



Differential geometry

A remark on the Bismut–Ricci form on 2-step nilmanifolds [☆]

Une remarque sur la forme de Bismut–Ricci des espaces homogènes sous l'action d'un groupe nilpotent de classe ≤ 2

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ABSTRACT

In this note, we observe that, on a 2-step nilpotent Lie group equipped with a left-invariant SKT structure, the $(1, 1)$ -part of the Bismut–Ricci form is seminegative definite. As an application, we give a simplified proof of the non-existence of invariant SKT static metrics on 2-step nilmanifolds and of the existence of a long-time solution to the pluriclosed flow in 2-step nilmanifolds.

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R É S U M É

Nous observons que, sur un groupe de Lie nilpotent de classe ≤ 2 , équipé d'une structure de Kähler forte avec torsion (SKT), invariante à gauche, la partie $(1, 1)$ de la forme de Bismut–Ricci est définie semi-négative. Comme application, nous donnons une démonstration simplifiée de la non-existence d'une métrique statique SKT sur un espace homogène sous l'action d'un groupe nilpotent de classe ≤ 2 . Nous montrons également l'existence d'une solution à long terme du flot plurifermé dans ces mêmes espaces.

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1. The Bismut–Ricci form on 2-step SKT nilmanifolds

An Hermitian manifold is called SKT if its fundamental form is $\partial\bar{\partial}$ -closed. The SKT condition can be described in terms of the Bismut connection by requiring that the torsion form is closed. Indeed, on any Hermitian manifold (M, g) , there is a unique Hermitian connection ∇ such that the tensor $c := g(T(\cdot, \cdot), \cdot)$ is skew-symmetric in its entries [2], where T is the torsion of ∇ . The metric g is SKT if and only if $dc = 0$. In this note, we focus on the Ricci form of ∇ . In analogy to the Kähler case, the form is defined by

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$$\rho^B(X, Y) = \text{tr}_\omega R^B(X, Y, \cdot, \cdot),$$

ω being the fundamental form of g and R^B the curvature tensor of ∇ .

We consider as a manifold M a 2-step nilpotent Lie group G equipped with an invariant Hermitian structure (J, g) . Under these assumptions, the form ρ^B takes the following expression

$$\rho^B(X, Y) = i \sum_{r=1}^n g([X, Y], [Z_r, \bar{Z}_r]), \quad \text{for every } X, Y \in \mathfrak{g}, \tag{1}$$

where $\{Z_r\}$ is an arbitrary g -unitary frame of the Lie algebra \mathfrak{g} of G (see [6,12], taking into account that here we adopt the convection $\omega(\cdot, \cdot) = g(J\cdot, \cdot)$ in contrast to the one adopted in [6]). More generally, if G is just a Lie group with an invariant Hermitian structure, ρ^B takes the following expression

$$\rho^B(X, Y) = -i \sum_{r=1}^n \left\{ g([X, Y]^{1,0}, Z_r, \bar{Z}_r) - g([X, Y]^{0,1}, \bar{Z}_r, Z_r) - g([X, Y], [Z_r, \bar{Z}_r]) \right\} \tag{2}$$

(see [6,12], again). We have the following proposition.

Proposition 1.1. *Let G be a $2n$ -dimensional 2-step nilpotent Lie group with a left-invariant SKT structure (J, g) . Then*

$$\rho^B(Z, \bar{Z}) = -i \sum_{r=1}^n \|[Z, \bar{Z}_r]\|^2$$

for every $Z \in \mathfrak{g}^{1,0}$, where $\{Z_r\}$ is an arbitrary unitary frame. In particular,

$$\rho^B(X, JX) \leq 0$$

for every $X \in \mathfrak{g}$.

Proof. Let Z and W be vector fields of type $(1, 0)$ on $\mathfrak{g} \otimes \mathbb{C}$, and let ω be the fundamental form of g . Then we directly compute

