. A subset M of X is called positively invariant if and only if $M\pi\mathbb{R}^+ = M$. A point $x \in X$ is called a critical point if and only if $x\pi\mathbb{R} = \{x\}$. A subset M of X is called stable if and only if every neighbourhood of M contains a positively invariant neighbourhood of M .

A Liapunov function for a positively invariant compact subset M of X is a continuous mapping V of a neighbour-

hood W of M into \mathbb{R}^+ such that $V^{-1}(0) = M$ and $V(x\pi t) \leq V(x)$ for $x \in W$ and $t \in \mathbb{R}^+$.

Absolute stability is defined in terms of a prolongation and is characterized by the following theorem, [1].

THEOREM. — *Let M be a compact subset of a locally compact metric space. Then the following are equivalent:*

- (i) *There is a Liapunov function V for M .*
- (ii) *M possesses a fundamental system of absolutely stable neighbourhoods.*
- (iii) *M is absolutely stable.*

LEMMA 1. — *Let $A \subset \mathbb{R}$ be uncountable. Then there exists an $x \in A$ such that every neighbourhood of x contains uncountably many elements of A .*

Proof. — [4, 6,23, III].

The following is a consequence of Lemma 1.

LEMMA 2. — *Let $A \subset \mathbb{R}$ be uncountable. Then there exists an $x \in A$ such that the sets $\{y \in A : y < x\}$ and $\{y \in A : x < y\}$ are uncountable.*

LEMMA 3. — *Let S and T be relatively compact sets of a locally compact connected metric space X and \mathcal{D} a family of open sets of X such that*

- (i) *for every $U \in \mathcal{D}$, $\bar{S} \subset U \subset \bar{U} \subset T$,*
 - (ii) *if $U, V \in \mathcal{D}$, then either $\bar{U} \subset V$ or $\bar{V} \subset U$.*
- Then there is a $W \in \mathcal{D}$ such that the sets $\{U \in \mathcal{D} : U \subset W\}$ and $\{U \in \mathcal{D} : W \subset U\}$ are uncountable.*

Proof. — Since X is connected, the boundary ∂U of $U \in \mathcal{D}$ is nonempty. If $U \in \mathcal{D}$, then ∂U is compact since T is relatively compact. Let d be a metric on X and define $f: \mathcal{D} \rightarrow \mathbb{R}^+$ by $f(U) = d(\bar{S}, \partial U)$. If $U, V \in \mathcal{D}$ with $\bar{U} \subset V$, then $f(U) < f(V)$. Let A be the image of \mathcal{D} under f .

Then f is a one-to-one order preserving mapping of \mathcal{D} onto A . A is uncountable since \mathcal{D} is such. By Lemma 2 there is an $x \in A$ such that the sets $\{y \in A : x < y\}$ and

$\{y \in A : y < x\}$ are uncountable. Set $W = f^{-1}(x)$. It is easily verified that

$$\begin{aligned}\{U \in \mathcal{D} : U \subset W\} &= \{f^{-1}(y) : y < x\}, \\ \{U \in \mathcal{D} : W \subset U\} &= \{f^{-1}(y) : x < y\},\end{aligned}$$

and that both sets are uncountable.

THEOREM 4. — *A nontrivial compact subset M of a locally compact connected metric space is absolutely stable if and only if M possesses a fundamental system \mathcal{F} of open positively invariant neighbourhoods such that*

(i) for each $U \in \mathcal{F}$, the set $\{V \in \mathcal{F} : V \subset U\}$ is uncountable,

(ii) if $U, V \in \mathcal{F}$, then either $\bar{U} \subset V$ or $\bar{V} \subset U$.

Proof. — Since X is connected, no nontrivial subset of X is both open and closed. If M is absolutely stable, then there is a continuous Liapunov function V for M . Set $\mathcal{F} = \{V^{-1}([0, r]) : r \text{ in the range of } V\}$. It is easily verified that \mathcal{F} possesses the desired properties. Now assume that \mathcal{F} is a fundamental system of open positively invariant neighbourhoods of M with properties (i) and (ii). For each dyadic rational we will construct a set $U(r) \in \mathcal{F}$ such that $U(r) \subset U(s)$ whenever $r < s$. We first obtain from \mathcal{F} a fundamental system of neighbourhoods $\left\{U\left(\frac{1}{2^n}\right) : n \text{ a non-negative integer}\right\}$ such that $U\left(\frac{1}{2^{n+1}}\right) \subset U\left(\frac{1}{2^n}\right)$ and the set $\left\{A \in \mathcal{F} : U\left(\frac{1}{2^{n+1}}\right) \subset A \subset U\left(\frac{1}{2^n}\right)\right\}$ is uncountable. This is done by induction in the following manner. Let N_i be a countable fundamental system of neighbourhoods of M . Let $U(1) \subset N_1$ be an element of \mathcal{F} which is relatively compact. Suppose that $U\left(\frac{1}{2^n}\right)$ has been defined. By Lemma 3 and property (ii), there is a $B \in \left\{W \in \mathcal{F} : W \subset U\left(\frac{1}{2^n}\right)\right\}$ such that $B \subset N_{n+1}$ and both $\{W \in \mathcal{F} : W \subset B\}$ and

