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## ON SETS FILLED BY ASYMPTOTIC SOLUTIONS OF DIFFERENTIAL EQUATIONS

### A. PLIS (Krakov)

Consider an ordinary differential equation

(1) 
$$x' = f(t, x) \\ x = (x_1, \ldots, x_n), \quad f = (f_1, \ldots, f_n).$$

Assumption I. Suppose that the domain D of f(t, x) is open, f(t, x) is continuous on D and through each point

A: 
$$t = a_0, \quad x = a = (a_1, a_2, \ldots, a_n)$$

of D passes only one integral x = x(t, A) of (1).

Denote by  $(\alpha(A), \beta(A))$  the maximal interval on which there exists the integral passing through A. We shall denote

$$X(t, A) = (t, x(t, A))$$
 for  $t \in (\alpha(A), \beta(A))$ .

Let E be an open subset of D. In the following we shall deal with the set Z(E) of such points A, that  $X(t, A) \in E$  for  $a_0 \le t < \infty$ . Obviously set Z(E) depends on both set E and system (1). It is evident that  $E \subset F$  implies  $Z(E) \subset Z(F)$ . Let  $\varphi$  be a family of subsets F of D. We shall consider the following properties of equation (1).

PROPERTY I (of equation (1) in respect to E and  $\varphi$ ). — For every  $F \in \varphi$  Z(E)  $\cap$  F is empty or consists of one point.

PROPERTY II. — For every  $F \in \varphi$   $Z(E) \cap F$  is not empty. Let  $I^+(A)$  denote the set of all points B = X(t, A) for  $t \ge a_0$ .

We say that the point  $A \in P(G) \cap D$ , where P(G) denotes the boundary of an open set G, is the point of egress from G (with respect to equation (1) and set D) if there exists such an integral x(t) of (1) and a positive number  $\varepsilon > 0$  that

$$x(a_0) = a$$
 and  $(t, x(t)) \in G$ 

for  $a_0 - \varepsilon < t < a_0$  (under Assumption I,  $X(t, A) \in G$  for  $a_0 - \varepsilon < t < a_0$ ). If no point of P(G) is a point of egress from G then  $A \in G$  implies  $I^+(A) \subset G$ . If Property I is satisfied and  $B \in Z(E) \cap F$  then  $(F - B) \cap Z(E) = \emptyset$ , where F - B denotes the set of all points of the set F except the point B. It follows that for every  $A \in F$ ,  $A \neq B$  either  $I^+(A) \sim \in E$  or  $\beta(A) < \infty$ . Let G be such a set that  $G \cap E$  has no common point with a plane  $t = c > a_0$ , where G denotes the closure of G, then  $I^+(A) \subset G$  implies  $A \sim \in Z(E)$ .

Lemma. — Suppose Assumption I and the following conditions. For each set  $G_i(i=1,\ldots)G_i \cap E$  is contained in a halfspace  $t < c_i$ . No point of  $P(G_i)$  is a point of egress. Set F satisfies inclusion  $F - O \subset \bigcup_{i=1}^{\infty} G_i$ .

Then 
$$(F - O) \cap Z(E) = \emptyset$$
.

Theorem 1. — Suppose Assumption I and the following conditions. The intersection E(s) of a given set E and the plane t=s satisfies the inequality diam(E(t)) < p(t), where p(t) is a positive function continuous on  $(-\infty, \infty)$ . No point of  $P(G_i)$  is a point of egress in respect to the equation

$$x' = f(t + a_0, x + a(t)) - f(t + a_0, a(t)),$$

where  $a_0$  is a real number and x = a(t) is such a Lipchitzian function that the right side of the equation is defined. Set F

satisfies inclusion  $F - O \subset \bigcup_{i=1}^{n} G_i$ . For any i and s there exists a constant c(i, s) that dist  $(G_i(t), O) \ge p(t + s)$  for  $t \ge c(i, s)$ ,

where  $G_i(s)$  is the intersection of  $G_i$  and the plane t = s. Under these assumptions if  $A \in Z(E)$ , then

$$(F(A) - A) \cap Z(E) = \emptyset$$

where F(A) denotes set obtained from A by translation of  $R^{n+1}$  transforming O on A.

THEOREM 2. — If assumptions of Theorem 1 are satisfied and F is a plane then equation (1) possesses property I in respect to E and the family of planes parallel to F (and of the same dimension).

Suppose now that set F is a plane and in the coordinate system t, x = (u, v),  $u = (u_1, \ldots, u_k)$ ,  $v = (v_1, \ldots, v_{n-k})$  it has the equation t = 0, u = 0. Now Property I (for the family of planes  $t = c_0$ ,  $u = (c_1, \ldots, c_k)$ ,  $c_i$  arbitrary) is necessary and sufficient for set Z(E) to be the graph of a single-valued function v = q(t, u). Putting  $g = (f_1, \ldots, f_k)$ ,  $h = (f_{k+1}, \ldots, f_n)$  system (1) takes the form

(2) 
$$u' = g(t, u, v), \qquad v' = h(t, u, v).$$

The following result formulated in terms of inequalities can be obtain from Theorem 1 formulated in terms of sets (1)

THEOREM 3. — Suppose that system (2) satisfies Assumption I and that the functions g(t, u, v), h(t, u, v) for

$$(t, u, v) \in \mathcal{D}, \qquad (t, \overline{u}, \overline{v}) \in \mathcal{D}$$

satisfy inequalities

$$(3) \quad (g(t, u, v) - g(t, \overline{u}, \overline{v})) \ (u - \overline{u}) \leqslant \gamma(t) \ (u - \overline{u})^2$$

for  $|v - \overline{v}| = |u - \overline{u}|$ , where |z| denotes Euclidean distance of point z from 0,

$$(4) \quad (h(t, u, v) - h(t, \overline{u}, \overline{v})) \ (v - \overline{v}) \geqslant \gamma(t) \ (v - \overline{v})^2,$$

for

$$|u-\overline{u}|\leqslant |v-\overline{v}|,$$

where  $\gamma(t)$  is a function summable in every finite interval, and such that

$$\int_0^\infty \gamma(s) \ ds = \infty,$$

then set Z of points A lying on the integrals of (2) (remaining in D) bounded for  $a_0 \leq t < \infty$  is a graph of a single-valued function v = q(t, u) defined in a certain set  $S(S \subset \mathbb{R}^{k+1})$  satisfying the Lipschitz condition with respect to all the variables

<sup>(1)</sup> Such kind of formulation was suggested by T. Wazewski.

194

and in particular the condition

$$|q(t, u) - q(t, \overline{u})| \leqslant |u - \overline{u}|$$

in the set S or the set Z is an empty set.

Theorem 3 is a particular case of theorem 2 in [1].

Now for illustration of Property II we present a variant of an example from [2].

Let system (2) satisfy Assumption I on a neighbourhood D of the set  $H: |u| \leq 1$ ,  $|v| \leq 1$ ,  $-\infty < t < \infty$ . Moreover suppose that g(t, u, v)u < 0 for |u| = 1,  $|v| \leq 1$  and arbitrary t, h(t, u, v) > 0 for |v| = 1,  $|u| \leq 1$  and arbitrary t.

Under these assumptions for every  $\overline{u}$ ,  $|\overline{u}| < 1$  and arbitrary  $\overline{t}$ , there exists  $\overline{v}$ , that  $I^+(\overline{t}, \overline{u}, \overline{v}) \in H$ .

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