$$\begin{aligned} \partial\bar{\partial}\omega(Z, \bar{Z}, W, \bar{W}) &= -\bar{\partial}\omega([Z, \bar{Z}], W, \bar{W}) + \bar{\partial}\omega([Z, W], \bar{Z}, \bar{W}) - \bar{\partial}\omega([Z, \bar{W}], \bar{Z}, W) \\ &\quad - \bar{\partial}\omega([\bar{Z}, W], Z, \bar{W}) + \bar{\partial}\omega([\bar{Z}, \bar{W}], Z, W) - \bar{\partial}\omega([W, \bar{W}], Z, \bar{Z}) \\ &= -\bar{\partial}\omega([Z, \bar{Z}]^{0,1}, W, \bar{W}) + \bar{\partial}\omega([Z, W], \bar{Z}, \bar{W}) - \bar{\partial}\omega([Z, \bar{W}]^{0,1}, \bar{Z}, W) \\ &\quad - \bar{\partial}\omega([\bar{Z}, W]^{0,1}, Z, \bar{W}) + \bar{\partial}\omega([\bar{Z}, \bar{W}], Z, W) - \bar{\partial}\omega([W, \bar{W}]^{0,1}, Z, \bar{Z}) \\ &= -\omega([Z, \bar{Z}]^{0,1}, [W, \bar{W}]^{1,0}) + \omega([Z, W], [\bar{Z}, \bar{W}]) - \omega([Z, \bar{W}]^{0,1}, [\bar{Z}, W]^{1,0}) \\ &\quad - \omega([\bar{Z}, W]^{0,1}, [Z, \bar{W}]^{1,0}) + \omega([\bar{Z}, \bar{W}], [Z, W]) - \omega([W, \bar{W}]^{0,1}, [Z, \bar{Z}]^{1,0}) \\ &= + \text{ig}([Z, \bar{Z}]^{0,1}, [W, \bar{W}]^{1,0}) + \text{ig}([Z, W], [\bar{Z}, \bar{W}]) + \text{ig}([Z, \bar{W}]^{0,1}, [\bar{Z}, W]^{1,0}) \\ &\quad + \text{ig}([\bar{Z}, W]^{0,1}, [Z, \bar{W}]^{1,0}) - \text{ig}([\bar{Z}, \bar{W}], [Z, W]) + \text{ig}([W, \bar{W}]^{0,1}, [Z, \bar{Z}]^{1,0}) \\ &= + \text{ig}([Z, \bar{Z}], [W, \bar{W}]) + \text{ig}([Z, \bar{W}], [\bar{Z}, W]). \end{aligned}$$

The SKT assumption $\partial\bar{\partial}\omega = 0$ implies

$$g([Z, \bar{Z}], [W, \bar{W}]) = -g([Z, \bar{W}], [\bar{Z}, W]).$$

Therefore, in view of (1), we get

$$\rho^B(Z, \bar{Z}) = i \sum_{r=1}^n g([Z, \bar{Z}], [Z_r, \bar{Z}_r]) = -i \sum_{r=1}^n g([Z, \bar{Z}_r], [\bar{Z}, Z_r]),$$

being $\{Z_r\}$ an arbitrary unitary frame, and the claim follows. \square

Remark 1.2. Another description of the Bismut–Ricci form on 2-step nilmanifolds can be found in [1].

Next we observe that in general the form ρ^B is not seminegative definite if we drop the assumption on G to be nilpotent or on the metric to be SKT.

Example 1.3. Let \mathfrak{g} be the solvable unimodular Lie algebra with structure equations

$$de^1 = 0, \quad de^2 = -e^{13}, \quad de^3 = e^{12}, \quad de^4 = -e^{23},$$

equipped with the complex structure $Je_1 = e_4$ and $Je_2 = e_3$ and the SKT metric

$$g = \sum_{r=1}^4 e^r \otimes e^r + \frac{1}{2}(e^1 \otimes e^3 + e^3 \otimes e^1) - \frac{1}{2}(e^2 \otimes e^4 + e^4 \otimes e^2).$$

By using (2) with respect to a unitary frame $\{Z_r\}$, we easily get

$$\rho^B = \frac{2}{3}e^{12} - \frac{2}{3}e^{13} + \frac{4}{3}e^{23}.$$

In particular,

$$\rho^B(e_2, Je_2) = \frac{4}{3} \quad \text{and} \quad \rho^B(4e_1 + e_2, J(4e_1 + e_2)) = -\frac{4}{3}$$

which implies that ρ^B is not seminegative definite as $(1, 1)$ -form.

Example 1.4. Let (\mathfrak{g}, J) be the 2-step nilpotent Lie algebra with structure equations

$$de^1 = de^2 = de^3 = 0, \quad de^4 = e^{12}, \quad de^5 = -e^{23}, \quad de^6 = e^{13},$$

and equipped with the complex structure $Je_1 = e_2$, $Je_3 = e_4$ and $Je_5 = e_6$ and the non-SKT metric

$$g = \sum_{r=1}^6 e^r \otimes e^r + \frac{1}{2}(e^3 \otimes e^6 + e^6 \otimes e^3) - \frac{1}{2}(e^4 \otimes e^5 + e^5 \otimes e^4).$$

Again by using (2) with respect to a unitary frame $\{Z_r\}$, we easily get

$$\rho^B = -e^{12} - \frac{1}{2}e^{23},$$

which implies that ρ^B is not seminegative definite as $(1, 1)$ -form.