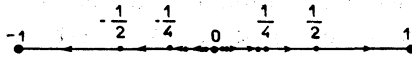
$$\left\{W \in \mathcal{F} : B \subset W \subset U\left(\frac{1}{2^n}\right)\right\}$$

are uncountable. Set $U\left(\frac{1}{2^{n+1}}\right) = B$. Now extend this system to one with the desired properties. For example, we chose $U\left(\frac{3}{4}\right)$ to be any element C of \mathcal{F} such that the sets $\left\{W \in \mathcal{F} : U\left(\frac{1}{2}\right) \subset V \subset C\right\}$ and $\{W \in \mathcal{F} : C \subset V \subset U(1)\}$ are uncountable. This is possible by the properties of the sets $U\left(\frac{1}{2^n}\right)$ and Lemma 3. Now define $V : U(1) \rightarrow \mathbb{R}^+$ by $V(x) = \inf \{r : x \in U(r)\}$. Evidently $V(x) = 0$ if and only if $x \in M$. If $x \in U(r)$ and $t \in \mathbb{R}^+$, then $x\pi t \in U(r)$ since $U(r)$ is positively invariant. Therefore,

$$V(x) = \inf \{r : x \in U(r)\} \geq \inf \{r : x\pi t \in U(r)\} = V(x\pi t).$$

The continuity of V is proved as in the proof of Urysohn's lemma. Thus we have constructed a Liapunov function for M . M is absolutely stable.

Example. — Let $X = [-1, 1]$, $M = \{0\}$, and π be the dynamical system indicated by the following diagram where the points $\pm 2^{-n}$, n a non-negative integer, are critical points.



Clearly M is stable. The only open positively invariant neighbourhoods of M are X and intervals of the form $(-2^{-m}, 2^{-n})$ where m and n are non-integers. There are only countably many such neighbourhoods. Hence, M is not absolutely stable.

PROPOSITION 5. — *Let X be the plane and p an isolated critical point. If each neighbourhood of p contains uncountably many periodic trajectories (cycles), then p is absolutely stable.*

Proof. — Let W be a disc neighbourhood of p which contains no critical points other than p . A cycle C is a Jordan curve and, hence, decomposes the plane into two components, one bounded (denoted by $\text{int } C$) and the other unbounded. If C is a cycle, then $\text{int } C$ contains a critical point, [3, VII,

4.8]. Hence, if C is a cycle in W , then C is the boundary of a neighbourhood (necessarily invariant) of p . It can be shown (the proof is almost identical with that of Proposition 1.10 of [6]) that if C_1 and C_2 are distinct cycles in W , then either $\overline{\text{int } C_1} \subset \text{int } C_2$ or $\overline{\text{int } C_2} \subset \text{int } C_1$. Theorem 4 may now be applied to obtain the desired result.

Another characterization of absolute stability of compact sets is found in [5]. Non-compact absolutely stable sets are characterized in [3].

BIBLIOGRAPHY

- [1] J. AUSLANDER, P. SEIBERT, Prolongations and stability in dynamical systems, *Ann. Inst. Fourier*, Grenoble, 14 (1964), 237-268.
- [2] O. HAJEK, Dynamical Systems in the Plane, Academic Press, London, 1968.
- [3] O. HAJEK, Absolute stability of non-compact sets, *J. Differential Equations* 9 (1971), 496-508.
- [4] K. KURATOWSKI, Topology Vol. I, Academic Press, London, 1966.
- [5] R. McCANN, Another characterization of absolute stability, *Ann. Inst. Fourier*, Grenoble, 21,4 (1971), 175-177.
- [6] R. McCANN, A classification of centers, *Pacific J. Math.*, 30 (1969), 733-746.

Manuscrit reçu le 7 février 1972,
accepté par M. Reeb.

Roger C. McCANN,
Department of Mathematics,
Case Western Reserve University,
Cleveland, Ohio 44 106 (USA).