2. Non-existence of invariant SKT metrics satisfying $(\rho^B)^{1,1} = \lambda\omega$

In this section, we observe that our Proposition 1.1 easily implies that, on a 2-step nilpotent Lie group, there are no SKT invariant metrics such that

$$(\rho^B)^{1,1} = \lambda\omega$$

for some constant λ . This result is already known: the case $\lambda = 0$ was studied in [4], while the case $\lambda \neq 0$ follows from [5].

Indeed, in the setting of Proposition 1.1, if we assume $(\rho^B)^{1,1} = \lambda\omega$, then, taking into account that the center of G is not trivial, formula (1) implies $\lambda = 0$ and, from Proposition 1.1, it follows $[\mathfrak{g}^{1,0}, \mathfrak{g}^{0,1}] = 0$. Therefore, if $\{\zeta^k\}$ is a unitary co-frame in \mathfrak{g} , we have

$$\bar{\partial}\zeta^k = 0$$

and we can write

$$\partial\zeta^k = c_{rs}^k \zeta^r \wedge \zeta^s,$$

for some c_{rs}^k in \mathbb{C} . Then

$$\partial\bar{\partial}\omega = i\partial\bar{\partial}\left(\sum_{k=1}^n \zeta^k \wedge \bar{\zeta}^k\right) = -i\partial\left(\sum_{k=1}^n \bar{c}_{rs}^k \zeta^k \wedge \bar{\zeta}^r \wedge \bar{\zeta}^s\right) = -i\sum_{k=1}^n c_{ab}^k \bar{c}_{rs}^k \zeta^a \wedge \zeta^b \wedge \bar{\zeta}^r \wedge \bar{\zeta}^s$$

and the SKT assumption implies that all the c_{rs}^k 's vanish in contrast to the assumption on G to be not abelian.

3. Long-time existence of the pluriclosed flow on 2-step nilmanifolds

The pluriclosed flow (PCF) is a parabolic flow of Hermitian metrics that preserves the SKT condition. The flow is defined on an SKT manifold (M, ω) as

$$\partial_t \omega_t = -(\rho_{\omega_t}^B)^{1,1}, \quad \omega|_{t=0} = \omega,$$

where $\rho_{\omega_t}^B$ is computed with respect to ω_t and the superscript “1, 1” is the (1, 1)-component with respect to J . The flow was introduced in [8] and then investigated in [3,8–11], and it is a powerful tool in SKT geometry.

In [6], it is proved that on a 2-step nilpotent Lie group, the flow has always a long-time solution for any initial invariant datum. The proof makes use of the bracket flow device introduced by Lauret in [7].

In our setting, let G be a 2-step nilpotent Lie group with a left-invariant complex structure J and consider the PCF equation starting from an invariant SKT form ω . The solution ω_t holds invariant for every t and, therefore, the flow can be regarded as an ODE on $\Lambda^2 \mathfrak{g}^* \otimes \mathfrak{g}$, where \mathfrak{g} is the Lie algebra of G . The bracket flow device consists in evolving the Lie bracket on \mathfrak{g} instead of the form ω . For this purpose, one considers the bracket variety \mathcal{A} consisting of the elements $\lambda \in \Lambda^2 \mathfrak{g}^* \otimes \mathfrak{g}$ such that

$$\lambda(\lambda(X, Y), V) = 0, \tag{3}$$

$$\lambda(JX, JY) - J\lambda(JX, Y) - J\lambda(X, JY) - \lambda(X, Y) = 0, \tag{4}$$

$$\partial_\lambda \bar{\partial}_\lambda \omega = 0, \tag{5}$$

for every $X, Y, V \in \mathfrak{g}$, where the operators ∂_λ and $\bar{\partial}_\lambda$ are computed by using the bracket λ . Any $\lambda \in \mathcal{A}$ gives a structure of 2-step nilpotent Lie algebra to \mathfrak{g} such that (J, ω) is an SKT structure. It turns out that the PCF is equivalent to a bracket flow-type equation, i.e. an ODE in \mathcal{A} . The equivalence between the two equations is obtained by evolving the initial bracket μ of \mathfrak{g} as

$$\mu_t(X, Y) = h_t \mu(h_t^{-1} X, h_t^{-1} Y), \quad X, Y \in \mathfrak{g},$$

being h_t the curve in $\text{End}(\mathfrak{g})$ solving

$$\frac{d}{dt} h_t = -\frac{1}{2} h_t P_{\omega_t}, \quad h|_{t=0} = I$$

and $P_{\omega_t} \in \text{End}(\mathfrak{g})$ is defined by

$$\omega_t(P_{\omega_t} X, Y) = \frac{1}{2} (\rho_{\omega_t}^B(X, Y) + \rho_{\omega_t}^B(JX, JY)).$$

The form ω_t reads in terms of h_t as

$$\omega_t(X, Y) = \omega(h_t X, h_t Y).$$

Now, in view of formula (1),

$$\rho_{\omega_t}^B(X, \cdot) = 0 \text{ for every } X \in \xi$$

and then $\omega_t(X, \cdot) = \omega(X, \cdot)$ for every $X \in \xi$, where ξ is the center of μ . Let ξ^\perp be the g -orthogonal complement of ξ in \mathfrak{g} and let g_t be the Hermitian metric corresponding to the solution to the PCF equation starting from ω . Then

$$\frac{d}{dt} g_t(X, \cdot) = 0 \text{ for every } X \in \xi$$

and g_t preserves the splitting $\mathfrak{g} = \xi \oplus \xi^\perp$, and the flow evolves only the component of g in $\xi^\perp \times \xi^\perp$. It follows that h_t preserves the splitting $\mathfrak{g} = \xi \oplus \xi^\perp$ and

$$h_t|_\xi = I_\xi.$$

Since (\mathfrak{g}, μ) is 2-step nilpotent, then $\mu(X, Y) \in \xi$ for every $X, Y \in \mathfrak{g}$ and

$$\mu_t(X, Y) = \mu(h_t^{-1} X, h_t^{-1} Y).$$

Therefore

$$\begin{aligned} \frac{d}{dt} \mu_t(X, Y) &= -\mu(h_t^{-1} \dot{h}_t h_t^{-1} X, h_t^{-1} Y) - \mu(h_t^{-1} X, h_t^{-1} \dot{h}_t h_t^{-1} Y) \\ &= -\mu_t(\dot{h}_t h_t^{-1} X, Y) - \mu_t(X, \dot{h}_t h_t^{-1} Y) = \frac{1}{2} \mu_t(P_{\mu_t} X, Y) + \frac{1}{2} \mu_t(X, P_{\mu_t} Y), \end{aligned}$$

where for any $\lambda \in \mathcal{A}$ we set

$$\omega(P_\lambda X, Y) = i \frac{1}{2} \sum_{r=1}^n (g(\lambda(X, Y), \lambda(Z_r, \bar{Z}_r)) + g(\lambda(JX, JY), \lambda(Z_r, \bar{Z}_r)))$$

being $\{Z_r\}$ an arbitrary g -unitary frame and in the last step we have used

$$h_t P_{\omega_t} = P_{\mu_t} h_t.$$

Hence the bracket flow equations writes as

$$\frac{d}{dt} \mu_t(X, Y) = \frac{1}{2} \mu_t(P_{\mu_t} X, Y) + \frac{1}{2} \mu_t(X, P_{\mu_t} Y), \quad \mu_{|t=0} = \mu \quad (6)$$

and its solution satisfies

$$\frac{d}{dt} g(\mu_t, \mu_t) = 2g(\dot{\mu}_t, \mu_t) = 4 \sum_{r,s=1}^{2n} g(\mu_t(P_{\mu_t} e_r, e_s), \mu_t(e_r, e_s))$$

being $\{e_r\}$ an arbitrary g -orthonormal frame. In view of [Proposition 1.1](#), all the eigenvalues of any P_{μ_t} are nonpositive. Fixing t and taking as $\{e_r\}$ an orthonormal basis of eigenvectors of P_{μ_t} , we get

$$\frac{d}{dt} g(\mu_t, \mu_t) = 4 \sum_{r,s=1}^{2n} a_r g(\mu_t(e_r, e_s), \mu_t(e_r, e_s)) \leq 0.$$

It follows that solution μ_t to (6) will stay forever in a compact subset, which implies that μ_t is defined for every $t \in [0, \infty)$, and the claim follows.

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